

# SCHOOL OF COMPUTER SCIENCE AND ENGINEERING

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# Image Convolution using Parallel Programming Techniques

A Report

submitted by

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CSE4001 – Parallel and Distributed Computing – J Component

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#### 1. INTRODUCTION

Convolution is the process of adding each element of the image to its local neighbors, weighted by the kernel. This is related to a form of mathematical convolution. The matrix operation being performed—convolution—is not traditional matrix multiplication, despite being similarly denoted by \*.

In image processing, a kernel, convolution matrix, or mask is a small matrix used for blurring, sharpening, embossing, edge detection, and more. This is accomplished by doing a convolution between the kernel and an image.

For Box Blur,

$$\frac{1}{9} \left[ \begin{array}{rrr} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{array} \right]$$

For Gaussian Blur,

$$\frac{1}{16} \left[ \begin{array}{ccc} 1 & 2 & 1 \\ 2 & 4 & 2 \\ 1 & 2 & 1 \end{array} \right]$$

For Sharpen,

$$\begin{bmatrix} 0 & -1 & 0 \\ -1 & 5 & -1 \\ 0 & -1 & 0 \end{bmatrix}$$

#### 2. PROPOSED WORK

The problem of image convergence parallelism requires careful planning and understanding of each component of the element. A direct approach, where we proceed to the implementation stage without the proper design of the parallel algorithm, leads to the

deterministic failure of the project on important issues such as scaling and execution time. Therefore, a systematic approach to our problem is necessary.

In this direction there is the Foster methodology, which defines four stages of design. Namely the stage of partitioning, communication, agglomeration and mapping.

#### 1. Partitioning

At this stage we try to export ways of parallelizing the execution. A good partition divides into small pieces both the calculations and the data of the problem. So, we divide the image into smaller images depending on the number of processes given. According to the methodology, in the first stages we have to choose more aggressive partitions.

More specifically, at the start of the program the user selects the number of processes for which the program will be executed. Based on an algorithm (which is described in the divide\_rows function, the optimal way in which the table will be distributed between the processes is calculated).

#### 2. Communication

As already mentioned the processes are distributed in the grid in such a way that they are next to each other in ascending order. This facilitates any process in finding its neighboring processes. A special case are the processes located in the periphery of the grid. In this case, adjacent processes are those that are on the appropriate off-limits opposite side.

Proceeding now to code issues as an option we have decided to use nonblocking sending and receiving messages thus being able to compile the central parts of the table (inner data) and leaving for later the calculation of peripheral pieces (outer and corner data). This allows a process to be busy with a task while waiting for the adjacent cells in the table to arrive. When this task is completed, if the data it has been waiting for has arrived, it proceeds to perform the required new tasks, otherwise it is still waiting to receive the required data.

For sending and receiving we decided to do with the help of Datatypes (vector, contiguous) data where possible (up, right, down, left) to avoid various risks and better manage them.

#### 3. Agglomeration

#### 4. Mapping

#### Algorithm for Convolution

```
for each image row in input image:
    for each pixel in image row:

    set accumulator to zero

    for each kernel row in kernel:
        for each element in kernel row:

        if element position corresponding* to pixel position then
            multiply element value corresponding* to pixel value
            add result to accumulator
        endif

    set output image pixel to accumulator
```

Flow of code:

In general, our implementation followed the following pattern:

for loop

**ISend** 

**IRecv** 

**Inner Data Computations** 

Wait(RRecv)

Outer Data Computations

Wait(RSend)

