

Swiss Institute of  
Bioinformatics

# Deep learning techniques in Life sciences

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SIB Swiss Institute of Bioinformatics

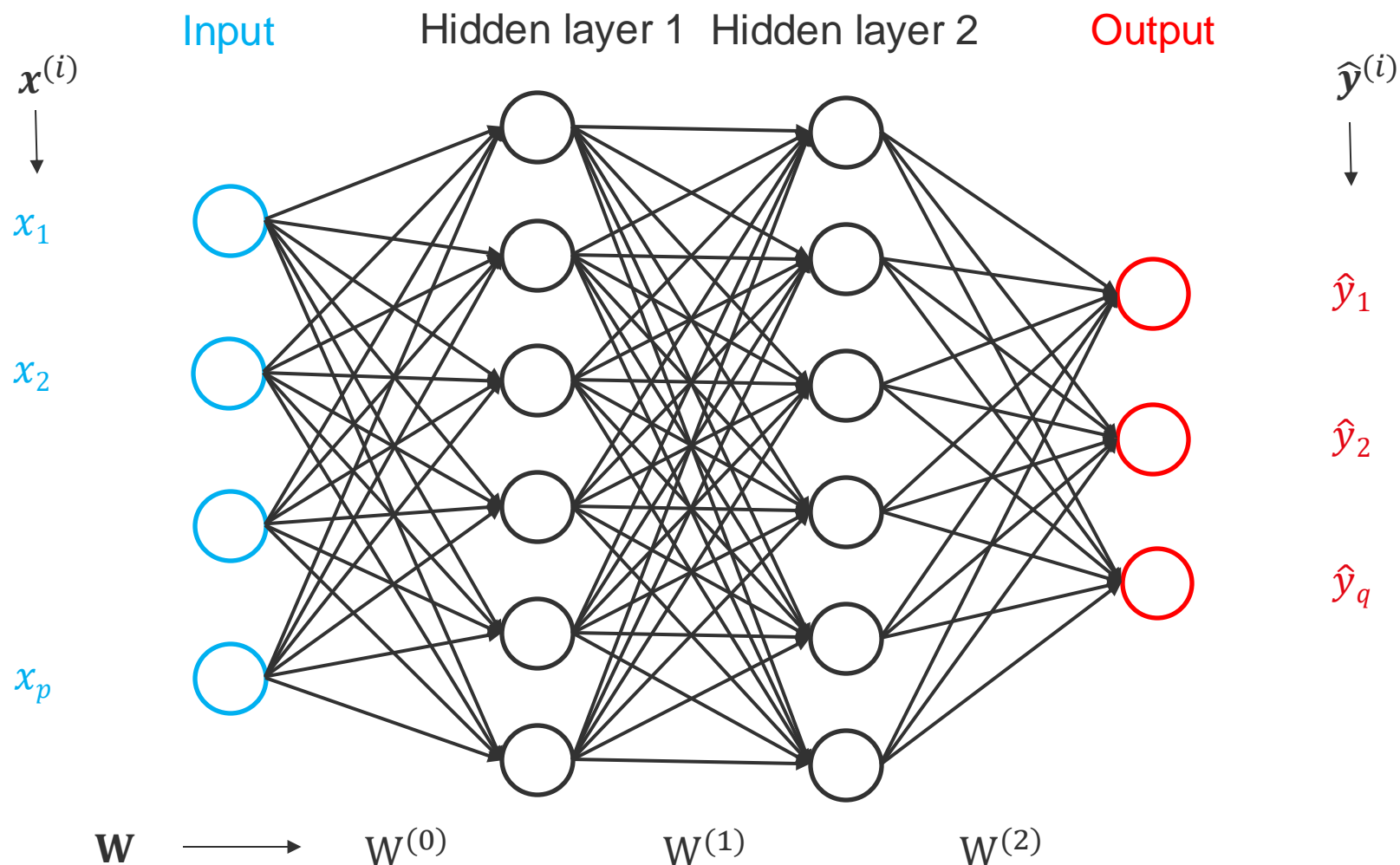
November 2024

# Outline

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- Autoencoders
- Convolutional neural networks
- Recurrent neural networks
- Attention mechanism and transformers
- Deep reinforcement learning
- Generative adversarial networks

# Neural Network revisited



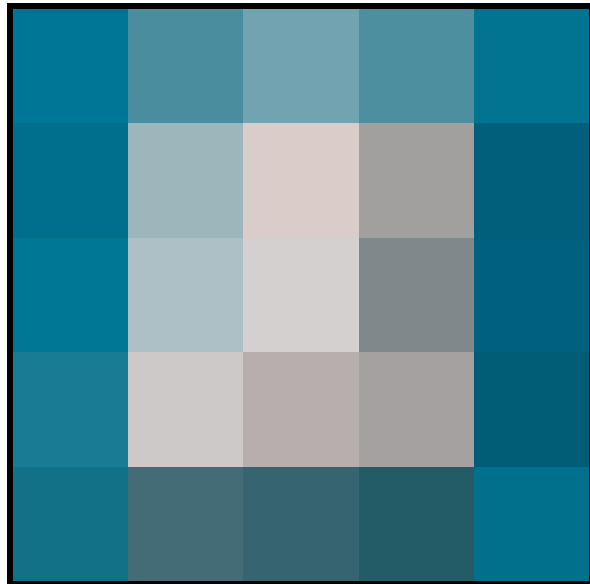
Activation functions on linear regressions

Loss optimization

$$\mathbf{W}^* = \operatorname{argmin}_{\mathbf{W}} \frac{1}{n} \sum_{i=1}^n \mathcal{L}(f(\mathbf{x}^{(i)}, \mathbf{W}), \mathbf{y}^{(i)})$$

# Dimensionality issue

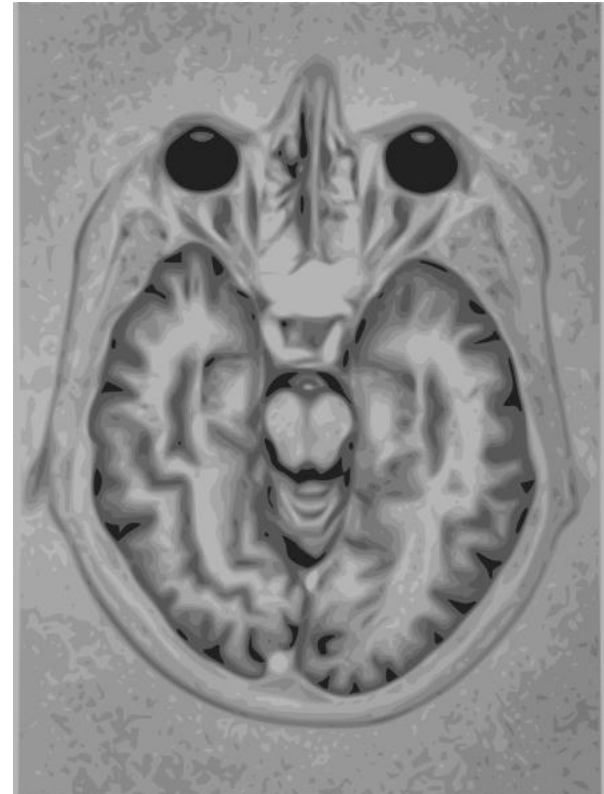
5x5 pixels



Sparsity

Closeness

1524 x 2048 pixels



Full connectivity => curse of dimensionality!

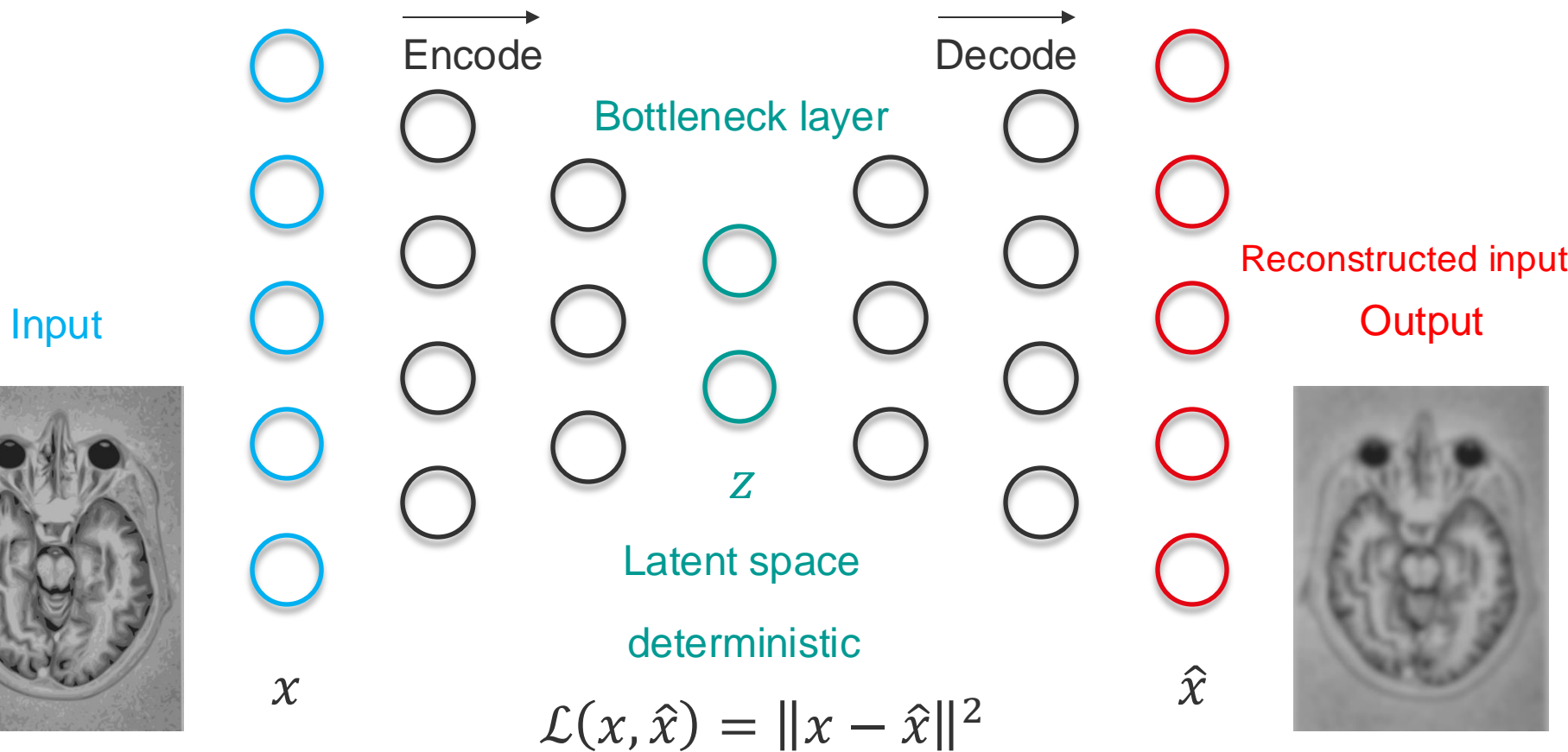
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# Autoencoder

