

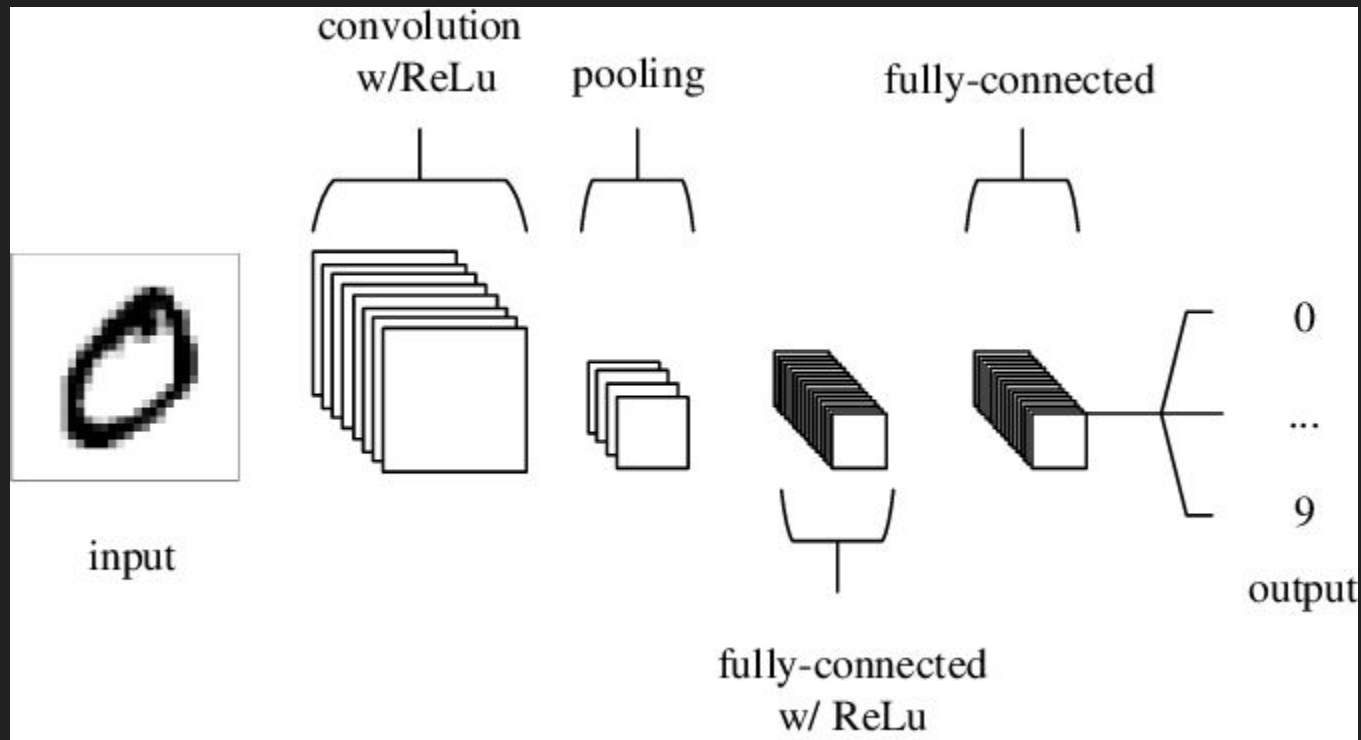
# **Deciphering Cognition: An Investigation into CNN Architectures**

