

# SPhO 2024 Theory Paper

## Comprehensive Solutions

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# 1 Simple Harmonic Motion

## 1.1 (a)(i) Determine the period of the motion.

The relationship between velocity  $v$  and displacement  $x$  for Simple Harmonic Motion (SHM) is given by:

$$v = \pm \omega \sqrt{x_0^2 - x^2}$$

where  $\omega$  is the angular frequency and  $x_0$  is the amplitude.

From the provided  $v - x$  graph, we identify:

- Maximum displacement (amplitude),  $x_0 = 3$  m.
- Maximum velocity,  $v_{\max} = 2$  m s<sup>-1</sup>.

In SHM, the maximum velocity is  $v_{\max} = \omega x_0$ .

$$2 \text{ m s}^{-1} = \omega \times 3 \text{ m} \implies \omega = \frac{2}{3} \text{ rad s}^{-1}$$

The period of motion  $T$  is:

$$T = \frac{2\pi}{\omega} = \frac{2\pi}{2/3} = 3\pi \text{ s}$$

The period is  $3\pi$  s (approximately 9.42 s).

## 1.2 (a)(ii) Calculate the time taken for the particle to move from point A to point B.

Let the motion be described by  $x(t) = 3 \sin(\frac{2}{3}t + \phi)$  and  $v(t) = 2 \cos(\frac{2}{3}t + \phi)$ .

**State A:**  $v_A = 1$  m s<sup>-1</sup>. The corresponding displacement  $x_A$  is found using the ellipse equation  $\frac{v^2}{v_{\max}^2} + \frac{x^2}{x_0^2} = 1$ :

$$\frac{1^2}{2^2} + \frac{x_A^2}{3^2} = 1 \implies x_A = \frac{3\sqrt{3}}{2} \text{ m}$$

The phase  $\theta_A = \frac{2}{3}t_A + \phi$  must satisfy:

$$\begin{aligned} x_A = \frac{3\sqrt{3}}{2} &= 3 \sin(\theta_A) \implies \sin(\theta_A) = \frac{\sqrt{3}}{2} \\ v_A = 1 &= 2 \cos(\theta_A) \implies \cos(\theta_A) = \frac{1}{2} \end{aligned}$$

This gives  $\theta_A = \frac{\pi}{3}$ .

**State B:**  $x_B = 0$  m and  $v_B = -2$  m s<sup>-1</sup>. The phase  $\theta_B$  must satisfy:

$$\begin{aligned} x_B = 0 &= 3 \sin(\theta_B) \implies \sin(\theta_B) = 0 \\ v_B = -2 &= 2 \cos(\theta_B) \implies \cos(\theta_B) = -1 \end{aligned}$$

This gives  $\theta_B = \pi$ .

The phase change is  $\Delta\theta = \theta_B - \theta_A = \pi - \frac{\pi}{3} = \frac{2\pi}{3}$ . The time taken is:

$$\Delta t = \frac{\Delta\theta}{\omega} = \frac{2\pi/3}{2/3} = \pi \text{ s}$$

The time taken is  $\pi$  s (approximately 3.14 s).

**1.3 (b)(i) Show that the potential energy is  $E_p = \frac{1}{2}m\omega^2x^2$ .**

Total energy  $E_T = K + E_p = \frac{1}{2}mv^2 + E_p$ . Total energy is also the maximum kinetic energy,  $E_T = \frac{1}{2}mv_{\max}^2 = \frac{1}{2}m(\omega x_0)^2$ . Using  $v^2 = \omega^2(x_0^2 - x^2)$ , the kinetic energy is  $K(x) = \frac{1}{2}m\omega^2(x_0^2 - x^2)$ . The potential energy is  $E_p(x) = E_T - K(x)$ :

$$E_p(x) = \frac{1}{2}m\omega^2x_0^2 - \frac{1}{2}m\omega^2(x_0^2 - x^2) = \frac{1}{2}m\omega^2x^2$$

