CS/ECE/EEE/INSTR F215:Digital Design

Lecture 27: *Design of clocked sequential circuits_2*

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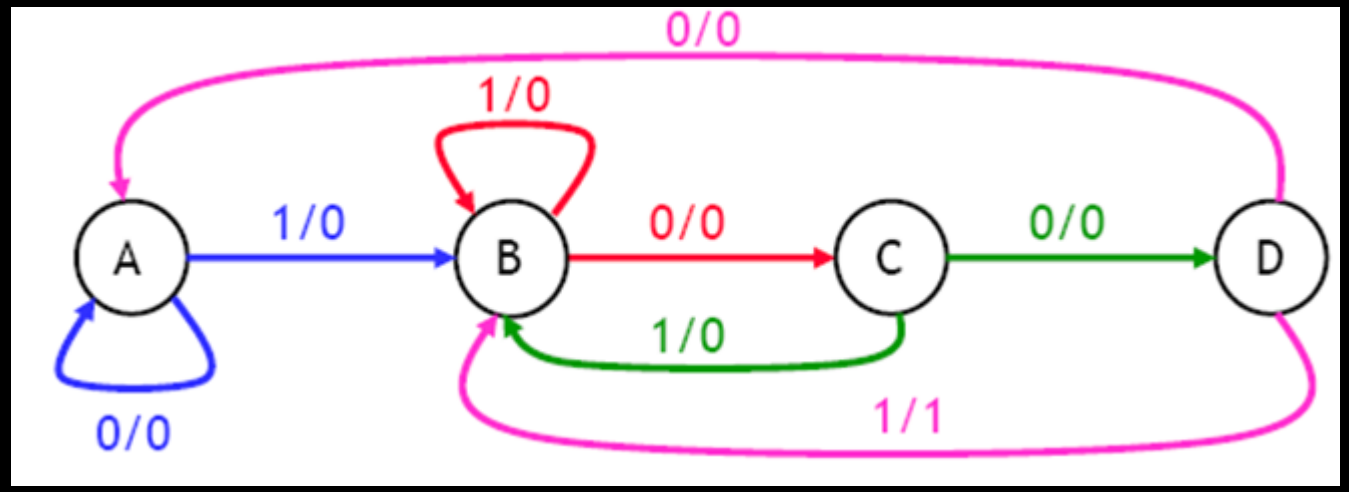
If you have choice

choose the best,

If you have No choice

do the best

➢To detect a pattern 1001



Present State	Input	Next State	Output
A	0	A	0
A	1	B	0
B	0	C	0
B	1	B	0
C	0	D	0
C	1	B	0
D	0	A	0
D	1	B	1

Present State Q_1	Present State Q_0	Input X	Next State Q_1	Next State Q_0	Output Z
0	0	0	0	0	0
0	0	1	0	1	0
0	1	0	1	0	0
0	1	1	0	1	0
1	0	0	1	1	0
1	0	1	0	1	0
1	1	0	0	0	0
1	1	1	0	1	1

Present State Q_1	Present State Q_0	Input X	Next State Q_1	Next State Q_0	Flip-flop Inputs J_1	Flip-flop Inputs K_1	Flip-flop Inputs J_0	Flip-flop Inputs K_0	Output Z
0	0	0	0	0	0	x	0	x	0
0	0	1	0	1	0	x	1	x	0
0	1	0	1	0	1	x	x	1	0
0	1	1	0	1	0	x	x	0	0
1	0	0	1	1	x	0	1	x	0
1	0	1	0	1	x	1	1	x	0
1	1	0	0	0	x	1	x	1	0
1	1	1	0	1	x	1	x	0	1