- Learning a lower-dimensional feature representation (compression) from unlabeled training data and learning a reconstruction back



```
tensorflow.keras.Model(name='autoencoder')
```

# Autoencoder

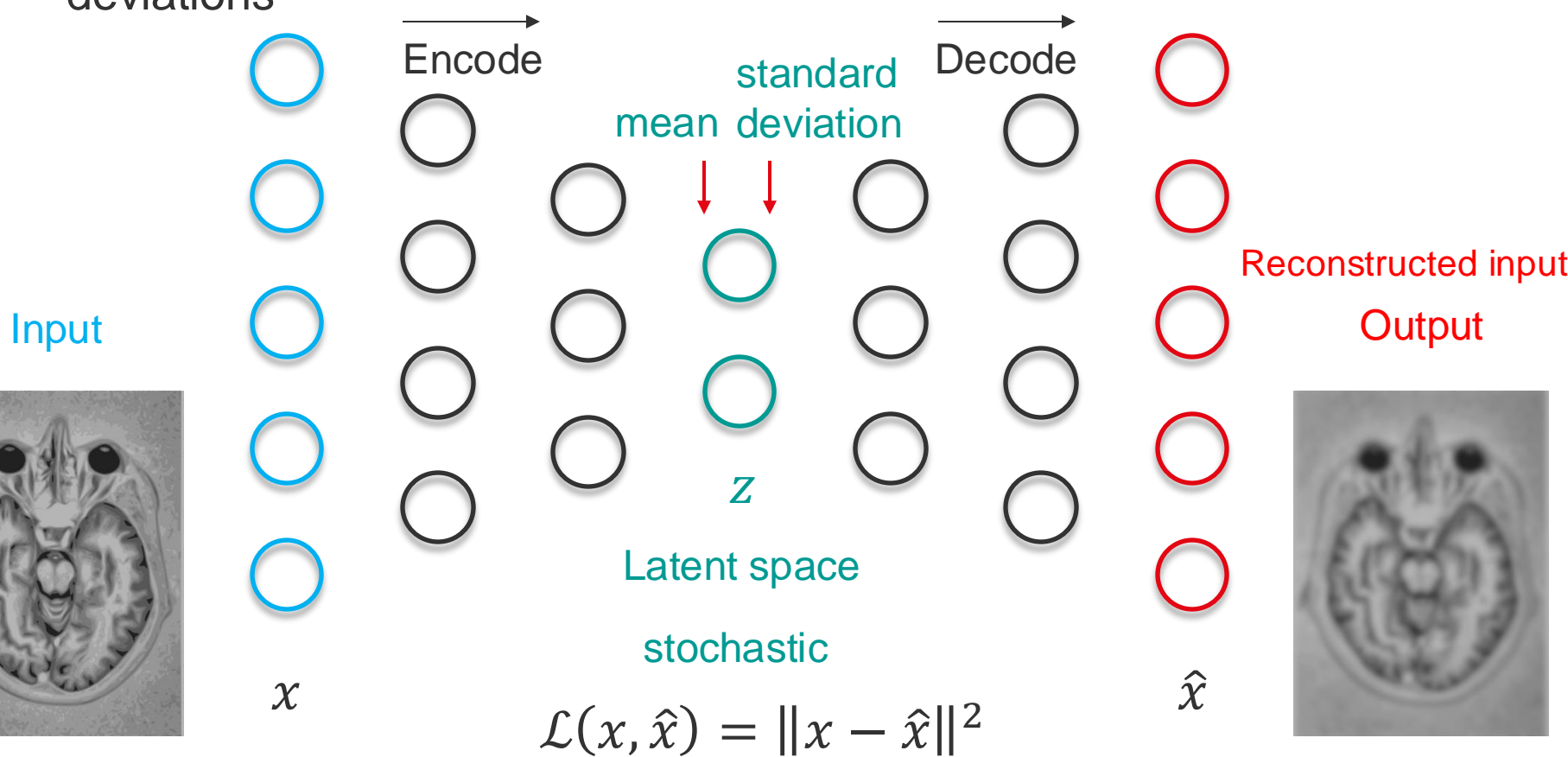
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- Generalization of PCA: non-linear
- Challenges: models that learn a meaningful and generalizable latent space representation



# Variational autoencoder

- Probabilistic twist on autoencoder: map the input into a distribution instead of a fixed vector => two vectors of means and standard deviations



```
tensorflow.keras.Model(name='vae')
```



# Autoencoders: When?

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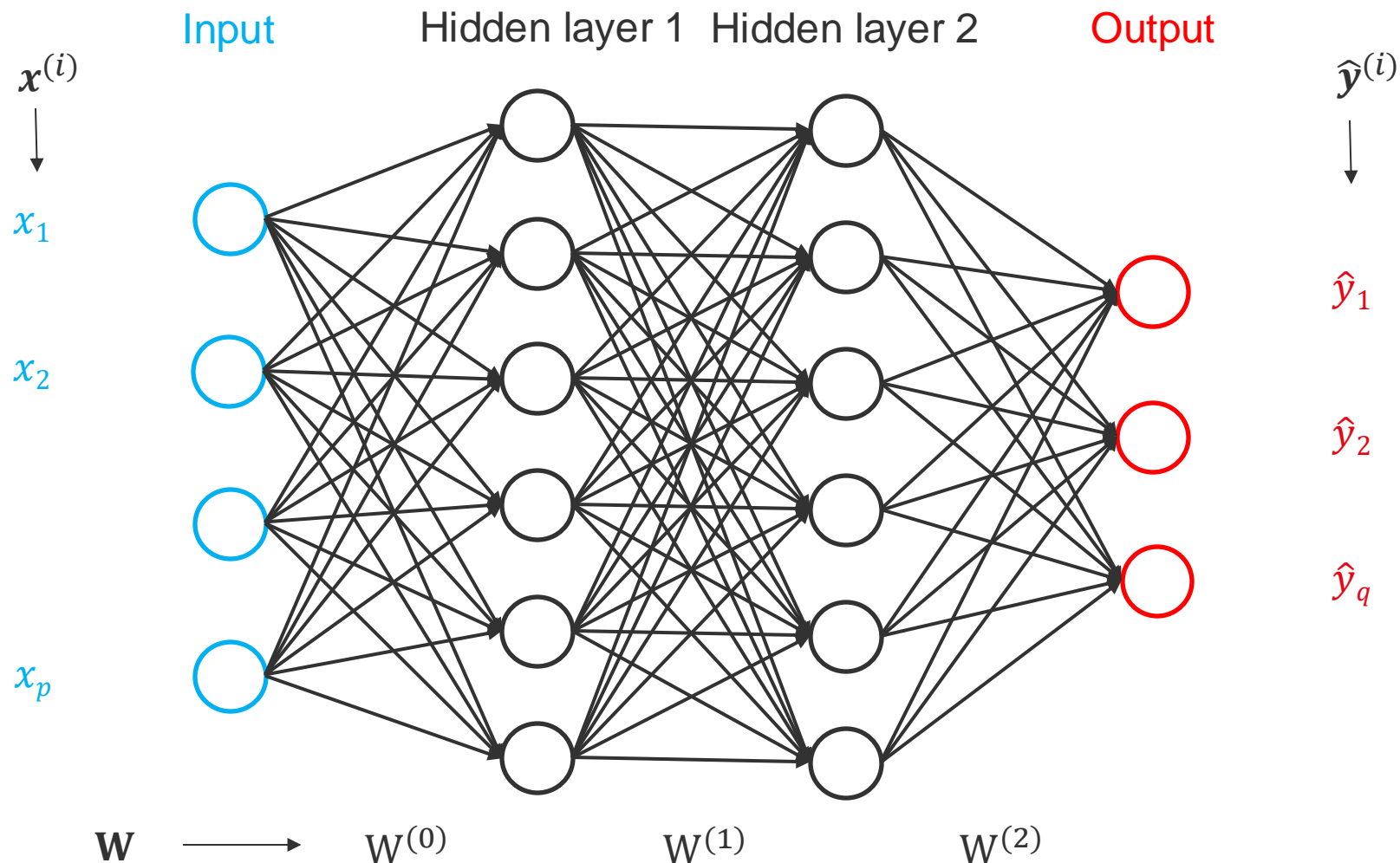
- Image compression, denoising and generation, recommendation system, anomaly detection, feature extraction
- Life sciences
  - dimensionality reduction (clustering) in sequencing data
  - multi-omics and biomedical data integration