**1.4 (b)(ii) Show that the potential energy of the pendulum is  $E = mgL - mg\sqrt{L^2 - x^2}$ .**

Let the equilibrium position be the reference for potential energy ( $E_p = 0$ ). When displaced by a horizontal distance  $x$ , the bob is raised by a vertical height  $h = L - \sqrt{L^2 - x^2}$ . The potential energy  $E$  is  $mgh$ :

$$E = mg(L - \sqrt{L^2 - x^2}) = mgL - mg\sqrt{L^2 - x^2}$$

**1.5 (b)(iii) Show that the period of a pendulum is  $T = 2\pi\sqrt{\frac{L}{g}}$  for small-angle oscillations.**

For small angles,  $x \ll L$ . We use the binomial approximation  $\sqrt{1 - u} \approx 1 - \frac{u}{2}$  for small  $u$ .

$$E = mgL \left( 1 - \sqrt{1 - \left(\frac{x}{L}\right)^2} \right) \approx mgL \left( 1 - \left( 1 - \frac{x^2}{2L^2} \right) \right) = \frac{mg}{2L}x^2$$

Comparing with  $E_p = \frac{1}{2}m\omega^2x^2$ , we get:

$$\frac{1}{2}m\omega^2x^2 = \frac{mg}{2L}x^2 \implies \omega^2 = \frac{g}{L} \implies \omega = \sqrt{\frac{g}{L}}$$

The period is  $T = \frac{2\pi}{\omega} = 2\pi\sqrt{\frac{L}{g}}$ .

## 2 Rotational Motion and Friction

### 2.1 (a) Calculate the maximum static frictional force that can act on the block.

The normal force  $N = mg = 2.5 \text{ kg} \times 9.81 \text{ m/s}^2 = 24.525 \text{ N}$ . The maximum static frictional force  $f_{s,max}$  is:

$$f_{s,max} = \mu_s N = 0.4 \times 24.525 \text{ N} = 9.81 \text{ N}$$

### 2.2 (b) Determine whether the block will slide or stay in place.

The required centripetal force is  $F_c = m\omega^2 r$ :

$$F_c = 2.5 \text{ kg} \times (3 \text{ rad/s})^2 \times 0.3 \text{ m} = 6.75 \text{ N}$$

Since  $F_c = 6.75 \text{ N} < f_{s,max} = 9.81 \text{ N}$ , the block will **stay in place**.

### 2.3 (c) Calculate the minimum coefficient of friction required for the block to stay in place at the edge.

At the edge,  $r_{\text{edge}} = 0.5 \text{ m}$ . The required centripetal force is:

$$F_{c,\text{edge}} = m\omega^2 r_{\text{edge}} = 2.5 \times (3)^2 \times 0.5 = 11.25 \text{ N}$$

For the block to stay,  $f_{s,max,min} = \mu_{s,min} mg \geq F_{c,\text{edge}}$ .

$$\mu_{s,min} \geq \frac{11.25 \text{ N}}{2.5 \text{ kg} \times 9.81 \text{ m/s}^2} \approx 0.4587$$

The minimum coefficient is approximately **0.459**.

### 2.4 (d) Determine the speed of the block when it begins to slip.

Slipping begins when  $\frac{mv^2}{r} = f_{s,max} = \mu_s mg$ .

$$v = \sqrt{\mu_s g r} = \sqrt{0.4 \times 9.81 \times 0.5} = \sqrt{1.962} \approx 1.40 \text{ m/s}$$

### 3 Spring and Conservation Laws

#### 3.1 (a) Derive an expression for the speed of the sphere when the block is fixed.

By conservation of energy (initial spring potential energy to final kinetic energy):

$$\frac{1}{2}kd^2 = \frac{1}{2}mv^2 \implies v = \sqrt{\frac{k}{m}}d$$

#### 3.2 (b) Derive an expression for the speed of the sphere when the block is free to move.

Let  $v_m$  be the sphere's velocity and  $v_M$  be the block's velocity. Conservation of Momentum:  $mv_m + Mv_M = 0 \implies v_M = -\frac{m}{M}v_m$ . Conservation of Energy:  $\frac{1}{2}kd^2 = \frac{1}{2}mv_m^2 + \frac{1}{2}Mv_M^2$ . Substituting for  $v_M$ :

$$\begin{aligned} kd^2 &= mv_m^2 + M\left(-\frac{m}{M}v_m\right)^2 = mv_m^2 + \frac{m^2}{M}v_m^2 \\ kd^2 &= v_m^2\left(m + \frac{m^2}{M}\right) = v_m^2\frac{m(M+m)}{M} \\ v_m &= d\sqrt{\frac{kM}{m(M+m)}} \end{aligned}$$