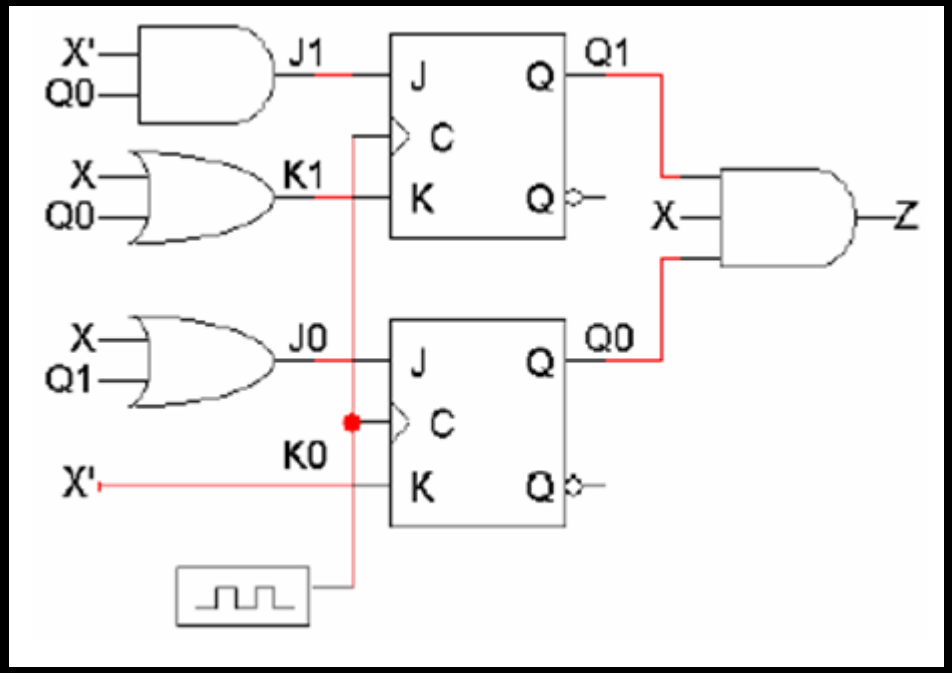
$J_1 = X'Q_0$

$K_1 = X + Q_0$

$J_0 = X + Q_1$

$K_0 = X'$

$Z = Q_1Q_0X$



Building the same circuit with D flip-flops

- What if you want to build the circuit using D flip-flops instead?
- We already have the state table and state assignments, so we can just start from Step 3, finding the flip-flop input values.
- D flip-flops have only one input, so our table only needs two columns for D_1 and D_0.

Present State Q_1	Present State Q_0	Input X	Next State Q_1	Next State Q_0	Flip-flop Inputs D_1	Flip-flop Inputs D_0	Output Z
0	0	0	0	0	0	0	0
0	0	1	0	1	0	1	0
0	1	0	1	0	1	0	0
0	1	1	0	1	0	1	0
1	0	0	1	1	1	1	0
1	0	1	0	1	0	1	0
1	1	0	0	0	0	0	0
1	1	1	0	1	0	1	1

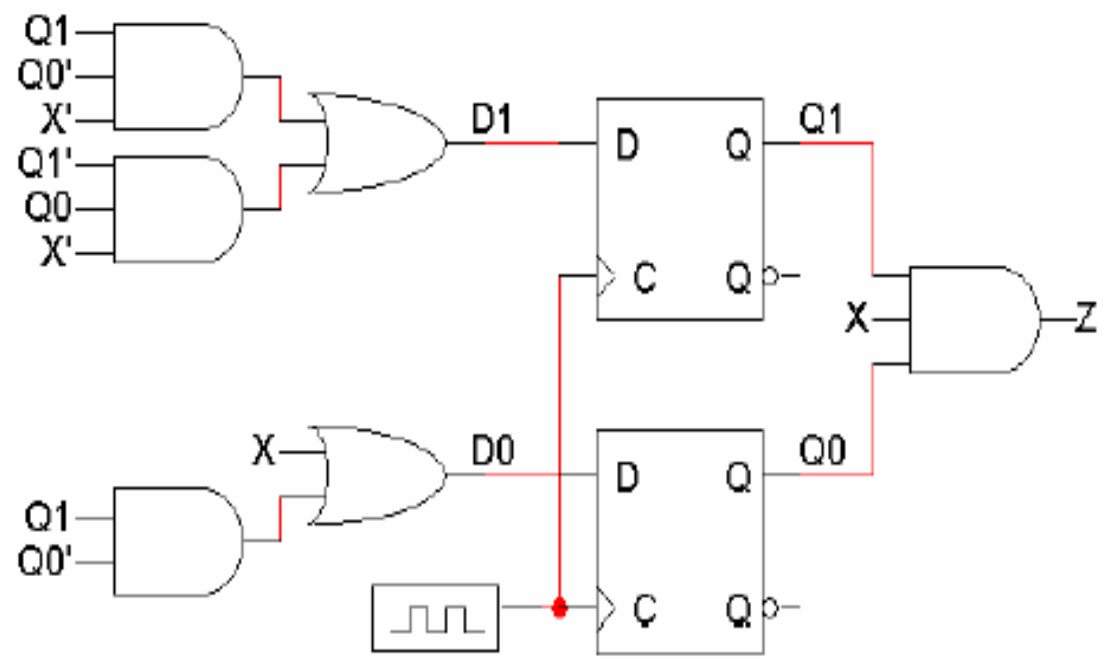
Finding equations (Step 4)