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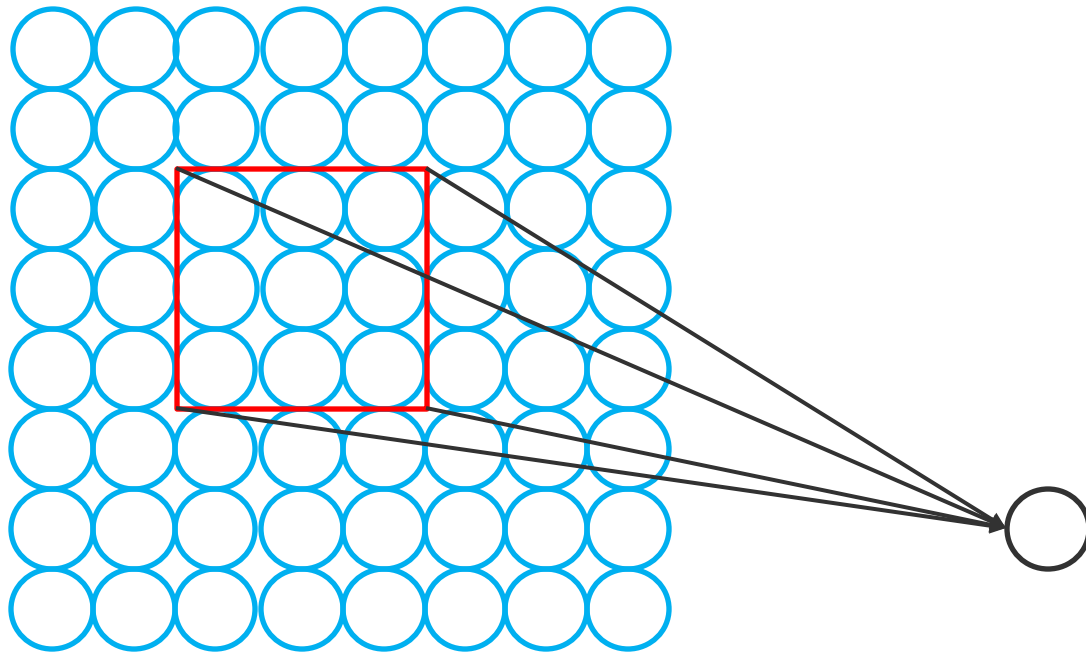
# Convolutional Neural Network (CNN, ConvNet)

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- Inspired by the organization of the visual cortex
- Image processing: take in image input => assign importance to features/objects => differentiate
- Each neuron receives connections only from a subset of neurons in the previous layer
- Spatial and temporal dependency

# CNN: How? Convolutional layer

---



# CNN: How? Convolutional layer

Input image

1	0	0	0	1
0	1	0	1	0
0	0	1	0	0
0	1	0	1	0
1	0	0	0	1

Filter

1	0	1
0	1	0
1	0	1

Feature map


Convolution operation: sum of element-wise products

# CNN: How? Convolutional layer

Input image

1	0	0	0	1
0	1	0	1	0
0	0	1	0	0
0	1	0	1	0
1	0	0	0	1

Filter

1	0	1
0	1	0
1	0	1

Feature map

3		

Convolution operation: sum of element-wise products



# CNN: How? Convolutional layer

Input image

1	0	0	0	1
0	1	0	1	0
0	0	1	0	0
0	1	0	1	0
1	0	0	0	1

Filter

1	0	1
0	1	0
1	0	1

Feature map

3	0	

Convolution operation: sum of element-wise products

# CNN: How? Convolutional layer

Input image

1	0	0	0	1
0	1	0	1	0
0	0	1	0	0
0	1	0	1	0
1	0	0	0	1

Filter

1	0	1
0	1	0
1	0	1

Feature map

3	0	3

Convolution operation: sum of element-wise products

# CNN: How? Convolutional layer

Input image

1	0	0	0	1
0	1	0	1	0
0	0	1	0	0
0	1	0	1	0
1	0	0	0	1

Filter

1	0	1
0	1	0
1	0	1

Feature map

3	0	3
0		

Convolution operation: sum of element-wise products

# CNN: How? Convolutional layer

Input image

1	0	0	0	1
0	1	0	1	0
0	0	1	0	0
0	1	0	1	0
1	0	0	0	1

Filter

1	0	1
0	1	0
1	0	1

Feature map

3	0	3
0	5	

Convolution operation: sum of element-wise products

# CNN: How? Convolutional layer

Input image

1	0	0	0	1
0	1	0	1	0
0	0	1	0	0
0	1	0	1	0
1	0	0	0	1

Filter

1	0	1
0	1	0
1	0	1

Feature map

3	0	3
0	5	0

Convolution operation: sum of element-wise products

# CNN: How? Convolutional layer

Input image

1	0	0	0	1
0	1	0	1	0
0	0	1	0	0
0	1	0	1	0
1	0	0	0	1

Filter

1	0	1
0	1	0
1	0	1

Feature map

3	0	3
0	5	0
3		

Convolution operation: sum of element-wise products

# CNN: How? Convolutional layer

Input image

1	0	0	0	1
0	1	0	1	0
0	0	1	0	0
0	1	0	1	0
1	0	0	0	1

Filter

1	0	1
0	1	0
1	0	1

Feature map

3	0	3
0	5	0
3	0	

Convolution operation: sum of element-wise products



# CNN: How? Convolutional layer

Input image

1	0	0	0	1
0	1	0	1	0
0	0	1	0	0
0	1	0	1	0
1	0	0	0	1

Filter

1	0	1
0	1	0
1	0	1

Feature map

3	0	3
0	5	0
3	0	3

Convolution operation: sum of element-wise products

# CNN: How? Convolutional layer

Input image

Filter

Feature map

1	0	0	0	1
0	1	0	1	0
0	0	1	0	0
0	1	0	1	0
1	0	0	0	1

1	0	1
0	1	0
1	0	1

3	0	3
0	5	0
3	0	3

Convolutional layers:

- Extract low to high-level features
- Reduce spatial size

1	0	0
0	1	0
0	0	1

0	0	1
0	1	0
1	0	0

Limitation: sensitive to position of features

`tensorflow.keras.layers.Conv2D`

# CNN: How? Pooling layer

- Down sampling: lower resolution + important features
- After Convolutional layer + Nonlinearity (ReLU) for each feature map
- Usually 2x2 pixels with stride of 2 pixels => reduce to  $\frac{1}{4}$  feature map
- Max or average pooling
- Invariance to local translation