#### 3.3 (c) Derive an expression for the distance the block has travelled.

The center of mass (CM) of the system remains stationary. Let the block's displacement be  $D_M$  and the sphere's be  $D_m$ .  $mD_m + MD_M = 0$ . The initial compression is the sum of the magnitudes of their displacements relative to the uncompressed position:  $d = |D_m| + |D_M|$ . From the first equation,  $|D_m| = \frac{M}{m}|D_M|$ . Substituting this into the second:

$$d = \frac{M}{m}|D_M| + |D_M| = |D_M|\left(\frac{M+m}{m}\right)$$

The distance travelled by the block is  $|D_M| = \frac{md}{m+M}$ .

## 4 Electromagnetic Induction

1. **Induced EMF ( $\mathcal{E}$ ):** At distance  $x$ , the rod length is  $L = 2x \tan(\frac{\alpha}{2})$ . The loop area is  $A = x^2 \tan(\frac{\alpha}{2})$ . The magnetic flux is  $\Phi_B = Bx^2 \tan(\frac{\alpha}{2})$ .

$$|\mathcal{E}| = \left| \frac{d\Phi_B}{dt} \right| = B \tan(\frac{\alpha}{2}) \cdot 2x \frac{dx}{dt} = 2Bxv \tan(\frac{\alpha}{2})$$

2. **Induced Current ( $I$ ):** The rod resistance is  $R_{\text{rod}} = R \cdot L = 2Rx \tan(\frac{\alpha}{2})$ .

$$I = \frac{|\mathcal{E}|}{R_{\text{rod}}} = \frac{2Bxv \tan(\frac{\alpha}{2})}{2Rx \tan(\frac{\alpha}{2})} = \frac{Bv}{R}$$

3. **Magnetic Braking Force ( $F_m$ ):**

$$F_m = ILB = \left( \frac{Bv}{R} \right) \left( 2x \tan(\frac{\alpha}{2}) \right) B = \frac{2B^2vx \tan(\frac{\alpha}{2})}{R}$$

4. **Equation of Motion:**  $ma = -F_m$ . Use  $a = v \frac{dv}{dx}$ :

$$mv \frac{dv}{dx} = -\frac{2B^2vx \tan(\frac{\alpha}{2})}{R} \implies m \frac{dv}{dx} = -\frac{2B^2x \tan(\frac{\alpha}{2})}{R}$$

5. **Integration:** Integrate from initial state ( $x = x_0, v = v_0$ ) to final state ( $x = x_f, v = 0$ ).

$$\begin{aligned} \int_{v_0}^0 m dv &= \int_{x_0}^{x_f} -\frac{2B^2 \tan(\frac{\alpha}{2})}{R} x dx \\ [mv]_{v_0}^0 &= -\frac{2B^2 \tan(\frac{\alpha}{2})}{R} \left[ \frac{x^2}{2} \right]_{x_0}^{x_f} \\ -mv_0 &= -\frac{B^2 \tan(\frac{\alpha}{2})}{R} (x_f^2 - x_0^2) \\ x_f^2 - x_0^2 &= \frac{mv_0 R}{B^2 \tan(\frac{\alpha}{2})} \\ x_f &= \sqrt{x_0^2 + \frac{mv_0 R}{B^2 \tan(\frac{\alpha}{2})}} \end{aligned}$$

## 5 Orbital Mechanics and Rotational Dynamics

### 5.1 (a)(i) Determine an expression for the minimum speed required to enter the transfer orbit.

The Hohmann transfer orbit has semi-major axis  $a = \frac{R_1 + R_2}{2}$ . The speed  $v_p$  at periapsis ( $r = R_1$ ) is given by the vis-viva equation:

$$\begin{aligned}v_p^2 &= GM \left( \frac{2}{R_1} - \frac{1}{a} \right) = GM \left( \frac{2}{R_1} - \frac{2}{R_1 + R_2} \right) \\v_p^2 &= 2GM \left( \frac{R_1 + R_2 - R_1}{R_1(R_1 + R_2)} \right) = \frac{2GM R_2}{R_1(R_1 + R_2)} \\v_p &= \sqrt{\frac{2GM R_2}{R_1(R_1 + R_2)}}\end{aligned}$$