end for

#### 3. CODE & IMPLEMENTATION

Image Convolution using MPI

```
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <fcntl.h>
#include <stdint.h>
#include "mpi.h"
```

```
typedef enum {RGB, GREY} color_t;
void convolute(uint8_t *, uint8_t *, int, int, int, int, int, int, float**, color_t);
void convolute_grey(uint8_t *, uint8_t *, int, int, int, int, float **);
void convolute rgb(uint8 t*, uint8 t*, int, int, int, int, float **);
void Usage(int, char **, char **, int *, int *, int *, color_t *);
uint8 t *offset(uint8 t *, int, int, int);
int divide_rows(int, int, int);
int main(int argc, char** argv) {
       int fd, i, j, k, width, height, loops, t, row_div, col_div, rows, cols;
       double timer, remote time;
       char *image;
       color_t imageType;
       /* MPI world topology */
  int process id, num processes;
       /* Find current task id */
  MPI Init(&argc, &argv);
  MPI_Comm_size(MPI_COMM_WORLD, &num_processes);
  MPI Comm rank(MPI COMM WORLD, &process id);
       /* MPI status */
  MPI_Status status;
       /* MPI data types */
  MPI_Datatype grey_col_type;
  MPI_Datatype rgb_col_type;
  MPI_Datatype grey_row_type;
  MPI_Datatype rgb_row_type;
       /* MPI requests */
  MPI Request send north reg;
  MPI Request send south reg;
  MPI Request send west reg;
  MPI_Request send_east_req;
  MPI Request recv north reg;
  MPI_Request recv_south_req;
  MPI Request recy west reg;
  MPI_Request recv_east_req;
       /* Neighbours */
       int north = -1;
       int south = -1;
  int west = -1;
  int east = -1;
  /* Check arguments */
  if (process id == 0) {
```

```
Usage(argc, argv, &image, &width, &height, &loops, &imageType);
             /* Division of data in each process */
             row_div = divide_rows(height, width, num_processes);
             if (row div <= 0 || height % row div || num processes % row div || width
% (col_div = num_processes / row_div)) {
                           fprintf(stderr, "%s: Cannot divide to processes\n", argv[0]);
                           MPI Abort(MPI COMM WORLD, EXIT FAILURE);
                           return EXIT_FAILURE;
      if (process id != 0) {
             image = malloc((strlen(argv[1])+1) * sizeof(char));
             strcpy(image, argv[1]);
      /* Broadcast parameters */
  MPI_Bcast(&width, 1, MPI_INT, 0, MPI_COMM_WORLD);
  MPI Bcast(&height, 1, MPI INT, 0, MPI COMM WORLD);
  MPI_Bcast(&loops, 1, MPI_INT, 0, MPI_COMM_WORLD);
  MPI_Bcast(&imageType, 1, MPI_INT, 0, MPI_COMM_WORLD);
      MPI_Bcast(&row_div, 1, MPI_INT, 0, MPI_COMM_WORLD);
  MPI Bcast(&col div, 1, MPI INT, 0, MPI COMM WORLD);
      /* Compute number of rows per process */
      rows = height / row div;
      cols = width / col_div;
      /* Create column data type for grey & rgb */
      MPI_Type_vector(rows, 1, cols+2, MPI_BYTE, &grey_col_type);
      MPI_Type_commit(&grey_col_type);
      MPI_Type_vector(rows, 3, 3*cols+6, MPI_BYTE, &rgb_col_type);
      MPI Type commit(&rgb col type);
      /* Create row data type */
      MPI_Type_contiguous(cols, MPI_BYTE, &grey_row_type);
      MPI Type commit(&grey row type);
      MPI_Type_contiguous(3*cols, MPI_BYTE, &rgb_row_type);
      MPI Type commit(&rgb row type);
       /* Compute starting row and column */
  int start row = (process id / col div) * rows;
  int start col = (process id % col div) * cols;
      /* Init filters */
      int box_blur[3][3] = \{\{1, 1, 1\}, \{1, 1, 1\}, \{1, 1, 1\}\};
      int gaussian_blur[3][3] = \{\{1, 2, 1\}, \{2, 4, 2\}, \{1, 2, 1\}\};
      int edge_detection[3][3] = \{\{1, 4, 1\}, \{4, 8, 4\}, \{1, 4, 1\}\};
      float **h = malloc(3 * sizeof(float *));
```

```
for (i = 0; i < 3; i++)
              h[i] = malloc(3 * sizeof(float));
       for (i = 0; i < 3; i++)
              for (j = 0; j < 3; j++)
                     // h[i][j] = box_blur[i][j] / 9.0;
                     h[i][j] = gaussian\_blur[i][j] / 16.0;
                     // h[i][j] = edge\_detection[i][j] / 28.0;
              }
       /* Init arrays */
       uint8_t *src = NULL, *dst = NULL, *tmpbuf = NULL, *tmp = NULL;
       MPI File fh:
       int filesize, bufsize, nbytes;
       if (imageType == GREY) {
              filesize = width * height;
              bufsize = filesize / num processes;
              nbytes = bufsize / sizeof(uint8_t);
              src = calloc((rows+2) * (cols+2), sizeof(uint8_t));
              dst = calloc((rows+2) * (cols+2), sizeof(uint8_t));
       } else if (imageType == RGB) {
              filesize = width*3 * height;
              bufsize = filesize / num_processes;
              nbytes = bufsize / sizeof(uint8 t);
              src = calloc((rows+2) * (cols*3+6), sizeof(uint8_t));
              dst = calloc((rows+2) * (cols*3+6), sizeof(uint8_t));
       if (src == NULL \parallel dst == NULL) {
    fprintf(stderr, "%s: Not enough memory\n", argv[0]);
    MPI_Abort(MPI_COMM_WORLD, EXIT_FAILURE);
    return EXIT FAILURE;
       }
       /* Parallel read */
       MPI_File_open(MPI_COMM_WORLD, image, MPI_MODE_RDONLY,
MPI INFO NULL, &fh);
       if (imageType == GREY) {
              for (i = 1; i \le rows; i++)
                     MPI_File_seek(fh, (start_row + i-1) * width + start_col,
MPI_SEEK_SET);
                     tmpbuf = offset(src, i, 1, cols+2);
                     MPI File read(fh, tmpbuf, cols, MPI BYTE, &status);
       } else if (imageType == RGB) {
              for (i = 1; i \le rows; i++)
```

```
MPI_File_seek(fh, 3*(start_row + i-1)*width + 3*start_col,