1	3	1	0
0	4	2	1
5	3	0	2
0	0	4	2

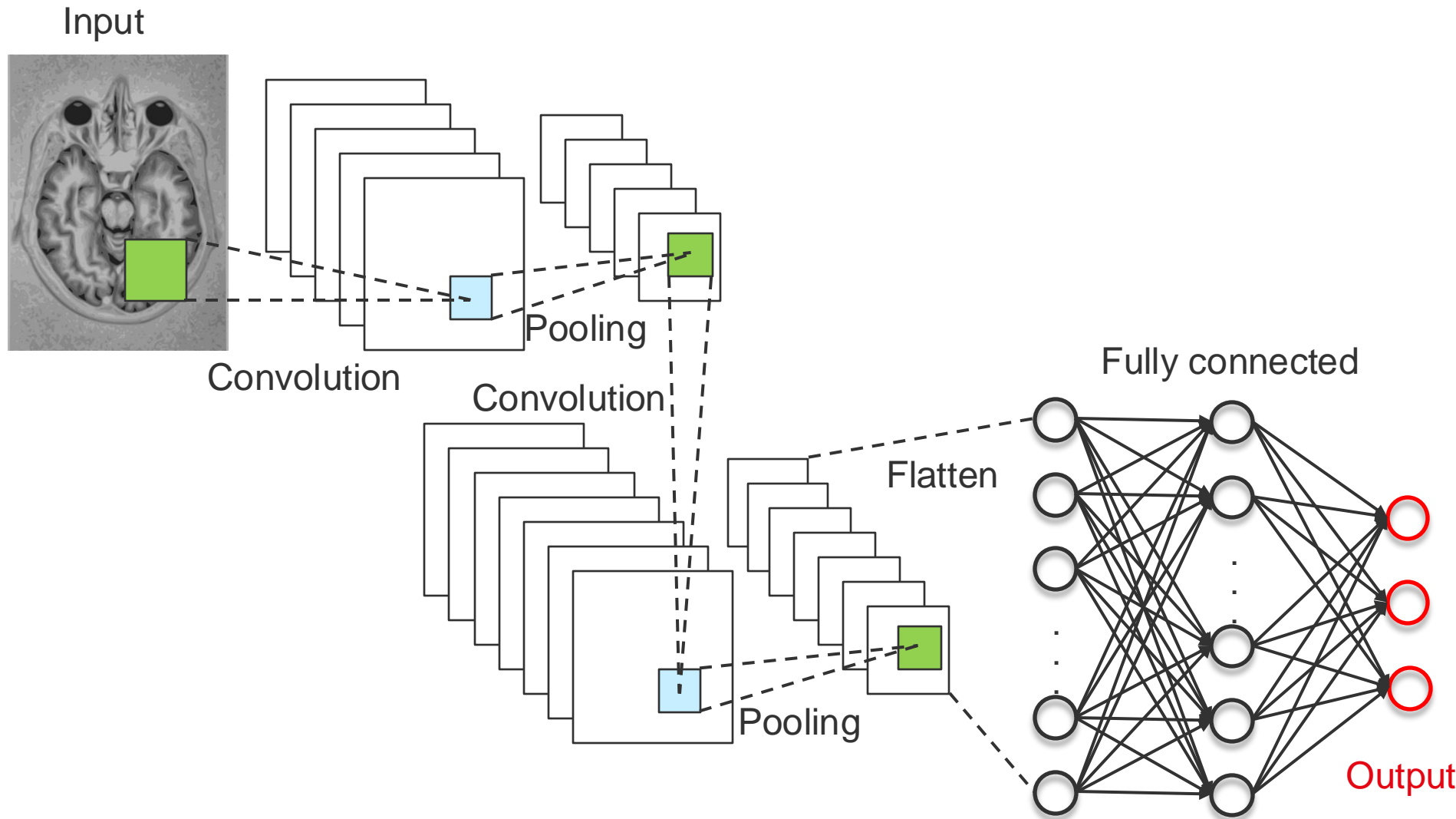
max  
average

4	2
5	4

2	1
2	2

`tensorflow.keras.layers.MaxPool2D`

# CNN: How? Fully connected layer



# CNN: When?

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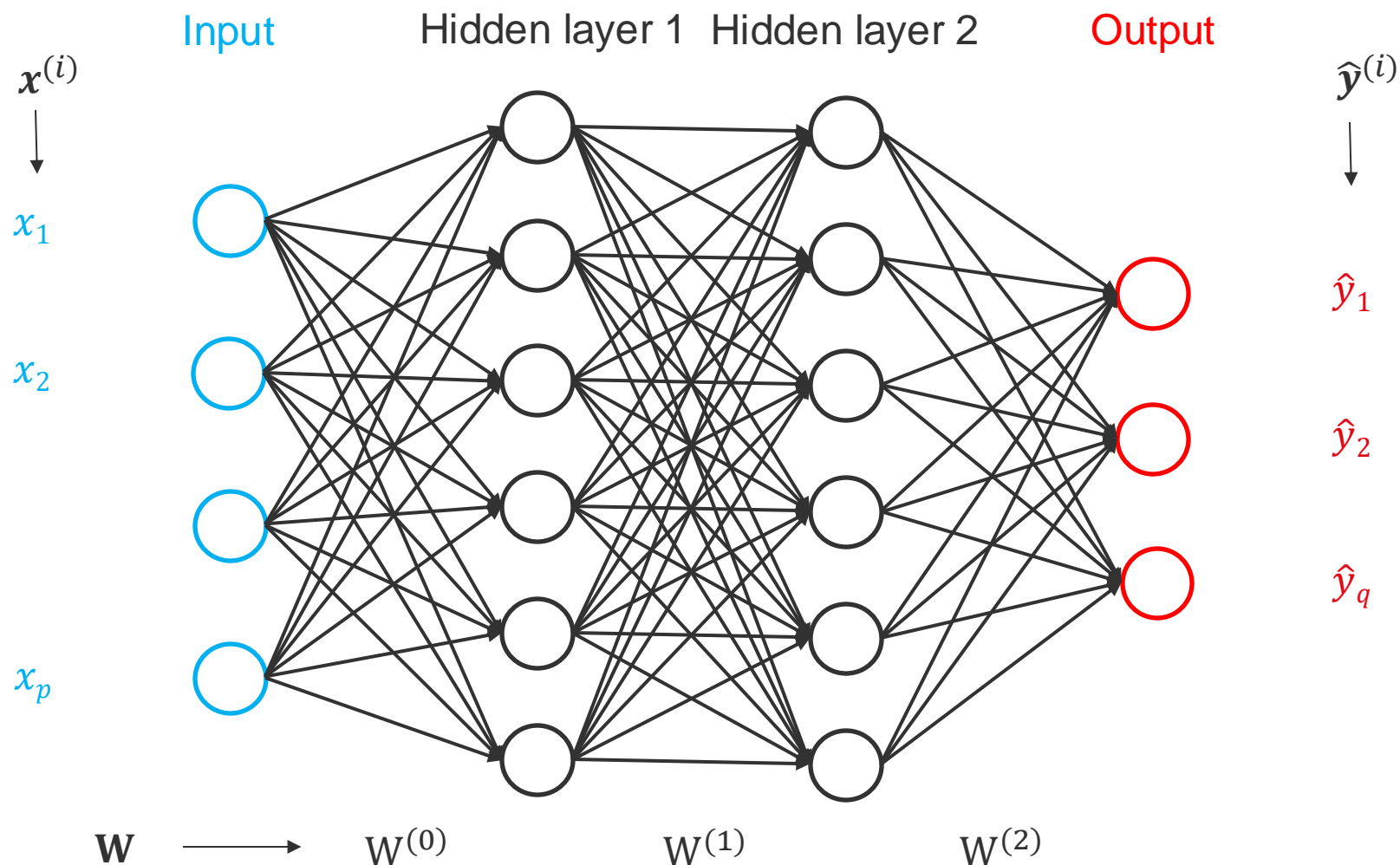
- Image recognition, video analysis, natural language processing
- Life sciences:
  - sequence analysis (DNA, RNA sequence data),
  - structure prediction (imaging data),
  - biomedical image processing and diagnosis (imaging data),
  - biomolecular function prediction (microarray, sequencing data, structure properties), protein variant impact prediction
  - biomolecule interaction prediction and system biology (microarray, interaction data)

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# Neural Network revisited



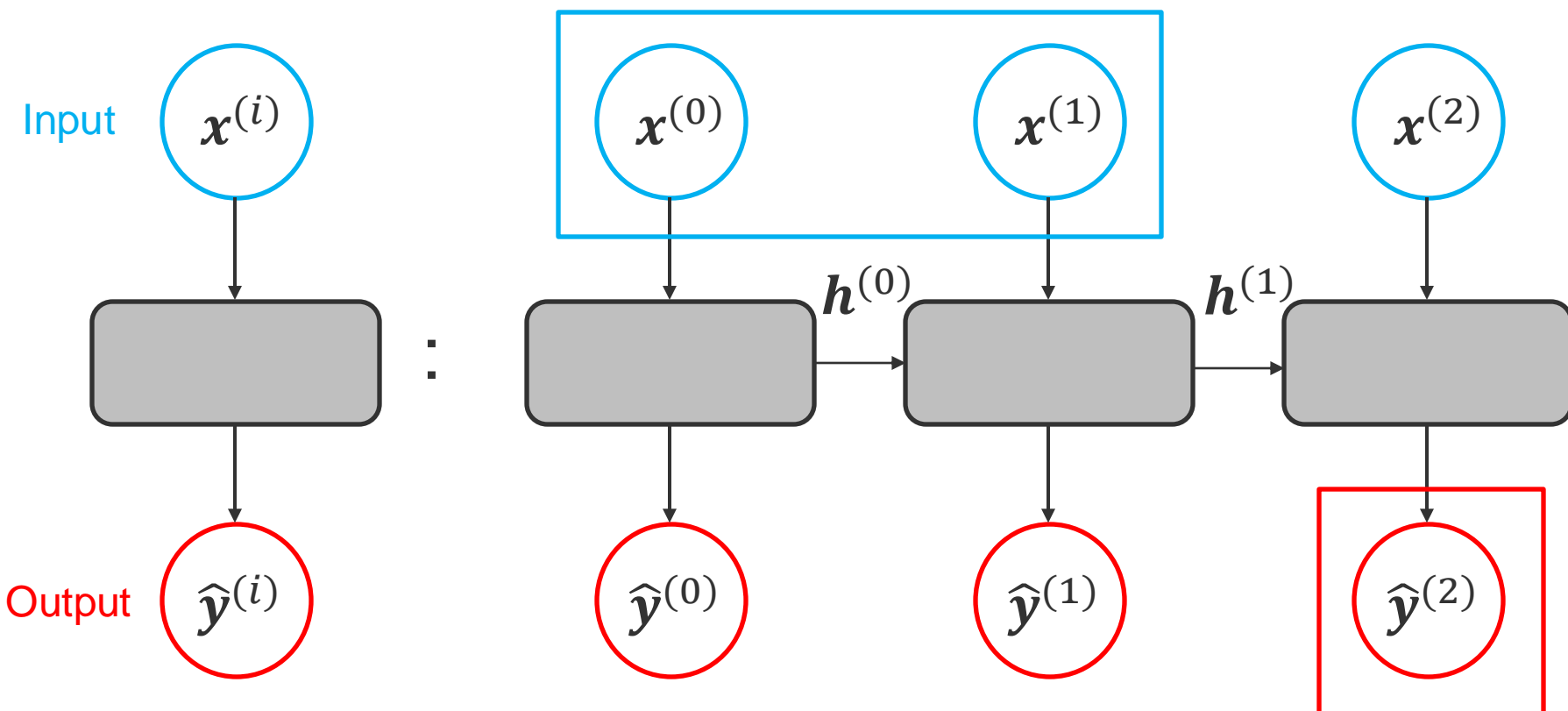
Activation functions on linear regressions

