

Math 357

Galois theory example

April 18, 2024

In these notes we use galois theory to analyze algebraic objects—zeros, field extensions, and groups—arising from the polynomial $f = t^3 - 2 \in \mathbf{Q}[t]$. We start with a summary of the story. We invite the reader to fill in details and justify the assertions before proceeding to following sections, in which we explore the story and logic together.

1 Overview

Let

$$f = t^3 - 2 \in \mathbf{Q}[t]$$

A splitting field for f is $K = \mathbf{Q}(\alpha, \zeta_3)$, where α is a zero of f , and ζ_3 is a zero of $g = t^2 + t + 1 \in \mathbf{Q}[t]$. A basis for K as a \mathbf{Q} -vector space is

$$\mathcal{B} = (1, \alpha, \alpha^2, \zeta_3, \zeta_3\alpha, \zeta_3\alpha^2)$$

The field extension $K : \mathbf{Q}$ is galois, with galois group

$$\text{Gal}(K : \mathbf{Q}) = \langle \sigma, \tau \mid \sigma^3, \tau^2, (\sigma\tau)^2 \rangle$$

where the automorphisms $\sigma, \tau : K \rightarrow K$ are defined by

$$\begin{array}{ll} \sigma : \alpha \mapsto \zeta_3\alpha & \tau : \alpha \mapsto \alpha \\ \zeta_3 \mapsto \zeta_3 & \zeta_3 \mapsto \zeta_3^2 = -(1 + \zeta_3) \end{array} \tag{1}$$

One can use the galois correspondence between subfields and subgroups to enumerate and match all of each. In particular, the subfield $\mathbf{Q}(\zeta_3\alpha)$ corresponds to the subgroup $\langle \sigma^2\tau \rangle$. That is,

$$\mathcal{F}(\langle \sigma^2\tau \rangle) = \mathbf{Q}(\zeta_3\alpha) \qquad \text{Aut}(K : \mathbf{Q}(\zeta_3\alpha)) = \langle \sigma^2\tau \rangle$$

2 Subfield–subgroup correspondence

Claim: $\mathcal{F}(\langle \sigma^2\tau \rangle) = \mathbf{Q}(\zeta_3\alpha)$.

To prove this claim, we show set containment in both directions. Recall that $\langle \sigma^2\tau \rangle = \{\text{id}_K, \sigma^2\tau\}$, and the identity map id_K fixes all of K , and hence, in particular, $\mathbf{Q} \subseteq K$. Thus for the fixed-field computations here, it suffices to analyze $\sigma^2\tau$. (More generally, we need to analyze a set of

generators of the subgroup.) Also recall that, by definition, ζ_3 is a zero of $g = t^2 + t + 1$, hence also a zero of $(t - 1)g = t^3 - 1$. Explicitly writing out what these zeros mean, we get

$$\zeta_3^2 = -(1 + \zeta_3) \quad \zeta_3^3 = 1$$

(\supseteq) Because $\sigma, \tau \in \text{Gal}(K : \mathbf{Q}) = \text{Aut}(K : \mathbf{Q})$, they are field homomorphisms. Using this fact and the defining images of σ and τ specified in equation (1), we compute

$$\begin{aligned} \sigma^2 \tau(\zeta_3 \alpha) &= \sigma(\sigma(\tau(\zeta_3 \alpha))) \\ &= \sigma(\sigma(\tau(\zeta_3) \tau(\alpha))) \\ &= \sigma(\sigma(\zeta_3^2 \cdot \alpha)) \\ &= \sigma(\sigma(\zeta_3)^2 \sigma(\alpha)) \\ &= \sigma(\zeta_3^2 \cdot \zeta_3 \alpha) = \sigma(\zeta_3^3 \alpha) = \sigma(\alpha) \\ &= \zeta_3 \alpha \end{aligned}$$

Alternatively, we can use the same hypotheses to compute where $\sigma^2 \tau$ sends each generator of $K = \mathbf{Q}(\alpha, \zeta_3)$:

$$\sigma^2 \tau(\alpha) = \zeta_3^2 \alpha \quad \sigma^2 \tau(\zeta_3) = \zeta_3^2 \quad (2)$$

to conclude that

$$\sigma^2 \tau(\zeta_3 \alpha) = \sigma^2 \tau(\zeta_3) \cdot \sigma^2 \tau(\alpha) = \zeta_3^2 \cdot \zeta_3^2 \alpha = \zeta_3^4 \alpha = \zeta_3 \alpha$$

