Project Design Phase-II Technology Stack (Architecture & Stack)

| Date | 20 May 2023 | |
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| Team ID | NM2023TMID16858 | |
| Project Name | Project – Al Enabled Car Parking Using | |
| | OpenCV | |

Technical Architecture:

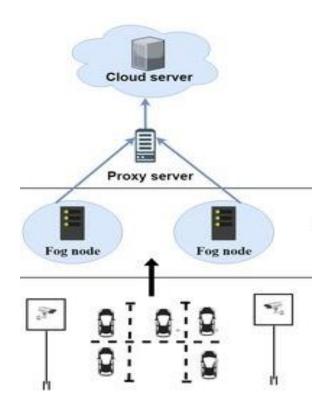


Table-1 : Components & Technologies:

| S.No | Component | Description | Technology |
|------|---------------------------------|--|---|
| 1. | User Interface | How user interacts with application e.g. Web UI, Mobile App, Chatbot etc. | HTML, CSS, JavaScript / Angular Js / React Js etc. |
| 2. | Application Logic | Logic for a process in the application | Java / Python |
| 3. | Database | Data Type, Configurations etc. | MySQL, NoSQL, etc. |
| 4. | Cloud Database | Database Service on Cloud | IBM DB2, IBM Cloudant etc. |
| 5. | File Storage | File storage requirements | IBM Block Storage or Other Storage Service or Local Filesystem |
| 6. | Machine Learning Model | Purpose of Machine Learning Model | Object Recognition Model, etc. |
| 7. | Infrastructure (Server / Cloud) | Application Deployment on Local System / Cloud Local Server Configuration: Cloud Server Configuration: | Local, Cloud Foundry, Kubernetes, etc. |
| 8. | Camera | The camera captures the live video feed or images of the parking area. It provides visual input to the system for analysis and processing. | USB camera , Raspberry Pi camera |

| 9. | Video Processing | The captured frames are preprocessed | OpenCV |
|----|---------------------------|---|-------------------------------|
| 10 | . Object Detection | Detects the car which occupied the parking slot | Haar cascades, HOG, SSD, YOLO |
| 1′ | . Parking Space Detection | Detects the empty slots | OpenCV's contour |

Table-2: Application Characteristics:

| S.No | Characteristics | Description | Technology |
|------|----------------------------|--|--|
| 1. | Real-time Object Detection | The system detects cars in real-time, providing live updates on parking space availability. | OpenCV, Object Detection Algorithms (Haar cascades, SSD, YOLO) |
| 2. | Parking Space Segmentation | The system segments the parking area into individual parking spaces for accurate identification and tracking. | OpenCV, Image Processing, Contour Detection |
| 3. | Occupancy Detection | The system determines the occupancy status (vacant or occupied) of each parking space. | OpenCV, Machine Learning, Deep Learning (SVM, CNN) |
| 4. | Accuracy and Reliability | The system achieves high accuracy and reliability in car detection and occupancy classification, minimizing false positives/negatives. | OpenCV, Machine Learning, Deep Learning |
| 5. | Scalability | The system can scale to accommodate parking areas of different sizes and configurations | OpenCV |
| 6. | User-friendly Interface | The system provides a user-friendly interface displaying the parking area and real-time parking space availability. | GUI Frameworks (PyQt, Tkinter) |
| 7. | Adaptability | The system adapts to changing conditions, such as varying lighting or different vehicle types, for robust performance. | OpenCV |