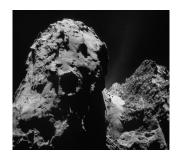
SAT: Modelling and Implementations

Mohamed Siala https://siala.github.io

INSA-Toulouse & LAAS-CNRS

January 18, 2022





https://homepages.laas.fr/ehebrard/rosetta.html







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- Resources: many.. a good start would be the online course on discrete optimisation
 - https://www.coursera.org/learn/discrete-optimization

Introduction & Context



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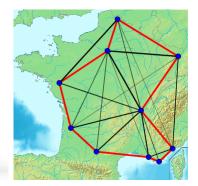
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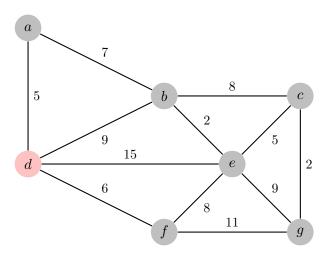
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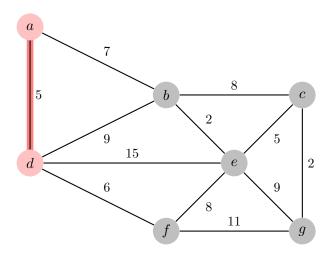
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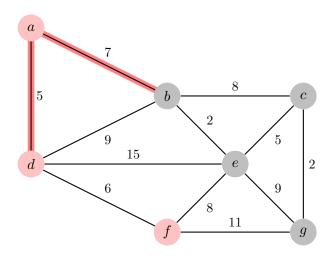
Travelling Salesman Problem

