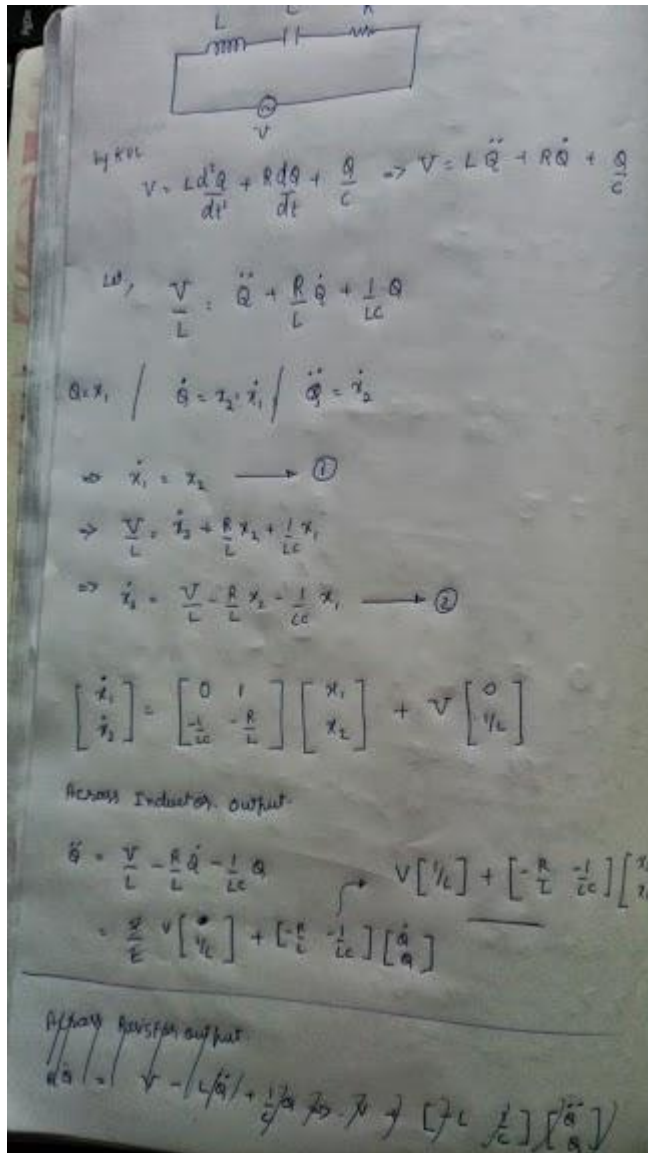


JED-I ASSIGNMENT-1 SUBMISSION ---TEAM NUMBER 12

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Kartik M Kerur

LCR circuit in State Space form



CASE 1

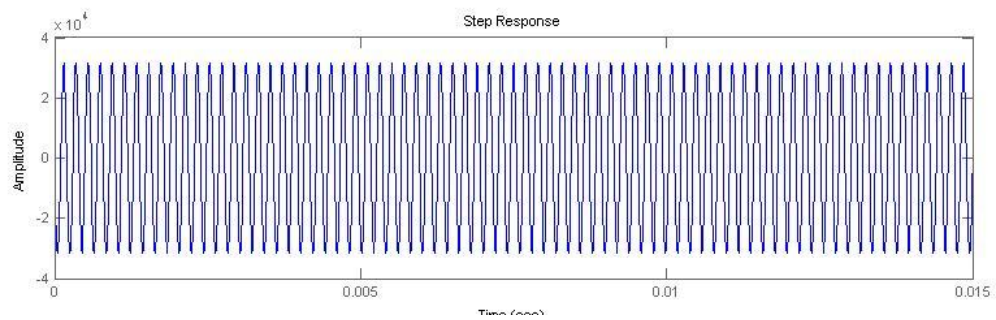
a) Output across inductor when $R=0$ ohms

```
function jedi_a1_r0_1
r=0; %ohm
l=1e-3; %henry
c=1e-6; %farads
A=[0 1;-1/(l*c) -r/l];
B=[0;1/l];
C_l=[-r -1/c];
```

```

D=0;
sys_lcr_l=ss(A,B,C_l,D);
[eig_vec,eig_val]=eig(A)
step(sys_lcr_l)
end

