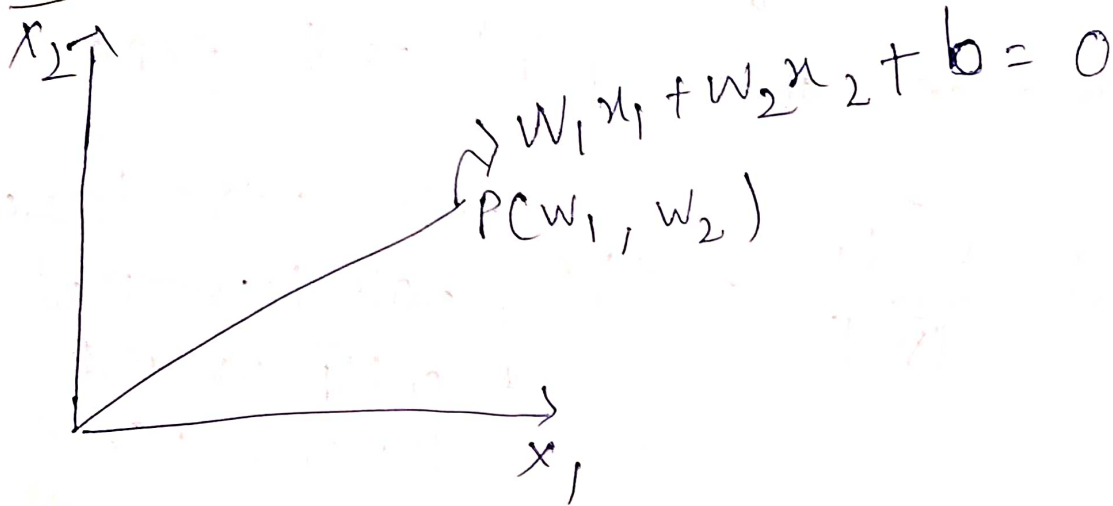


# Support Vector Machine (SVM)

- ① Classification  $\rightarrow$  SVC (Support Vector Classifier)
- ② Regression  $\rightarrow$  SVR (Support Vector Regressor)

basics

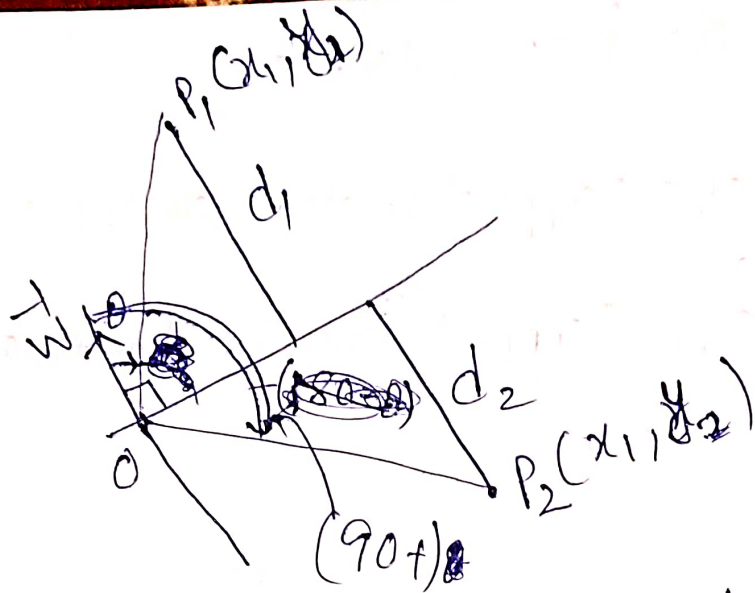


$$w_1x_1 + w_2x_2 + b = 0$$

$$\Rightarrow w^T x + b = 0 \quad \left[ \begin{array}{c} w_1x_1 + w_2x_2 \\ \begin{bmatrix} w_1 \\ w_2 \end{bmatrix} \begin{bmatrix} x_1 & x_2 \end{bmatrix} \end{array} \right]$$

$$\Rightarrow w^T x = 0 \quad [\because \text{intercept } b = 0]$$

$\downarrow$   
equation of a line passing through origin.



