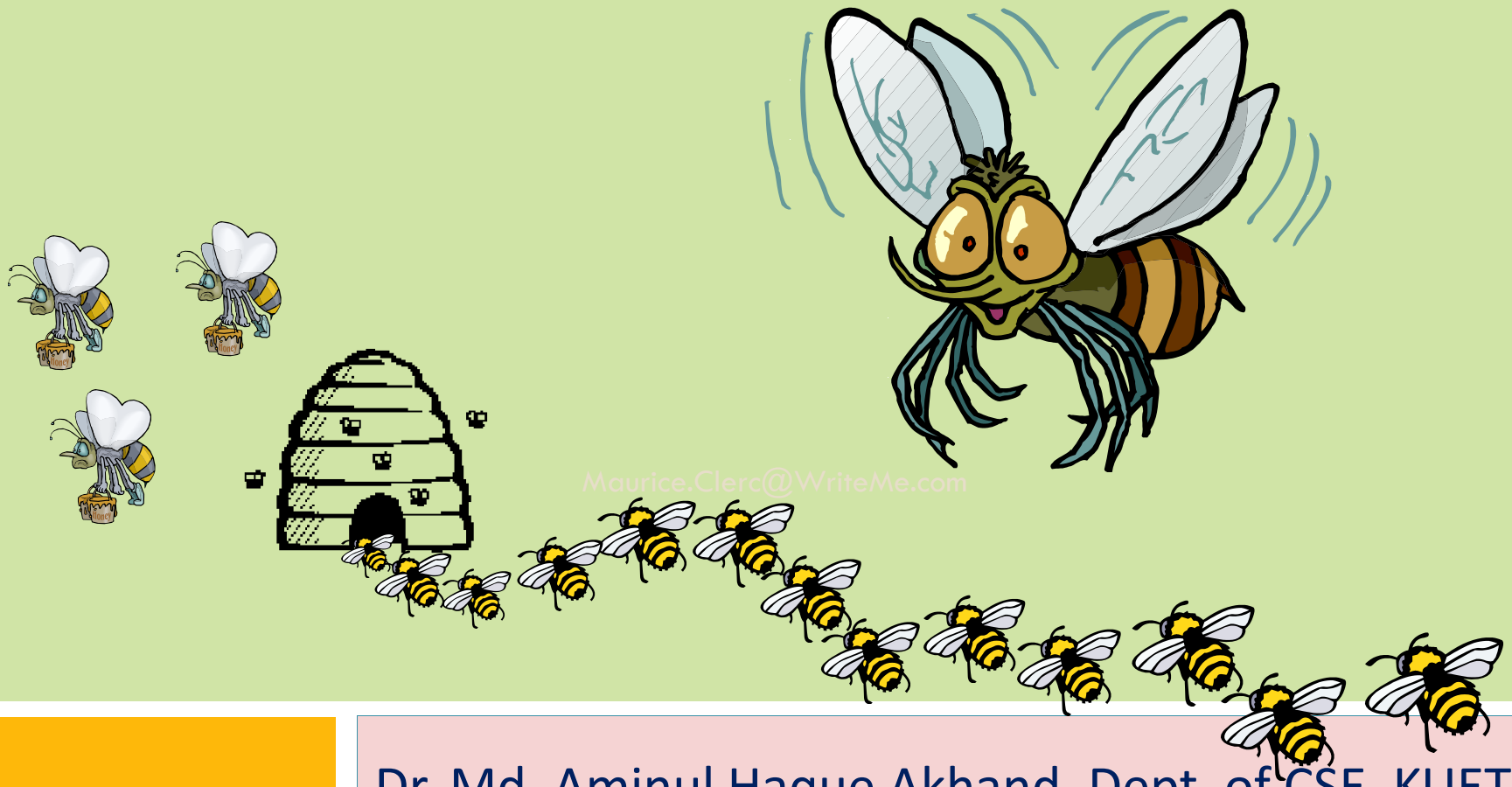


# Particle Swarm Optimization (PSO)



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# Introduction : Swarm Intelligence (SI)

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- Study of collective behavior in decentralized, self-organized systems.
- Originated from the study of colonies, or swarms of social organisms.
- Collective intelligence arises from interactions.



# Overview of Particle Swarm Optimization(PSO)

PSO is a population based on stochastic optimization algorithms to find a solution and then solve an optimization problem in a search space.



How can birds or fish exhibit such a coordinated collective behavior?



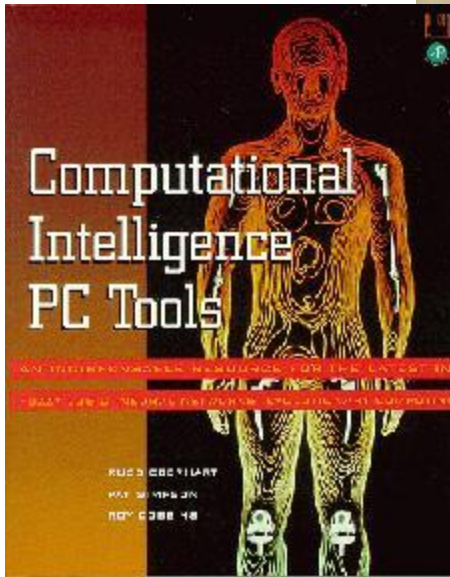
# PSO: History and Properties

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- Particle Swarm Optimization:
  - ▣ Introduced by Kennedy & Eberhart 1995
  - ▣ Inspired by social behavior of birds and shoals of fish
  - ▣ Swarm Intelligence-based optimization
  - ▣ Population-based optimization
  - ▣ Nondeterministic
  - ▣ Performance comparable to Genetic Algorithms