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# Introduction

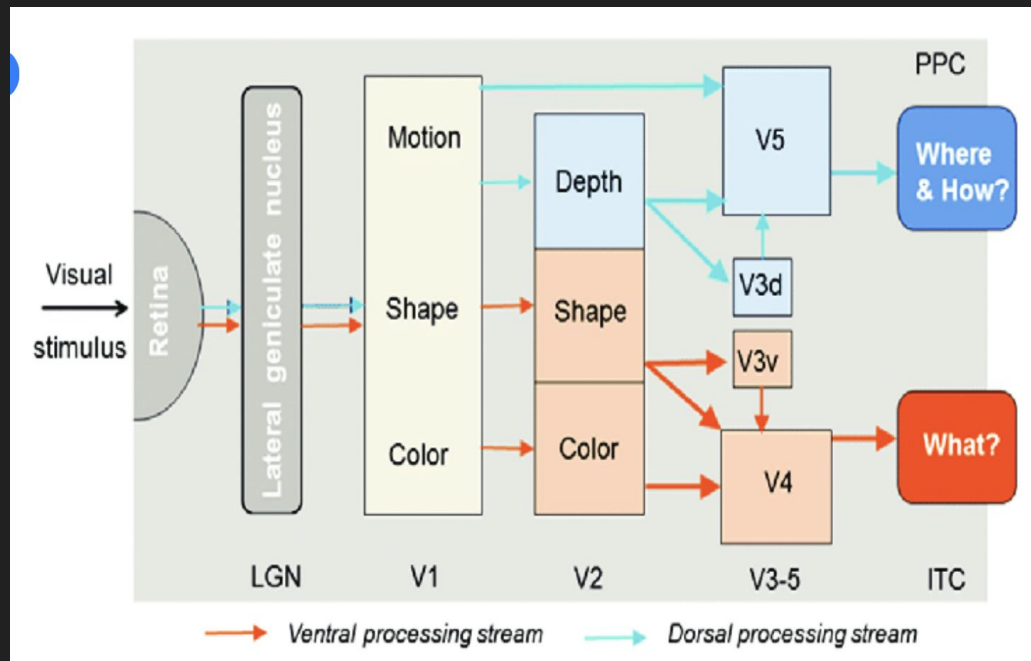
- Convolutional Neural Networks are inspired by the biological **visual cortex**.
- CNNs consist of an input layer, convolutional layers, pooling layers, fully connected layers, and an output layer.
- **Convolutional layers** capture spatial hierarchies and patterns in the images.
- **Pooling layers** help in developing a compressed representation of input data.
- **Fully connected layers** do the high-level reasoning after the feature extraction and down-sampling to classify the input.

# CNNs



# Similarities with Human Visual Cortex

- **Hierarchical Processing:** We start processing simple features like edges in V1 and complex objects in ITC.
- **Spatial Invariance:** We can detect objects regardless of orientation, or variation in size. **Pooling layers** mirror this property.



# Motivation

- Given the similarities in CNNs and human visual cortex, we want to understand how varying CNN architecture can provide understanding of human visual processing.
- Specifically, how do network depth and width affect the performance and learning abilities of CNNs?

**Hypothesis:** Increasing depth will enhance learning more effectively than increasing width.

## Related Work

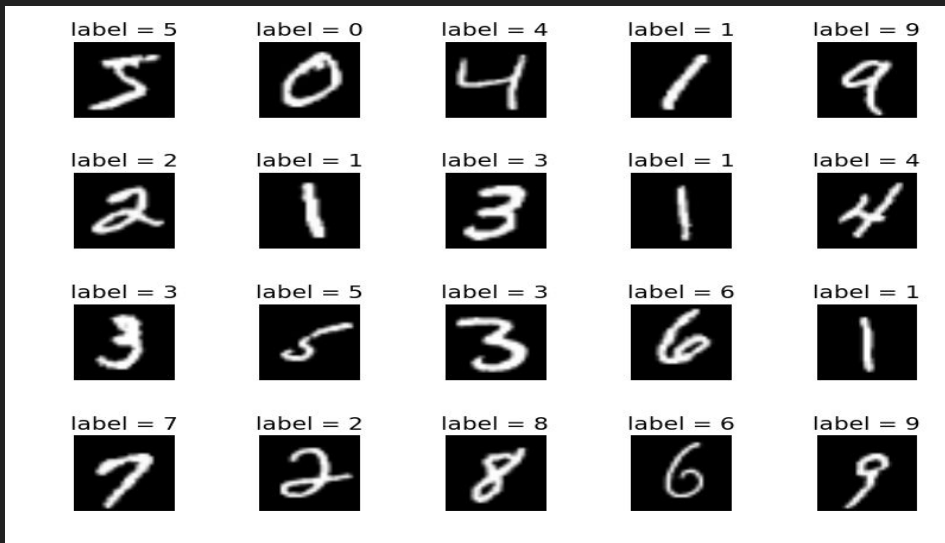
- He et al (2015) demonstrated that networks with increased depth significantly improved performance on image recognition tasks.
- Deeper networks can achieve higher levels of feature abstraction, analogous to complex cognition in humans
- Tan and Le (2019) determined that by doubling the depth, the computational cost roughly squares, while doubling the width or resolution increases the computational cost linearly.