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# Neural Network with recurrence



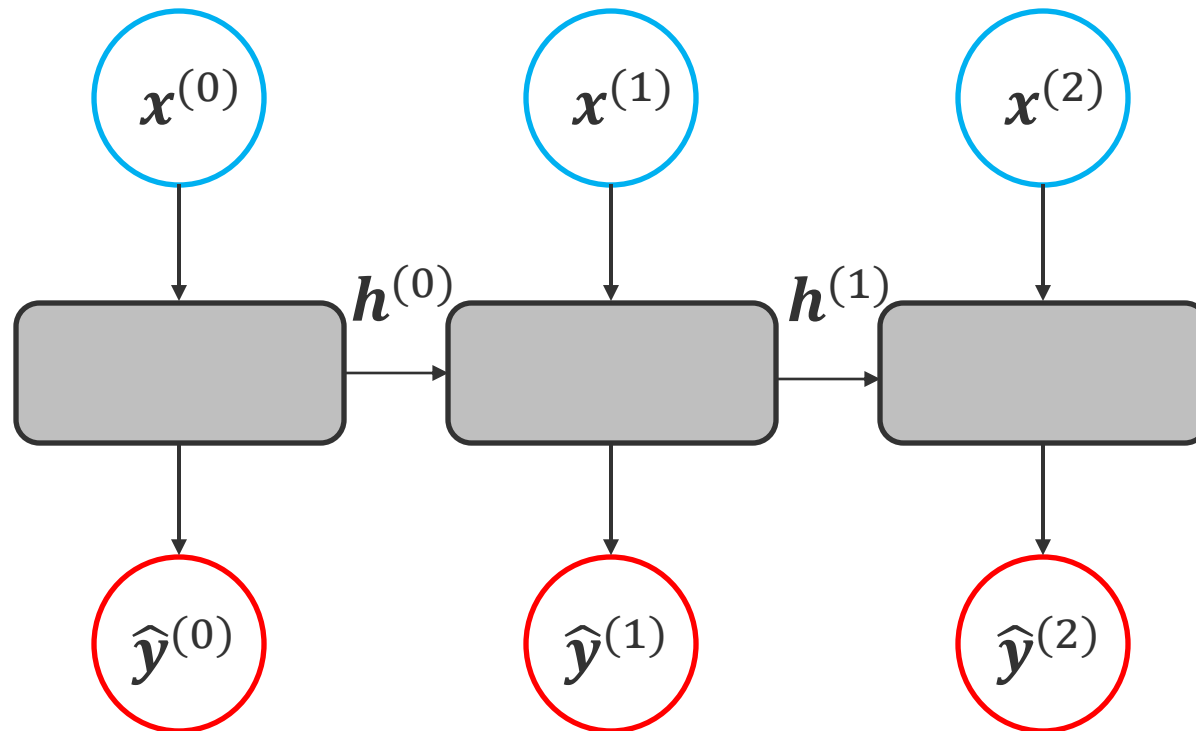
$$\hat{y}^{(i)} = f(x^{(i)})$$

$$\hat{y}^{(i)} = f(x^{(i)}, h_{i-1})$$

past memory

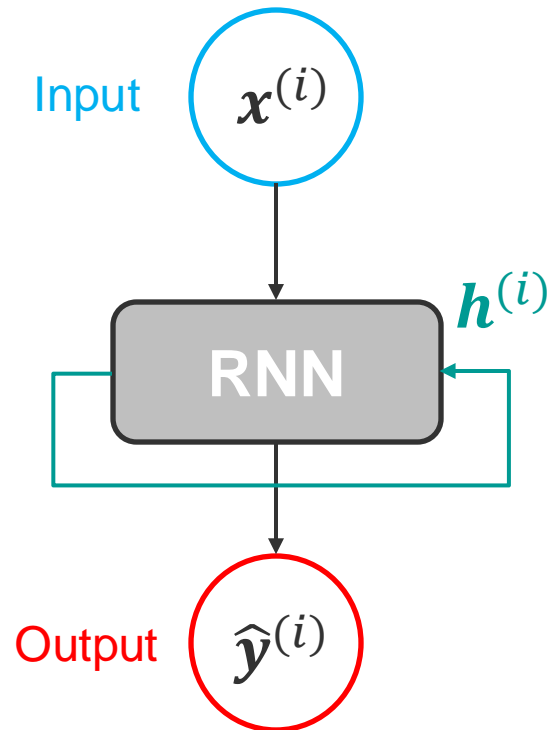
# Recurrent Neural Network (RNN)

- Sequential or time series data: data points depend upon previous data points
- Memory: store historical information to forecast future values

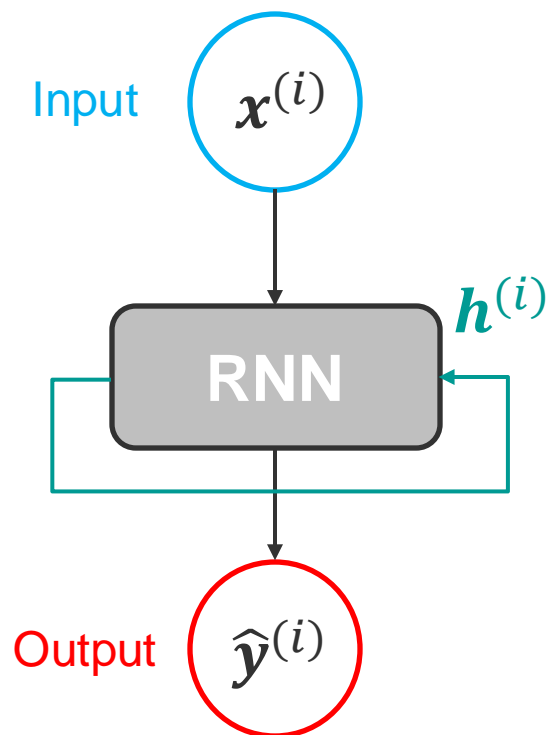


# Recurrent Neural Network (RNN)

- Sequential or time series data: data points depend upon previous data points
- Memory: store historic information to forecast future values

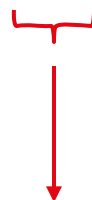


# RNN: How?



State  $h^{(i)}$  is updated at each time step with a recurrence relation:

$$h^{(i)} = f_w(x^{(i)}, h^{(i-1)})$$



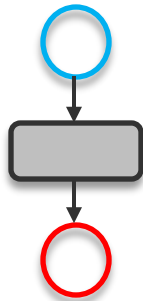
Same function (sigmoid, tanh, ReLU) and parameters at every time step!

$$h^{(i)} = f(W_x^T x^{(i)} + W_h^T h^{(i-1)} + b_h)$$

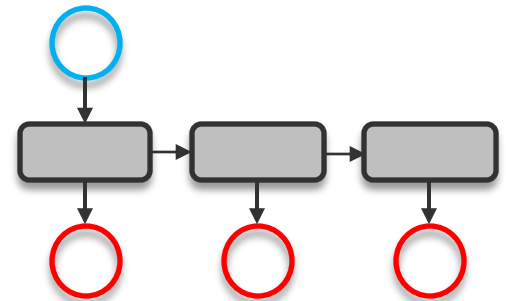
$$\hat{y}^{(i)} = f(W_y^T h^{(i)} + b_y)$$