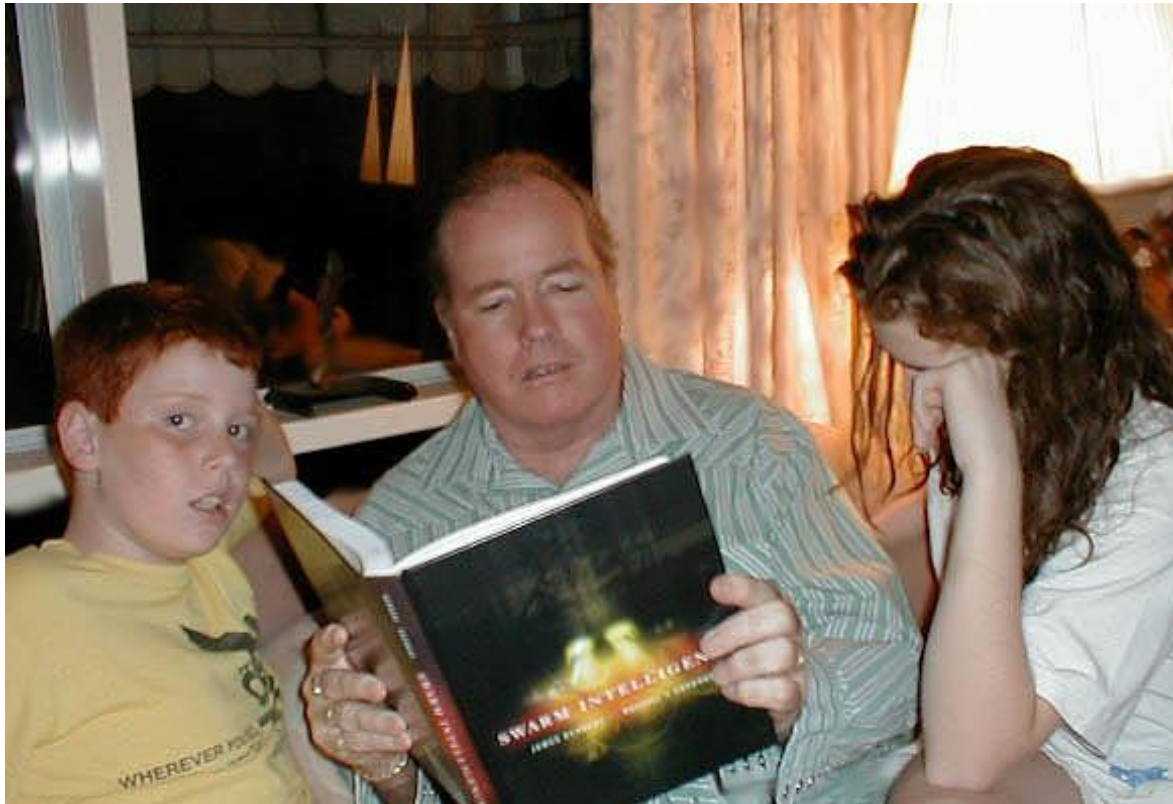
# PSO Inventors



Russell Eberhart

[eberhart@engr.iupui.edu](mailto:eberhart@engr.iupui.edu)

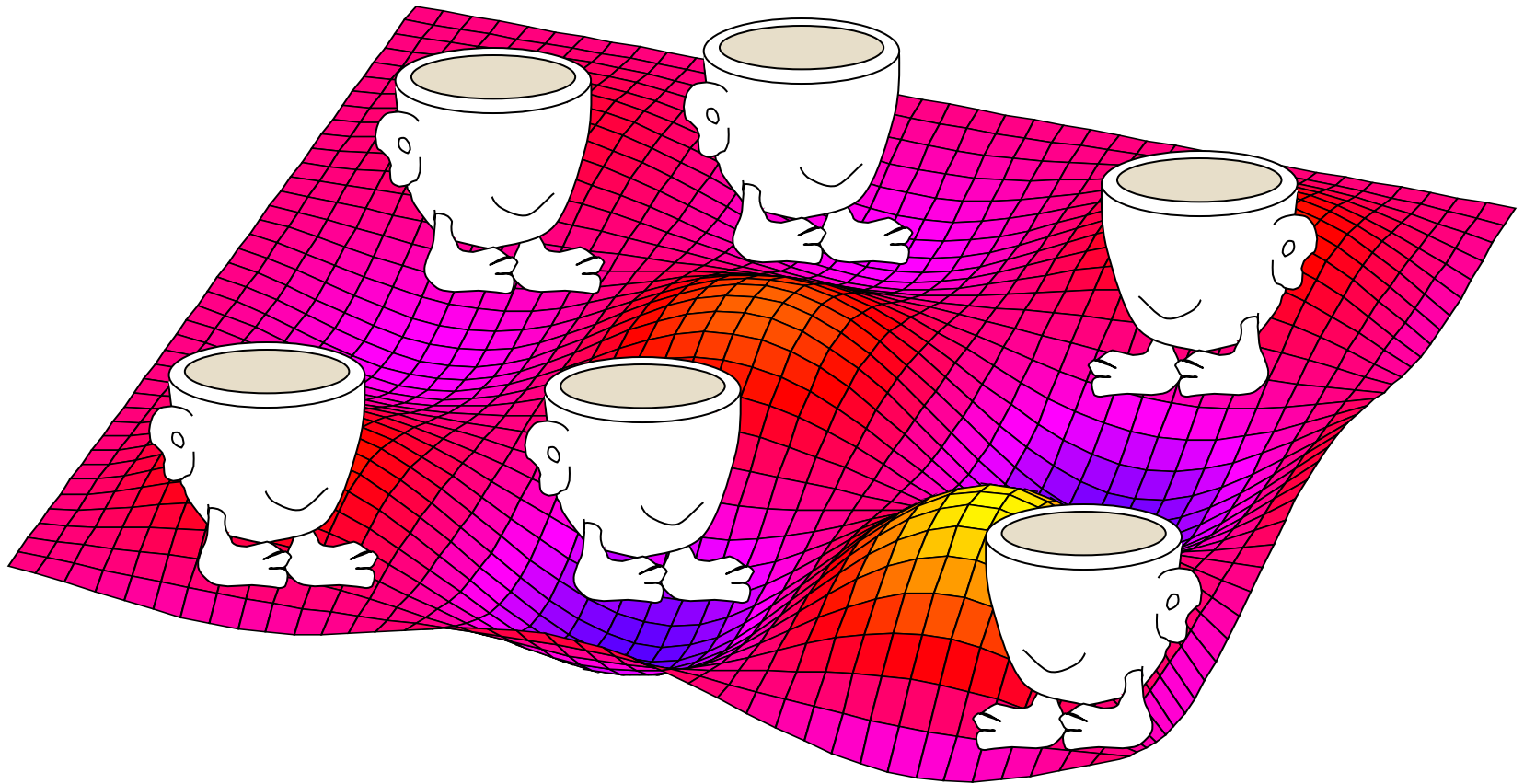
# PSO Inventors (2)