# Methodology

- **Models used:** One-layer, two-layer, three-layer CNNs (90 total). All layers are followed by pooling with the final layer in each model being a fully connected layer.
- **Training parameters:**
  - Epochs: 5
  - Batch size: 64
  - Learning rate: 0.001
  - Optimizer: Stochastic Gradient Descent (SGD) with momentum 0.9.
- **Training setup:**
  - Loss: Cross-entropy loss

# Dataset

- **MNIST**: 60,000 training images and 10,000 testing images
- Black and white
- 10 classes

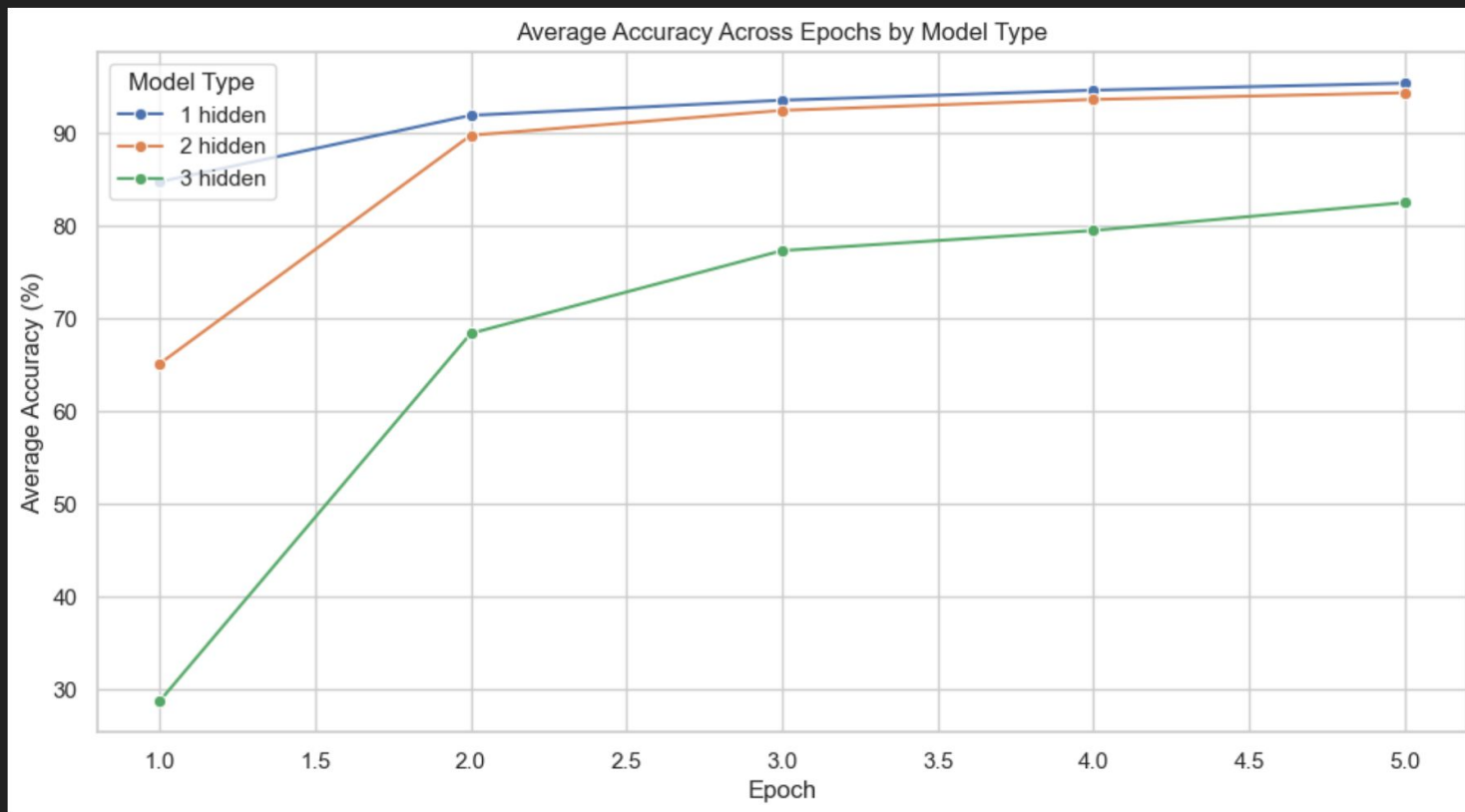




## Results: Model-wise Summaries

Model Type	Mean Accuracy	Mean Loss
1 Hidden Layer	95 +- 1	0.14 +- 0.03
2 Hidden Layer	95 +- 3	0.16 +- 0.09
3 Hidden Layer	86 +- 22	0.39 +- 0.58