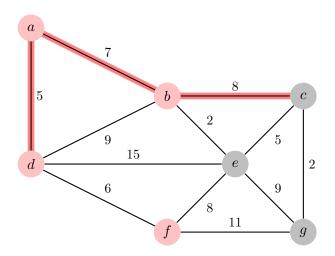


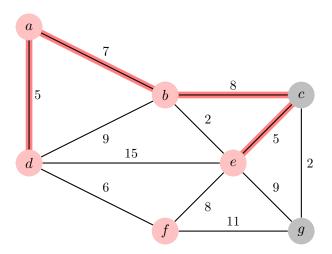


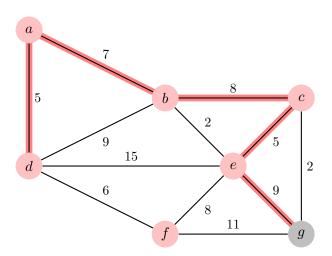


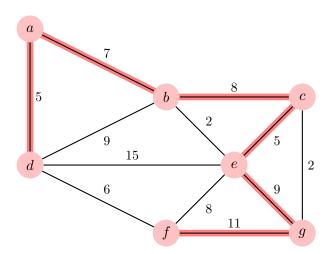


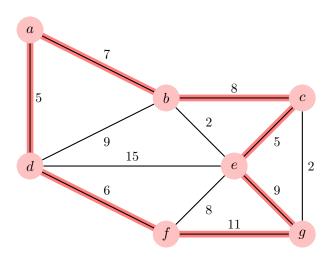


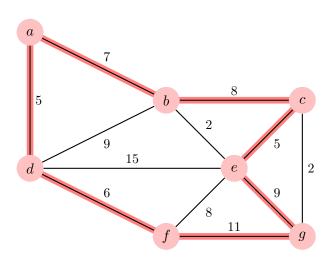






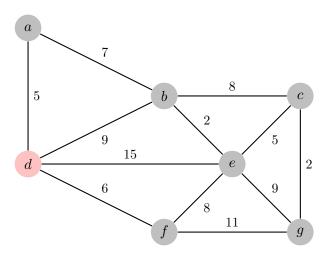




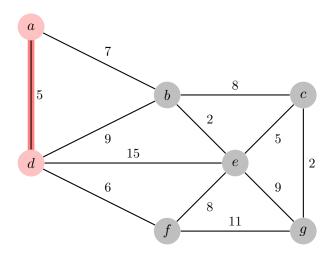


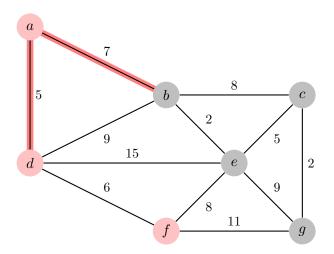
$$--> Cost: 5+7+8+5+9+11+6=53Km$$

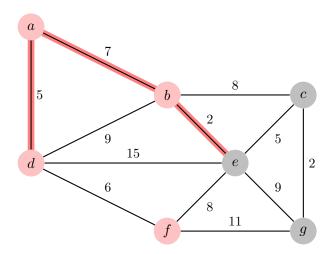
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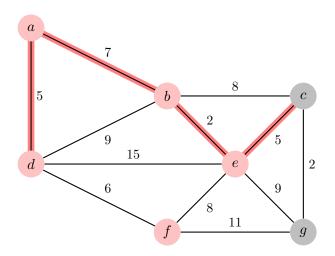


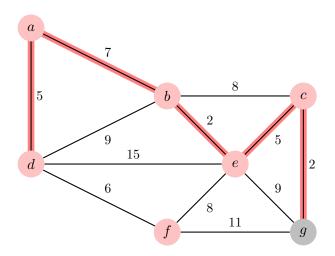
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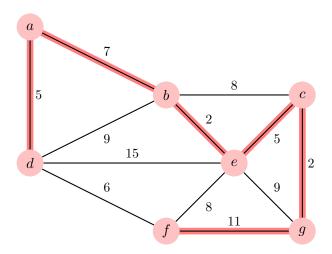


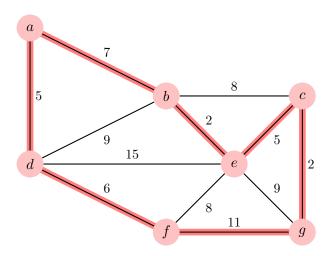


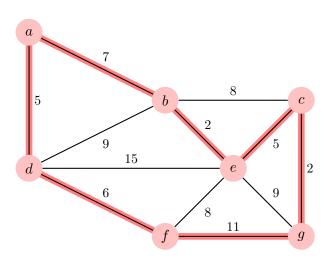












$$--> Cost: 5+7+2+5+2+11+6=38Km$$

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The problem is inherently hard. However, the Concorde algorithm can solve instances up to 86 000 cities!

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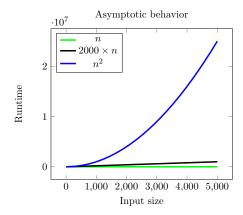
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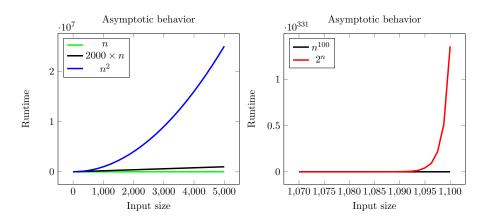
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- Example: Th sorting problem is easy because we have an algorithm that runs in the worst case in $O(n^2)$ (and actually the same for memory consumption)
- What if we don't know if a problem has a polynomial time algorithm?

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- \bullet For many Problems in NP, we don't know if a polynomial time algorithm exists.
- 1 Million \$ question: Is P=NP?

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Given a set of Boolean variables $x_1, \ldots x_n$ and a CNF formulae Φ over $x_1, \ldots x_n$, the Boolean Satisfiability problem (SAT) is to find an assignment of the variables that satisfies all the clauses.

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- How to use it to solve problems (Modelling)
- Discover some efficient implementations

Example

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$$x \lor \neg y \lor z$$
$$\neg x \lor \neg z$$
$$y \lor w$$
$$\neg w \lor \neg x$$

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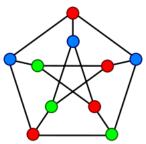
$$x \lor \neg y \lor z$$
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A possible solution:

$$x \leftarrow 1; y \leftarrow 1; z \leftarrow 0; w \leftarrow 0$$

The example of Graph Colouring

- Graph Coloring is a well know combinatorial problem that has many applications (in particular in scheduling problems)
- Let G = (V, E) be an undirected graph where V is a set of n vertices and E is a set of m edges. Is it possible to colour the graph with k colours such that no two adjacent nodes share the same colour?