# Types of RNNs

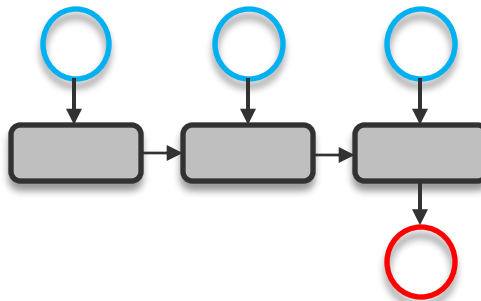
■ One to One



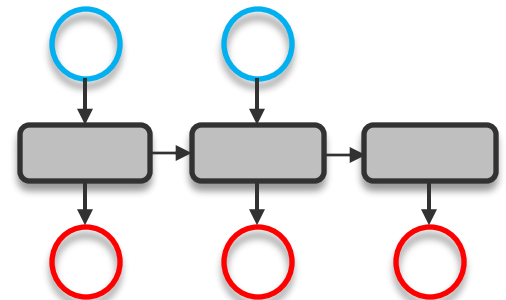
■ One to Many



■ Many to One

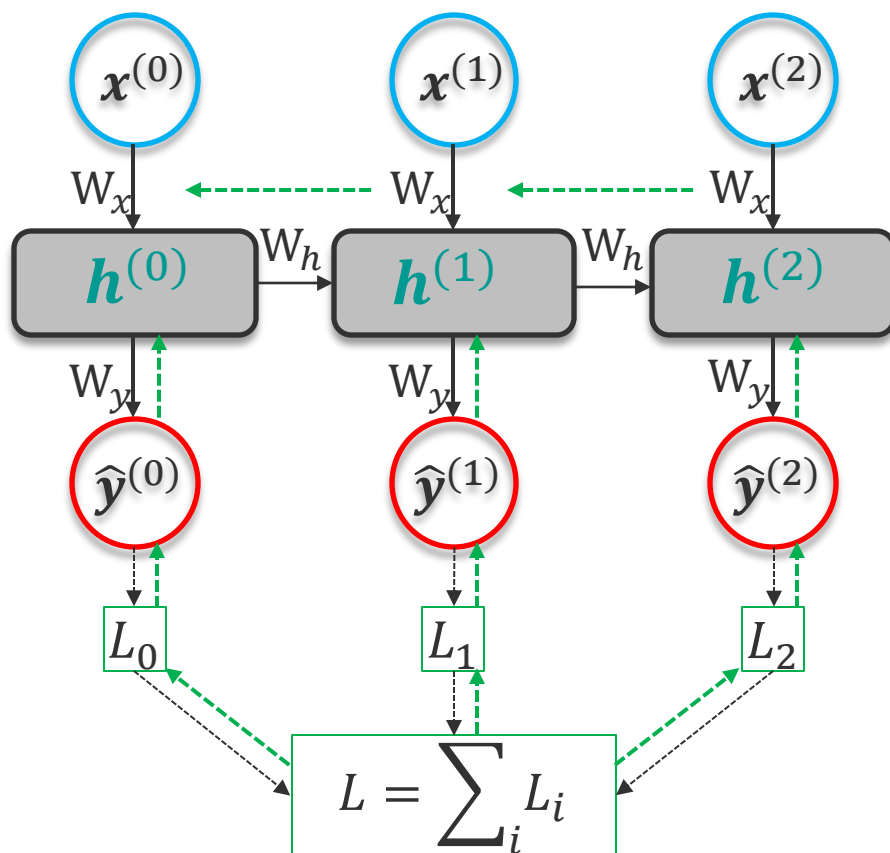


■ Many to Many



# Back propagation through time

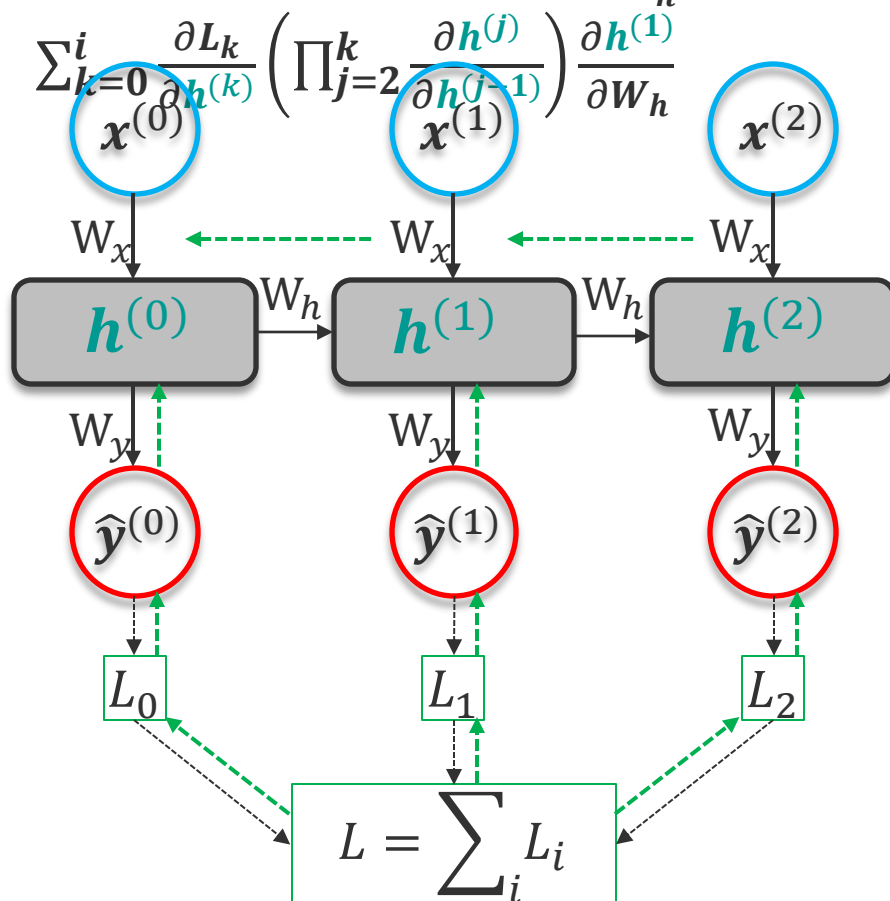
- Calculate gradient of the loss function w.r.t. each parameter backward through the network
- Adapt parameter to minimize loss



# Gradient issues

- Gradient w.r.t.  $W_h$  involves repeated computation of gradients w.r.t.  $h^{(i)}, h^{(i-1)}, \dots, h^{(1)}$

$\Rightarrow$  many factors of  $W_h$ :  $\frac{\partial L}{\partial W_h} = \sum_{k=0}^i \frac{\partial L_k}{\partial W_h} \propto$



$1.1^{100} \sim 1e+5$

## Exploding gradient:

when many values  $> 1$

$\Rightarrow$  Quickly reach infinity

$\Rightarrow$  Gradient clipping to scale large gradients

$0.9^{100} \sim 2e-5$

## Vanishing gradient:

when many values  $< 1$

$\Rightarrow$  Difficult to learn long period dependencies

$\Rightarrow$  Activation function, weight initialization, network structure



# Adapted network structure

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- “I grew up in France... I speak fluently (?)”
- Long Short-Term Memory Network: track information throughout many timesteps => memorize long-term dependencies
  - Memory cell: store information
  - Forget gate: what information to ignore
  - Input gate: which values from input to update memory state
  - Output gate: what to output based on input and memory state
  - Gate ~ neuron: activation of a weighted sum

# RNN: When?

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- Language translation, speech recognition, natural language processing
- Life sciences:
  - sequence analysis, genomic sequence evolution,
  - biomolecular function prediction
  - human-virus protein-protein interaction prediction,
  - biomedical ontologies,
  - forecast the spread of virus,
  - pharmaceutical development

# Outline

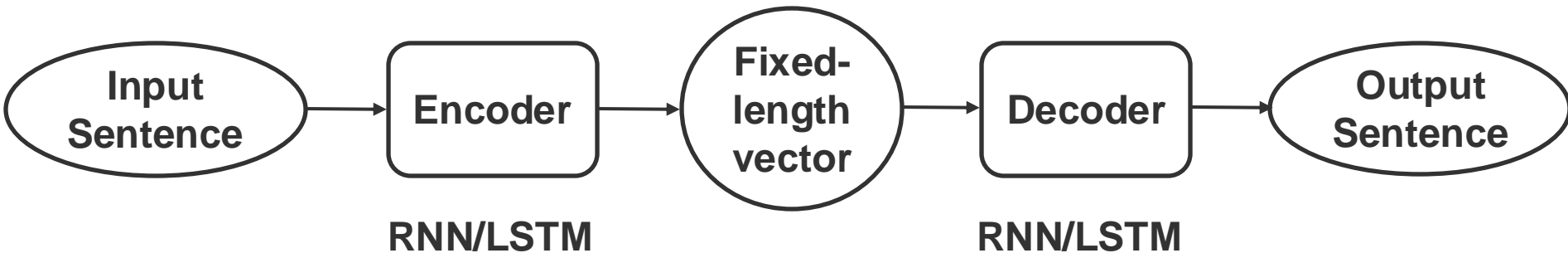
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- **Attention mechanism and transformers**
- Deep reinforcement learning
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# Attention

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## ■ Machine translation



*I do deep learning*

*I often find myself daydreaming about what I could do with deep pockets full of knowledge, learning from the depths of experience.*