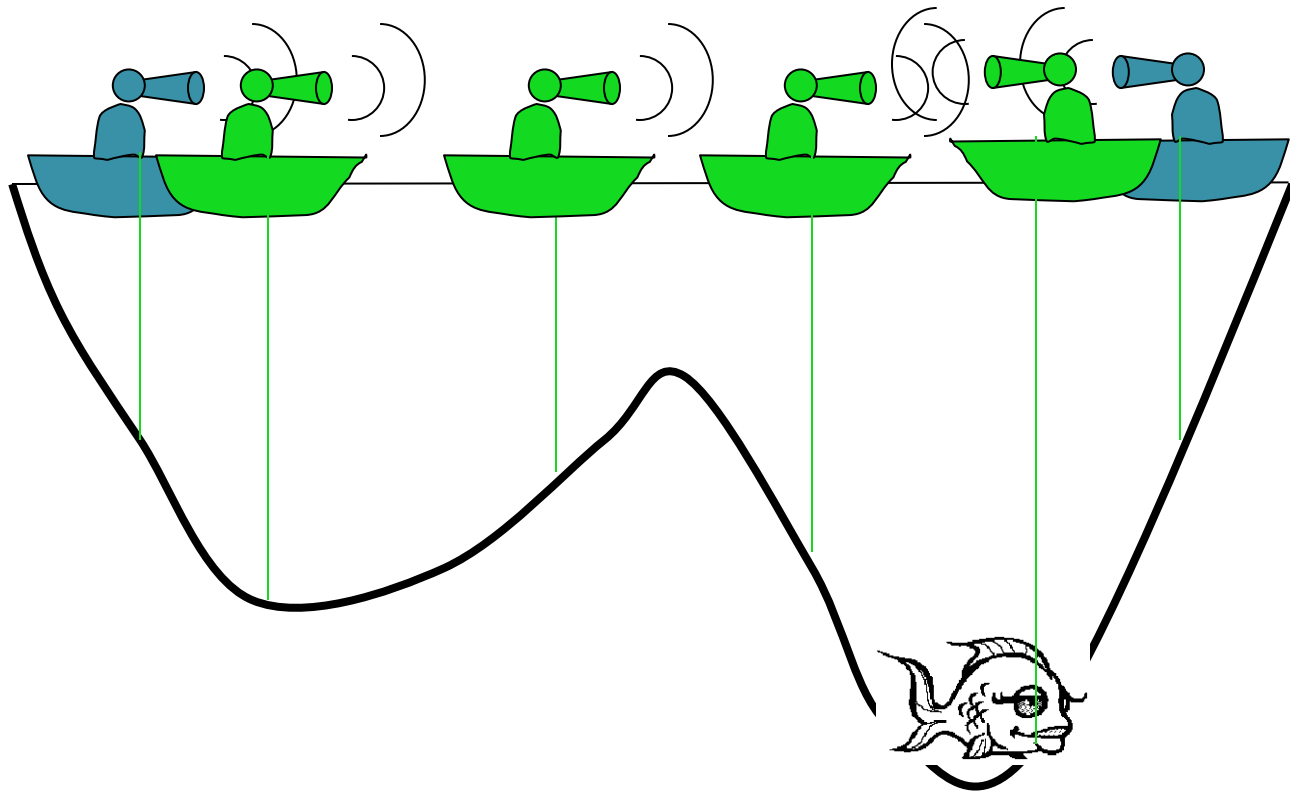
James Kennedy

[Kennedy\\_Jim@bls.gov](mailto:Kennedy_Jim@bls.gov)

# PSO: United We Stand



# Cooperation Example for PSO





# PSO Formulation

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- Swarm : a set of particles (S)
- Particle: a potential solution
  - ▣ Position,  $X_i = (x_{i1}, x_{i2}, \dots, x_{in}) \in \mathbb{R}^n$
  - ▣ Velocity,  $V_i = (v_{i1}, v_{i2}, \dots, v_{in}) \in \mathbb{R}^n$

- Each particle maintains

- ▣ Individual best position:  $P_i = (p_{i1}, p_{i2}, \dots, p_{in}) \in \mathbb{R}^n$   
 $pbest_i = f(P_i)$

- Swarm maintains its global best:

$$P_g \in \mathbb{R}^n$$
$$gbest = f(P_g)$$

# PSO Algorithm

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## ■ Basic Algorithm of PSO:

1. Initialize the swarm from the solution space
2. Evaluate fitness of each particle
3. Update individual and global bests
4. Update velocity and position of each particle
5. Go to Step 2, and repeat until termination condition

# PSO Algorithm (cont.)

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## ■ Original velocity update equation:

$$V_i^{t+1} = \underbrace{V_i^t}_{\text{Inertia}} + \underbrace{\varphi_1 \cdot r_1 (P_i - X_i^t)}_{\text{Cognitive Component}} + \underbrace{\varphi_2 \cdot r_2 (P_g - X_i^t)}_{\text{Social Component}}$$

- with  $r_1, r_2 \sim U(0,1)$
- $\varphi_1, \varphi_2$  : acceleration constant

# PSO Algorithm (cont.)

12

## ■ Original velocity update equation:

$$V_i^{t+1} = \underbrace{V_i^t}_{\text{Inertia}} + \underbrace{\varphi_1 \cdot r_1 (P_i - X_i^t)}_{\text{Cognitive Component}} + \underbrace{\varphi_2 \cdot r_2 (P_g - X_i^t)}_{\text{Social Component}}$$

- with  $r_1, r_2 \sim U(0,1)$
- $\varphi_1, \varphi_2$  : Acceleration constants or coefficients
- Acceleration constants sometimes define as  $C_1$  and  $C_2$

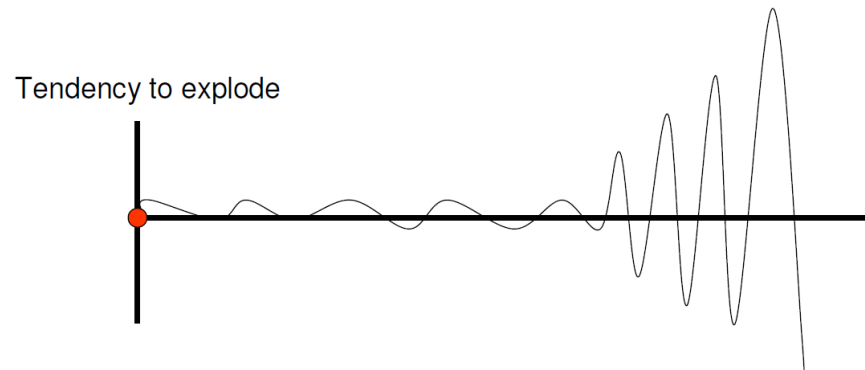
## ■ Position Update $X_i^{t+1} = X_i^t + V_i^{t+1}$

# PSO Algorithm - Parameters

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## ■ Acceleration constant $\varphi_1, \varphi_2$

- Small values limit the movement of the particles
- Large values : tendency to explode toward infinity
- In general  $\varphi_1 + \varphi_2 \leq 4$



## ■ Maximum velocity

- Velocity is a stochastic variable => uncontrolled trajectory

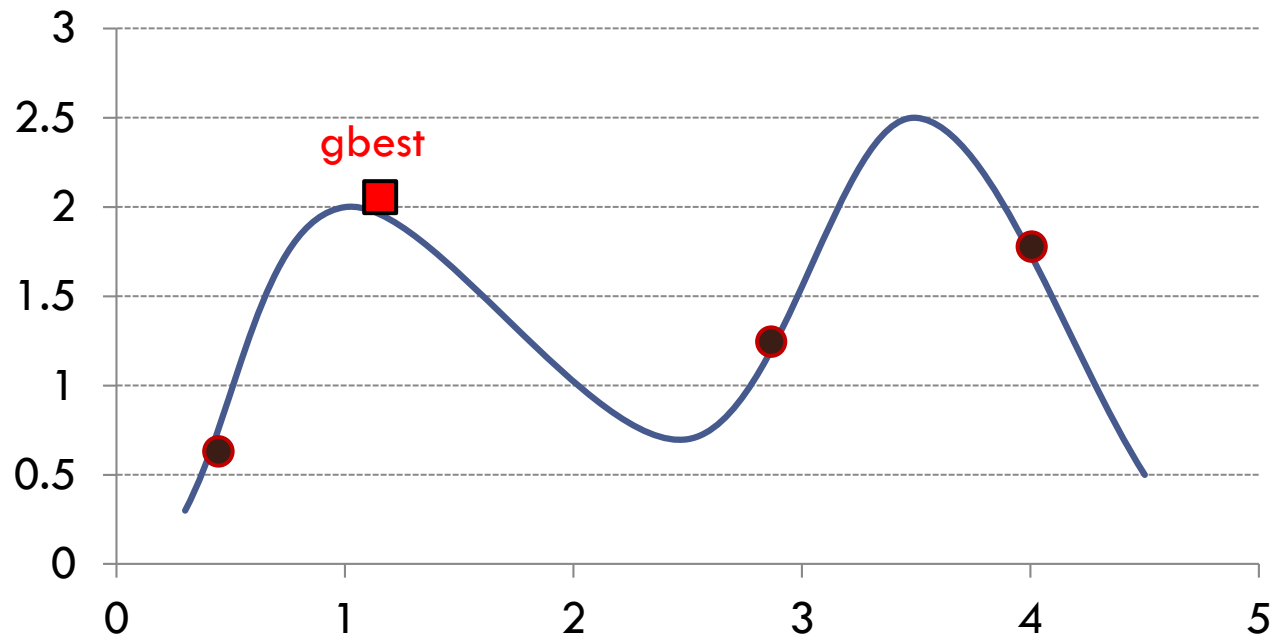
If  $v_{id} > v_{max}$  then  $v_{id} = v_{max}$   
else if  $v_{id} < -v_{max}$  then  $v_{id} = -v_{max}$