### 5.2 (a)(ii) Show that the increase in total energy for the first burn is as given.

Initial energy in circular orbit:  $E_1 = -\frac{GMm}{2R_1}$ . Energy in transfer orbit:  $E_t = -\frac{GMm}{2a} = -\frac{GMm}{R_1 + R_2}$ . Increase in energy:

$$\begin{aligned}\Delta E &= E_t - E_1 = -\frac{GMm}{R_1 + R_2} + \frac{GMm}{2R_1} \\&= GMm \left( \frac{1}{2R_1} - \frac{1}{R_1 + R_2} \right) = GMm \left( \frac{R_2 - R_1}{2R_1(R_1 + R_2)} \right)\end{aligned}$$

### 5.3 (a)(iii) Determine an expression for the time of flight for the transfer.

The transfer takes half the period  $T$  of the transfer orbit. By Kepler's Third Law:

$$T^2 = \frac{4\pi^2}{GM} a^3 = \frac{4\pi^2}{GM} \left( \frac{R_1 + R_2}{2} \right)^3 = \frac{\pi^2 (R_1 + R_2)^3}{2GM}$$

The time of flight is:

$$t_{\text{flight}} = \frac{T}{2} = \frac{\pi}{2} \sqrt{\frac{(R_1 + R_2)^3}{2GM}} = \pi \sqrt{\frac{(R_1 + R_2)^3}{8GM}}$$



## 6 Electromagnetism and Dynamics

### 6.1 (a)(i) Determine the magnitude of the magnetic dipole moment.

The magnitude of the magnetic dipole moment  $\mu$  is:

$$\mu = NIA = 10 \times 5.0 \text{ A} \times (0.80 \text{ m} \times 0.50 \text{ m}) = 20 \text{ A m}^2$$

### 6.2 (a)(ii) Determine the magnitude of the initial magnetic torque on the loop.

The torque is  $\tau = \mu B \sin \theta$ . Initially, the loop is horizontal, so its moment  $\vec{\mu}$  is vertical. The field  $\vec{B}$  is horizontal, so  $\theta = 90^\circ$ .

$$\tau_{\text{mag}} = \mu B \sin(90^\circ) = (20 \text{ A m}^2) \times (0.50 \text{ T}) = 10 \text{ N m}$$

### 6.3 (b) Calculate the net torque acting on the pulley.

Torque from the mass:  $\tau_{\text{mass}} = rF_g = r(mg) = (0.10 \text{ m})(5.0 \text{ kg} \times 9.81 \text{ m/s}^2) = 4.905 \text{ N m}$ . The torques are in opposite directions.

$$\tau_{\text{net}} = \tau_{\text{mag}} - \tau_{\text{mass}} = 10 - 4.905 = 5.095 \text{ N m} \approx 5.10 \text{ N m}$$

### 6.4 (c)(i) Calculate the change in potential energy of the magnetic dipole.

Potential energy is  $U_{\text{mag}} = -\mu B \cos \theta$ . Initial state:  $\theta_i = 90^\circ \implies U_i = 0$ . Final state (upright):  $\vec{\mu}$  aligns with  $\vec{B}$ , so  $\theta_f = 0^\circ \implies U_f = -\mu B \cos(0^\circ) = -10 \text{ J}$ .

$$\Delta U_{\text{mag}} = U_f - U_i = -10 \text{ J}$$

### 6.5 (c)(ii) Calculate the speed of the mass at this position.

Use conservation of energy:  $E_i = E_f$ .  $E_i = K_i + U_{g,i} + U_{\text{mag},i} = 0 + 0 + 0 = 0$ . The loop rotates  $90^\circ$ , so the mass moves up by  $h = r\Delta\theta = 0.10 \times \frac{\pi}{2} = 0.05\pi \text{ m}$ .  $E_f = K_f + U_{g,f} + U_{\text{mag},f} = \frac{1}{2}mv^2 + mgh + U_f$ .

$$\begin{aligned} 0 &= \frac{1}{2}mv^2 + mgh + (-\mu B) \\ \frac{1}{2}(5.0)v^2 &= 10 - (5.0)(9.81)(0.05\pi) \\ 2.5v^2 &\approx 10 - 7.705 = 2.295 \\ v &= \sqrt{\frac{2.295}{2.5}} \approx 0.958 \text{ m/s} \end{aligned}$$

The speed is approximately **0.96 m/s**.