Distance of a point to the plane

is  $d_1 = \frac{w^T P_1}{\|w\|} = +ve$  [always +ve because angle between  $\vec{w}$  and  $\vec{OP_1}$  always less than  $90^\circ$ ]

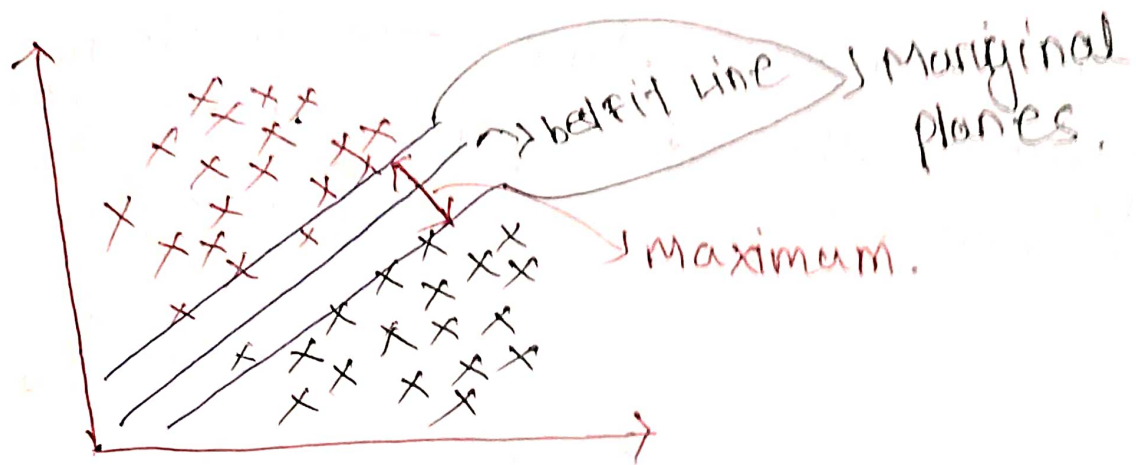
$d_2 = \frac{w^T P_2}{\|w\|} = -ve$  [angle between  $\vec{w}$  and  $\vec{OP_2}$  is always greater than  $90^\circ$ ]

## Geometric Intuition Behind SVM



best fit line as per Logistic regression.

