ESE-3025 Homework 5

Submitted By:

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1. Consider the problem of flashing the LEDs as you have done in the FreeRTOS Blinky Project, with the timings for on/off described there, as well as the fact that the LED colours (Red, Green and Blue) must not mix using the FreeRTOS mutex API.

Solution-

```
ile Edit View Search Project Build Debug Tools Plugins Settings Help
<global>
                                       main(void):int
main.c 🗶 *main.c 🗶
            #include "FreeRTOS.h'
#include "task.h"
#include "semphr.h"
            SemaphoreHandle t led mutex;
            void prvSetupHardware()
                 GPIO0->FIODIR = 0x00400000;//P0.22 = red led output
GPIO3->FIODIR = 0x06000000;//P3.26 = blue led output, P3.25 = green led output
GPIO3->FIOCLR = 0x06000000;//P3.26 = blue led output, P3.25 = green led output
GPIO3->FIOCLR = 0x06000000;//blue led off, green led off
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             int main( void )
                  led mutex = xSemaphoreCreateMutex();
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                  prvSetupHardware();
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                  xTaskCreate( prvRedFlashDTask, "red_flashing", configMINIMAL_STACK_SIZE, ( void * ) NULL, tskIDLE_PRIORITY + 1, NULL );
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                  xTaskCreate( prvBlueFlashTask, "blue_flashing", configMINIMAL_STACK_SIZE, ( void * ) NULL, tskIDLE_PRIORITY + 1, NULL );
                  xTaskCreate( prvGreenFlashTask, "green_flashing", configMINIMAL_STACK_SIZE, ( void * ) NULL, tskIDLE_PRIORITY + 1, NULL );
                  /* Will only get here if there was insufficient memory to create the idle task. The idle task is created within vTaskStartScheduler() */
```

```
-
                                   main(void):int
main.c 💥 *main.c 💥
                for( :: ):
               return 0;
         L}
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            static void prvRedFlashDTask( void *pvParameters )
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                    if(xSemaphoreTake(led_mutex, portMAX_DELAY))
                        GPIO0->FIOSET |= 0x00400000;//red on
vTaskDelay( ( TickType_t ) 400 / portTICK_PERIOD_MS );
                         VTdSADECAY( | = 0x90409000;//red off
vTaskDelay( ( TickType_t ) 400 / portTICK_PERIOD_MS );
xSemaphoreGive(led_mutex);
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        (E,
         static void prvBlueFlashTask( void *pvParameters )

[□]{
                for(;;)
                    if(xSemaphoreTake(led_mutex, portMAX_DELAY))
                        GPIO3->FIOSET |= 0x04000000;//blue on VTaskDelay( ( TickType_t ) 400 / portTICK_PERIOD_MS );
GPIO3->FIOCLR |= 0x04000000://blue_off
    62
```

```
*main.c [project-mutex] - Code::Blocks 16.01
                                                                                                    c main(void): int
<global>
main.c 💥 *main.c 💥
              static void prvBlueFlashTask( void *pvParameters )
     57
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                        if(xSemaphoreTake(led_mutex, portMAX_DELAY))
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                             GPI03->FIOSET |= 0x04000000;//blue on

VTaskDelay( ( TickType t ) 400 / portTICK_PERIOD_MS );

GPI03->FIOCLR |= 0x04000000;//blue off

VTaskDelay( ( TickType_t ) 400 / portTICK_PERIOD_MS );
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                              xSemaphoreGive(led_mutex);
            L,
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           for(;;)
                         if(xSemaphoreTake(led_mutex, portMAX_DELAY))
                             GGPT03->FT0SFT |= 0x020000000://qu
                              OBPIDS=FIDSET| = OX22000000;//gfeel OH OX y
VTaskDelay( TickType_t) 400 / portTICK_PERIOD_MS );
GPIO3->FIDCLR |= OX22000000;///green off
VTaskDelay( TickType_t) 400 / portTICK_PERIOD_MS );
xSemaphoreGive(led_mutex);
     81
     82
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     84
```