MPI_SEEK_SET);
                     tmpbuf = offset(src, i, 3, cols*3+6);
                     MPI_File_read(fh, tmpbuf, cols*3, MPI_BYTE, &status);
       MPI File close(&fh);
       /* Compute neighbours */
  if (start_row != 0)
     north = process id - col div;
  if (start_row + rows != height)
     south = process_id + col_div;
  if (start col != 0)
     west = process_id - 1;
  if (start_col + cols != width)
    east = process_id + 1;
       MPI_Barrier(MPI_COMM_WORLD);
       /* Get time before */
  timer = MPI Wtime();
       /* Convolute "loops" times */
       for (t = 0; t < loops; t++) {
    /* Send and request borders */
              if (imageType == GREY) {
                     if (north != -1) {
                            MPI_Isend(offset(src, 1, 1, cols+2), 1, grey_row_type,
north, 0, MPI_COMM_WORLD, &send_north_req);
                            MPI Irecv(offset(src, 0, 1, cols+2), 1, grey_row_type,
north, 0, MPI_COMM_WORLD, &recv_north_req);
                     if (west != -1) {
                            MPI Isend(offset(src, 1, 1, cols+2), 1, grey col type,
west, 0, MPI_COMM_WORLD, &send_west_req);
                            MPI_Irecv(offset(src, 1, 0, cols+2), 1, grey_col_type,
west, 0, MPI_COMM_WORLD, &recv_west_req);
                     if (south != -1) {
                            MPI_Isend(offset(src, rows, 1, cols+2), 1, grey_row_type,
south, 0, MPI_COMM_WORLD, &send_south_req);
                            MPI Irecv(offset(src, rows+1, 1, cols+2), 1,
grey_row_type, south, 0, MPI_COMM_WORLD, &recv_south_req);
                     if (east !=-1) {
```

```
MPI_Isend(offset(src, 1, cols, cols+2), 1, grey_col_type,
east, 0, MPI_COMM_WORLD, &send_east_req);
                            MPI_Irecv(offset(src, 1, cols+1, cols+2), 1, grey_col_type,
east, 0, MPI COMM WORLD, &recv east req);
              } else if (imageType == RGB) {
                     if (north != -1) {
                            MPI_Isend(offset(src, 1, 3, 3*cols+6), 1, rgb_row_type,
north, 0, MPI COMM WORLD, &send north reg);
                            MPI_Irecv(offset(src, 0, 3, 3*cols+6), 1, rgb_row_type,
north, 0, MPI COMM WORLD, &recv north req);
                     if (west != -1) {
                            MPI_Isend(offset(src, 1, 3, 3*cols+6), 1, rgb_col_type,
west, 0, MPI_COMM_WORLD, &send_west_req);
                            MPI_Irecv(offset(src, 1, 0, 3*cols+6), 1, rgb_col_type,
west, 0, MPI_COMM_WORLD, &recv_west_req);
                     if (south != -1) {
                            MPI_Isend(offset(src, rows, 3, 3*cols+6), 1, rgb_row_type,
south, 0, MPI COMM WORLD, &send south req);
                            MPI Irecv(offset(src, rows+1, 3, 3*cols+6), 1,
rgb_row_type, south, 0, MPI_COMM_WORLD, &recv_south_req);
                     if (east !=-1) {
                            MPI_Isend(offset(src, 1, 3*cols, 3*cols+6), 1,
rgb_col_type, east, 0, MPI_COMM_WORLD, &send_east_req);
                            MPI Irecv(offset(src, 1, 3*cols+3, 3*cols+6), 1,
rgb_col_type, east, 0, MPI_COMM_WORLD, &recv_east_req);
              /* Inner Data Convolute */
              convolute(src, dst, 1, rows, 1, cols, cols, rows, h, imageType);
    /* Request and compute */
              if (north != -1) {
                     MPI Wait(&recv north req, &status);
                     convolute(src, dst, 1, 1, 2, cols-1, cols, rows, h, imageType);
              if (west != -1) {
                     MPI_Wait(&recv_west_req, &status);
                     convolute(src, dst, 2, rows-1, 1, 1, cols, rows, h, imageType);
              if (south != -1) {
```

```
MPI_Wait(&recv_south_req, &status);
                     convolute(src, dst, rows, rows, 2, cols-1, cols, rows, h,
imageType);
              if (east !=-1) {
                     MPI_Wait(&recv_east_req, &status);
                     convolute(src, dst, 2, rows-1, cols, cols, cols, rows, h, imageType);
               }
              /* Corner data */
              if (north !=-1 \&\& west !=-1)
                      convolute(src, dst, 1, 1, 1, 1, cols, rows, h, imageType);
              if (west != -1 \&\& south != -1)
                      convolute(src, dst, rows, rows, 1, 1, cols, rows, h, imageType);
              if (south != -1 \&\& east != -1)
                     convolute(src, dst, rows, rows, cols, cols, cols, rows, h,
imageType);
              if (east != -1 && north != -1)
                      convolute(src, dst, 1, 1, cols, cols, cols, rows, h, imageType);
              /* Wait to have sent all borders */
              if (north !=-1)
                      MPI_Wait(&send_north_req, &status);
              if (west !=-1)
                      MPI_Wait(&send_west_req, &status);
              if (south !=-1)
                      MPI_Wait(&send_south_req, &status);
              if (east !=-1)
                     MPI_Wait(&send_east_req, &status);
              /* swap arrays */
              tmp = src;
     src = dst;
     dst = tmp;
       /* Get time elapsed */
  timer = MPI_Wtime() - timer;
       /* Parallel write */
       char *outImage = malloc((strlen(image) + 9) * sizeof(char));
       strcpy(outImage, "blur_");
       strcat(outImage, image);
       MPI File outFile;
       MPI File open(MPI COMM WORLD, outImage, MPI MODE CREATE |
MPI_MODE_WRONLY, MPI_INFO_NULL, &outFile);
       if (imageType == GREY) {
```

```
for (i = 1; i \le rows; i++)
                    MPI_File_seek(outFile, (start_row + i-1) * width + start_col,
