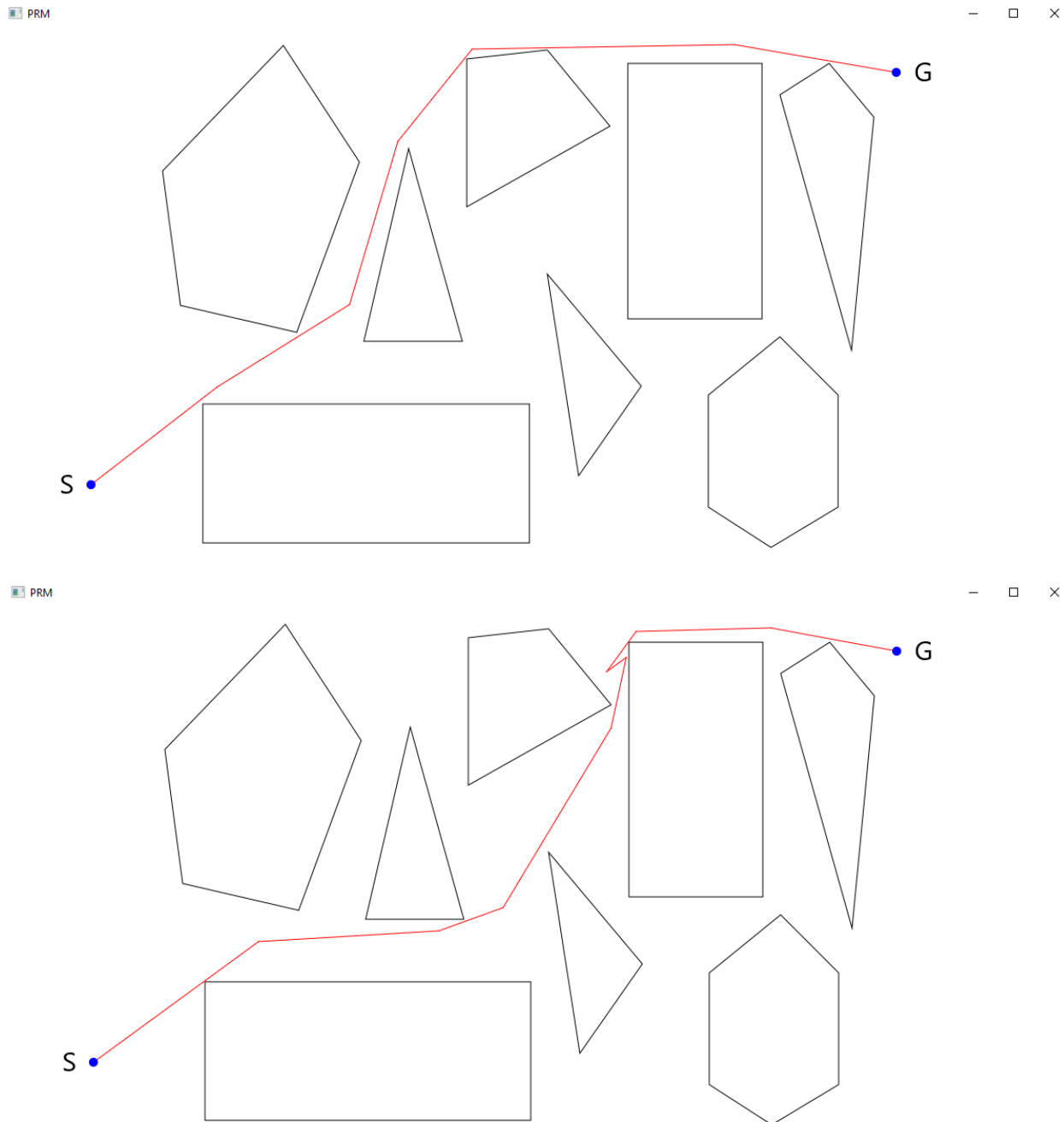


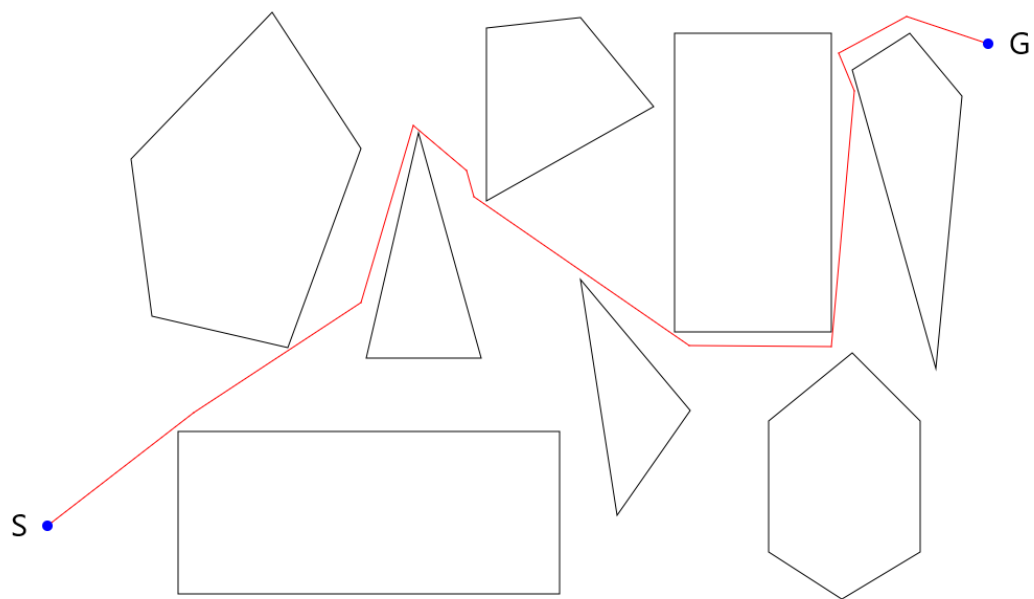
Here are some of the paths that were created using PRM. Two different environments were used. Each environment was given a different start and goal point.

Environment 1:



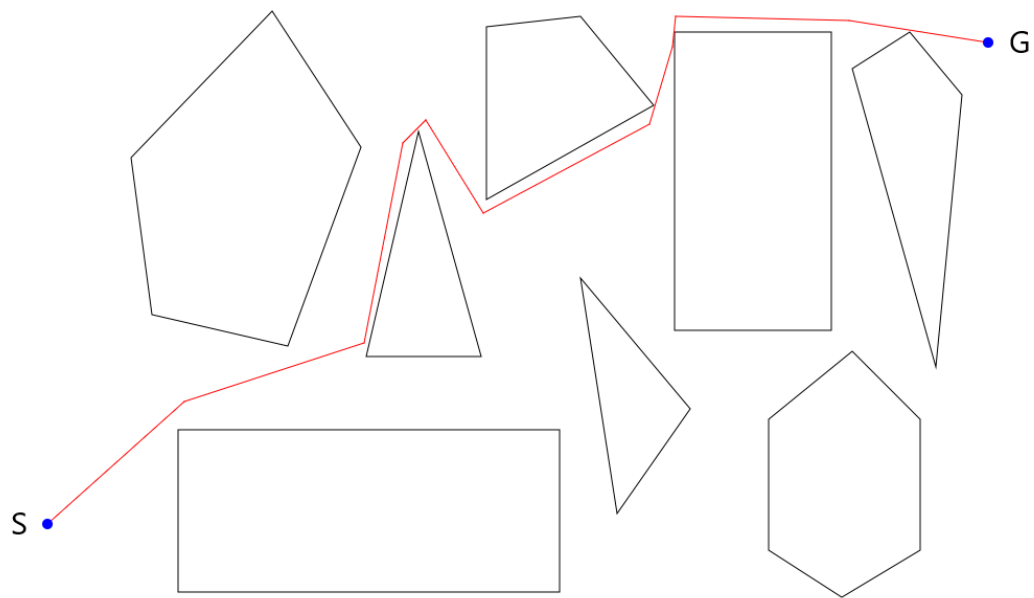
PRM

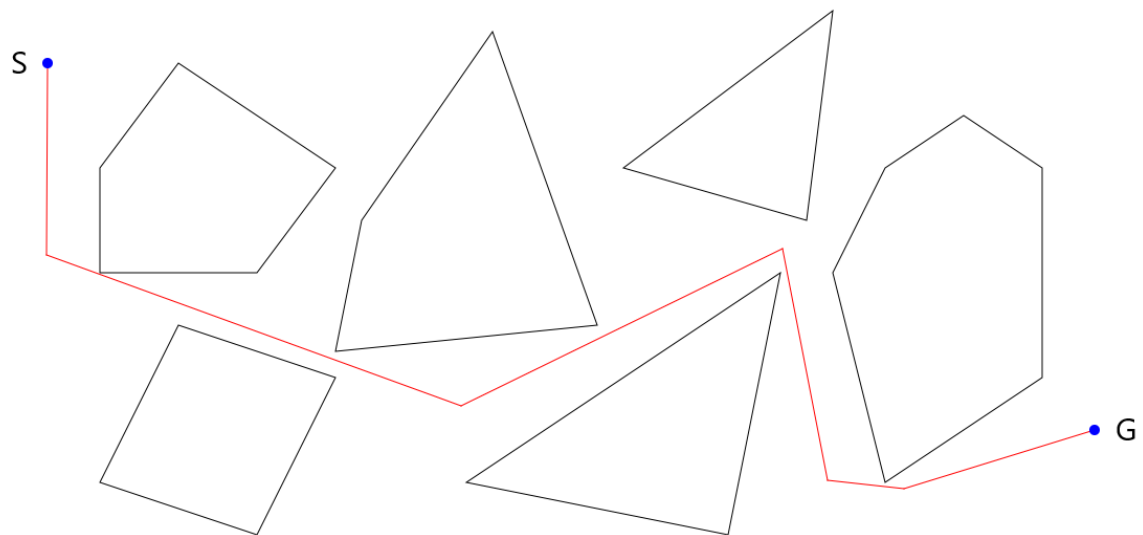
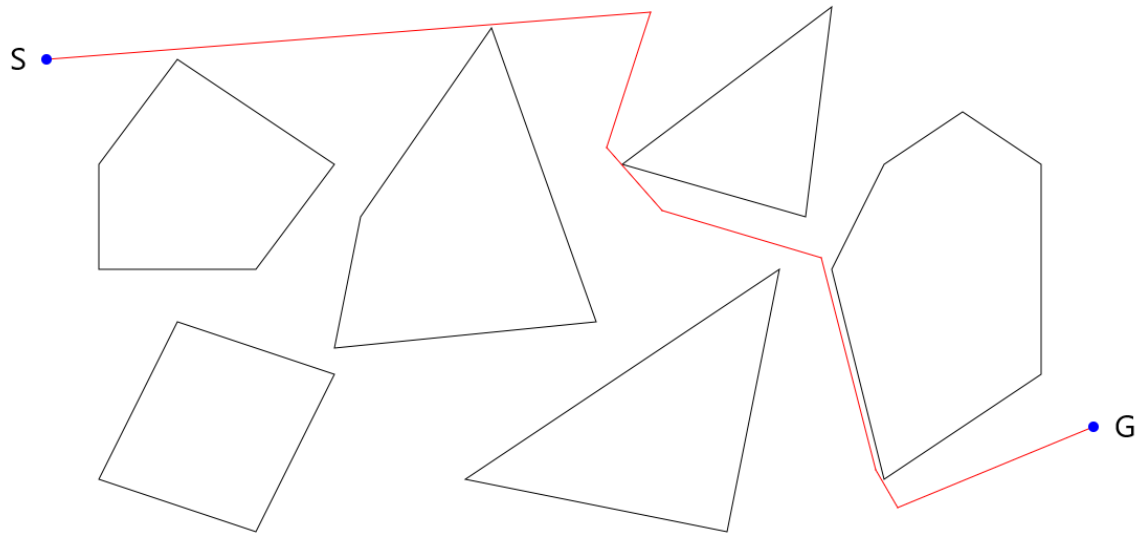
- □ ×



PRM