- If you use K-maps again, you should find the following equations.

$$D_1 = Q_1Q_0'X' + Q_1'Q_0X'$$
$$D_0 = X + Q_1Q_0'$$
$$Z = Q_1Q_0X$$

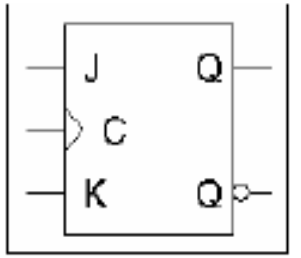
Present State		Input	Next State		Flip-flop Inputs		Output
Q_1	Q_0	X	Q_1	Q_0	D_1	D_0	Z
0	0	0	0	0	0	0	0
0	0	1	0	1	0	1	0
0	1	0	1	0	1	0	0
0	1	1	0	1	0	1	0
1	0	0	1	1	1	1	0
1	0	1	0	1	0	1	0
1	1	0	0	0	0	0	0
1	1	1	0	1	0	1	1

Building the circuit (Step 5)

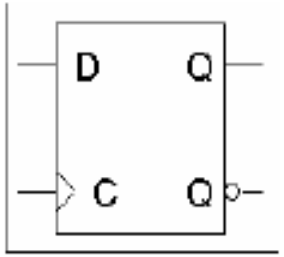


Flip-flop comparison

- JK flip-flops are good because there are many don't care values in the flip-flop inputs, which can lead to a simpler circuit.



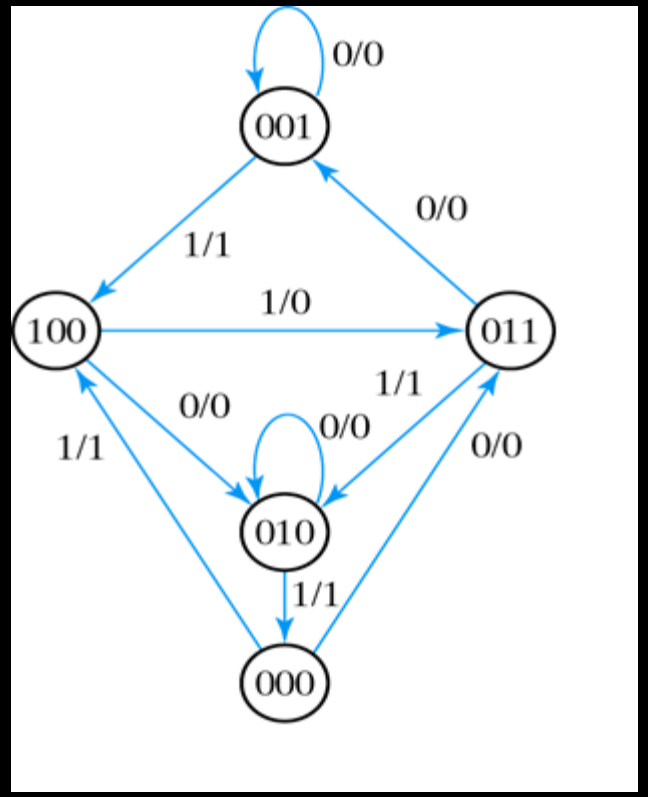
- D flip-flops have the advantage that you don't have to set up flip-flop inputs at all, since Q(t+1) = D. However, the D input equations are usually more complex than JK input equations.



- In practice, D flip-flops are used more often.
  - There is only one input for each flip-flop, not two.
  - There are no excitation tables to worry about.
  - D flip-flops themselves are simpler to implement than JK flip-flops.

