

Complete Dictionary Learning via ℓ_p -norm Maximization

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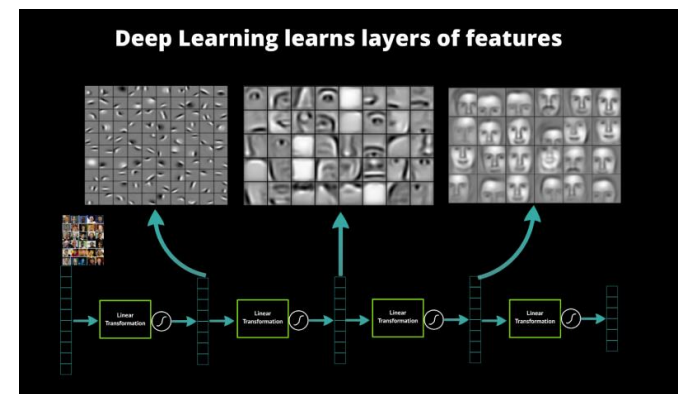
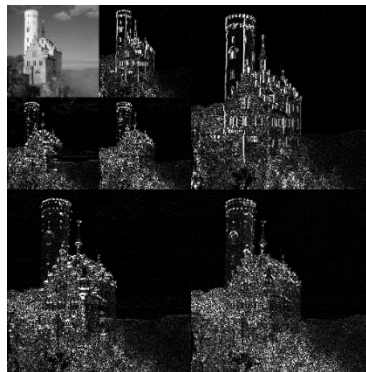
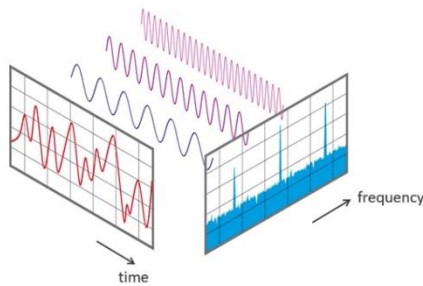
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Representation of Data

- Finding a good representation of data is what we pursue for centuries
 - Fourier Transform (Fourier ~1800)
 - Wavelet Transform (Haar ~1900)
 - Deep Learning (Now)



What representation should we use?



“It is human nature to prefer simplicity”

Dictionary Learning – Finding the most sparse representation

$$\underbrace{\mathbf{Y}}_{\text{Known Data}} = \underbrace{\mathbf{D}}_{\text{Unknown Transform}} \cdot \underbrace{\mathbf{X}}_{\text{Unknown Sparse Representation}}$$

$$\begin{aligned} & \underset{\mathbf{D}, \mathbf{X}}{\text{minimize}} && \|\mathbf{X}\|_0 \\ & \text{subject to} && \mathbf{Y} = \mathbf{D}\mathbf{X} \end{aligned}$$

Dictionary Learning Challenges

- Computational challenges
 - The signals are usually high dimension
 - NP-hard in general due to non-convexity
- Sample complexity challenges
 - We would like to learn from as few as possible samples
- Goal: Design an **efficient** algorithm to learn the **optimal** dictionary with **tractable** sample complexity

Preliminary

- Complete dictionary learning can be converted to an orthogonal dictionary learning through preconditioning [SQW15]

$$\bar{\mathbf{Y}} = \left(\frac{1}{p\theta} \mathbf{Y} \mathbf{Y}^* \right)^{-\frac{1}{2}} \mathbf{Y}$$

- Assumptions for tractable analysis
 - [SWW12] assumes the data \mathbf{Y} is generated by an orthogonal dictionary \mathbf{D}_0 and sparse coefficients \mathbf{X}_0 with $\mathbf{Y} = \mathbf{D}_0 \mathbf{X}_0$
 - $\mathbf{D}_0 \in O(n)$, i.e., $\mathbf{D}_0^* \mathbf{D}_0 = \mathbf{D}_0 \mathbf{D}_0^* = \mathbf{I}$

