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1  # -*- coding: utf-8 -*-
2  """Copy of Untitled4.ipynb
3
4  Automatically generated by Colab.
5
6  Original file is located at
7      https://colab.research.google.com/drive/19RTN-GtwoSXWtBv29r3Kf2F5ofBZaQyW
8  """
9
10 import pandas as pd
11 import numpy as np
12 import matplotlib.pyplot as plt
13 import matplotlib.axes as ax
14 from matplotlib.animation import FuncAnimation
15 url = 'https://media.geeksforgeeks.org/wp-content/uploads/20240320114716/data_for_lr.csv'
16 data = pd.read_csv(url)
17 data
18
19 # Drop the missing values
20 data = data.dropna()
21
22 # training dataset and labels
23 train_input = np.array(data.x[0:500]).reshape(500, 1)
24 train_output = np.array(data.y[0:500]).reshape(500, 1)
25
26 # valid dataset and labels
27 test_input = np.array(data.x[500:700]).reshape(199, 1)
28 test_output = np.array(data.y[500:700]).reshape(199, 1)
29 class LinearRegression:
30     def __init__(self):
31         self.parameters = {}
32
33     def forward_propagation(self, train_input):
34         m = self.parameters['m']
35         c = self.parameters['c']
36         predictions = np.multiply(m, train_input) + c
37         return predictions
38
39     def cost_function(self, predictions, train_output):
40         cost = np.mean((train_output - predictions) ** 2)
41         return cost
42
43     def backward_propagation(self, train_input, train_output, predictions):
44         derivatives = {}
45         df = (predictions - train_output)
46         # dm= 2/n * mean of (predictions-actual) * input
47         dm = 2 * np.mean(np.multiply(train_input, df))
48         # dc = 2/n * mean of (predictions-actual)
49         dc = 2 * np.mean(df)
50         derivatives['dm'] = dm
51         derivatives['dc'] = dc
52         return derivatives
53
54     def update_parameters(self, derivatives, learning_rate):
55         self.parameters['m'] = self.parameters['m'] - learning_rate * derivatives['dm']
56         self.parameters['c'] = self.parameters['c'] - learning_rate * derivatives['dc']
57
58     def train(self, train_input, train_output, learning_rate, iters):
59         # Initialize random parameters
60         self.parameters['m'] = np.random.uniform(0, 1) * -1
61         self.parameters['c'] = np.random.uniform(0, 1) * -1
62
63         # Initialize loss
64         self.loss = []
65
66         # Initialize figure and axis for animation
67         fig, ax = plt.subplots()
68         x_vals = np.linspace(min(train_input), max(train_input), 100)

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69 | line, = ax.plot(x_vals, self.parameters['m'] * x_vals +
70 |                 self.parameters['c'], color='red', label='Regression Line')
71 | ax.scatter(train_input, train_output, marker='o',
72 |           color='green', label='Training Data')
73 |
74 | # Set y-axis limits to exclude negative values
75 | ax.set_ylim(0, max(train_output) + 1)
76 |
77 | def update(frame):
78 |     # Forward propagation
79 |     predictions = self.forward_propagation(train_input)
80 |
81 |     # Cost function
82 |     cost = self.cost_function(predictions, train_output)
83 |
84 |     # Back propagation
85 |     derivatives = self.backward_propagation(
86 |         train_input, train_output, predictions)
87 |
88 |     # Update parameters
89 |     self.update_parameters(derivatives, learning_rate)
90 |
91 |     # Update the regression line
92 |     line.set_ydata(self.parameters['m']
93 |                   * x_vals + self.parameters['c'])
94 |
95 |     # Append loss and print
96 |     self.loss.append(cost)
97 |     print("Iteration = {}, Loss = {}".format(frame + 1, cost))
98 |
99 |     return line,
100 | # Create animation
101 | ani = FuncAnimation(fig, update, frames=iters, interval=200, blit=True)
102 |
103 | # Save the animation as a video file (e.g., MP4)
104 | ani.save('linear_regression_A.gif', writer='ffmpeg')
105 |
106 | plt.xlabel('Input')
107 | plt.ylabel('Output')
108 | plt.title('Linear Regression')
109 | plt.legend()
110 | plt.show()
111 |
112 | return self.parameters, self.loss
113 |
114 | #Example usage
115 | linear_reg = LinearRegression()
116 | parameters, loss = linear_reg.train(train_input, train_output, 0.0001, 20)

```