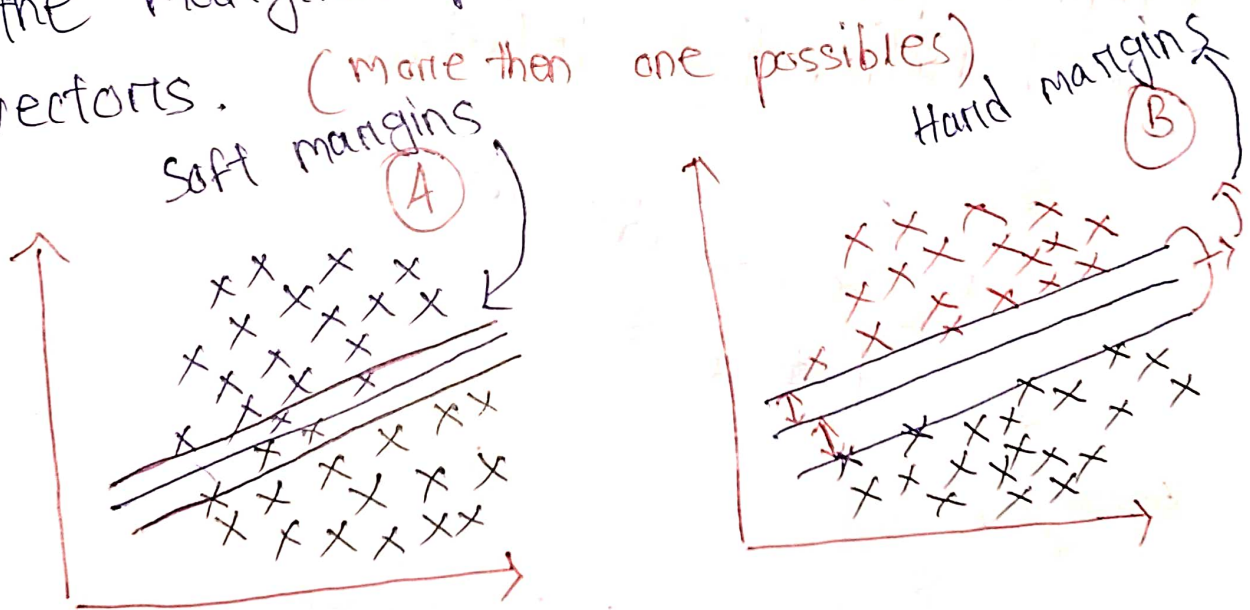
with Support vector classifier



→ Along with the best fit Line we try to make two marginals planes such that distance between two planes is maximum.

### Support vectors

The lines on which data points touches the marginal plane is called support vectors. (more than one possible)

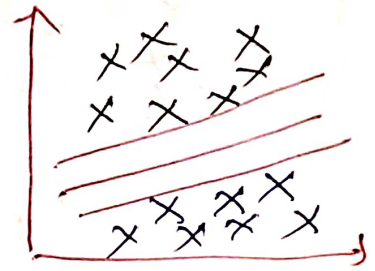


Q which is better marginal planes (A or B)  
definitely B is better because it has maximum marginal distance.



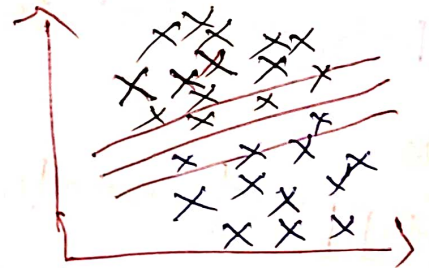
## Hard margins (without errors)

If the marginal plane able to clearly separate the data points it called hard margins