# Simple 1D Example

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Initialize swarm and evaluate fitness ( $t=0$ )

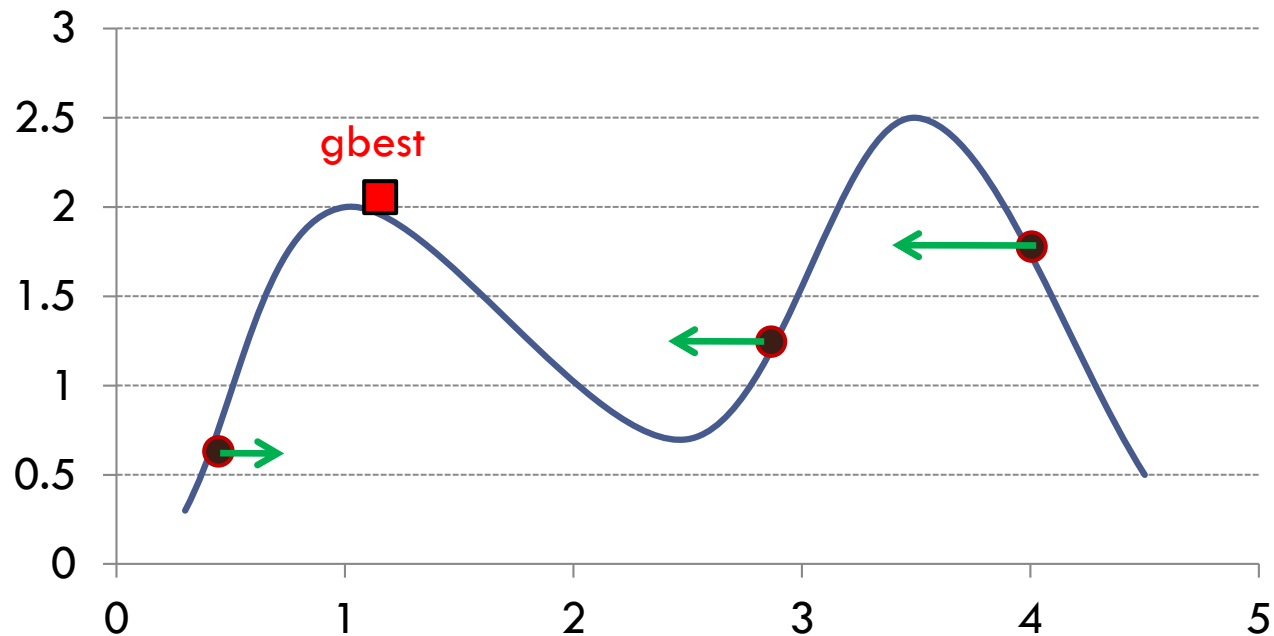


# Simple 1D Example

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Update velocity and position (t=1)

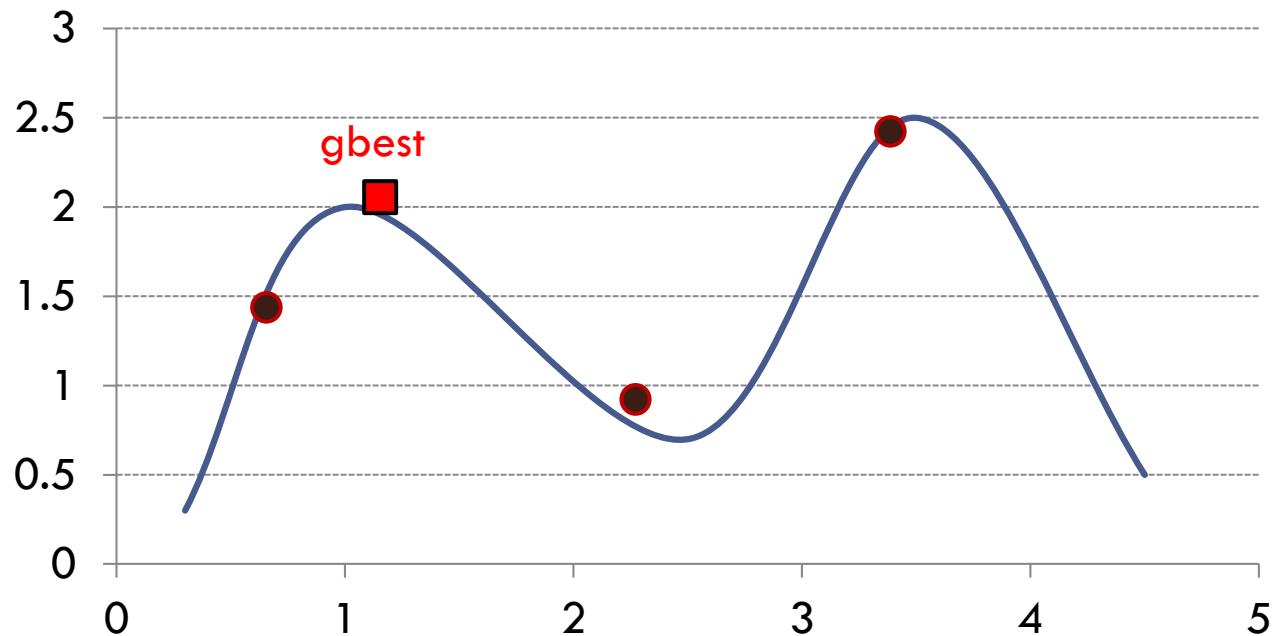
$$V_i^{t+1} = V_i^t + \varphi_1 \cdot r_1 (P_i - X_i^t) + \varphi_2 \cdot r_2 (P_g - X_i^t)$$