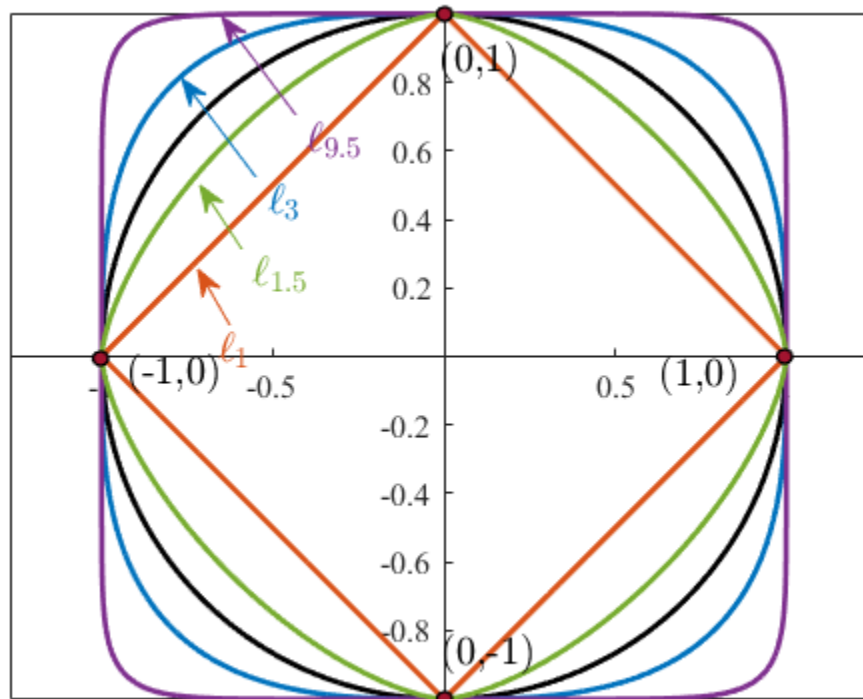
Existing Works - ℓ_1 -norm Minimization

$$\begin{array}{ll} \min_{\mathbf{D}, \mathbf{X}} & \|\mathbf{X}\|_0 \\ \text{s.t.} & \mathbf{Y} = \mathbf{D}\mathbf{X} \\ & \mathbf{D} \in O(n) \end{array} \quad \Rightarrow \quad \begin{array}{ll} \min_{\mathbf{D}} & \|\mathbf{D}^* \mathbf{Y}\|_0 \\ \text{s.t.} & \mathbf{D} \in O(n) \end{array} \quad \Rightarrow \quad \begin{array}{ll} \min_{\mathbf{D}} & \|\mathbf{D}^* \mathbf{Y}\|_1 \\ \text{s.t.} & \mathbf{D} \in O(n) \end{array}$$

- Pros: Can achieve optimal solution [SQW15]
- Cons: Algorithmic challenges
 - Slow convergence due to non-smoothness
 - Difficult to tune parameters
- Question: Can we use other norm for relaxation?

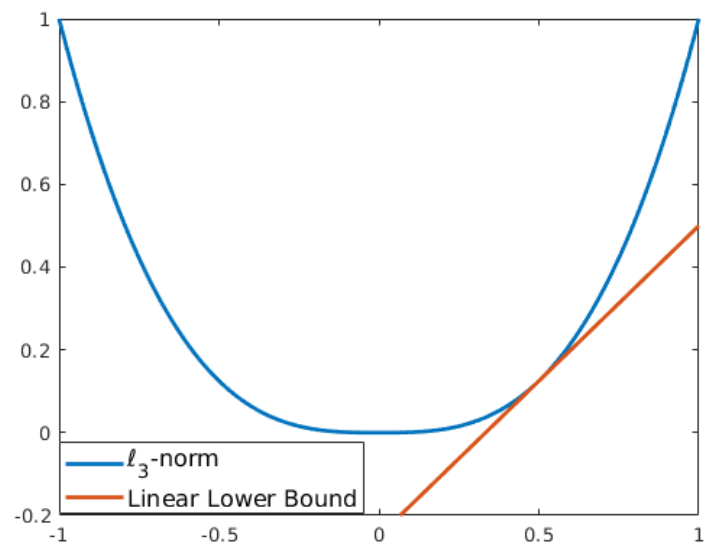
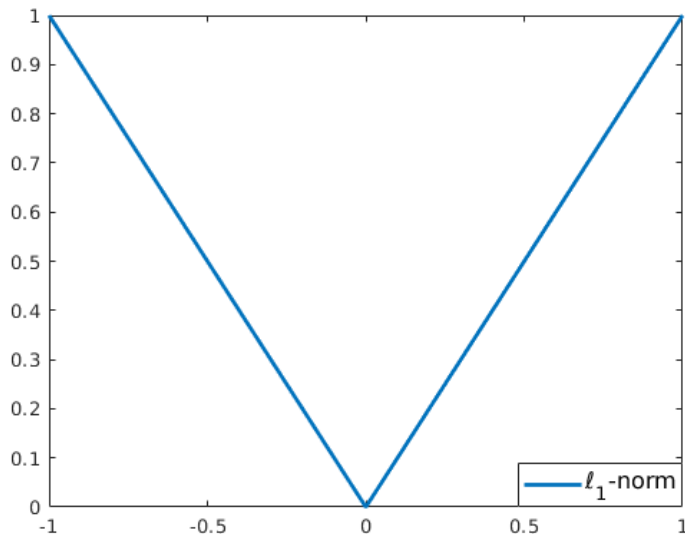
ℓ_p -norm Maximization - Observations