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• Forbid two nodes that share an edge to be coloured with the same colour

$$\forall \{i, j\} \in E, \forall a \in [1, k] : \neg x_i^a \to \neg x_j^a$$

(This is a translation of $x_i^a \to \neg x_i^a$)

The Example of Graph Coloring: The Model Size

What is the (space) size of the model?

- $n \times k$ Boolean variables
- \bullet Constraints form 1: n clauses with k literals each
- Constraints form 2: $n \times k^2$ binary clauses
- Constraints form 3: $m \times k$ binary clauses

The Example of Graph Coloring: The Minimization Version

• Propose a method that uses SAT for the minimisation version of the problem. That is, given G = (V, E), we seek to find the minimum value of k to satisfy the colouring requirements.



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 - Decreasing linear Search: Run iteratively $SAT(V, E, UB-1), SAT(V, E, UB-2), \ldots$ until the problem is unsatisfiable. The last satisfiable value of k is the optimal value
 - Binary search: Run iteratively SAT(V, E, z) as long as UB > LB where $z = \lceil (UB LB)/2 \rceil$. If the result is satisfiable, then and $UB \leftarrow z$ otherwise $LB \leftarrow z$



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 - The run time complexity is $O(n^2 \times m)$
- Lower bound: Well, we can simply consider 2 as long as there is an edge. A more advanced one is to look for a clique in the graph.

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 - Each vertex v is considered non-coloured and has a portfolio S_v of available colours. The set is initially $\{1, 2, \dots n\}$ for each vertex
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- An alternative approach is to look for valid theoretical bounds in the literature.

Modelling Cardinality Constraints

• The general form of cardinality constraints is the following:

$$a \le \sum_{1}^{n} x_i \le b$$

where a and b are positive integers and $x_1 \dots x_n$ are Boolean variables

- Cardinality constraints are everywhere!
- Many ways to encode such constraints. See for instance https://www.carstensinz.de/papers/CP-2005.pdf

Quadratic encoding for $\sum_{i=1}^{n} x_i = 1$

• At least one constraint:

$$x_1 \vee x_2 \dots x_n$$

• at most one constraints:

$$\forall i, j : \neg x_i \lor \neg x_j$$

This generates one clause of size n and (n^2) binary clauses without introducing additional variables.

Linear encoding for $\sum_{i=1}^{n} x_i = 1$

New variables are added as follows: for $i \in [1, n], y_i$ is a new variable that is true iff $\sum_{l=1}^{l=i} x_l = 1$.

$$x_1 \lor x_2 \dots x_n$$

$$y_n^1$$

$$\forall i \in [1, n-1] : y_i \to y_{i+1}$$

$$\forall i \in [1, n-1] : y_i \to \neg x_{i+1}$$

$$\forall i \in [1, n] : x_i \to y_i$$

Size: n new variables, 1 n-ary clause and $3 \times n$ binary clauses,

Linear encoding for $\sum_{1}^{n} x_i \ge k$

New variables: $\forall z \in [0, k], \forall i \in [1, n], y_i^z \iff \sum_{l=1}^{l=i} x_l \geq z$

Linear encoding for $\sum_{i=1}^{n} x_i \geq k$

New variables:
$$\forall z \in [0, k], \forall i \in [1, n], y_i^z \iff \sum_{l=1}^{l=i} x_l \ge z$$

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$$y_1^1 \leftarrow x_1 \text{ and } \forall z \in [2, k], y_1^z \leftarrow 0$$

 $y_n^k \leftarrow 1$

$$\forall i \in [1, n], \forall z \in [1, k - 1] : y_i^{z+1} \to y_i^z$$

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$$y_{i-1}^z \wedge x_i \rightarrow y_i^{z+1}$$

Linear encoding for $\sum_{i=1}^{n} x_i \ge k$

Size of the encoding:

- $\Theta(n \times k)$ variables
- $\Theta(n+k)$ unary clauses
- $\Theta(n \times k)$ binary clauses
- $\Theta(n \times k)$ ternary clauses

Linear encoding for $\sum_{1}^{n} x_i = k$?