# Simple 1D Example

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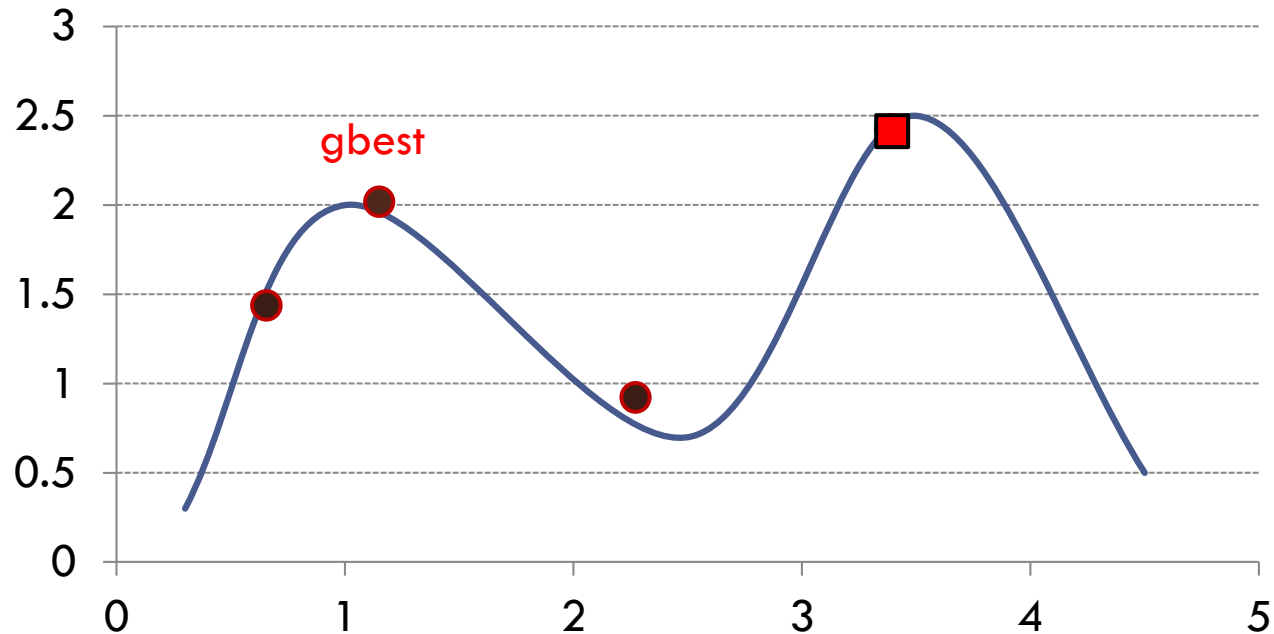
Evaluate fitness  
Update personal and global best ( $t=2$ )



# Simple 1D Example

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Evaluate fitness  
Update personal and global best ( $t=2$ )

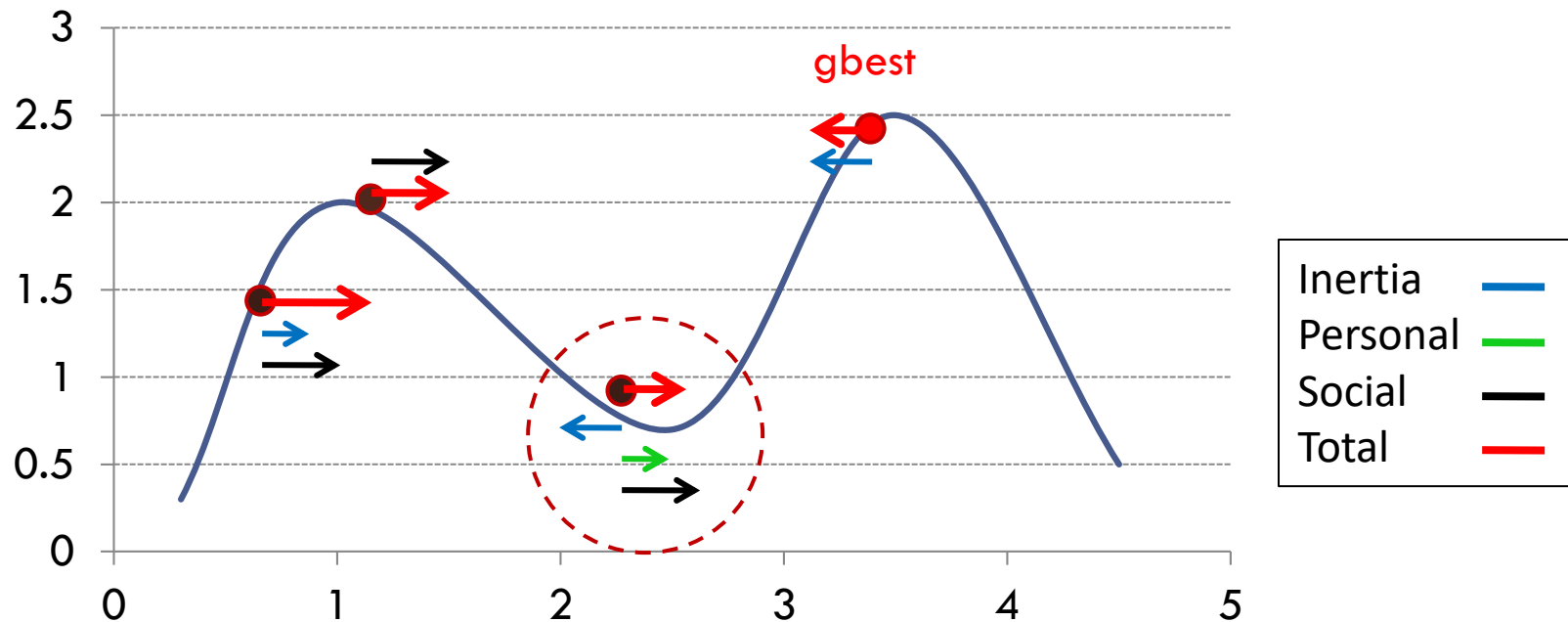


# Simple 1D Example

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Update velocity and position (t=2)