```



eig_vec =

```

0 - 0.0000i    0 + 0.0000i
1.0000         1.0000

```

eig_val =

```

1.0e+004 *

```

```

0 + 3.1623i    0
0              0 - 3.1623i

```

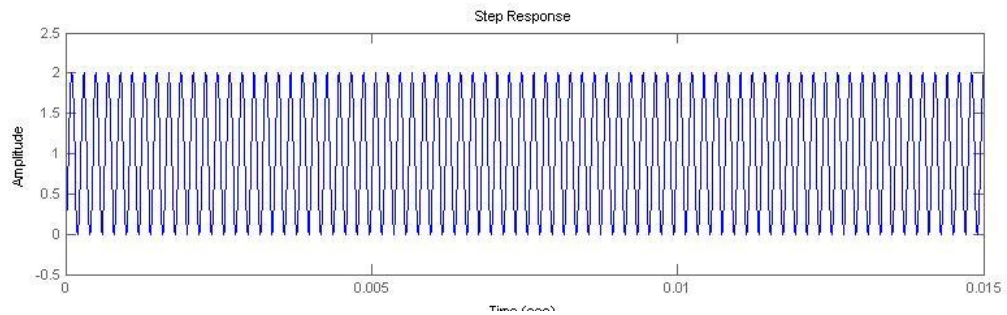
b) Output across capacitor when R=0 ohms

```

function jedi_al_r0_c
r=0; %ohm
l=1e-3; %henry
c=1e-6; %farads
A=[0 1;-1/(l*c) -r/l];
B=[0;1/l];
C_c=[1/c 0];
D=0;
sys_lcr_c=ss(A,B,C_c,D);
[eig_vec,eig_val]=eig(A)

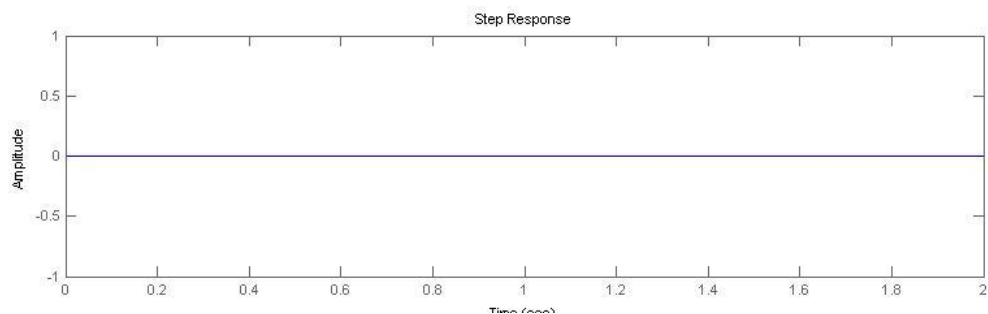
```

```
step(sys_lcr_c)
end
```



c) Output across resistor when $R=0$ ohms

```
function jedi_a1_r0_r
r=0; %ohm
l=1e-3; %henry
c=1e-6; %farads
A=[0 1;-1/(l*c) -r/l];
B=[0;1/l];
C_r=[0 r];
D=0;
sys_lcr_r=ss(A,B,C_r,D);
[eig_vec,eig_val]=eig(A)
step(sys_lcr_r)
end
```

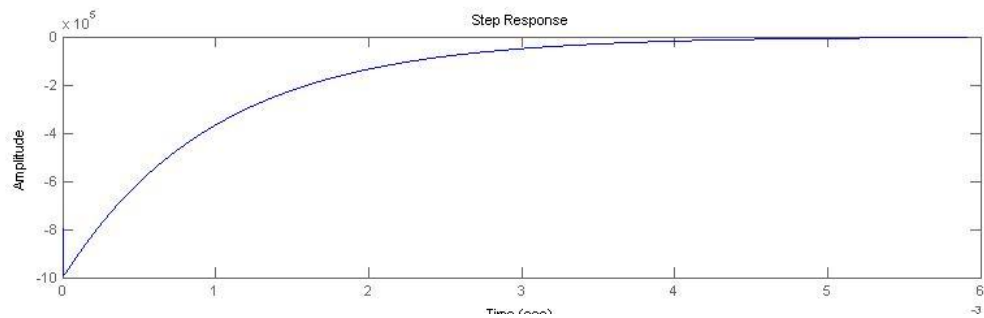


CASE 2

a) Output across inductor when $R=1000$ ohms

```
function jedi_a1_r1000_l
r=1000; %ohm
l=1e-3; %henry
c=1e-6; %farads
A=[0 1;-1/(l*c) -r/l];
B=[0;1/l];
C_l=[-r/l -1/(c*l)];
D=0;
sys_lcr_l=ss(A,B,C_l,D);
[eig_vec,eig_val]=eig(A)
step(sys_lcr_l)
```