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- Encode $\sum_{1}^{n} x_i \ge k+1$
- Force y_n^{k+1} to be false and y_n^k to be true

Size of the encoding: Same as $\sum_{i=1}^{n} x_i \ge k$ (asymptotically)

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- Force y_n^a to be true

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Modelling

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- Check the MaxSAT competition

Example of applications for MaxSAT

Let G = (V, E) be an undirected graph where V is the set of vertices and E is the set of edges. In the (decision version of the) graph colouring problem, we are given k colours to colour the graph such that no two adjacent nodes share the same colour.

• Propose a MaxSAT model for the minimisation version of the problem. That is, given G = (V, E), we seek to find the minimum value of k to satisfy the colouring requirements.

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The Example of Graph Coloring: A Possible MaxSAT Model

- We shall extend the previous model:
- Consider the previous model SAT(V, E, k) with k an upper bound.
- All the previous clauses are hard.
- Add the following hard clauses:

$$\forall i \in [1, n], \forall a \in [1, k] : \neg u_a \to \neg x_i^a$$

- Eventually we can add symmetry constraints: $u_a \to u_{a-1}$
- Then add the soft clauses:

$$\forall a \in [1, k] : \neg u_a$$

• A MaxSAT Optimal solution satisfies all the hard coloring clauses (valid colouring) and maximizes the number of non used colours.

Extensions: Quantified Boolean Formula (QBF)

- A QBF has the form Q.F , where F is a CNF-SAT formulae, and Q is a sequence of quantified variables $(\forall x \text{ or } \exists x)$.
- Example $\forall x, \exists y, \exists z, (x \lor \neg y) \land (\neg y \lor z)$
- QBF Solver Competition: https://www.qbflib.org/solvers_list.php
- QBF is less used in practice

Other Extensions

- Satisfiability Modulo Theories
- Answer Set Programming
- More generally: Automated reasoning community
- Check the SAT/SMT summer schools http://satassociation.org/sat-smt-school.html

• [?, ?]

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- But also:
 - Activity-based branching
 - Lazy data structures (2-Watched Literals)
 - Clause Database Reduction
 - Simplifications
 - Restarts
 - . . .

Exercise: Propose a filtering algorithm for clauses. The algorithm takes as input a clause and has access (read and write) for the variables domains.

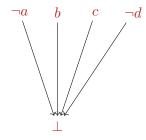
Unit Propagation

Given a clause C of arity n. If n-1 literals are false then set the last one to be true.

Example: $(a \lor \neg b \lor \neg c \lor d)$



$$\neg a \land b \land \neg d \Rightarrow \neg c$$



$$\neg a \land b \land c \land \neg d \Rightarrow \bot$$

- Unit propagation is implemented with an "intelligent" data structure called Two-watched literals
- Observe first that propagation happens only in two cases:
 - The clause becomes unit (i.e., all variables except one is instantiated): Propagate the only uninstantiated literal to satisfy the clause
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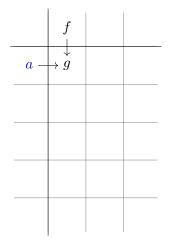
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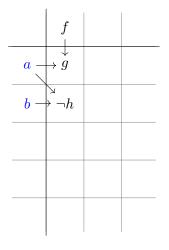
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- The idea of the Two-watched literals is to keep 2 literals for every clause that are not instantiated. Those literals will "watch the clause" and guarantee that no propagation is needed.
- If a literal watching a clause C becomes false, look for replacement. If no replacement found, then perform propagation

f	

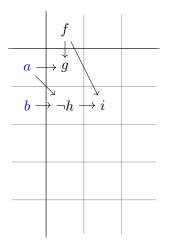
$\neg a \lor \neg f \lor g$	$c \vee h \vee n \vee \neg m$
$\neg a \lor \neg b \lor \neg h$	$c \vee l$
$a \lor c$	$d \vee \neg k \vee l$
$a \vee \neg i \vee \neg l$	$d \vee \neg g \vee l$
$a \vee \neg k \vee \neg j$	$\neg g \vee n \vee o$
$b \lor d$	$h \vee \neg o \vee \neg j \vee n$
$b \vee g \vee \neg n$	$\neg i \lor j$
$b \vee \neg f \vee n \vee k$	$\neg d \vee \neg l \vee \neg m$
$\neg c \lor k$	$\neg e \vee m \vee \neg n$
$\neg c \vee \neg k \vee \neg i \vee l$	$\neg f \lor h \lor i$