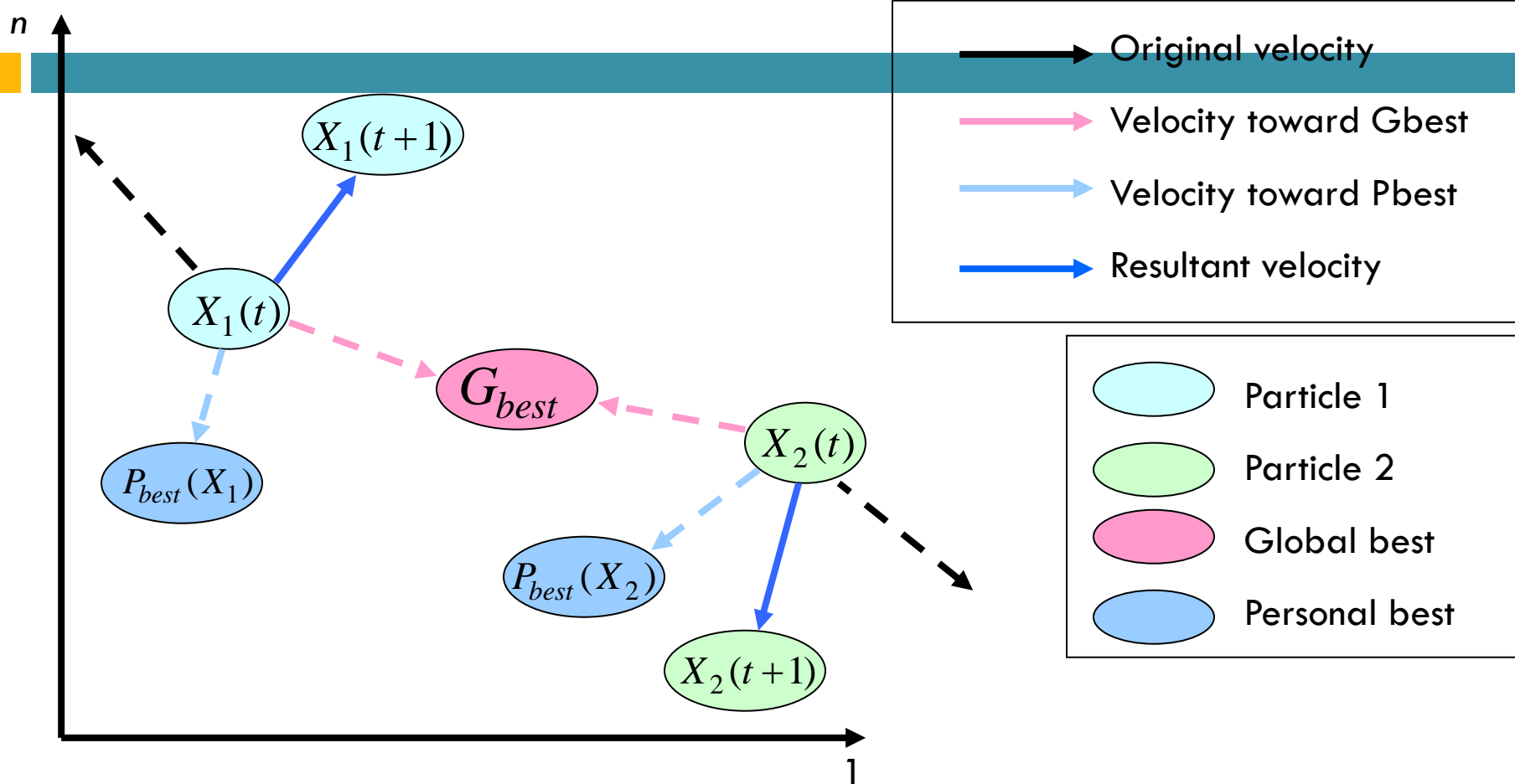
$$V_i^{t+1} = V_i^t + \varphi_1.r_1(P_i - X_i^t) + \varphi_2.r_2(P_g - X_i^t)$$





# Movement of Particles

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Individual particles (1 and 2) are accelerated toward the location of the global best solution ( $G_{best}$ ) and the location of their own personal best ( $P_{best}$ ) in the  $n$ -dimensional space.

# PSO with Inertia Weight (w)

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## ■ Inertia weight:

$$V_i^{t+1} = \underset{\downarrow}{\textcircled{w}} V_i^t + \varphi_1 \cdot r_1 (P_i - X_i^t) + \varphi_2 \cdot r_2 (P_g - X_i^t)$$

## ■ Scaling the previous velocity

## ■ Rate of Convergence Improvement

## ■ Control search behavior

- ▣ High values → exploration
- ▣ Low values → exploitation

# PSO with Inertia Weight (w) (Cont.)

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- Can be decreased over time:

- ▣ Linear [0.9 to 0.4]

- ▣ Nonlinear

$$w(t) = \frac{A}{e^t}$$

- Main disadvantage:


- ▣ Once the inertia weight is decreased, the swarm loses its ability to search new areas (can not recover its exploration mode).

# Rate of Convergence Improvement (Cont.)

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## ■ Constriction Factor:

- ▣ Canonical PSO

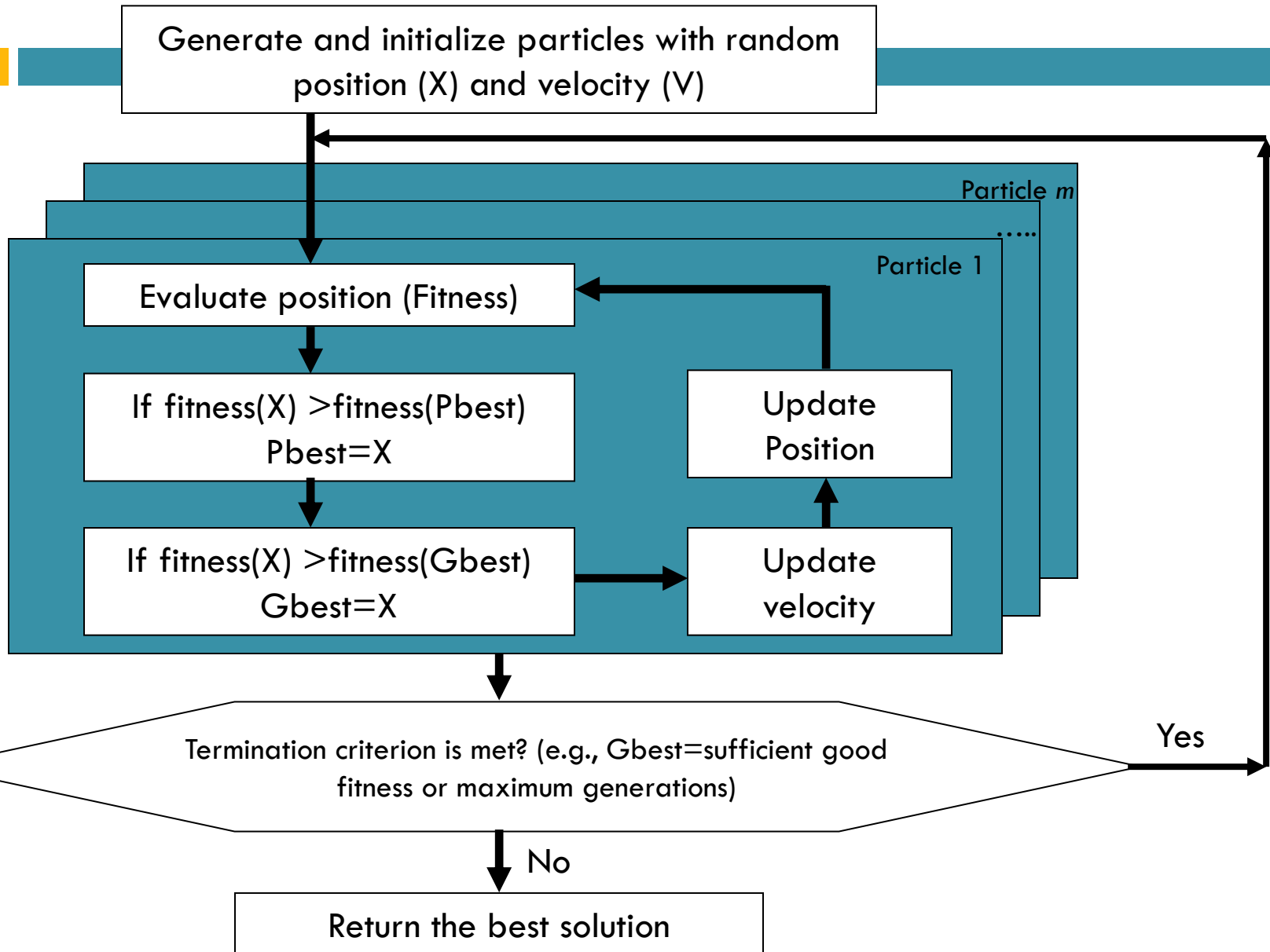

$$V_i^{t+1} = \chi \cdot (V_i^t + \varphi_1 \cdot r_1 (P_i - X_i^t) + \varphi_2 \cdot r_2 (P_g - X_i^t))$$

$$\chi = \frac{2}{\left| 2 - \varphi - \sqrt{\varphi^2 - 4\varphi} \right|} \quad , \quad \varphi = \varphi_1 + \varphi_2 \quad , \quad \varphi > 4$$