This shows that $\sigma^2 \tau$ fixes the element $\zeta_3 \alpha \in K$. Because $\sigma^2 \tau \in \text{Gal}(K : \mathbf{Q})$, $\sigma^2 \tau$ also fixes the base field \mathbf{Q} . Hence $\sigma^2 \tau$ fixes $\mathbf{Q}(\zeta_3 \alpha)$. That is,

$$\mathbf{Q}(\zeta_3 \alpha) \subseteq \mathcal{F}(\langle \sigma^2 \tau \rangle) \quad (3)$$

(\subseteq) To show the reverse inclusion, let $\beta \in \mathcal{F}(\langle \sigma^2 \tau \rangle) \subseteq K$. Because $\mathcal{B} = (1, \alpha, \alpha^2, \zeta_3, \zeta_3 \alpha, \zeta_3 \alpha^2)$ is a \mathbf{Q} -basis for K , there exist unique $a_{i,j} \in \mathbf{Q}$ such that

$$\begin{aligned} \beta &= \sum_{\substack{i \in \{0,1\}, \\ j \in \{0,1,2\}}} a_{i,j} \zeta_3^i \alpha^j \\ &= a_{0,0} 1 + a_{0,1} \alpha + a_{0,2} \alpha^2 + a_{1,0} \zeta_3 + a_{1,1} \zeta_3 \alpha + a_{1,2} \zeta_3 \alpha^2 \end{aligned} \quad (4)$$

Because $\sigma^2 \tau \in \text{Gal}(K : \mathbf{Q}) = \text{Aut}(K : \mathbf{Q})$, it is a field homomorphism that fixes all elements of \mathbf{Q} . In particular, it fixes each $a_{i,j}$. Using these facts and our computation of $\sigma^2 \tau$ on generators of $K : \mathbf{Q}$ in equation (2), we compute

$$\begin{aligned} \sigma^2 \tau(\beta) &= \sigma^2 \tau \left(\sum_{\substack{i \in \{0,1\}, \\ j \in \{0,1,2\}}} a_{i,j} \zeta_3^i \alpha^j \right) = \sum_{\substack{i \in \{0,1\}, \\ j \in \{0,1,2\}}} a_{i,j} \cdot (\sigma^2 \tau(\zeta_3))^i \cdot (\sigma^2 \tau(\alpha))^j \\ &= a_{0,0} \cdot 1 + a_{0,1} \cdot \sigma^2 \tau(\alpha) + a_{0,2} \cdot (\sigma^2 \tau(\alpha))^2 \\ &\quad + a_{1,0} \cdot \sigma^2 \tau(\zeta_3) + a_{1,1} \cdot \sigma^2 \tau(\zeta_3) \cdot \sigma^2 \tau(\alpha) + a_{1,2} \cdot \sigma^2 \tau(\zeta_3) \cdot (\sigma^2 \tau(\alpha))^2 \\ &= a_{0,0} 1 + a_{0,1} \zeta_3^2 \alpha + a_{0,2} \zeta_3^2 \alpha^2 + a_{1,0} \zeta_3^2 + a_{1,1} \zeta_3 \alpha + a_{1,2} \alpha^2 \\ &= a_{0,0} 1 - a_{0,1} (1 + \zeta_3) \alpha + a_{0,2} \zeta_3 \alpha^2 - a_{1,0} (1 + \zeta_3) + a_{1,1} \zeta_3 \alpha + a_{1,2} \alpha^2 \\ &= (a_{0,0} - a_{1,0}) 1 - a_{0,1} \alpha + a_{1,2} \alpha^2 - a_{1,0} \zeta_3 + (a_{1,1} - a_{0,1}) \zeta_3 \alpha + a_{0,2} \zeta_3 \alpha^2 \end{aligned} \quad (5)$$

By hypothesis, $\beta \in \mathcal{F}(\langle \sigma^2 \tau \rangle)$, so

$$\sigma^2 \tau(\beta) = \beta$$

That is, the right sides of equations (4) and (5) are equal. Because \mathcal{B} is a \mathbf{Q} -basis (so, in particular, it is linear independent over \mathbf{Q}), for each basis element, the corresponding coefficients in these equations are equal. This gives a system of six linear equations in \mathbf{Q} :

$$\begin{array}{ll} 1 : a_{0,0} = a_{0,0} - a_{1,0} & \zeta_3 : a_{1,0} = -a_{1,0} \\ \alpha : a_{0,1} = -a_{0,1} & \zeta_3 \alpha : a_{1,1} = a_{1,1} - a_{0,1} \\ \alpha^2 : a_{0,2} = a_{1,2} & \zeta_3 \alpha^2 : a_{1,2} = a_{0,2} \end{array}$$