DESIGN WITH UNUSED STATES

- **Design the circuit using D Flip Flops**



PS			X	NS			D_a	D_b	D_c	Y
A	B	C		A	B	C				
0	0	0	0	0	1	1				0
0	0	0	1	1	0	0				1
0	0	1	0	0	0	1				0
0	0	1	1	1	0	0				1
0	1	0	0	0	1	0				0
0	1	0	1	0	0	0				1
0	1	1	0	0	0	1				0
0	1	1	1	0	1	0				1
1	0	0	0	0	1	0				0
1	0	0	1	0	1	1				0

PS			X	NS			D_A	D_B	D_C	Y
A	B	C		A	B	C				
0	0	0	0	0	1	1	0	1	1	0
0	0	0	1	1	0	0	1	0	0	1
0	0	1	0	0	0	1	0	0	1	0
0	0	1	1	1	0	0	1	0	0	1
0	1	0	0	0	1	0	0	1	0	0
0	1	0	1	0	0	0	0	0	0	1
0	1	1	0	0	0	1	0	0	1	0
0	1	1	1	0	1	0	0	1	0	1
1	0	0	0	0	1	0	0	1	0	0
1	0	0	1	0	1	1	0	1	1	0

$T_A = A + \bar{B}X$

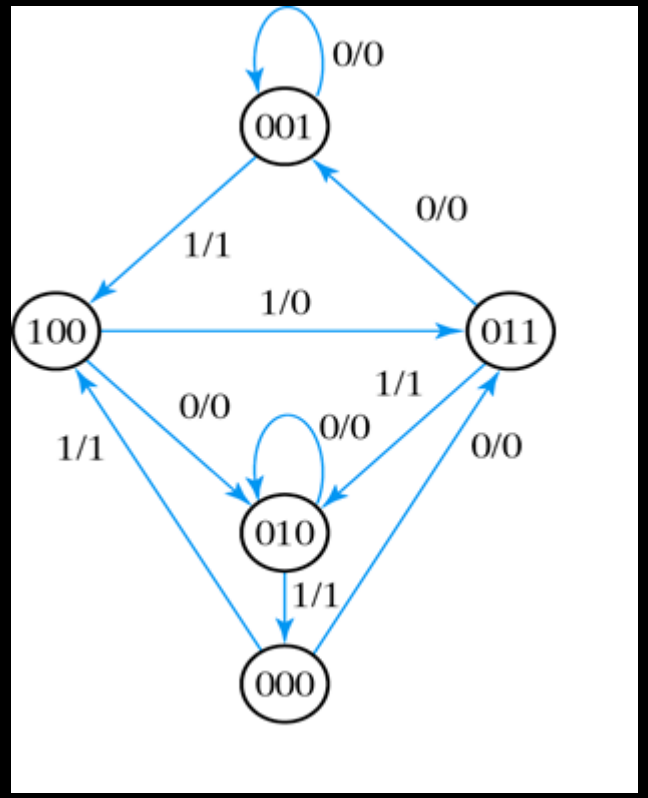
$T_B = A + \bar{B}\bar{C}X$

AB \ CX	00	01	11	10
00	0	1	1	0
01	0	0	0	0
11	X	X	X	X
10	0	0	X	X

AB \ CX	00	01	11	10
00	1			
01	1		1	
11	X	X	X	X
10	1	1	X	X

AB \ CX	00	01	11	10
00	1			1
01				1
11	X	X	X	X
10		1	X	X

AB \ CX	00	01	11	10
00		1	1	
01		1	1	
11	X	X	X	X
10			X	X



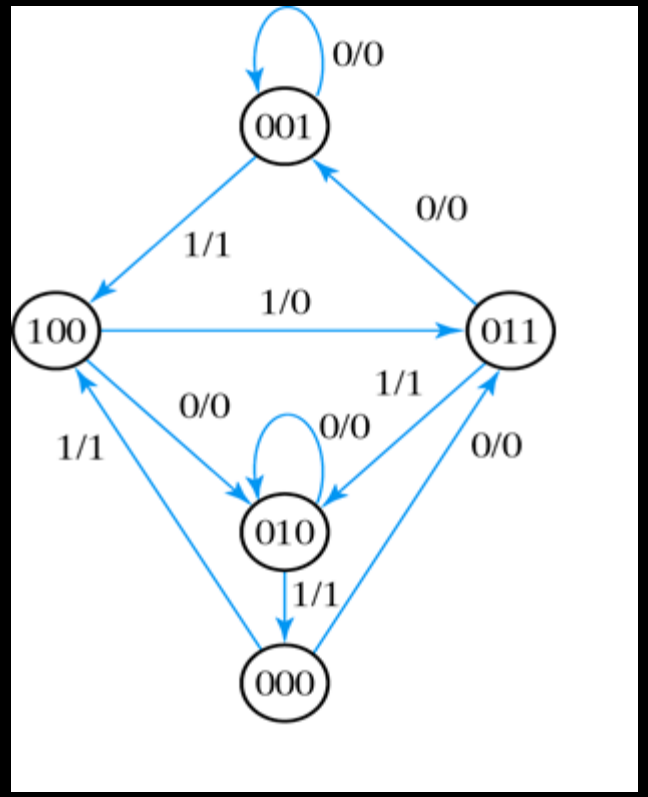
Answer:

$D_a = A'B'x$

$D_b = C'x' + A + BCx$

$D_c = A'B'x' + Cx' + Ax$

$Y = A'x$



Answer:

$D_a = A'B'x$

$D_b = C'x' + A + BCx$

$D_c = A'B'x' + Cx' + Ax$

$Y = A'x$

The circuit is self correcting

PS			X	NS			T_a	T_b	T_c	Y
A	B	C		A	B	C				
0	0	0	0	0	1	1				0
0	0	0	1	1	0	0				1
0	0	1	0	0	0	1				0
0	0	1	1	1	0	0				1
0	1	0	0	0	1	0				0
0	1	0	1	0	0	0				1
0	1	1	0	0	0	1				0
0	1	1	1	0	1	0				1
1	0	0	0	0	1	0				0
1	0	0	1	0	1	1				0

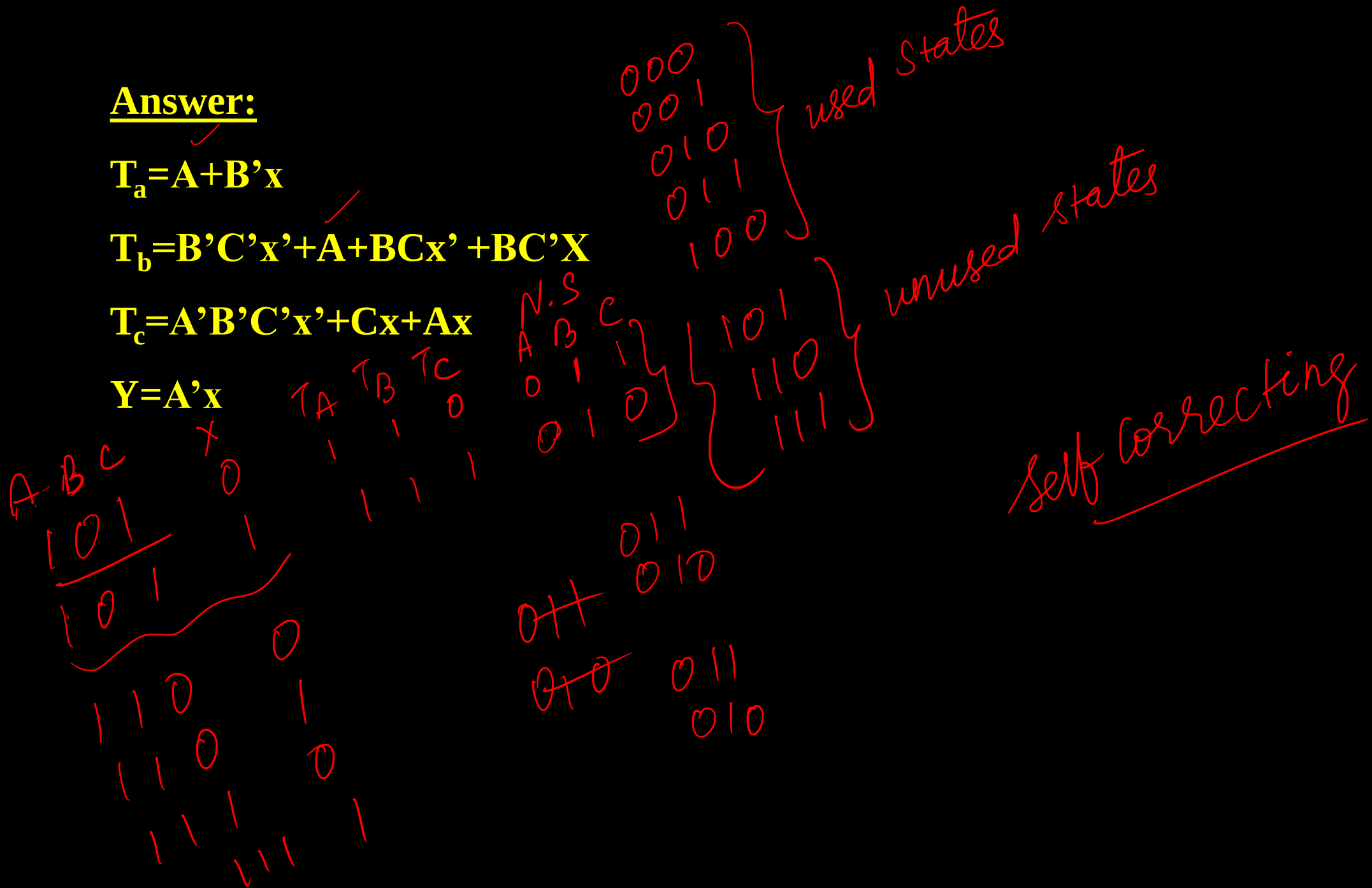
Answer:

$T_a = A + B'x$

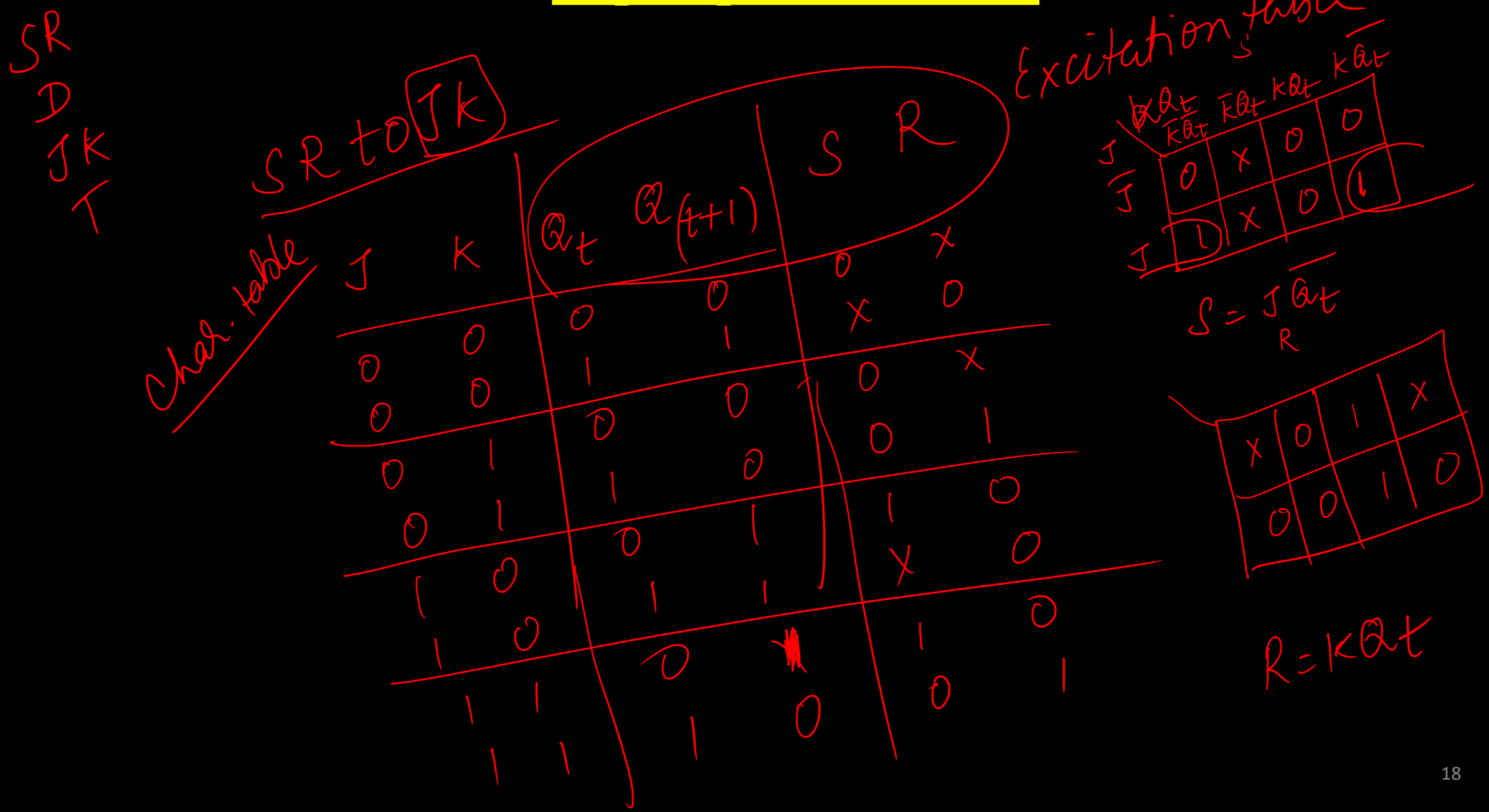
$T_b = B'C'x' + A + BCx' + BC'X$

$T_c = A'B'C'x' + Cx + Ax$

$Y = A'x$



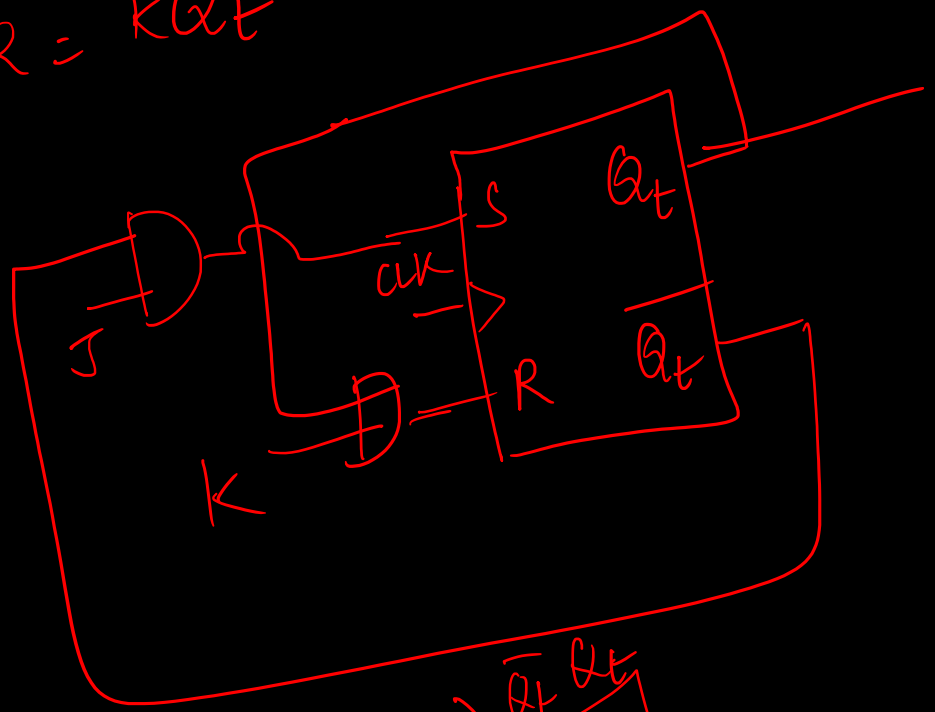
Flip flop Conversions



SR to JK

$S = J\bar{Q}_t$

$R = KQ_t$



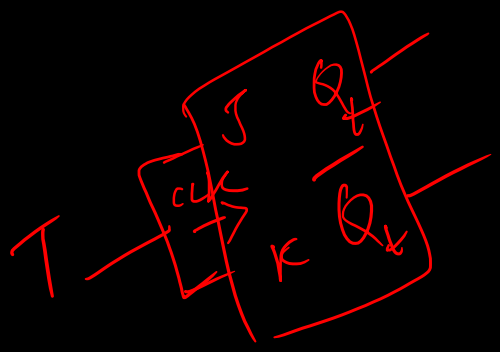
$\bar{T}$	Q_t	Q_{t+1}	J	K
0	0	0	0	x
0	0	1	1	x
0	1	1	x	0
0	1	0	x	1
1	0	0	0	x
1	0	1	1	x
1	1	0	x	1
1	1	1	x	0

$\bar{T}$ \ Q_t	$\bar{Q}_t$	Q_t
0	0	x
1	1	x

JK to T

$J = T$

$K = T$



Registers

- Register is an extension of a Flip-flop that can store multiple bits

Register consists of group of flip-flops and some combinational gates. Each FF is capable of storing one bit of information.
N-bit register has group of n-FFs capable of storing n-bits of binary information. The logic gates determine how the information is transferred into the register.

- Ex: Used as a Temporary storage in Microprocessors

A basic register

An example: Register constructed using D FFs.

D0-D3 Data inputs; Q0-Q3 data output.