- ▣ Typically  $\varphi = 4.1$   $\chi = 0.729$
- ▣ Can converge without using Vmax (velocity clamping)
- ▣ Improve the convergence by damping the oscillations

# The Flowchart of PSO

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# Overview of PSO with Pseudocode

```
For each particle  
    Initialize particle  
END
```

```
Do  
    For each particle  
        Calculate fitness value  
        If the fitness value is better than the best fitness value (pBest) in history  
            set current value as the new pBest  
    End
```

```
Choose the particle with the best fitness value of all the particles as the gBest  
For each particle  
    Calculate particle velocity according equation of updating velocity  
    Update particle position according equation of updating position  
End
```

```
While maximum iterations or minimum error criteria is not attained
```

Pseudo-code for PSO

# Aspects of PSO

$$V_i^{t+1} = w.V_i^t + \varphi_1.r_1(P_i - X_i^t) + \varphi_2.r_2(P_g - X_i^t)$$

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## ➤ Previous Velocity, $V_i^t$

- ✓ Inertia component
- ✓ Memory of previous flight direction
- ✓ Prevents particle from drastically changing direction

## ➤ Cognitive Component, $\varphi_1.r_1(P_i - X_i^t)$

- ✓ Quantifies performance relative to past performances
- ✓ Memory of previous best position
- ✓ Nostalgia

## ➤ Social Component, $\varphi_2.r_2(P_g - X_i^t)$

- ✓ Quantifies performance relative to neighbors
- ✓ Envy

# Aspects of PSO (Cont.)

$$V_i^{t+1} = \textcolor{red}{w} \cdot V_i^t + \varphi_1 \cdot r_1 (P_i - X_i^t) + \varphi_2 \cdot r_2 (P_g - X_i^t)$$

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**Inertia weight (w) Controls the tendency of particles to keep searching in the same direction**

➤ **For  $w \geq 1$**

- ✓ Velocities increase over time
- ✓ Swarm diverges
- ✓ Particles fail to change direction towards more promising regions

➤ **For  $0 < w < 1$**

- ✓ Particles decelerate
- ✓ Convergence also depend on values of  $\varphi_1$  and  $\varphi_2$

➤ **Exploration–Exploitation**

- Large values – Favor exploration
- Small values – Promote exploitation

➤ **Problem-dependent**

# Aspects of PSO (Cont.)

$$V_i^{t+1} = w.V_i^t + \varphi_1.r_1(P_i - X_i^t) + \varphi_2.r_2(P_g - X_i^t)$$

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## Exploration–exploitation tradeoff

- exploration – the ability to explore regions of the search space
- exploitation – the ability to concentrate the search around a promising area to refine a candidate solution
- $c_1$  vs  $c_2$  ( $\varphi_1$  vs  $\varphi_2$ ) : influence on the exploration–exploitation tradeoff

# Aspects of PSO (Cont.)

$$V_i^{t+1} = w.V_i^t + \varphi_1.r_1(P_i - X_i^t) + \varphi_2.r_2(P_g - X_i^t)$$

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- $\varphi_1$  and  $\varphi_2$ , together with  $r_1$  and  $r_2$ , control the stochastic influence of the cognitive and social components on the overall velocity of a particle.
- The acceleration constants  $\varphi_1$  and  $\varphi_2$  are also referred to as trust parameters, where  $\varphi_1$  expresses how much confidence a particle has in itself, while  $\varphi_2$  expresses how much confidence a particle has in its neighbors.
- If  $\varphi_1 > 0$  and  $\varphi_2 = 0$ , all particles are independent hill-climbers. Each particle finds the best position in its neighborhood by replacing the current best position if the new position is better. Particles perform a local search.
- If  $\varphi_2 > 0$  and  $\varphi_1 = 0$ , the entire swarm is attracted to a single point  $P_g$



# Aspects of PSO (Comparing with GA)

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- PSO shares many similarities with evolutionary computation techniques such as Genetic Algorithms (GA).
- The system is initialized with a population of random solutions and searches for optima by updating generations.
- However, unlike GA, PSO has **no evolution operators such as crossover and mutation**.
- In PSO, the potential solutions, called particles, fly through the problem space by following the current optimum particles.
- Compared to GA, the advantages of PSO are that PSO is easy to implement and there are few parameters to adjust.
- PSO has been successfully applied in many areas: function optimization, artificial neural network training, fuzzy system control, and other areas where GA can be applied.

# PSO Variants

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- Hybrid PSO
  - ▣ Incorporate the capabilities of other evolutionary computation techniques.
- Adaptive PSO
  - ▣ Adaptation of PSO parameters for a better performance.
- PSO in complex environments
  - ▣ Multiobjective or constrained optimization problems or tracking dynamic systems.
- Other variants
  - ▣ variations to the original formulation to improve its performance.

# Hybrid PSO

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## ■ GA-PSO:

- ▣ combines the advantages of swarm intelligence and a natural selection mechanism.
- ▣ jump from one area to another by the selection mechanism → accelerating the convergence speed.
- ▣ capability of “breeding”.
- ▣ replacing agent positions with low fitness values, with those with high fitness, according to a selection rate

# Hybrid PSO

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## ■ EPSO:

- ▣ Evolutionary PSO
- ▣ Incorporates a selection procedure
- ▣ Self-adapting of parameters

## ■ The particle movement is defined as:

$$V_i^t = w'_{i1} V_i^{t-1} + w'_{i2} r_1 (P_i - X_i^{t-1}) + w'_{i3} r_2 (P'_g - X_i^{t-1})$$
$$X_i^t = X_i^{t-1} + V_i^t$$

# Hybrid PSO : EPSO

33

- Mutation of weights and global best:

$$w'_{ik} = w_{ik} + \tau.N(0,1)$$

$$P'_g = P_g + \tau'.N(0,1)$$

- Learning parameters  $\tau'$  ,  $\tau$  can be either fixed or dynamically changing as strategic parameters.
- 
- Survival Selection:
    - Stochastic tournament.