MPI_SEEK_SET);
                    tmpbuf = offset(src, i, 1, cols+2);
                    MPI_File_write(outFile, tmpbuf, cols, MPI_BYTE,
MPI_STATUS_IGNORE);
       } else if (imageType == RGB) {
             for (i = 1; i \le rows; i++)
                    MPI_File_seek(outFile, 3*(start_row + i-1) * width + 3*start_col,
MPI SEEK SET);
                    tmpbuf = offset(src, i, 3, cols*3+6);
                    MPI_File_write(outFile, tmpbuf, cols*3, MPI_BYTE,
MPI_STATUS_IGNORE);
      MPI_File_close(&outFile);
      /* Get times from other processes and print maximum */
  if (process_id != 0)
    MPI Send(&timer, 1, MPI DOUBLE, 0, 0, MPI COMM WORLD);
  else {
    for (i = 1; i != num\_processes; ++i)
       MPI Recv(&remote time, 1, MPI DOUBLE, i, 0, MPI COMM WORLD,
&status);
      if (remote_time > timer)
         timer = remote_time;
    }
    printf("%f\n", timer);
  /* De-allocate space */
  free(src);
  free(dst);
  MPI_Type_free(&rgb_col_type);
  MPI Type free(&rgb row type);
  MPI_Type_free(&grey_col_type);
  MPI_Type_free(&grey_row_type);
      /* Finalize and exit */
  MPI Finalize();
      return EXIT SUCCESS;
```

```
void convolute(uint8_t *src, uint8_t *dst, int row_from, int row_to, int col_from, int
col_to, int width, int height, float** h, color_t imageType) {
       int i, j;
       if (imageType == GREY) {
               for (i = row\_from; i \le row\_to; i++)
                       for (j = col\_from; j \le col\_to; j++)
                               convolute_grey(src, dst, i, j, width+2, height, h);
        } else if (imageType == RGB) {
               for (i = row from ; i \le row to ; i++)
                       for (j = col\_from; j \le col\_to; j++)
                               convolute_rgb(src, dst, i, j*3, width*3+6, height, h);
        }
}
void convolute_grey(uint8_t *src, uint8_t *dst, int x, int y, int width, int height, float** h)
       int i, j, k, l;
       float val = 0;
       for (i = x-1, k = 0; i \le x+1; i++, k++)
               for (j = y-1, l = 0; j \le y+1; j++, l++)
                       val += src[width * i + i] * h[k][l];
       dst[width * x + y] = val;
}
void convolute_rgb(uint8_t *src, uint8_t *dst, int x, int y, int width, int height, float** h)
       int i, j, k, l;
       float redval = 0, greenval = 0, blueval = 0;
       for (i = x-1, k = 0; i \le x+1; i++, k++)
               for (i = v-3, 1 = 0; i \le v+3; i+3, 1++)
                       redval += src[width * i + j]* h[k][1];
                       greenval += src[width * i + j+1] * h[k][l];
                       blueval += src[width * i + j+2] * h[k][1];
       dst[width * x + y] = redval;
       dst[width * x + y+1] = greenval;
       dst[width * x + y+2] = blueval;
}
/* Get pointer to internal array position */
uint8_t *offset(uint8_t *array, int i, int j, int width) {
  return & array[width *i + j];
}
void Usage(int argc, char **argv, char **image, int *width, int *height, int *loops,
color t *imageType) {
```

```
if (argc == 6 \&\& !strcmp(argv[5], "grey")) {
               *image = malloc((strlen(argv[1])+1) * sizeof(char));
              strcpy(*image, argv[1]);
               *width = atoi(argv[2]);
              *height = atoi(argv[3]);
               *loops = atoi(argv[4]);
              *imageType = GREY;
       } else if (argc == 6 && !strcmp(argv[5], "rgb")) {
               *image = malloc((strlen(argv[1])+1) * sizeof(char));
              strcpy(*image, argv[1]);
              *width = atoi(argv[2]);
              *height = atoi(argv[3]);
              *loops = atoi(argv[4]);
              *imageType = RGB;
       } else {
              fprintf(stderr, "\nError Input!\n%s image_name width height loops
[rgb/grey].\n', argv[0]);
              MPI_Abort(MPI_COMM_WORLD, EXIT_FAILURE);
              exit(EXIT_FAILURE);
}
/* Divide rows and columns in a way to minimize perimeter of blocks */
int divide rows(int rows, int cols, int workers) {
  int per, rows_to, cols_to, best = 0;
  int per_min = rows + cols + 1;
  for (rows_to = 1; rows_to <= workers; ++rows_to) {
     if (workers % rows_to || rows % rows_to) continue;
     cols to = workers / rows to;
     if (cols % cols_to) continue;
     per = rows / rows_to + cols / cols_to;
     if (per < per_min) {
       per_min = per;
       best = rows to;
  return best;
Image Convolution using OMP
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <fcntl.h>
#include <stdint.h>
```

```
#include "mpi.h"
#include "omp.h"
typedef enum {RGB, GREY} color_t;
void convolute(uint8_t *, uint8_t *, int, int, int, int, int, int, float**, color_t);
void convolute grey(uint8 t*, uint8 t*, int, int, int, int, float **);
void convolute_rgb(uint8_t *, uint8_t *, int, int, int, int, float **);
void Usage(int, char **, char **, int *, int *, int *, color_t *);
uint8_t *offset(uint8_t *, int, int, int);
/* Divide rows and columns in a way to minimize perimeter of blocks */
int divide_rows(int rows, int cols, int workers) {
  int per, rows_to, cols_to, best = 0;
  int per min = rows + cols + 1;
  for (rows_to = 1; rows_to <= workers; ++rows_to) {
     if (workers % rows_to || rows % rows_to) continue;
     cols_to = workers / rows_to;
     if (cols % cols to) continue;
     per = rows / rows to + cols / cols to;
    if (per < per_min) {
       per min = per;
       best = rows_to;
  return best;
int main(int argc, char** argv) {
       int thread_count = 4;
       int fd, i, j, k, width, height, loops, t, row div, col div, rows, cols;