This system of equations implies

$$a_{0,1} = 0 \quad a_{1,0} = 0 \quad a_{1,2} = a_{0,2} \quad a_{0,0}, a_{1,1} \in \mathbf{Q}$$

(The final expression simply states that $a_{0,0}$ and $a_{1,1}$ are free parameters.) That is, if $\beta \in \mathcal{F}(\langle \sigma^2 \tau \rangle)$, then β has the form

$$\beta = a_{0,0}1 + a_{1,1}\zeta_3\alpha + a_{0,2}(\alpha^2 + \zeta_3\alpha^2)$$

for some $a_{0,0}, a_{1,1}, a_{0,2} \in \mathbf{Q}$.¹

The first two terms are in $\mathbf{Q}(\zeta_3\alpha)$. What about the last term? Using the relation $\zeta_3^2 = -(1 + \zeta_3)$, we compute

$$\alpha^2 + \zeta_3\alpha^2 = (1 + \zeta_3)\alpha^2 = -\zeta_3^2\alpha^2 = -(\zeta_3\alpha)^2 \in \mathbf{Q}(\zeta_3\alpha)$$

¹If you like to think in matrices, then we can reinterpret our work here in that language. Having chosen a basis \mathcal{B} for the \mathbf{Q} -vector space K , we get a matrix $M_{\mathcal{B}}(\sigma^2\tau)$ for the linear transformation $\sigma^2\tau : K \rightarrow K$. For our basis $\mathcal{B} = (1, \alpha, \alpha^2, \zeta_3, \zeta_3\alpha, \zeta_3\alpha^2)$, we get

$$M_{\mathcal{B}}(\sigma^2\tau) = \begin{pmatrix} 1 & & -1 & & & \\ & -1 & & & & \\ & & & -1 & & \\ & -1 & & & 1 & \\ & & 1 & & & \\ & & & & & \end{pmatrix}$$

Recall that the columns of this matrix are the coefficients of the linear combination with respect to the chosen basis \mathcal{B} of each basis vector in \mathcal{B} ; that is, $M_{\mathcal{B}}(\sigma^2\tau(\zeta_3^i\alpha^j))$. Given an arbitrary $\beta \in K$, its unique \mathbf{Q} -linear combination with respect to the basis \mathcal{B} given in equation (4) writes as the 6×1 matrix (column vector)

$$M_{\mathcal{B}}(\beta) = (a_{0,0} \quad a_{0,1} \quad a_{0,2} \quad a_{1,0} \quad a_{1,1} \quad a_{1,2})^t$$

Multiplying $M_{\mathcal{B}}(\sigma^2\tau)$ by $M_{\mathcal{B}}(\beta)$ gives a 6×1 matrix, equal to $M_{\mathcal{B}}(\sigma^2\tau(\beta))$, whose entries are the coefficients in equation (5). Setting this matrix equal to $M_{\mathcal{B}}(\beta)$ gives the six linear equations we listed above.

Note that, in this matrix view, solving

$$M_{\mathcal{B}}(\sigma^2\tau)M_{\mathcal{B}}(\beta) = M_{\mathcal{B}}(\beta)$$

is equivalent to solving

$$(I - M_{\mathcal{B}}(\sigma^2\tau))M_{\mathcal{B}}(\beta) = 0$$

where I denotes the 6×6 identity matrix. That is, to compute the fixed field of an element of the galois group, we can compute the eigenspace associated to the eigenvalue 1 for that element.

Remember, $\mathbf{Q}(\zeta_3\alpha)$ denotes the field generated by $\zeta_3\alpha$ over \mathbf{Q} . It contains \mathbf{Q} and $\zeta_3\alpha$, and it is closed under the field operations. Thus, in particular, it also contains $(-1)(\zeta_3\alpha)^2$, as we asserted above. The same logic shows that $\beta \in \mathbf{Q}(\zeta_3\alpha)$. Because $\beta \in \mathcal{F}(\langle\sigma^2\tau\rangle)$ was arbitrary, we conclude that $\mathcal{F}(\langle\sigma^2\tau\rangle) \subseteq \mathbf{Q}(\zeta_3\alpha)$. Combining this with equation (3), we conclude that $\mathcal{F}(\langle\sigma^2\tau\rangle) = \mathbf{Q}(\zeta_3\alpha)$, as desired.