# Simplicity in PSO and Applications

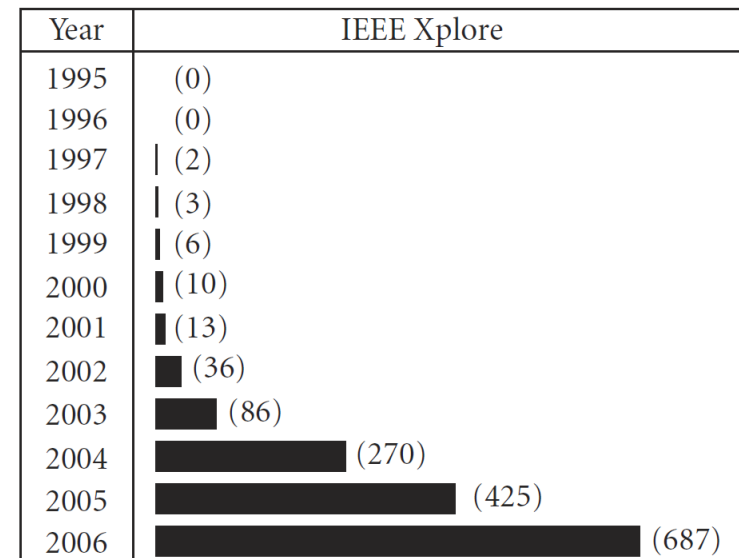
34

## ■ Simplicity make PSO be applied in more and more fields

- ▣ Convenience of realization
- ▣ Properties of low constraint on the continuity of objective function
- ▣ Joint of search space
- ▣ Ability of adapting to dynamic environment
- ▣ -----

## ■ Some PSO applications:

- ▣ Electronics and electromagnetic
- ▣ Signal, Image and video processing
- ▣ Neural networks
- ▣ Communication networks
- ▣ ...



# PSO Applications

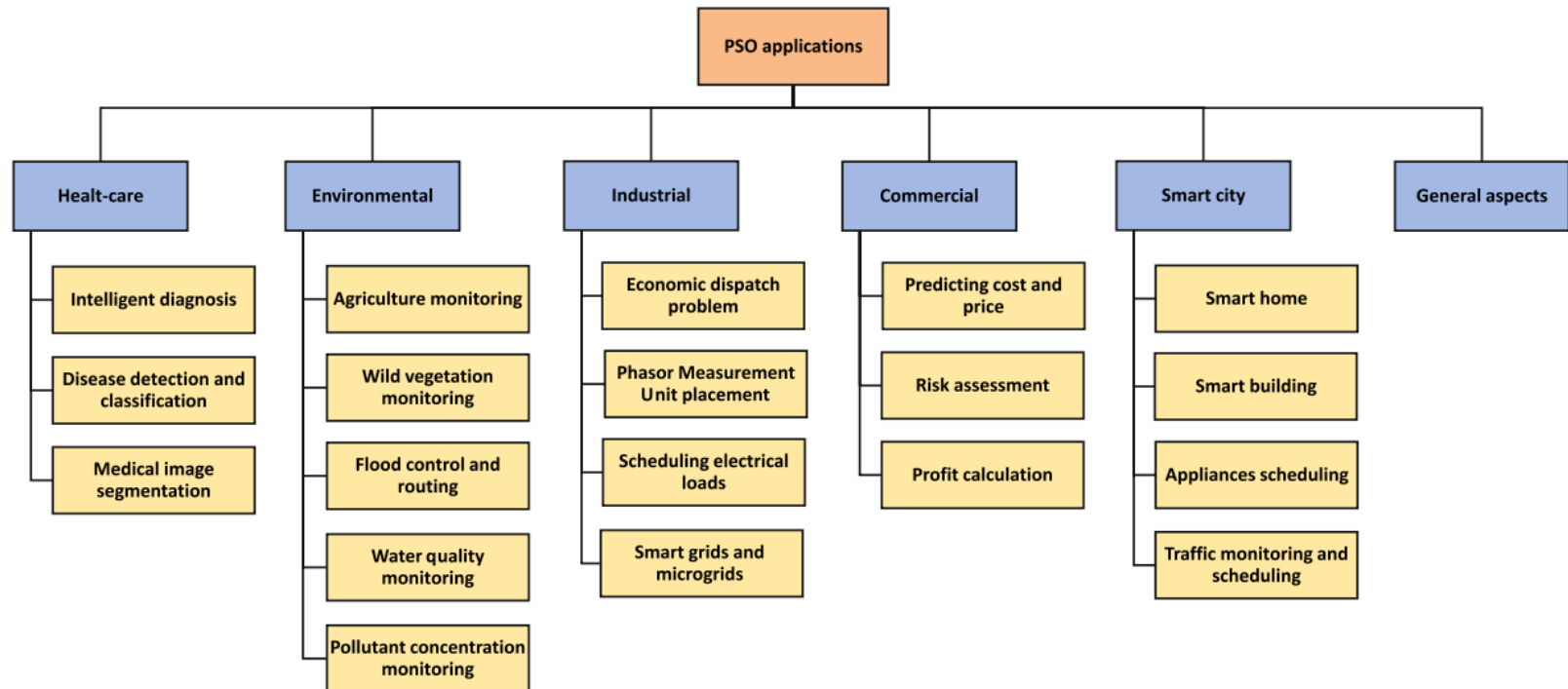
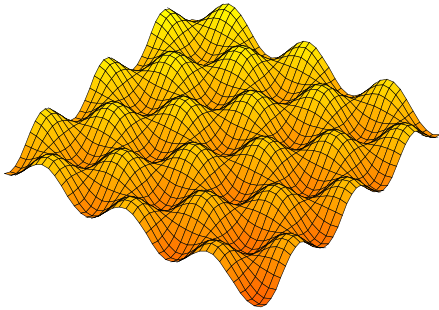


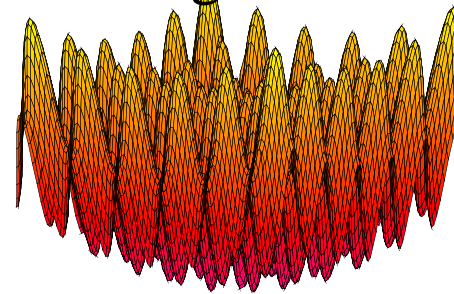
Fig. 5 The taxonomy of PSO applications

# Some functions ...

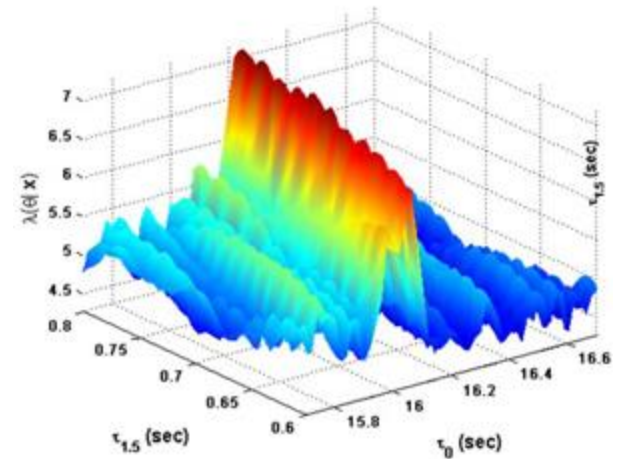
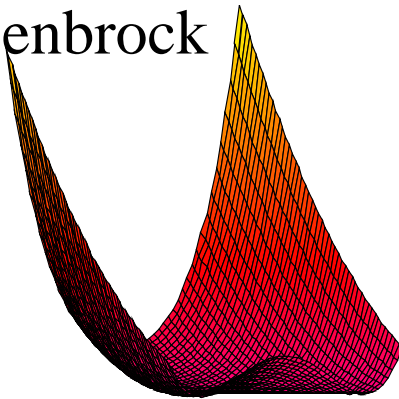
Griewank



Rastrigin



Rosenbrock





# A Detailed Problem Solving

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- [TextBook] 2021 - Evolutionary Optimization Algorithms-CRC Press
- 5.7 Example -> Page 98

**Thanks for your attention**