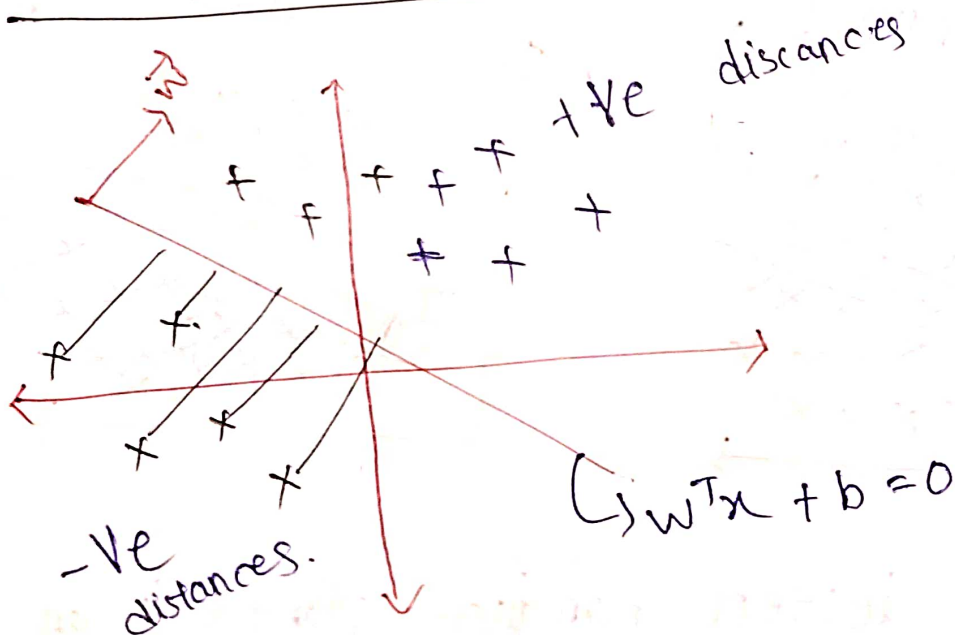


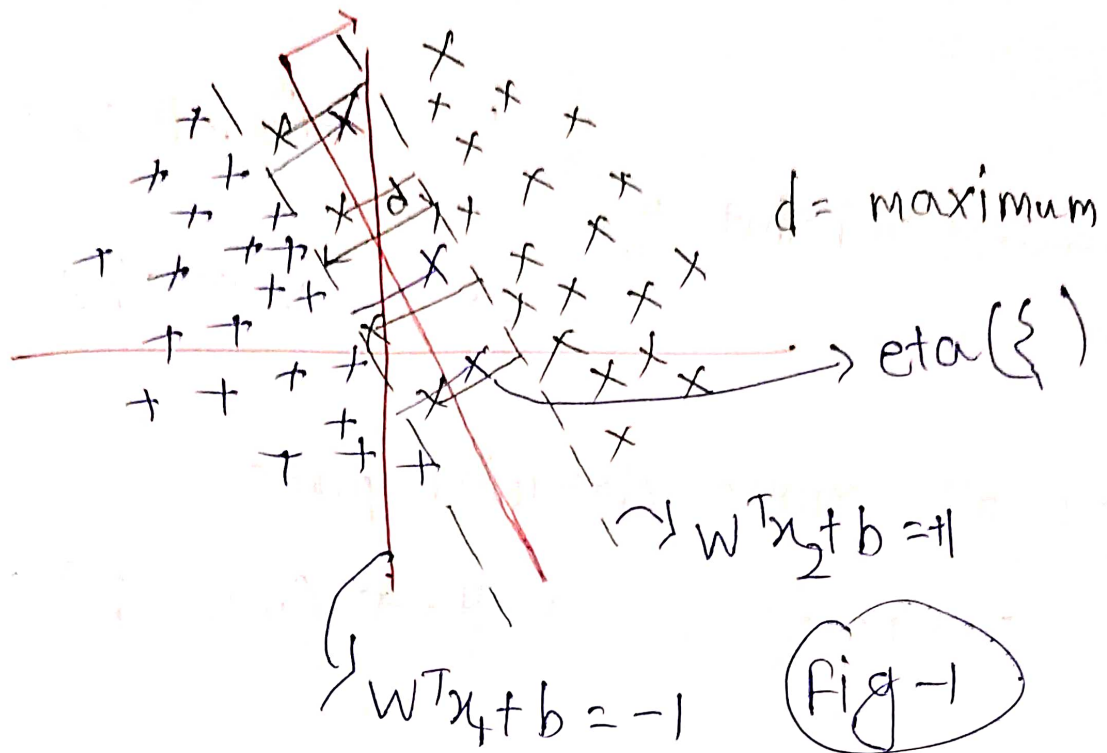
## Soft margins (with errors)

If the plane not able to clearly separate the data points then it's called soft margin



→ In real life we get soft margins  
→ marginal planes are equidistant ( $d_1 = d_2$ )  
SVM mathematical Intuition





$$w^T x_1 + b = +1$$

$$w^T x_2 + b = -1$$

$$\Rightarrow w^T (x_1 - x_2) = 2$$

$$\Rightarrow \frac{w^T (x_1 - x_2)}{\|w\|} = \frac{2}{\|w\|} \quad \left( \begin{array}{l} \text{for converting it to} \\ \text{unit vector we divide} \\ \|w\| \end{array} \right)$$

Cost function

Maximize  $\frac{2}{\|w\|}$  by changing  $w, b$

distance between marginal planes.

constraint such that  $y_i \begin{cases} 1 & w^T x + b \geq 1 \\ -1 & w^T x + b \leq -1 \end{cases}$

