

Si ModuleNotFoundError: No module named 'tqdm' faire !pip install tqdm dans une cellule code

```
In [1]: import os
import cv2
import numpy as np
import matplotlib.pyplot as plt

from sklearn.cluster import MiniBatchKMeans
from sklearn.svm import SVC
from sklearn.model_selection import train_test_split, GridSearchCV
from sklearn.metrics import accuracy_score, confusion_matrix, classification_report

import joblib
from tqdm import tqdm
import time
import GPUtil
import psutil
```

```
In [2]: TRAIN_PATH = "../dataset/seg_train"
TEST_PATH = "../dataset/seg_test"
```

```
In [3]: MAX_FEATURES = 1500 # ORB keypoints
K = 300 # taille du vocabulaire visuel
```

```
In [4]: class PerformanceTracker:
    def __init__(self):
        self.start_time = None
        self.logs = {}

    def start(self, name):
        self.start_time = time.time()
        self.cpu_start = psutil.cpu_percent(interval=None)
        self.mem_start = psutil.virtual_memory().used

    def stop(self, name):
        elapsed = time.time() - self.start_time
        cpu = psutil.cpu_percent(interval=None)
        mem = psutil.virtual_memory().used
        self.logs[name] = {
            "time_sec": elapsed,
            "cpu_percent": cpu,
            "ram_mb": mem / 1024**2
        }
        print(f"[{name}] Time: {elapsed:.1f}s | CPU: {cpu}% | RAM: {mem/1024**2:.1f}GB")
```

```
In [5]: def load_images(folder_path):
    image_paths = []
    labels = []
    class_names = sorted(os.listdir(folder_path))

    for label, class_name in enumerate(class_names):
        class_path = os.path.join(folder_path, class_name)
        for img in os.listdir(class_path):
            image_paths.append(os.path.join(class_path, img))
            labels.append(label)
```



```
kmeans.fit(all_train_des)
tracker.stop("KMeans vocab")

print("Vocabulaire visuel créé :", K)
```

[KMeans vocab] Time: 20.5s | CPU: 41.6% | RAM: 5901 MB
Vocabulaire visuel créé : 300

```
In [11]: def build_histograms(des_list, kmeans, k):
          X = np.zeros((len(des_list), k))
          for i, des in enumerate(des_list):
              words = kmeans.predict(des)
              for w in words:
                  X[i, w] += 1
          norm = np.linalg.norm(X, axis=1, keepdims=True) + 1e-8
          return X / norm

          tracker.start("BoVW histograms")
          X_train = build_histograms(train_des, kmeans, K)
          X_test = build_histograms(test_des, kmeans, K)
          tracker.stop("BoVW histograms")

          print(X_train.shape, X_test.shape)
```

[BoVW histograms] Time: 16.2s | CPU: 37.5% | RAM: 6088 MB
(14015, 300) (2997, 300)

```
In [12]: svm = SVC(
          kernel='rbf',
          C=50,
          gamma=0.005,
          decision_function_shape='ovo'
          )

          tracker.start("SVM training")
          svm.fit(X_train, y_train)
          tracker.stop("SVM training")
```

[SVM training] Time: 32.6s | CPU: 16.9% | RAM: 6160 MB

```
In [13]: y_pred = svm.predict(X_test)

          print("Accuracy :", accuracy_score(y_test, y_pred))
          print("\nRapport de classification :\n")
          print(classification_report(y_test, y_pred, target_names=class_names))
```