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$$\begin{array}{c} c \vee h \vee n \vee \neg m \\ c \vee l \\ d \vee \neg k \vee l \\ d \vee \neg g \vee l \\ \neg g \vee n \vee o \\ h \vee \neg o \vee \neg j \vee n \\ \neg i \vee j \\ \neg d \vee \neg l \vee \neg m \\ \neg e \vee m \vee \neg n \\ \neg f \vee h \vee i \end{array}$$



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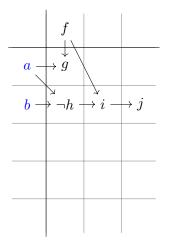
$$h \vee \neg o \vee \neg j \vee n$$

$$\neg i \vee j$$

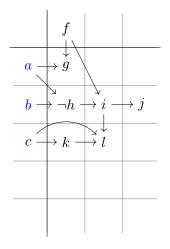
$$\neg d \vee \neg l \vee \neg m$$

$$\neg e \vee m \vee \neg n$$

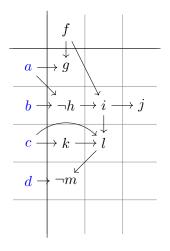
$$\neg f \vee h \vee i$$



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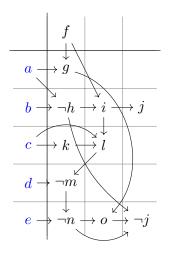


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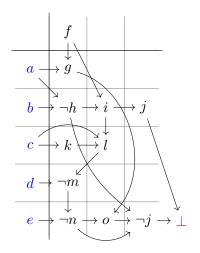
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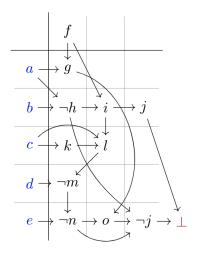
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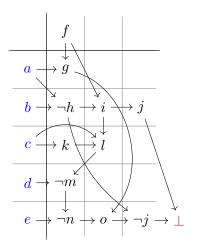
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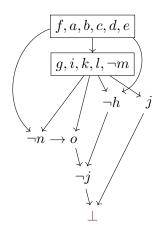
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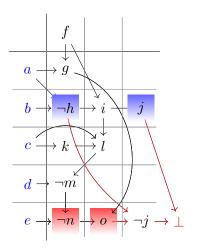


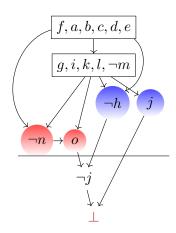
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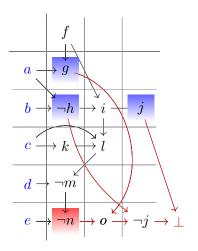
$$\begin{array}{c} c \vee h \vee n \vee \neg m \\ c \vee l \\ d \vee \neg k \vee l \\ d \vee \neg g \vee l \\ \neg g \vee n \vee o \\ \hline h \vee \neg o \vee \neg j \vee n \\ \neg i \vee j \\ \neg d \vee \neg l \vee \neg m \\ \neg e \vee m \vee \neg n \\ \neg f \vee h \vee i \end{array}$$