- Observation 1: Over an ℓ_2 -norm constraint, minimizing any ℓ_q -norm ($0 \leq q < 2$) or maximizing any ℓ_p -norm ($p > 2$) are equivalent
 - Maximizing ℓ_p -norm ($p > 2$) induces sparsity



ℓ_p -norm Maximization - Observations

- Observation II: ℓ_p -norms ($p > 2$) is smooth and majorized by linear functions
 - ℓ_1 -norm: non-smooth, hard to optimize over a non-convex constraint
 - ℓ_p -norms ($p > 2$): smooth, efficient algorithm can be designed by maximize linear lower bound at each iteration



ℓ_p -based Formulation

- Instead of minimizing ℓ_1 , we maximize ℓ_p ($p > 2$)

$$\begin{array}{ll} \underset{\mathbf{D}}{\text{minimize}} & \|\mathbf{D}^* \mathbf{Y}\|_1 \\ \text{subject to} & \mathbf{D} \in O(n) \end{array}$$



$$\begin{array}{ll} \underset{\mathbf{D}}{\text{maximize}} & \|\mathbf{D}^* \mathbf{Y}\|_p \\ \text{subject to} & \mathbf{D} \in O(n) \end{array}$$

An Efficient Parameter-free Algorithm

- Maximize a linear lower bound at each time

$$f(\mathbf{A}) = \|\mathbf{A}^* \mathbf{Y}\|_p^p$$

$$\mathbf{A}^{(t+1)} = \operatorname{argmax}_{\mathbf{s} \in O(n)} \langle \mathbf{s}, f'(\mathbf{A}^{(t)}) \rangle$$

Algorithm 2 The GPM algorithm for ℓ_p -based dictionary learning

- 1: Initialize $\mathbf{A}^{(0)*} \in \operatorname{St}(n, m)$.
 - 2: **for** $t = 0 \dots T$ **do**
 - 3: $\nabla f(\mathbf{A}^{(t)}) = \left(|(\mathbf{A}^{(t)} \mathbf{Y})^{\circ(p-1)}| \circ \operatorname{sign}(\mathbf{A}^{(t)} \mathbf{Y}) \right) \mathbf{Y}^*$
 - 4: $\mathbf{A}^{(t+1)} = \operatorname{Polar}(\nabla^* f(\mathbf{A}^{(t)}))^*$
 - 5: **end for**
-

ℓ_p -norm Minimization

- Can ℓ_p formulations provably recover the true dictionary?
 - $X_0 \sim \Omega \cdot G, \Omega_{i,j} \sim \text{Ber}(\theta), G_{i,j} \sim \mathcal{N}(0, 1)$
 - All $\ell_p (p > 2)$ can recover the dictionary when the sample size is large and ℓ_3 achieves the best sample complexity

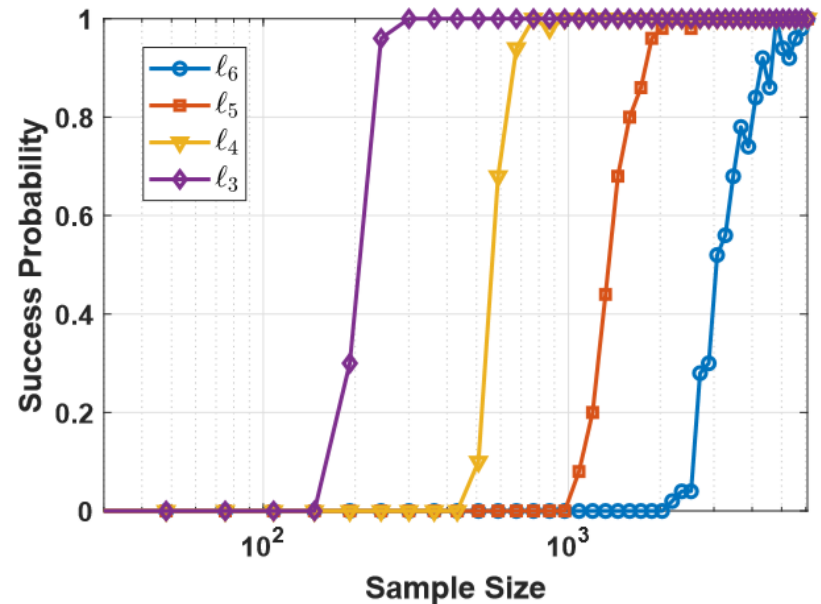
Theorem 2.1. Let $X \in \mathbb{R}^{n \times r}, x_{i,j} \sim \mathcal{BG}(\theta)$ with $\theta \in (0, 1), D_0 \in \mathbb{O}(n)$ be an orthogonal dictionary, and $Y = D_0 X$. Suppose \hat{A} is a global maximizer to

$$\underset{A}{\text{maximize}} \quad \|AY\|_p^p \quad \text{subject to } A \in \mathbb{O}(n).$$