## 7 RLC Circuit

### 7.1 (a) Show $V = Ae^{-\alpha t} \cos(\omega t)$ is a solution and find $\omega$ .

Given:  $\frac{d^2V}{dt^2} + \frac{R}{L} \frac{dV}{dt} + \frac{1}{LC} V = 0$ . Substituting  $V(t) = Ae^{-\alpha t} \cos(\omega t)$  and its derivatives into the equation yields:

$$\cos(\omega t) \left[ \alpha^2 - \omega^2 - \frac{R}{L} \alpha + \frac{1}{LC} \right] + \sin(\omega t) \left[ 2\alpha\omega - \frac{R}{L} \omega \right] = 0$$

For this to be true for all  $t$ , the coefficients must be zero. From the  $\sin(\omega t)$  term:  $2\alpha\omega - \frac{R}{L}\omega = 0 \implies \alpha = \frac{R}{2L}$ . From the  $\cos(\omega t)$  term, substituting  $\alpha = R/2L$ :

$$\begin{aligned} \left( \frac{R}{2L} \right)^2 - \omega^2 - \frac{R}{L} \left( \frac{R}{2L} \right) + \frac{1}{LC} &= 0 \\ \omega^2 = \frac{1}{LC} - \frac{R^2}{4L^2} &\implies \omega = \sqrt{\frac{1}{LC} - \left( \frac{R}{2L} \right)^2} \end{aligned}$$

### 7.2 (b)(i) Calculate oscillation frequency and decay time.

Given:  $C = 15.0 \times 10^{-9}$  F,  $L = 0.22 \times 10^{-3}$  H,  $R = 75.0 \Omega$ .  $\alpha = \frac{R}{2L} = \frac{75.0}{2 \times 0.22 \times 10^{-3}} \approx 1.705 \times 10^5$  s<sup>-1</sup>.  $\omega = \sqrt{\frac{1}{(0.22 \times 10^{-3})(15.0 \times 10^{-9})} - (1.705 \times 10^5)^2} \approx 5.234 \times 10^5$  rad/s. Oscillation frequency  $f = \frac{\omega}{2\pi} \approx \frac{5.234 \times 10^5}{2\pi} \approx 8.33 \times 10^4$  Hz = **83.3 kHz**. Decay to 10%:  $e^{-\alpha t} = 0.10 \implies t = \frac{\ln(10)}{\alpha} \approx \frac{2.3026}{1.705 \times 10^5} \approx 1.35 \times 10^{-5}$  s = **13.5  $\mu$ s**.

### 7.3 (b)(ii) Calculate the value of R for a critically damped circuit.

Critical damping occurs when  $\omega = 0$ .

$$\frac{1}{LC} = \left( \frac{R_{\text{crit}}}{2L} \right)^2 \implies R_{\text{crit}} = 2\sqrt{\frac{L}{C}}$$

$$R_{\text{crit}} = 2\sqrt{\frac{0.22 \times 10^{-3}}{15.0 \times 10^{-9}}} \approx 242.2 \Omega$$

The resistance is approximately **242  $\Omega$** .

## 8 Special Relativity

- 8.1 (a) Calculate the time it takes for the spacecraft to travel from A to B as measured by the observer on Earth.

$$\Delta t_{\text{Earth}} = \frac{L_0}{v} = \frac{10 \text{ light-years}}{0.8c} = 12.5 \text{ years}$$

- 8.2 (b) Determine the time experienced by a clock on the spacecraft.

This is the proper time  $\Delta t_0$ . First, find the Lorentz factor  $\gamma$ :

$$\gamma = \frac{1}{\sqrt{1 - (v/c)^2}} = \frac{1}{\sqrt{1 - 0.8^2}} = \frac{1}{0.6} = \frac{5}{3}$$

$$\Delta t_0 = \frac{\Delta t_{\text{Earth}}}{\gamma} = \frac{12.5 \text{ years}}{5/3} = 7.5 \text{ years}$$

- 8.3 (c) How much time does it take for the signal to reach point B as measured by:

i. **The observer on Earth.** The light signal travels 10 light-years at speed  $c$ . Time taken is **10 years**.

ii. **The astronaut on the spacecraft.** Use the Lorentz transformation for time. Earth frame is S, spacecraft is S'. Event 1 (Signal sent from A):  $(t_1, x_1) = (0, 0)$  in S. Event 2 (Signal reaches B):  $(t_2, x_2) = (10 \text{ yr}, 10 \text{ ly})$  in S. Time of Event 2 in S':

$$t'_2 = \gamma \left( t_2 - \frac{vx_2}{c^2} \right) = \frac{5}{3} \left( 10 \text{ yr} - \frac{(0.8c)(10 \text{ ly})}{c^2} \right) = \frac{5}{3}(10 - 8) \text{ yr} = \frac{10}{3} \text{ years}$$

Time taken is **3.33 years**.