end



eig_vec =

0.0010 -0.0000

-1.0000 1.0000

eig_val =

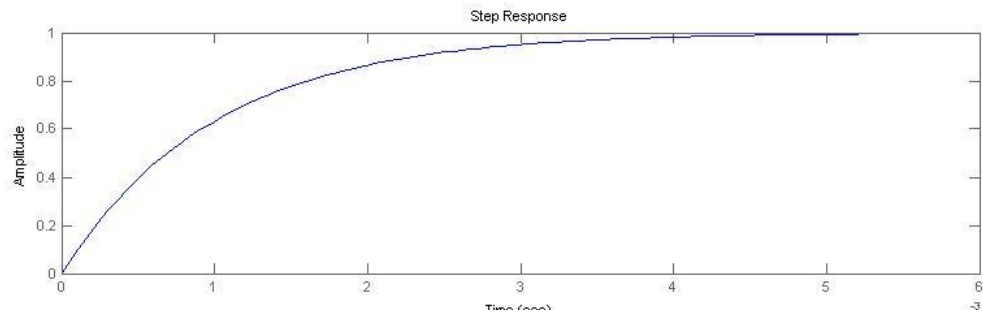
1.0e+005 *

-0.0100 0

0 -9.9900

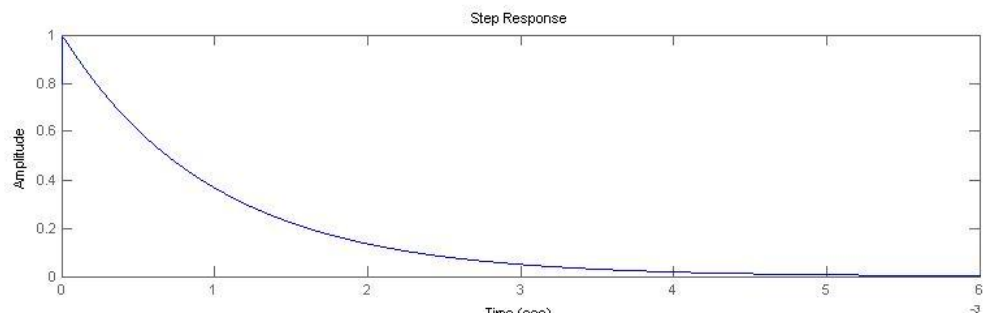
b)Output across capacitor when R=1000

```
function jedi_a1_r1000_c
r=1000; %ohm
l=1e-3; %henry
c=1e-6; %farads
A=[0 1;-1/(l*c) -r/l];
B=[0;1/l];
C_c=[1/c 0];
D=0;
sys_lcr_c=ss(A,B,C_c,D);
[eig_vec,eig_val]=eig(A)
step(sys_lcr_c)
end
```



c)Output across resistor when R=1000

```
function jedi_al_r1000_r
r=1000; %ohm
l=1e-3; %henry
c=1e-6; %farads
A=[0 1;-1/(l*c) -r/l];
B=[0;1/l];
C_r=[0 r];
D=0;
sys_lcr_r=ss(A,B,C_r,D);
[eig_vec,eig_val]=eig(A)
step(sys_lcr_r)
end
```



CASE 3

When unit step input is given the D values in Matlab Programme change to 1

i.e D=1

Ana it was observed that al the graphs shift by one unit in y axis

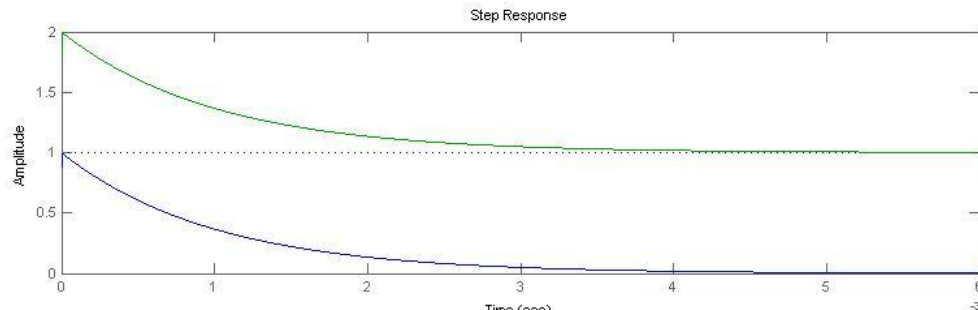
Example is shown for Resistor

```
function jedi_al_r1000_u1_r
r=1000; %ohm
l=1e-3; %henry
c=1e-6; %farads
A=[0 1;-1/(l*c) -r/l];
B=[0;1/l];
C_r=[0 r];
d=0;
D=1;
sys_lcr_r=ss(A,B,C_r,D);
```

```

sys_lcr_ul_r=ss(A,B,C_r,d)
[eig_vec,eig_val]=eig(A)
step(sys_lcr_ul_r,sys_lcr_r)
end

```



For CASE 2 when $R=1000$

Oscillatory Response was not got instead Damped response was found

Damping ratio= (α/Ω)

Alfa for series LCR= $R/(2 \cdot L)$

$\Omega = 1/\sqrt{L \cdot C}$

For CASE 1 since $R=0$ $\alpha=0$ so no Damping

For CASE 2 Since $R=1000$

$\text{Alfa} = 1000 / (2 \cdot (1/1000))$

$\text{Alfa} = 500000$

$\Omega = 1/\sqrt{(1/1000) \cdot (1/1000000)}$

$\Omega = 31623$

Damp Ratio= Alfa/Ω

Damp Ratio= $500000/31623=15.8113$

The Given System is Over Damped because of Highly negative eigen values in the real part of eigen values.

Eigen Values of the system is mentioned above