Generated by ChatGPT

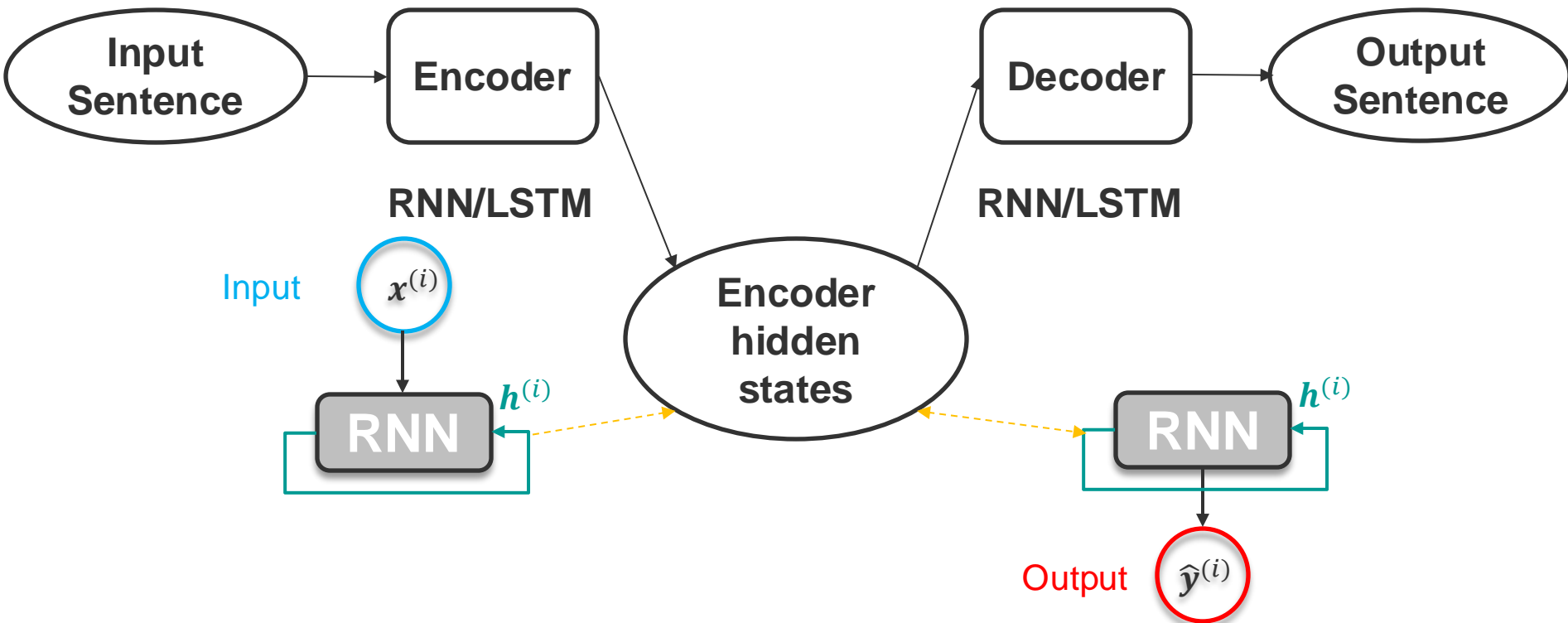
# Attention

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- Mimic cognitive attention
- Improve RNN drawbacks: favor recent elements, fail to handle long sequences
- Model dependency without regard to the distance between elements in the sequences

# Attention

## Machine translation



Global attention: all hidden states

Local attention: a few hidden states

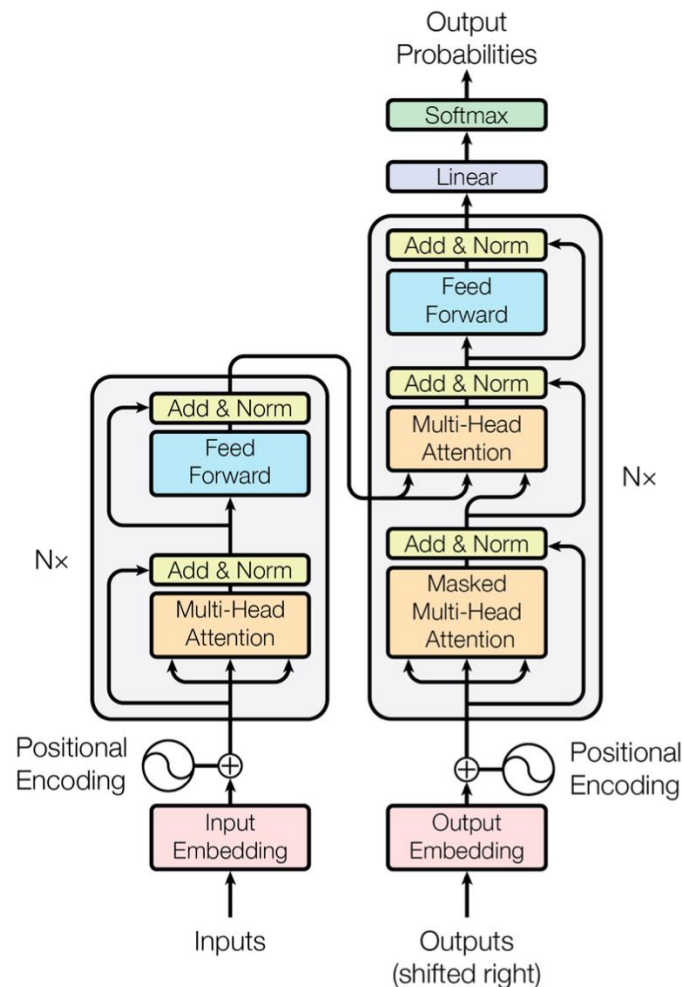
Hierarchical-nested attention: both word and sentence levels

# Transformer

- Encoder-Decoder using only Attention mechanism for global dependencies between input and output
- Self-attention
- Parallelized processing
- No recurrence or convolution

## Large Language Model

- Pre-trained autoencoding models: BERT (Bidirectional Encoder Representations from Transformers)
- Autoregressive models: GPT (Generative Pretrained Transformer)



# Application in life sciences

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- Sequence analysis, genome analysis
- Multi-omics, spatial transcriptomics
- Biomedical informatics
- Drug discovery
- Protein structure prediction
- Foundation model for human single-cell transcriptomics, human genomics



# Outline

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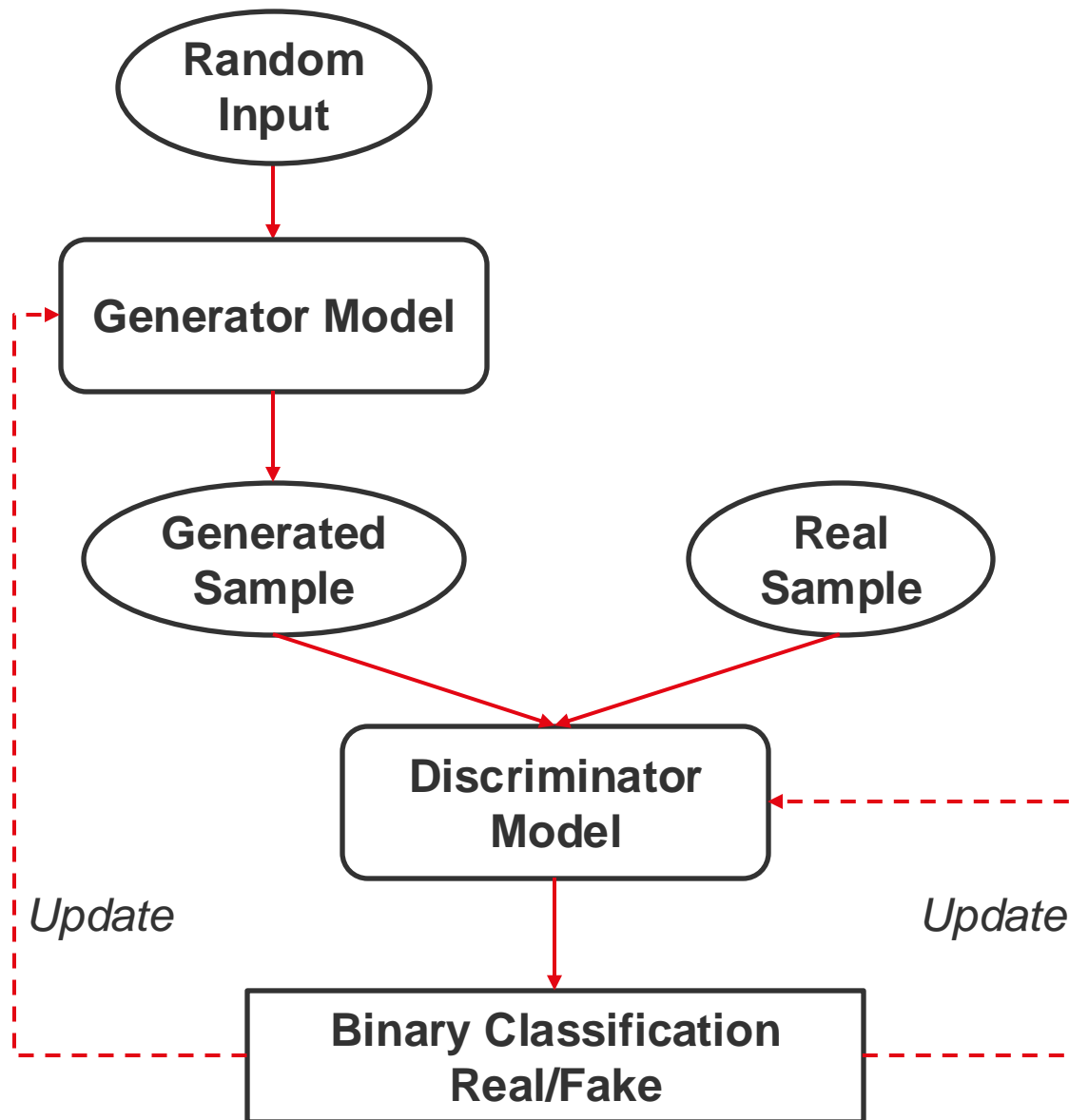
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# Generative Adversarial Network (GAN)

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- Deep-learning-based generative model
- Data augmentation
- Generator: generate new plausible examples from the problem domain.
- Discriminator: classify examples as real (from the domain) or fake (generated).