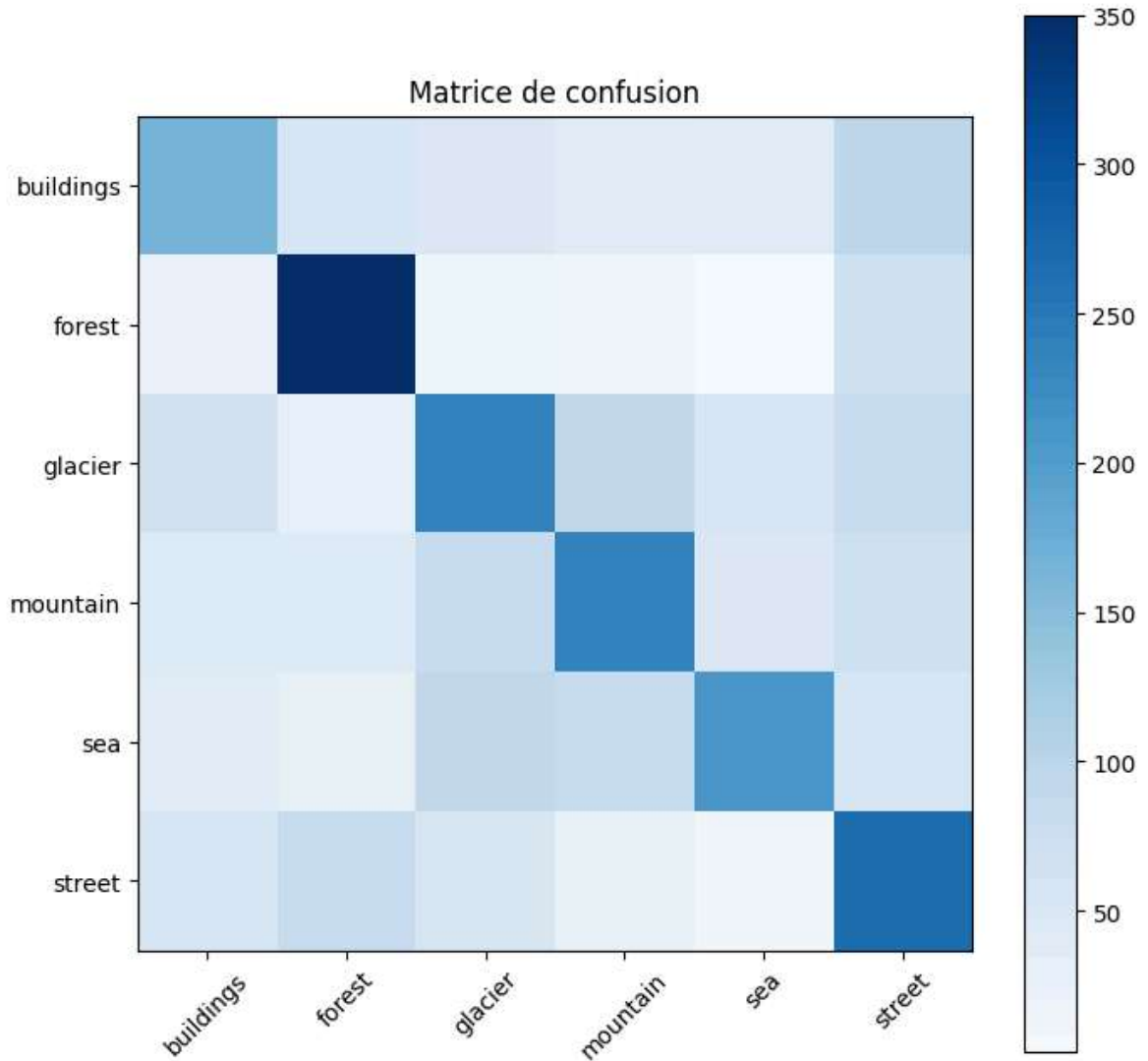
Accuracy : 0.4881548214881548

Rapport de classification :

	precision	recall	f1-score	support
buildings	0.43	0.38	0.40	437
forest	0.59	0.74	0.66	474
glacier	0.45	0.43	0.44	552
mountain	0.48	0.45	0.46	524
sea	0.58	0.41	0.48	509
street	0.41	0.53	0.47	501
accuracy			0.49	2997
macro avg	0.49	0.49	0.48	2997
weighted avg	0.49	0.49	0.48	2997

```
In [14]: cm = confusion_matrix(y_test, y_pred)

plt.figure(figsize=(8,8))
plt.imshow(cm, cmap='Blues')
plt.title("Matrice de confusion")
plt.xticks(range(len(class_names)), class_names, rotation=45)
plt.yticks(range(len(class_names)), class_names)
plt.colorbar()
plt.show()
```



```
In [15]: output_dir = "checkpoints_ORB"
os.makedirs(output_dir, exist_ok=True)
```

```
In [16]: joblib.dump(svm, os.path.join(output_dir, "svm_bovw_orb_Intel.pkl"))
joblib.dump(kmeans, os.path.join(output_dir, "kmeans_vocab_Intel.pkl"))
print("Modèle sauvegardé")
```

Modèle sauvegardé

CONCLUSION

L'utilisation d'ORB et du Bag of Visual Words pour la classification des images du jeu de données Intel a mis en évidence les limites des approches basées sur des descripteurs locaux dans un contexte de scènes naturelles variées. La diversité des textures et des structures présentes dans les images rend la représentation BoVW peu discriminante.

En outre, le temps de calcul lié à l'extraction des descripteurs et au clustering KMeans sur CPU s'est avéré élevé, sans amélioration significative des résultats. Ce déséquilibre entre coût computationnel et performance a conduit à écarter cette méthode.

```
In [ ]:
```