Provided that the sample size $r = \Omega(\delta^{-2} n \log(n/\delta)(\theta n \log^2 n)^{\frac{p}{2}})$, then for $\delta > 0$, there exists a signed permutation Π , such that

$$\frac{1}{n} \left\| \hat{A}^* - D_0 \Pi \right\|_F^2 \leq C_\theta \delta$$

with probability at least $1 - r^{-1}$ and C_θ is a constant that depends on θ .



Experiments - Scalability

- Benchmarks
 - K-SVD [AEB06]: A classic algorithm for dictionary learning

Table 1: The performance of different algorithms for noiseless objectives. Since the dictionary recovery is up to some signed permutations, we adopt the error metric $1 - \|AD_0\|_4^4/n$ in [26], which gives 0% error for a perfect recovery.

Settings			ℓ_3 -based		ℓ_4 -based [26]		ℓ_5 -based		K-SVD [18]	
n	θ	$p(\times 10^4)$	Time	Error	Time	Error	Time	Error	Time	Error
100	0.1	4	0.8s	0.056%	1.8s	0.21%	1.7s	0.50%	61s	1.45%
200	0.1	8	4.1s	0.056%	9.3s	0.21%	8.0s	0.51%	131s	3.03%
400	0.1	16	35s	0.056%	50s	0.21%	41s	0.50%	315s	6.45%
100	0.3	4	1.2s	0.094%	3.4s	0.34%	3.1s	0.84%	98s	2.60%
200	0.3	8	10s	0.094%	18s	0.35%	15s	0.85%	215s	6.41%
400	0.3	16	91s	0.096%	122s	0.35%	146s	1.00%	589s	8.25%

Smaller p: faster, more accurate!

Experiments - Robustness

- Benchmarks
 - K-SVD [AEB06]: A classic algorithm for dictionary learning
 - RTR [SQW15]: ℓ_1 -based formulation and Riemannian Trust Region
 - ℓ_4 [ZMLZM19]: ℓ_4 -based formulation and specialized *matching, stretching, pursuit* algorithm

Table 2: The performance of different algorithms under Gaussian noise. We set sparsity level $\theta = 0.3$.

Settings			ℓ_3 -based		ℓ_4 -based [26]		RTR [21]		K-SVD [18]	
n	$p(\times 10^4)$	σ	Time	Error	Time	Error	Time	Error	Time	Error
32	1	0	0.05s	0.10%	0.24s	0.4%	100s	0.05%	25s	0.2%
32	1	0.2	0.05s	0.27%	0.24s	0.6%	250s	0.5%	25s	0.37%
32	1	0.4	0.1s	0.79%	0.36s	1.2%	577s	4.27%	25s	2.0%
32	1	0.6	0.2s	2.3%	0.7s	3.4%	823s	57.4%	25s	57.4%
100	4	0	1.2s	0.1%	3.4s	0.35%	863s	0.05%	98s	2.60%
100	4	0.2	2.2s	0.2%	4.2s	0.5%	1643s	0.3%	104s	3.46%
100	4	0.4	3.5s	0.6%	6.1s	1.1%	3796s	5.26%	105s	3.56%
100	4	0.6	8.4s	1.95%	13.5s	2.63%	5412s	50.5%	104s	51.26%

Beyond the work region of existing works!

Conclusion

- ℓ_p norm maximization enables **efficient** and **robust** solution for complete dictionary learning.
- Simple parameter-free algorithm can be used to solve ℓ_p norm maximization, which is **tractable** and **optimal-achievable**.
- Among all the choices of p ($p > 2$), ℓ_3 is the best.

References

- [SWW12] Daniel A Spielman, Huan Wang, and John Wright. Exact recovery of sparsely-used dictionaries. In Conference on Learning Theory, pages 1–37, 2012.
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- [ZMLZM19] Yuexiang Zhai, Zitong Yang, Zhenyu Liao, John Wright, and Yi Ma. Complete dictionary learning via ℓ_4 -norm maximization over the orthogonal group. arXiv preprint arXiv:1906.02435, 2019.