       double timer, remote_time;
       char *image:
       color_t imageType;
       /* MPI world topology */
  int process id, num processes;
       /* Find current task id */
  MPI Init(&argc, &argv);
  MPI Comm size(MPI COMM WORLD, &num processes);
  MPI Comm rank(MPI COMM WORLD, &process id);
       /* MPI status */
  MPI_Status status;
       /* MPI data types */
```

```
MPI_Datatype grey_col_type;
  MPI_Datatype rgb_col_type;
  MPI_Datatype grey_row_type;
  MPI_Datatype rgb_row_type;
      /* MPI requests */
  MPI_Request send_north_req;
  MPI Request send south reg;
  MPI_Request send_west_req;
  MPI Request send east reg;
  MPI_Request recv_north_req;
  MPI Request recv south reg;
  MPI_Request recv_west_req;
  MPI_Request recv_east_req;
      /* Neighbours */
      int north = -1;
      int south = -1;
  int west = -1;
  int east = -1;
  /* Check arguments */
 if (process id == 0) {
             Usage(argc, argv, &image, &width, &height, &loops, &imageType);
             /* Division of data in each process */
             row_div = divide_rows(height, width, num_processes);
             if (row_div <= 0 || height % row_div || num_processes % row_div || width
% (col_div = num_processes / row_div)) {
                          fprintf(stderr, "%s: Cannot divide to processes\n", argv[0]);
                          MPI Abort(MPI COMM WORLD, EXIT FAILURE);
                          return EXIT FAILURE;
      if (process_id!=0) {
             image = malloc((strlen(argv[1])+1) * sizeof(char));
             strcpy(image, argv[1]);
      /* Broadcast parameters */
  MPI_Bcast(&width, 1, MPI_INT, 0, MPI_COMM_WORLD);
  MPI Bcast(&height, 1, MPI INT, 0, MPI COMM WORLD);
  MPI Bcast(&loops, 1, MPI INT, 0, MPI COMM WORLD);
  MPI Bcast(&imageType, 1, MPI INT, 0, MPI COMM WORLD);
      MPI Bcast(&row div, 1, MPI INT, 0, MPI COMM WORLD);
  MPI Bcast(&col div, 1, MPI INT, 0, MPI COMM WORLD);
      /* Compute number of rows per process */
      rows = height / row div;
```

```
cols = width / col_div;
    /* Create column data type for grey & rgb */
    MPI Type vector(rows, 1, cols+2, MPI BYTE, &grey col type);
    MPI Type_commit(&grey_col_type);
    MPI_Type_vector(rows, 3, 3*cols+6, MPI_BYTE, &rgb_col_type);
    MPI Type commit(&rgb col type);
    /* Create row data type */
    MPI Type contiguous(cols, MPI BYTE, &grey row type);
    MPI_Type_commit(&grey_row_type);
    MPI Type contiguous(3*cols, MPI BYTE, &rgb row type);
    MPI_Type_commit(&rgb_row_type);
     /* Compute starting row and column */
int start row = (process id / col div) * rows;
int start_col = (process_id % col_div) * cols;
    /* Init filters */
    int box_blur[3][3] = \{\{1, 1, 1\}, \{1, 1, 1\}, \{1, 1, 1\}\};
    int gaussian_blur[3][3] = \{\{1, 2, 1\}, \{2, 4, 2\}, \{1, 2, 1\}\};
    int edge_detection[3][3] = \{\{1, 4, 1\}, \{4, 8, 4\}, \{1, 4, 1\}\};
    float **h = malloc(3 * sizeof(float *));
    for (i = 0; i < 3; i++)
            h[i] = malloc(3 * sizeof(float));
    for (i = 0; i < 3; i++)
            for (j = 0; j < 3; j++)
                   // h[i][j] = box_blur[i][j] / 9.0;
                   h[i][j] = gaussian_blur[i][j] / 16.0;
                   // h[i][j] = edge\_detection[i][j] / 28.0;
    }
    /* Init arrays */
    uint8 t *src = NULL, *dst = NULL, *tmpbuf = NULL, *tmp = NULL;
    MPI File fh:
    int filesize, bufsize, nbytes;
    if (imageType == GREY) {
            filesize = width * height;
            bufsize = filesize / num processes;
            nbytes = bufsize / sizeof(uint8 t);
            src = calloc((rows+2) * (cols+2), sizeof(uint8_t));
            dst = calloc((rows+2) * (cols+2), sizeof(uint8 t));
     } else if (imageType == RGB) {
            filesize = width*3 * height;
            bufsize = filesize / num_processes;
            nbytes = bufsize / sizeof(uint8 t);
```

```
src = calloc((rows+2) * (cols*3+6), sizeof(uint8_t));
              dst = calloc((rows+2) * (cols*3+6), sizeof(uint8_t));
       if (src == NULL \parallel dst == NULL) {
    fprintf(stderr, "%s: Not enough memory\n", argv[0]);
    MPI_Abort(MPI_COMM_WORLD, EXIT_FAILURE);
    return EXIT FAILURE;
       /* Parallel read */
       MPI File open(MPI COMM WORLD, image, MPI MODE RDONLY,
MPI_INFO_NULL, &fh);
       if (imageType == GREY) {
              for (i = 1; i \le rows; i++)
                     MPI_File_seek(fh, (start_row + i-1) * width + start_col,
MPI_SEEK_SET);
                     tmpbuf = offset(src, i, 1, cols+2);
                     MPI_File_read(fh, tmpbuf, cols, MPI_BYTE, &status);
       } else if (imageType == RGB) {
              for (i = 1; i \le rows; i++)
                     MPI File seek(fh, 3*(\text{start row} + i-1)* \text{width} + 3* \text{start col},
MPI_SEEK_SET);
                     tmpbuf = offset(src, i, 3, cols*3+6);
                     MPI_File_read(fh, tmpbuf, cols*3, MPI_BYTE, &status);
       MPI_File_close(&fh);
       /* Compute neighbours */
  if (start row != 0)
    north = process id - col div;
  if (start_row + rows != height)
     south = process id + col div;
  if (start\_col != 0)
     west = process id - 1;
  if (start_col + cols != width)
    east = process_id + 1;
       /* Get time before */
  timer = MPI_Wtime();
       /* Convolute "loops" times */
       for (t = 0; t < loops; t++)
    /* Send and request borders */
              if (imageType == GREY) {
                     if (north != -1) {
```

```