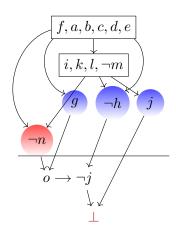


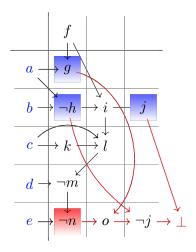


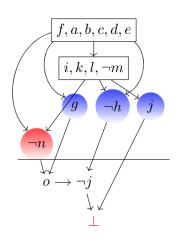


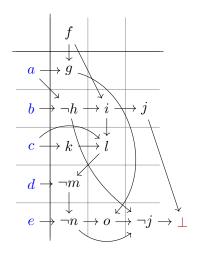






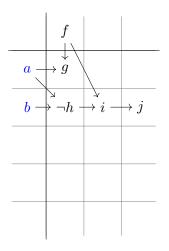






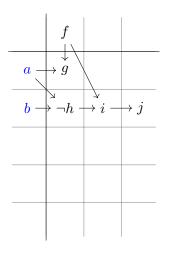
$$\neg a \lor \neg f \lor g
\neg a \lor \neg b \lor \neg h
a \lor c
a \lor \neg i \lor \neg l
a \lor \neg k \lor \neg j
b \lor d
b \lor g \lor \neg n
b \lor \neg f \lor n \lor k
\neg c \lor k
\neg c \lor \neg k \lor \neg i \lor l$$

$$\begin{array}{c} c \vee h \vee n \vee \neg m \\ c \vee l \\ d \vee \neg k \vee l \\ d \vee \neg g \vee l \\ \neg g \vee n \vee o \\ h \vee \neg o \vee \neg j \vee n \\ \neg i \vee j \\ \neg d \vee \neg l \vee \neg m \\ \neg e \vee m \vee \neg n \\ \neg f \vee h \vee i \end{array}$$



$$\neg a \lor \neg f \lor g
\neg a \lor \neg b \lor \neg h
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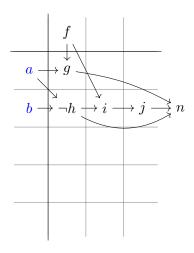
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b \lor \neg f \lor n \lor k
\neg c \lor k
\neg c \lor \neg k \lor \neg i \lor l$$

$$c \lor h \lor n \lor \neg m$$

$$c \lor l$$

$$d \lor \neg k \lor l$$

$$d \lor \neg g \lor l$$

$$\neg g \lor n \lor o$$

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$$\boxed{\neg g \lor h \lor \neg j \lor n}$$

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- When there is only one literal uip propagated in the last level in the current explanation, learn the associated new clause C, backjump (to the last level of propagated literals in C), propagate $\neg uip$ via the new clause, and continue the exploration

Boosting Search through Randomization and Restarts [?]

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- Randomization: breaking ties, random decision between k best choices, . . .
- Restarts: Geometric/Luby

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SAT Solvers (Few examples)

- MiniSat: http://minisat.se/
- Glucose: http://www.labri.fr/perso/lsimon/glucose/
- LingeLing http://fmv.jku.at/lingeling
- Any Solver by Armin Biere http://fmv.jku.at/software/index.html
- Any winner from past and future SAT competitions: https://www.satcompetition.org/



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- Mostly solvable by backtracking algorithms (Search and Filtering)

Search

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Value Ordering

'Succeed-first' [Geelen, 1992]:

"Follow the best chances leading to a solution"

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Arc Consistency

Let C be a constraint and D be a list of domains for the variables in the scope of C.

C is Arc Consistent (AC) iff for every variable x in the scope of C, for every value $v \in D(x)$, there exists an assignment w in D satisfying C in which v is assigned to x

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- If all the domains are singleton, the propagator must be able to check if the assignment corresponds to a solution or not.

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CP vs. SAT

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- CP vs. SAT: a fundamental difference is the presence of global reasoning win CP.

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- Can we find something that takes advantages from both worlds? → Clause learning in CP