For all correct classified points

constraints  $\longrightarrow y_i * (w^T x + b) \geq 1$

maximize  $\frac{2}{\|w\|}$  with changing  $w, b$   
 $\Downarrow$

minimize  $\frac{\|w\|}{2}$  by changing  $w, b$

So

cost function

$$\min_{w, b} \frac{\|w\|}{2} + \boxed{C_i \sum_{i=1}^n \xi_i}$$

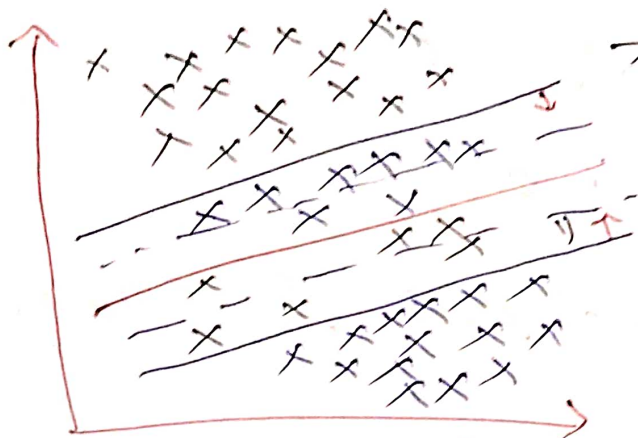
soft margins  $\swarrow$  eta  
 $\nwarrow$   
 $\Downarrow$   
 Hinge loss

$C_i$  = How many points we can ignore for misclassification

For fig-1 its  $C_i = 7$

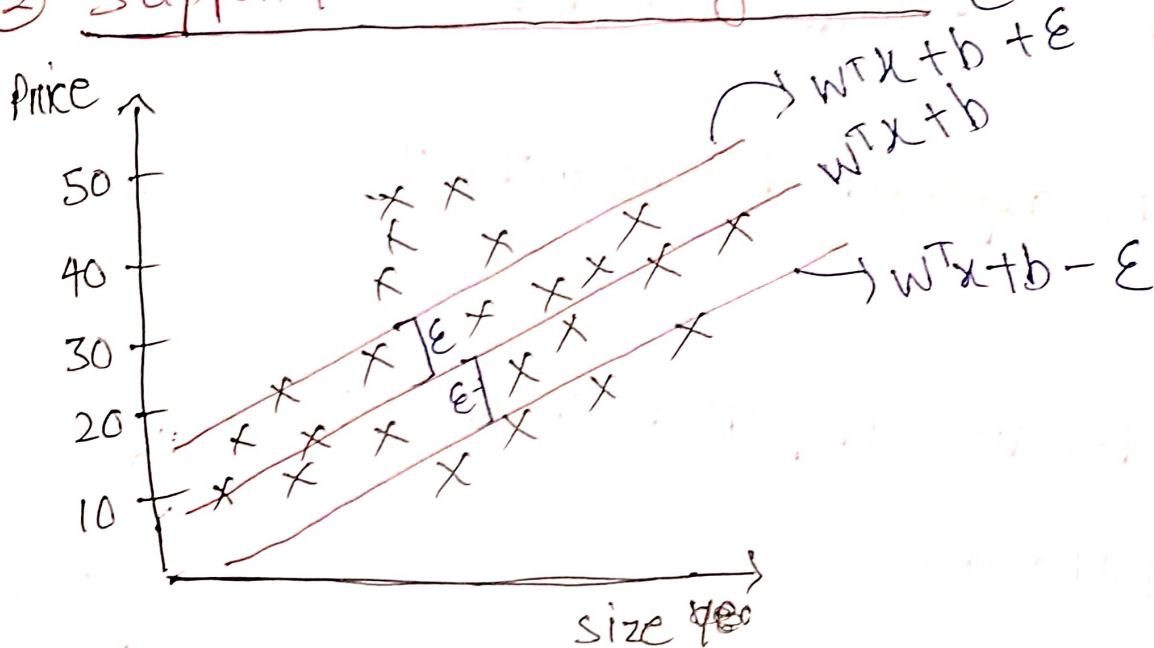


$\sum_i$  = summation of the distance of incorrect data points from the marginal points.