MPI_Isend(offset(src, 1, 1, cols+2), 1, grey_row_type,
north, 0, MPI COMM WORLD, &send north req);
                           MPI_Irecv(offset(src, 0, 1, cols+2), 1, grey_row_type,
north, 0, MPI COMM WORLD, &recv north reg);
                    if (west != -1) {
                           MPI Isend(offset(src, 1, 1, cols+2), 1, grey col type,
west, 0, MPI_COMM_WORLD, &send_west_req);
                           MPI Irecv(offset(src, 1, 0, cols+2), 1, grey col type,
west, 0, MPI_COMM_WORLD, &recv_west_req);
                    if (south != -1) {
                           MPI_Isend(offset(src, rows, 1, cols+2), 1, grey_row_type,
south, 0, MPI_COMM_WORLD, &send_south_req);
                           MPI_Irecv(offset(src, rows+1, 1, cols+2), 1,
grey_row_type, south, 0, MPI_COMM_WORLD, &recv_south_req);
                    if (east !=-1) {
                           MPI Isend(offset(src, 1, cols, cols+2), 1, grey col type,
east, 0, MPI_COMM_WORLD, &send_east_req);
                           MPI Irecv(offset(src, 1, cols+1, cols+2), 1, grey col type,
east, 0, MPI COMM WORLD, &recv east req);
             } else if (imageType == RGB) {
                    if (north != -1) {
                           MPI_Isend(offset(src, 1, 3, 3*cols+6), 1, rgb_row_type,
north, 0, MPI_COMM_WORLD, &send_north_req);
                           MPI_Irecv(offset(src, 0, 3, 3*cols+6), 1, rgb_row_type,
north, 0, MPI_COMM_WORLD, &recv_north_req);
                    if (west != -1) {
                           MPI Isend(offset(src, 1, 3, 3*cols+6), 1, rgb col type,
west, 0, MPI_COMM_WORLD, &send_west_req);
                           MPI Irecv(offset(src, 1, 0, 3*cols+6), 1, rgb col type,
west, 0, MPI_COMM_WORLD, &recv_west_req);
                    if (south != -1) {
                           MPI Isend(offset(src, rows, 3, 3*cols+6), 1, rgb_row_type,
south, 0, MPI COMM WORLD, &send south req);
                           MPI Irecv(offset(src, rows+1, 3, 3*cols+6), 1,
rgb_row_type, south, 0, MPI_COMM_WORLD, &recv_south_req);
                    if (east !=-1) {
                           MPI Isend(offset(src, 1, 3*cols, 3*cols+6), 1,
rgb_col_type, east, 0, MPI_COMM_WORLD, &send_east_req);
```

```
MPI_Irecv(offset(src, 1, 3*cols+3, 3*cols+6), 1,
rgb_col_type, east, 0, MPI_COMM_WORLD, &recv_east_req);
               /* Inner Data Convolute */
               convolute(src, dst, 1, rows, 1, cols, cols, rows, h, imageType);
          /* Request and compute */
               if (north != -1) {
                      MPI_Wait(&recv_north_req, &status);
                      convolute(src, dst, 1, 1, 2, cols-1, cols, rows, h, imageType);
               if (west != -1) {
                      MPI_Wait(&recv_west_req, &status);
                      convolute(src, dst, 2, rows-1, 1, 1, cols, rows, h, imageType);
               if (south !=-1) {
                      MPI_Wait(&recv_south_req, &status);
                      convolute(src, dst, rows, rows, 2, cols-1, cols, rows, h,
imageType);
               if (east !=-1) {
                      MPI_Wait(&recv_east_req, &status);
                      convolute(src, dst, 2, rows-1, cols, cols, cols, rows, h, imageType);
               }
               /* Corner data */
               if (north != -1 \&\& west != -1)
                      convolute(src, dst, 1, 1, 1, 1, cols, rows, h, imageType);
               if (west != -1 \&\& south != -1)
                      convolute(src, dst, rows, rows, 1, 1, cols, rows, h, imageType);
               if (south != -1 \&\& east != -1)
                      convolute(src, dst, rows, rows, cols, cols, cols, rows, h,
imageType);
               if (east != -1 && north != -1)
                      convolute(src, dst, 1, 1, cols, cols, cols, rows, h, imageType);
               /* Wait to have sent all borders */
               if (north !=-1)
                      MPI Wait(&send north req, &status);
               if (west !=-1)
                      MPI Wait(&send west req, &status);
               if (south !=-1)
                      MPI Wait(&send south req, &status);
```

```
if (east !=-1)
                    MPI_Wait(&send_east_req, &status);
             /* swap arrays */
             tmp = src;
         src = dst;
         dst = tmp;
      /* Get time elapsed */
  timer = MPI_Wtime() - timer;
      /* Parallel write */
      char *outImage = malloc((strlen(image) + 9) * sizeof(char));
      strcpy(outImage, "blur_");
      strcat(outImage, image);
      MPI_File outFile;
      MPI_File_open(MPI_COMM_WORLD, outImage, MPI_MODE_CREATE |
MPI_MODE_WRONLY, MPI_INFO_NULL, &outFile);
      if (imageType == GREY) {
             for (i = 1; i \le rows; i++)
                    MPI File seek(outFile, (start row + i-1) * width + start col,
MPI SEEK SET);
                    tmpbuf = offset(src, i, 1, cols+2);
                    MPI File write(outFile, tmpbuf, cols, MPI BYTE,
MPI_STATUS_IGNORE);
       } else if (imageType == RGB) {
             for (i = 1; i \le rows; i++)
                    MPI_File_seek(outFile, 3*(start_row + i-1) * width + 3*start_col,
MPI SEEK SET);
                    tmpbuf = offset(src, i, 3, cols*3+6);
                    MPI File write(outFile, tmpbuf, cols*3, MPI BYTE,
MPI_STATUS_IGNORE);
      MPI File close(&outFile);
      /* Get times from other processes and print maximum */
  if (process id != 0)
    MPI Send(&timer, 1, MPI DOUBLE, 0, 0, MPI COMM WORLD);
  else {
    for (i = 1; i! = num processes; ++i)