- 8.4 (d) Do the events "spacecraft reaches point B" and "signal reaches point A" occur simultaneously according to the observer on Earth?

No.

- Spacecraft reaches B at  $t_1 = 12.5$  years.
- The signal is sent from B at  $t = 12.5$  years and travels 10 light-years back to A, which takes another 10 years. The signal reaches A at  $t_2 = 12.5 + 10 = 22.5$  years.

Since  $t_1 \neq t_2$ , the events are not simultaneous.

## 9 Thermodynamics

### 9.1 (a) Calculate the total work done by the gas.

**State A:**  $P_A = 101.3$  kPa,  $T_A = 278.15$  K,  $n = 1$  mole. Initial volume  $V_A = \frac{nRT_A}{P_A} = \frac{1 \times 8.31 \times 278.15}{101.3 \times 10^3} \approx 0.02283$  m<sup>3</sup>.

**Process A  $\rightarrow$  B (isochoric):** Volume is constant, so  $W_{AB} = 0$ . **Process B  $\rightarrow$  C (isobaric):**  $P_B = P_A/2$ ,  $V_C = 2V_B = 2V_A$ .

$$W_{BC} = P_B(V_C - V_B) = P_B V_B = \left(\frac{P_A}{2}\right) V_A = \frac{1}{2} nRT_A$$

$$W_{BC} = \frac{1}{2}(1)(8.31)(278.15) \approx 1155.7 \text{ J}$$

Total work  $W_{\text{total}} = W_{AB} + W_{BC} = 1155.7 \text{ J} \approx \mathbf{1160 \text{ J}}$ .

### 9.2 (b) Determine the work done by the gas for a process from state A to state C at constant temperature.

State C has  $P_C = P_A/2$  and  $V_C = 2V_A$ , which implies  $T_C = T_A$ . Work done during an isothermal process:

$$W = \int_{V_A}^{V_C} P dV = nRT_A \ln\left(\frac{V_C}{V_A}\right)$$

$$W = nRT_A \ln(2) = (1)(8.31)(278.15) \ln(2) \approx 1601.9 \text{ J} \approx \mathbf{1600 \text{ J}}$$

## 10 Wave Optics

### 10.1 (a) Find an expression for the total path difference and the condition for maximum intensity.

Path difference before slits:  $\Delta L_1 = d \sin \alpha$ . Path difference after slits:  $\Delta L_2 = d \sin \beta$ .  
Total path difference  $\Delta L$ :

$$\Delta L = \Delta L_2 - \Delta L_1 = d(\sin \beta - \sin \alpha)$$

Condition for maximum intensity (constructive interference):

$$d(\sin \beta - \sin \alpha) = m\lambda, \quad \text{where } m = 0, \pm 1, \pm 2, \dots$$

### 10.2 (b) Show that the angular separation between adjacent maxima is independent of $\alpha$ for small $\beta$ .

For the  $m$ -th and  $(m+1)$ -th maxima:

$$\begin{aligned}\sin \beta_m &= \sin \alpha + \frac{m\lambda}{d} \\ \sin \beta_{m+1} &= \sin \alpha + \frac{(m+1)\lambda}{d}\end{aligned}$$

The difference is:

$$\sin \beta_{m+1} - \sin \beta_m = \frac{\lambda}{d}$$

For small angles  $\beta$ , we can use the approximation  $\sin \beta_{m+1} - \sin \beta_m \approx \Delta\beta \cos \beta$ , where  $\Delta\beta = \beta_{m+1} - \beta_m$ .

$$\Delta\beta \cos \beta \approx \frac{\lambda}{d}$$

For small values of  $\beta$ ,  $\cos \beta \approx 1$ . Therefore, the angular separation is:

$$\Delta\beta \approx \frac{\lambda}{d}$$

This expression is independent of the angle of incidence  $\alpha$ .