# Shuyu van Kerkwijk

 ♥ Vancouver / Toronto
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 • Portfolio
 in Linkedin
 • Github

## Education

# University of British Columbia (GPA: 93%)

Sept 2022 - May 2027

BASc Engineering Physics, BSc Honours Computer Science & Physics

• Coursework: Probability, Linear Algebra, ODEs, PDEs, Signals and Systems, Reinforcement & Imitation learning, Data Structures & Algorithms, Digital Systems, Microcomputers, Instrument Design

# Research Experience

# Caltech DSA-2000 Radio Array, Software Intern

Pasadena, CA

Recipient of Caltech SURF Award under Dr. Vikram Ravi

May - Aug 2025

- $\circ$  Here  $\square$  is a description of the DSA-2000 project and my approved proposal on characterizing the test array.
- Developing the software pipeline for raw cross-correlation data, including fringe stopping and phase correction.

# UBC-NASA CGEM Telescope, Electrical Intern

Vancouver, BC

Recipient of national NSERC USRA Award under Dr. Mark Halpern

Apr 2024 - May 2025

- Built and validated the azimuthal and elevation angle pointing data systems for the telescope.
- o Optimized ADC signal chain, reducing artifacts, quantization error, 60Hz radiated pickup, and aliasing.
- Programmed STM F4/H7 microcontrollers, RPis, and FPGA for fast data acquisition and networking.

## UofT LT Research Institute, Research Student

Toronto, ON

Recipient of UofT SUDS Award under Dr. Mei Zhen

May - Aug 2023

- Built a pipeline for 3D neuron-reconstruction from 2D image slices using image and graph algorithms.
- Trained a U-Net CNN to segment nuclei, as part of a global effort to generate full brain connectivity models.
- Presented 2x award-winning research of on stress-induced neuron structural changes at conferences

# **Projects**

## Flatiron Institute (Simon's Foundation) CryoJax (2025)

Github 🗹

Contributing to CryoJax, a cryo-EM simulation framework, by implementing its first physical solvent model.

#### Self-Driving Robot Competition (2025), 1ST PLACE

Link 🗹

- Trained an end-to-end imitation learning model in ROS/Gazebo for real-time autonomous navigation.
- Built a custom CNN in TensorFlow for real-time alphanumeric character recognition on road-signs

# Burger-Cooking Robot Competition (2024)

Link 🗹

- $\circ\,$  Built an autonomous 22-DOF robot with vacuum-based crane arms to cook and assemble burgers.
- Developed FreeRTOS firmware coordinating 3 microcontrollers and 40+ calibrated sensors/actuators.
- Designed and soldered custom PCBs (motor drivers, bandpass filters, etc.) and fabricated chassis components.

# National Physics Team (2021-2022), 2ND PLACE

Finals 🗹

• Selected for IYPT Team Canada based on national performance; researched and presented fluid flow problems.

### Skills

Languages: Python, C++, C, Java, SQL, Assembly, VHDL & English, Dutch, Mandarin

**Technologies:** JAX, TensorFlow, PyTorch, ROS1, Gazebo, ImageJ, NumPy, Pandas, Scikit-learn, OpenCV, PyQt, KiCad, STM32CubeIDE, PlatformIO, Excel, Git

#### Awards

Academic: UBC Charles & Jane Banks Scholarship, UBC Dean's Scholar, UTS W. Livingstone Physics Prize

Other: Scratch Featured Project Z (age 11), 2nd at Volleyball Nationals (2024), Harold Smith Essay Award