      MPI_Recv(&remote_time, 1, MPI_DOUBLE, i, 0, MPI_COMM_WORLD,
&status):
      if (remote_time > timer)
         timer = remote time;
```

```
printf("%f\n", timer);
  /* De-allocate space */
  free(src);
  free(dst);
  MPI_Type_free(&rgb_col_type);
  MPI_Type_free(&rgb_row_type);
  MPI_Type_free(&grey_col_type);
  MPI_Type_free(&grey_row_type);
       /* Finalize and exit */
  MPI_Finalize();
       return EXIT_SUCCESS;
}
void convolute(uint8_t *src, uint8_t *dst, int row_from, int row_to, int col_from, int
col_to, int width, int height, float** h, color_t imageType) {
       int i, j;
       if (imageType == GREY) {
#pragma omp parallel for shared(src, dst) schedule(static) collapse(3)
               for (i = row\_from; i \le row\_to; i++)
                       for (j = col\_from; j \le col\_to; j++)
                              convolute_grey(src, dst, i, j, width+2, height, h);
       } else if (imageType == RGB) {
#pragma omp parallel for shared(src, dst) schedule(static) collapse(3)
               for (i = row\_from ; i \le row\_to ; i++)
                       for (j = col\_from; j \le col\_to; j++)
                              convolute_rgb(src, dst, i, j*3, width*3+6, height, h);
       }
}
void convolute grey(uint8 t *src, uint8 t *dst, int x, int y, int width, int height, float** h)
       int i, j, k, l;
       float val = 0;
       for (i = x-1, k = 0; i \le x+1; i++, k++)
               for (i = y-1, l = 0; j \le y+1; j++, l++)
                       val += src[width * i + j] * h[k][l];
       dst[width * x + y] = val;
void convolute rgb(uint8 t *src, uint8 t *dst, int x, int y, int width, int height, float** h)
       int i, j, k, l;
```

```
float redval = 0, greenval = 0, blueval = 0;
       for (i = x-1, k = 0; i \le x+1; i++, k++)
               for (j = y-3, l = 0; j \le y+3; j+3, l++)
                      redval += src[width * i + j]* h[k][l];
                      greenval += src[width * i + j+1] * h[k][l];
                      blueval += src[width * i + j+2] * h[k][l];
       dst[width * x + y] = redval;
       dst[width * x + y+1] = greenval;
       dst[width * x + y+2] = blueval;
}
/* Get pointer to internal array position */
uint8_t *offset(uint8_t *array, int i, int j, int width) {
  return & array[width *i + j];
void Usage(int argc, char **argv, char **image, int *width, int *height, int *loops,
color_t *imageType) {
       if (argc == 6 \&\& !strcmp(argv[5], "grey")) {
               *image = malloc((strlen(argv[1])+1) * sizeof(char));
               strcpy(*image, argv[1]);
               *width = atoi(argv[2]);
               *height = atoi(argv[3]);
               *loops = atoi(argv[4]);
               *imageType = GREY;
       } else if (argc == 6 && !strcmp(argv[5], "rgb")) {
               *image = malloc((strlen(argv[1])+1) * sizeof(char));
               strcpy(*image, argv[1]);
               *width = atoi(argv[2]);
               *height = atoi(argv[3]);
               *loops = atoi(argv[4]);
               *imageType = RGB;
       } else {
               MPI_Abort(MPI_COMM_WORLD, EXIT_FAILURE);
               fprintf(stderr, "Error Input!\n%s image name width height loops
[rgb/grey].\n", argv[0]);
               exit(EXIT_FAILURE);
Image Convolution done serially
#include<iostream>
#include<opencv2/imgproc/imgproc.hpp>
#include<opency2/highgui/highgui.hpp>
```

```
using namespace std;
using namespace cv;
int reflect(int M, int x)
  if(x < 0)
     return -x - 1;
  if(x >= M)
     return 2*M - x - 1;
 return x;
int circular(int M, int x)
  if (x<0)
     return x+M;
  if(x >= M)
     return x-M;
 return x;
void noBorderProcessing(Mat src, Mat dst, float Kernel[][3])
  float sum;
  for(int y = 1; y < src.rows - 1; y++){
     for(int x = 1; x < src.cols - 1; x++){
       sum = 0.0;
       for(int k = -1; k \le 1; k++){
          for(int j = -1; j <=1; j++){
             sum = sum + Kernel[j+1][k+1]*src.at < uchar > (y - j, x - k);
          }
       dst.at < uchar > (y,x) = sum;
void refletedIndexing(Mat src, Mat dst, float Kernel[][3])
```

```
float sum, x1, y1;
  for(int y = 0; y < src.rows; y++){
     for(int x = 0; x < src.cols; x++){
       sum = 0.0;
       for(int k = -1; k \le 1; k++)
          for(int j = -1; j \le 1; j++ ){
             x1 = reflect(src.cols, x - j);
             y1 = reflect(src.rows, y - k);
             sum = sum + Kernel[j+1][k+1]*src.at < uchar > (y1,x1);
       dst.at < uchar > (y,x) = sum;
}
void circularIndexing(Mat src, Mat dst, float Kernel[][3])
  float sum, x1, y1;
  for(int y = 0; y < src.rows; y++){
     for(int x = 0; x < src.cols; x++){
       sum = 0.0;
       for(int k = -1; k \le 1; k++){
          for(int j = -1; j \le 1; j++ ){
             x1 = circular(src.cols, x - j);
             y1 = circular(src.rows, y - k);
             sum = sum + Kernel[j+1][k+1]*src.at < uchar > (y1,x1);
          }
       dst.at < uchar > (y,x) = sum;
}
int main()
   Mat src, dst;
   /// Load an image
   src = imread("salt.jpg", CV_LOAD_IMAGE_GRAYSCALE);
   if(!src.data)
    { return -1; }
```

```
float Kernel[3][3] = \{
               {1/9.0, 1/9.0, 1/9.0},
               {1/9.0, 1/9.0, 1/9.0},
               {1/9.0, 1/9.0, 1/9.0}
               };
  dst = src.clone();
  for(int y = 0; y < src.rows; y++)
     for(int x = 0; x < src.cols; x++)
       dst.at < uchar > (y,x) = 0.0;
  circularIndexing(src, dst, Kernel);
  namedWindow("final");
  imshow("final", dst);
  namedWindow("initial");
  imshow("initial", src);
 waitKey();
return 0;
```