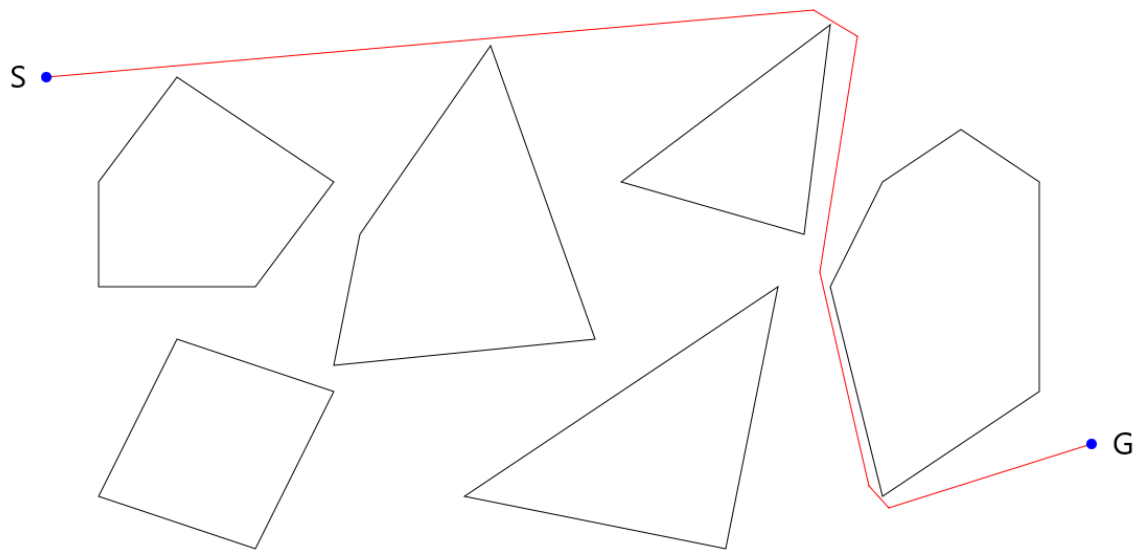
- □ ×





PRM

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PRM

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