2. Using taskENTER_CRITICAL() and taskEXIT_CRITICAL() API functions.

Solution-

```
*main.c [project-mutex] - Code::Blocks 16.01
File Edit View Search Project Build Debug Tools Plugins Settings Help
                                                                                                <global>
                                          prvGreenFlashTask(void* pvParameters): void
 main.c 🗶 *main.c 🗶
              #include "FreeRTOS.h"
#include "task.h"
              void prvSetupHardware()
                   GPIO0->FIODIR = 0x00400000;//P0.22 = red led output
GPIO3->FIODIR = 0x06000000;//P3.26 = blue led output, P3.25 = green led output
GPIO0->FIOCLR = 0x00400000;//red led off
GPIO3->FIOCLR = 0x06000000;//blue led off, green led off
      10
11
              int main( void )
                   prvSetupHardware();
      14
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19
                   /* Create task for red led flashing. */
xTaskCreate( prvRedFlashDTask, "red_flashing", configMINIMAL_STACK_SIZE, ( void * ) NULL, tskIDLE_PRIORITY + 1, NULL );
                   xTaskCreate( prvBlueFlashTask, "blue_flashing", configMINIMAL_STACK_SIZE, ( void * ) NULL, tskIDLE_PRIORITY + 1, NULL );
      20
21
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                   /* Create task for green led flashing. */
xTaskCreate( prvGreenFlashTask, "green_flashing", configMINIMAL_STACK_SIZE, ( void * ) NULL, tskIDLE_PRIORITY + 1, NULL );
     23
24
25
                   vTaskStartScheduler();
      26
27
                    /* Will only get here if there was insufficient memory to create the idle task. The idle task is created within vTaskStartScheduler(). */
      28
      29
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                   return 0;
```

```
*main.c [project-mutex] - Code::Blocks 16.01
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    IP
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    III</t
                                                                                                                                                                                                                                                                                                                                                                                               prvGreenFlashTask(void* pvParameters) : void
main.c 💥 *main.c 💥
                    33
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                                                      static void prvRedFlashDTask( void *pvParameters )
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                                                                                             taskENTER_CRITICAL();
                    39
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                                                                                             taskniek_CKITICAL();
GF100->F105ET |= 0x00400000;//red on
VTaskDelay( TickType t ) 400 / portTICK_PERIOD_MS );
GF100->F10CLR |= 0x004000008;//red off
VTaskDelay( TickType_t ) 400 / portTICK_PERIOD_MS );
                                                                                             taskEXIT_CRITICAL();
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                                                        static void prvBlueFlashTask( void *pvParameters )
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                                                                           for(;;)
                                                                                               taskENTER_CRITICAL();
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                                                      static void pryGreenFlashTask( void *pyParameters )
```

```
*main.c [project-mutex] - Code::Blocks 16.01
prvGreenFlashTask(void* pvParameters) : void
main.c 💥 *main.c 💥
    45
          L}
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            static void prvBlueFlashTask( void *pvParameters )
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                 for(;;)
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                     taskEXIT_CRITICAL();
         [}
            static void prvGreenFlashTask( void *pvParameters )
                for(;;)
                          taskENTER_CRITICAL();
                         LaskENIER_CHILICAL();
G6PI03->FIOSET |= 0x02000000;//green on
VTaskDelay( ( TickType_t ) 400 / portTICK_PERIOD_MS );
GPI03->FIOCUR |= 0x02000000;///green off
VTaskDelay( ( TickType_t ) 400 / portTICK_PERIOD_MS );
taskEXIT_CRITICAL();
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         L 3
```

3. Write a short evaluation of used versions of code stating it's advantages and disadvantages?

Solution- Using Mutex

Advantages-

Tasks and resources/data can be synchronized by the use of mutex and it also doesn't impacts interrupts.

Disadvantages-

Mutex can only be unlocked from the same process which loced it thus if the locking process is in blocked state or is sleeping, then other tasks which require the same mutex will remain in blocked state thus freezing the system into deadlock.

Using taskENTER_CRITICAL() & taskEXIT_CRITICAL()

Advantages-

No initialization has to be done so it is simple and easy to use.

Disadvantages-

It messes with scheduler because it has to disable interrupts and thus preemption and freeRTOS working is affected. The system becomes less responsive due to disabled interrupts.

Link to the output:

https://youtu.be/7WYSJC1aBoI