• Learning from conflict



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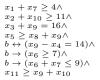
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```
x_2 + x_{10} \ge 11 \land
x_3 + x_9 = 16 \wedge
x_5 \geq x_8 + x_9 \wedge
b \leftrightarrow (x_9 - x_4 = 14) \land
b \to (x_6 > 7) \land
b \rightarrow (x_6 + x_7 \leq 9) \wedge
x_{11} \geq x_9 + x_{10}
                                              30
   x_3
   x_4
                                              45
   x_5
                                              10
   x_6
   x_7
                           10
                                                   30
   x_8
  x_9
         13
```

 $x_1 + x_7 \ge 4 \land$

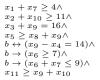
 $\begin{array}{ccc}
x_9 & 13 \\
x_{10} & 0 \\
x_{11} & 15
\end{array}$

$$[x_1 = 1]$$





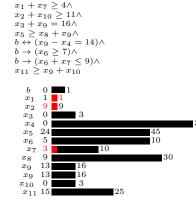
$$[x_1 = 1] \rightarrow [x_7 > 3]$$





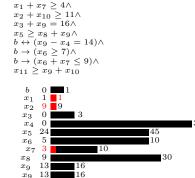
$$[x_1 = 1] \rightarrow [x_7 \ge 3]$$

$$[x_2 = 9]$$



$$[x_1 = 1] \rightarrow [x_7 \ge 3]$$

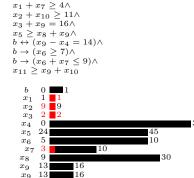
$$[\![x_2=9]\!] \rightarrow [\![x_{10}\geq 2]\!]$$



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$$[x_3 = 2]$$



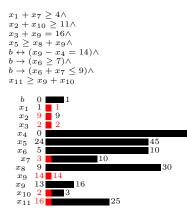
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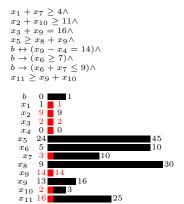
$$[x_2 = 9] \rightarrow [x_{10} \ge 2]$$

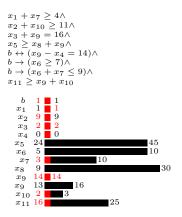
$$[x_3 = 2] \rightarrow [x_9 = 14]$$



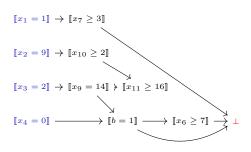


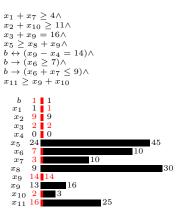


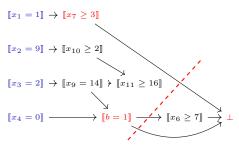




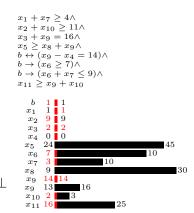
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        0 0
                                                45
  x_5
   x_6
                           10
   x_7
                                                    30
  x_8
  x_9 14 14
  x_9 = 13
  x_{11} 16
```







• Conflict analysis: $[\![b=1]\!] \wedge [\![x_7 \geq 3]\!] \Rightarrow \bot$



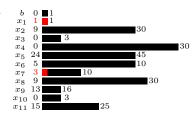
- Conflict analysis: $[b=1] \land [x_7 \ge 3] \Rightarrow \bot$
- New clause: $\llbracket b \neq 1 \rrbracket \vee \llbracket x_7 \leq 2 \rrbracket$

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x_{11} > x_9 + x_{10}
                                                     45
   x_6
                              10
                                                          30
  x_8
```

$$[x_1 = 1] \rightarrow [x_7 > 3]$$

- Conflict analysis: $[b=1] \land [x_7 \ge 3] \Rightarrow \bot$
- New clause: $[b \neq 1] \lor [x_7 \leq 2]$
- Backtrack to level 1

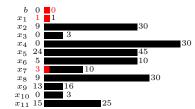
```
\begin{array}{l} x_1+x_7 \geq 4 \wedge \\ x_2+x_{10} \geq 11 \wedge \\ x_3+x_9=16 \wedge \\ x_5 \geq x_8+x_9 \wedge \\ b \leftrightarrow (x_9-x_4=14) \wedge \\ b \rightarrow (x_6 \geq 7) \wedge \\ b \rightarrow (x_6+x_7 \leq 9) \wedge \\ x_{11} \geq x_9+x_{10} \end{array}
```



$$\llbracket x_1 = 1 \rrbracket \rightarrow \llbracket x_7 \ge 3 \rrbracket \longrightarrow \llbracket b = 0 \rrbracket$$

- Conflict analysis: $[b=1] \land [x_7 \ge 3] \Rightarrow \bot$
- New clause: $[b \neq 1] \vee [x_7 \leq 2]$
- Backtrack to level 1
- Propagate the learnt clause

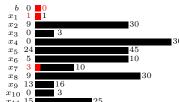
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- \bullet Conflict analysis: $[\![b=1]\!] \wedge [\![x_7 \geq 3]\!] \Rightarrow \bot$
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- Backtrack to level 1
- Propagate the learnt clause
- Continue exploration