# 4. RESULTS & DISCUSSION

<u>MPI</u>

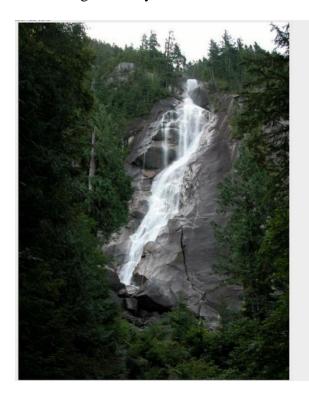
On running the MPI

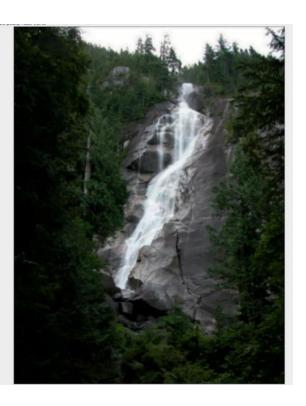


On running OMP

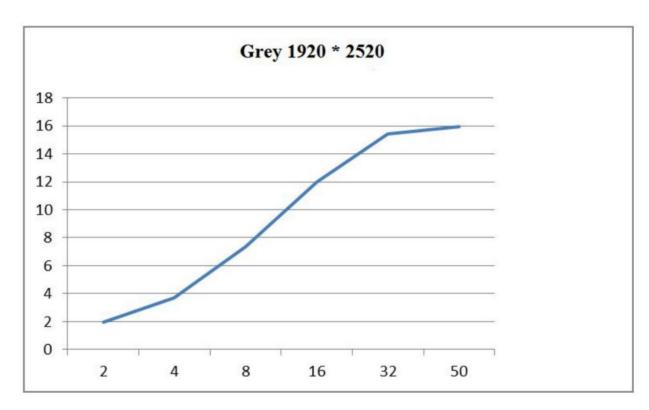


# On running it serially

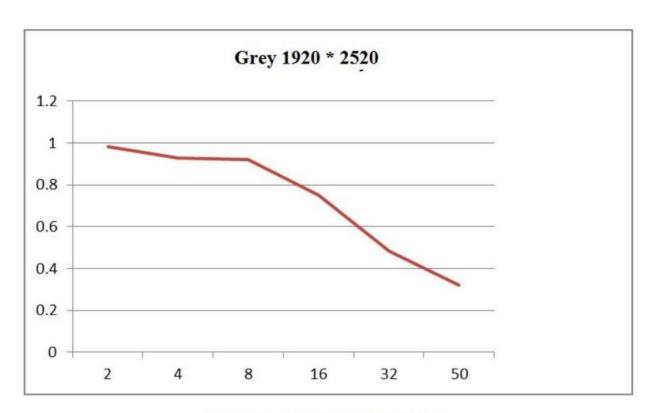




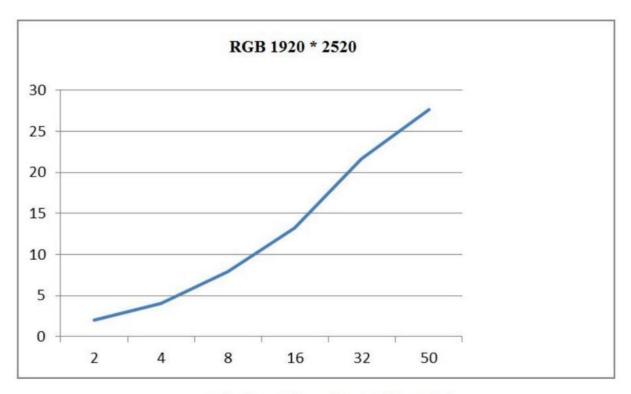
Some comparative charts between MPI and OMP were created to evaluate. MPI



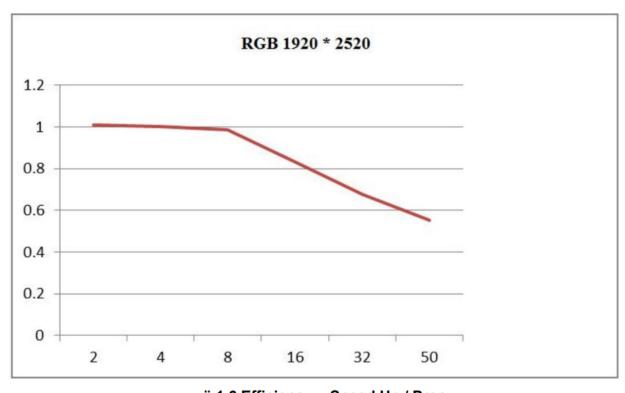
ÿ.1.3 Speed Up = Tserial / Tparallel



ÿ.1.4 Efficiency = Speed Up / Proc

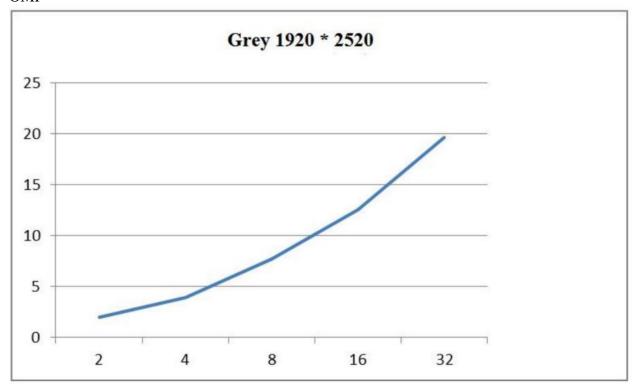


ÿ.1.5 Speed Up = Tserial / Tparallel

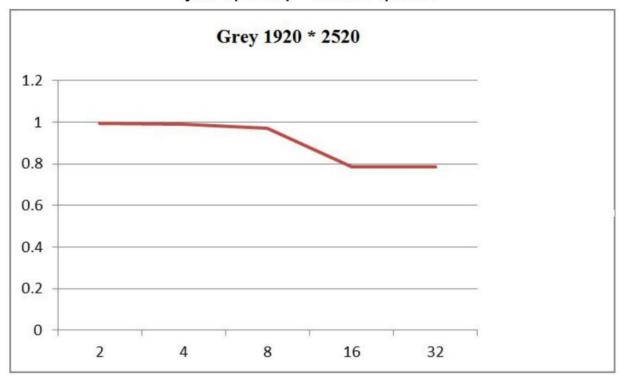


ÿ.1.6 Efficiency = Speed Up / Proc

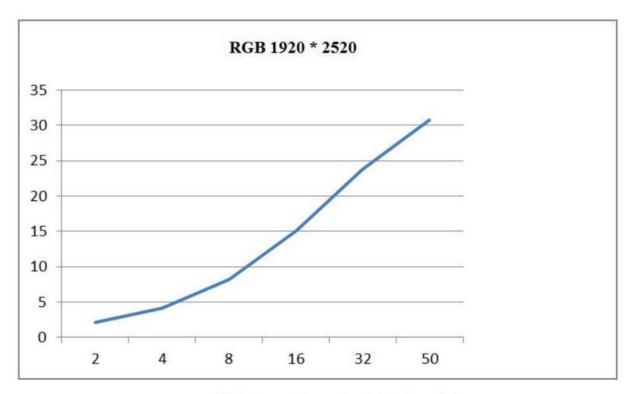
OMP



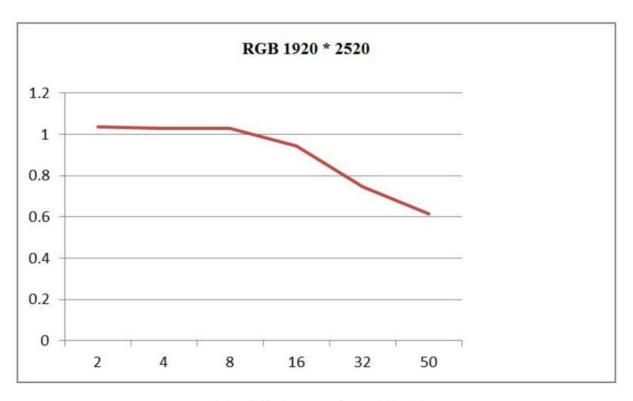
ÿ.2.3 Speed Up = Tserial / Tparallel



ÿ.2.3 Efficiency = Speed Up / Proc



ÿ.2.4 Speed Up = Tserial / Tparallel



ÿ.2.5 Efficiency = Speed Up / Proc

# 5. CONCLUSION

The image convolution works faster using parallel programming because the work is done to each section of the picture separately.

The efficiency and speed up for MPI and OMP is calculated to compare the overall performance of the algorithm.

### 6. FUTURE WORK

The efficiency of the code could be improved by refactoring the code more.