# GAN: How?



# GAN: When?

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- Digital image processing
- Life sciences:
  - Medical imaging processing
  - Medical informatics: generating discrete data based on real medical data, addressing imbalanced samples problem
  - Generating scRNA-seq data, genomic sequences, compound and protein designs

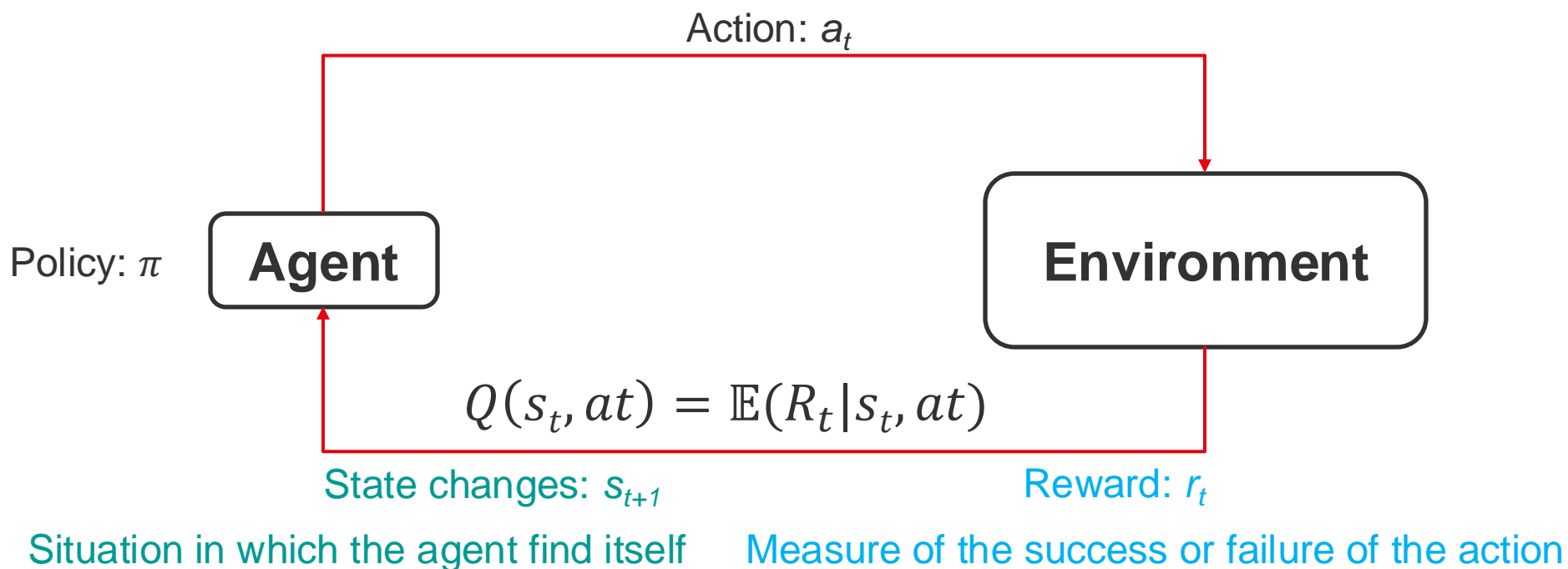
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# Reinforcement Learning

- Reinforcement learning: learning to make decisions through trial and error → Goal: *to act*

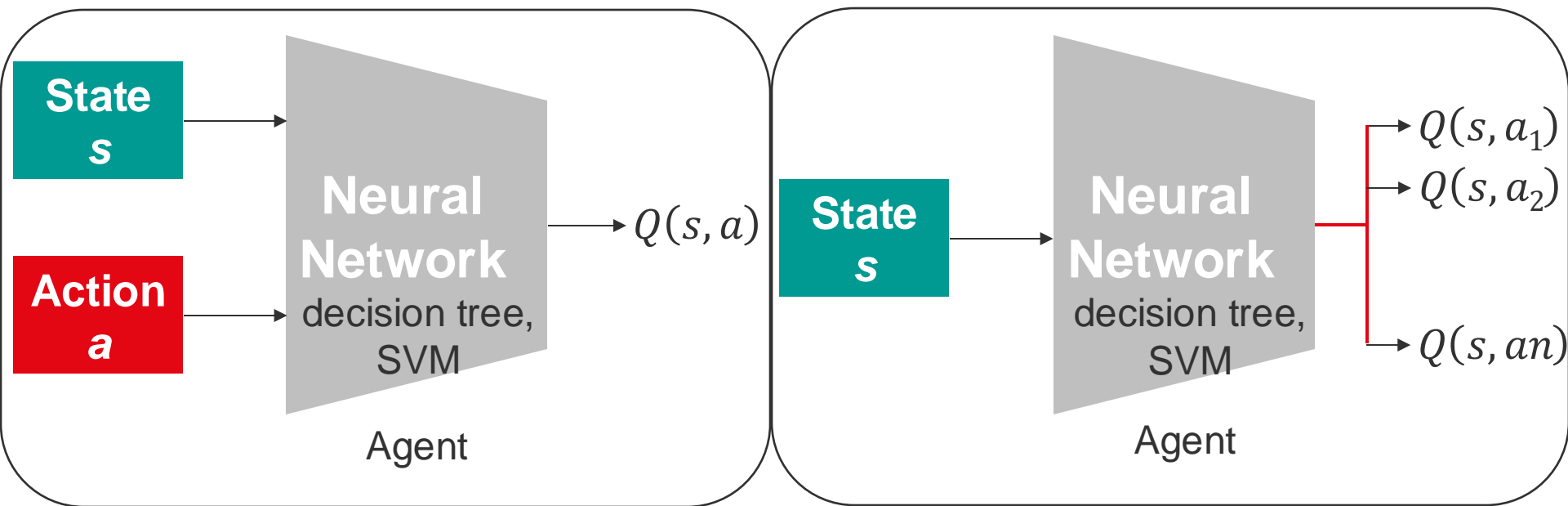


Total Reward (return):  $R_t = \sum_{i=t}^{\infty} r_i$

Discounted Total Reward (return):  $R_t = \sum_{i=t}^{\infty} \gamma^i r_i$

# Deep Reinforcement Learning

- Large state and action spaces
- Map states and actions to Q values



Action + State  $\rightarrow$  Expected Return

State  $\rightarrow$  Expected Return for each action

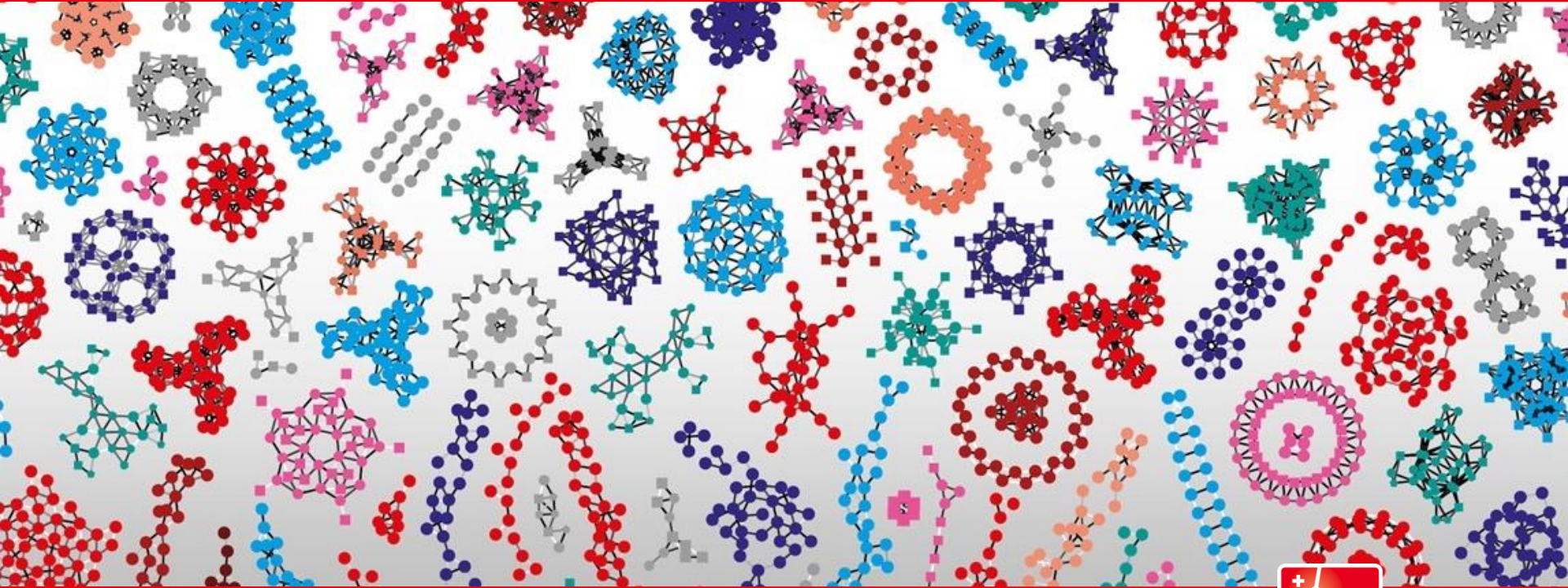
Use neural networks to learn Q, then infer the optimal policy  $\pi(s)$

# Deep Reinforcement Learning: When?

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- Recommendation systems, robotics, energy smart grids
  
- Life sciences
  - biological sequence annotation,
  - biological data mining,
  - prediction of bacterial genomes,
  - protein-protein interaction,
  - segmentation in medical imaging,
  - brain machine interface





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# Thank you!