```
\begin{array}{l} x_1 + x_7 \geq 4 \land \\ x_2 + x_{10} \geq 11 \land \\ x_3 + x_9 = 16 \land \\ x_5 \geq x_8 + x_9 \land \\ b \leftrightarrow (x_9 - x_4 = 14) \land \\ b \rightarrow (x_6 \geq 7) \land \\ b \rightarrow (x_6 + x_7 \leq 9) \land \\ x_{11} \geq x_9 + x_{10} \end{array}
```



Conflict analysis

Algorithm 1: 1-UIP-with-Propagators

```
\begin{array}{ll} \mathbf{1} \  \, \Psi \leftarrow explain(\bot) \; ; \\ \mathbf{2} \  \, \mathbf{while} \; | \{q \in \Psi \mid level(q) = current \; level\} | > 1 \; \mathbf{do} \\ & \quad | \quad p \leftarrow \arg \max_q \{ \{rank(q) \mid level(q) = current \; level \; \wedge \; q \in \Psi \} ) \; ; \\ \mathbf{3} \quad | \quad \Psi \leftarrow \Psi \cup \{q \mid q \in explain(p) \wedge level(q) > 0\} \setminus \{p\} \; ; \\ & \quad \mathbf{return} \; \Psi \; ; \end{array}
```

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Explaining constraints

- To enable clause learning in CP, every propagator must be able to explain their filtering in the form of clauses ("Lazy Clause Generation").
- We distinguish two types of explanations:
 - Explaining Failure
 - Explaining Domain filtering
- Example: Explain the constraint $X \leq Y$ with two scenarios (failure and propagation).

Exercise

- Let (x_1, \ldots, x_n) be a sequence of Boolean variables, and let d be a positive integer.
- The CARDINALITY (x_1, \ldots, x_n, d) constraint holds iff exactly d variables from the sequence (x_1, \ldots, x_n) are true.
- Write a filtering algorithm for CARDINALITY.
- What is the time complexity?
- Does it enforce arc consistency?
- Explain the CARDINALITY filtering.

Correction

```
Algorithm 4: CARDINALITY([x_1, ..., x_n], d)
  if |\{x_j \mid \mathcal{D}(x_j) = \{1\}\}| > d then
1 | D ←⊥;
  if |\{x_j \mid \mathcal{D}(x_j) = \{0\}\}| > n - d then
2 | D ←⊥;
  if |\{x_i \mid \mathcal{D}(x_i) = \{1\}\}| = d then
       foreach i \in \{1..n\} do
            if \mathcal{D}(x_i) = \{0, 1\} then
              \mathcal{D}(x_i) \leftarrow \{0\};
3
  else
       if |\{x_i \mid \mathcal{D}(x_i) = \{0\}\}| = n - d then
            foreach i \in \{1..n\} do
                 if \mathcal{D}(x_i) = \{0,1\} then
                   \mathcal{D}(x_i) \leftarrow \{1\};
4
  return \mathcal{D};
```



• Failure 1:

$$x^1 \wedge x^2 \wedge x^{d+1} \rightarrow \bot$$

Where $D(x^i) = \{1\}$

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• Failure 2:

$$\neg x^1 \wedge \neg x^2 \wedge \neg x^{n-d+1} \rightarrow \bot$$

Where
$$D(x^i) = \{0\}$$

• Explaining the propagating the value 1: the conjunction of all the assigned variables

• Failure 1:

$$x^1 \wedge x^2 \wedge x^{d+1} \rightarrow \bot$$

Where $D(x^i) = \{1\}$

• Failure 2:

$$\neg x^1 \land \neg x^2 \land \neg x^{n-d+1} \rightarrow \bot$$

Where
$$D(x^i) = \{0\}$$

- Explaining the propagating the value 1: the conjunction of all the assigned variables
- Explaining the propagating the value 0: the conjunction of all the assigned variables



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