# Accuracy Measures

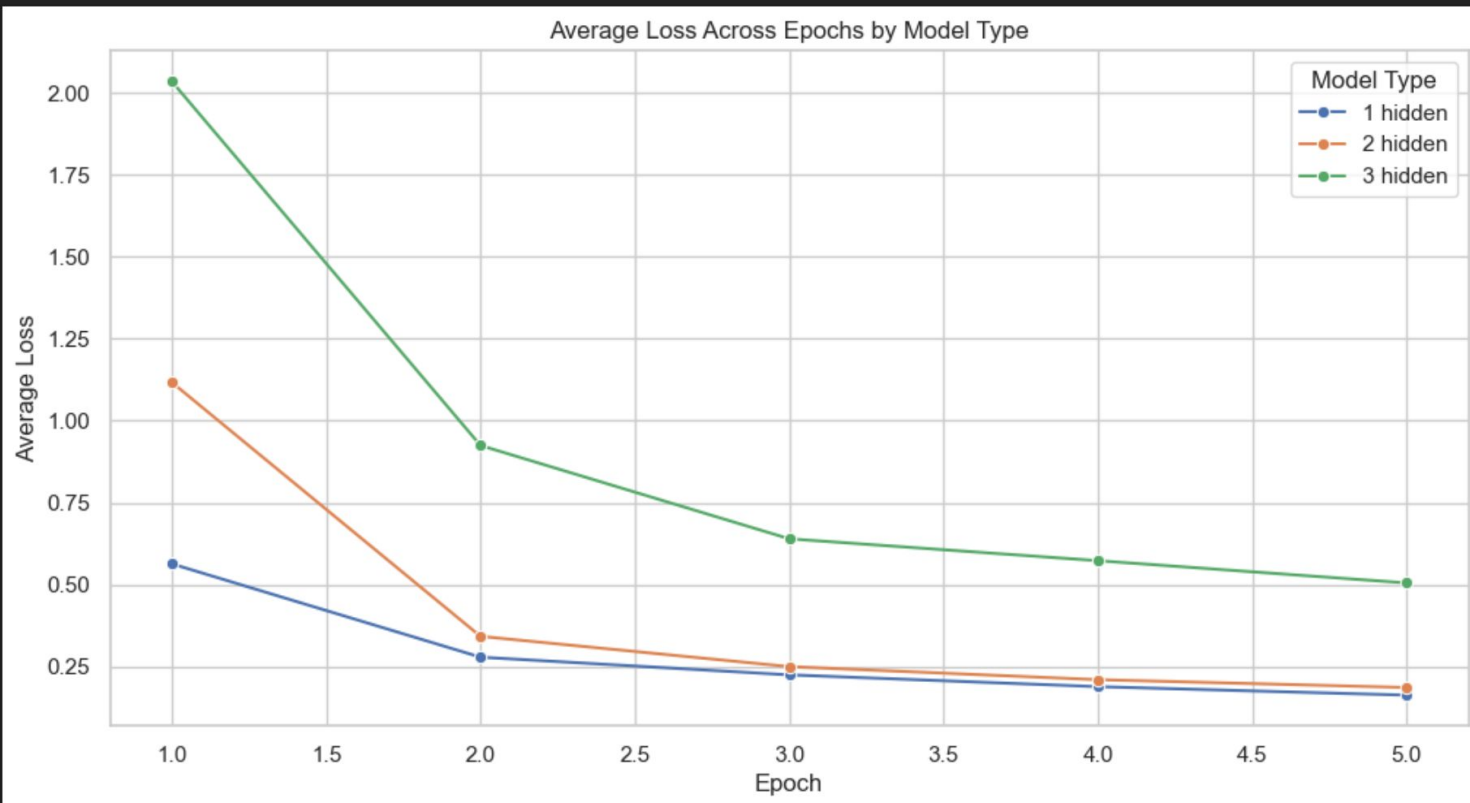


H1: 95%

H2: 94%

H3: 84%

# Loss Measures



# Interpretation

- Sometimes, higher-level abstraction offered by adding more layers might be unnecessary for the task.
- Adding more filters allows the model to learn a diverse set of features, providing richer representation for decision-making layers.
- More filters probably also help the model to generalize better to unseen data.

# Conclusion

- The experimentation with CNN architectures on the MNIST dataset demonstrates the **delicate balance** between model complexity (depth and width) and performance.
- After adding a certain number of layers that mitigate any over-simplicity or over-complexity concerns, it is both computationally and performance-wise better to experiment with width to increase accuracy.
- **Future research:**
  - a. Testing on datasets like Omniglot, because of the diversity of characters and languages
  - b. Expanding testing on different cognitive tasks like auditory processing

# References

He, K., Zhang, X., Ren, S., & Sun, J. (2016). Deep residual learning for image recognition. *Proceedings of the IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, 770-778.

<https://doi.org/10.1109/CVPR.2016.90>

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Riesenhuber, M., & Poggio, T. (1999). Hierarchical models of object recognition in cortex. *Nature Neuroscience*, 2(11), 1019-1025.

Tan, M., & Le, Q. V. (2019). EfficientNet: Rethinking model scaling for convolutional neural networks. *Proceedings of the 36th International Conference on Machine Learning*. <https://arxiv.org/abs/1905.11946>

**Thank you!**

Do you have any questions?