→ As both  $C_i$  &  $\epsilon$  is high for this plot we can reduce this by closing marginal planes.

## ② Support Vector Regressor (SVR)



$\epsilon$  = Marginal error from best fit line.

Cost function

$$\underset{w, b}{\text{minimize}} \quad \frac{\|w\|^2}{2} + \left[ C_i \sum_{i=1}^n \epsilon_i \right] \rightarrow \text{Hinge Loss}$$

## Constraint

$$|y_i - w_i x_i| \leq \epsilon + \xi_i$$

for point lies inside  $\epsilon$

$$|y_i - w_i x_i| \leq \epsilon$$

for point lies outside  $\epsilon$ ,  $\xi_i$  (eta) added

$$|y_i - w_i x_i| \leq \epsilon + \xi_i$$

$\epsilon \rightarrow$  marginal error

$\xi \rightarrow$  Error outside margin.

Q. SVM impacted by outliers?

$\rightarrow$  yes

Q. Standardize required or not?

$\rightarrow$  Required.

## SVM kernels

In this figure our  
line not able to  
classify data points  
(accuracy 50% or less)

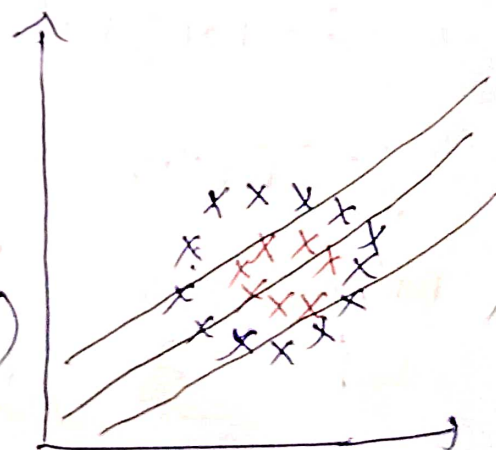
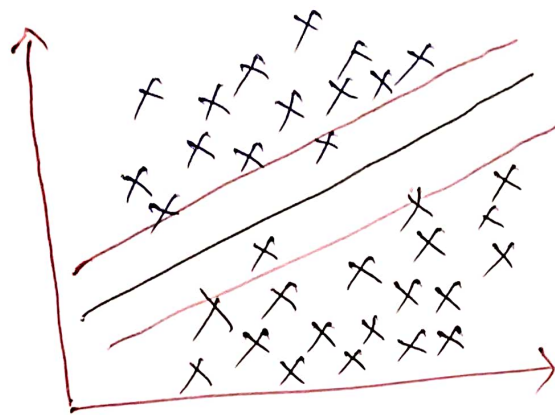


fig-2



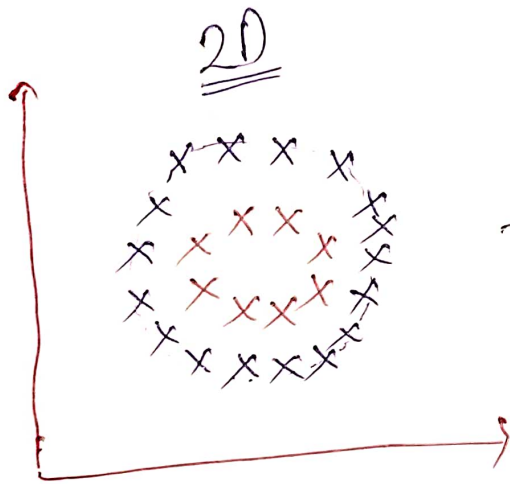
for that we use different transformation  
convert to 3D by using SVM kernels.

examples

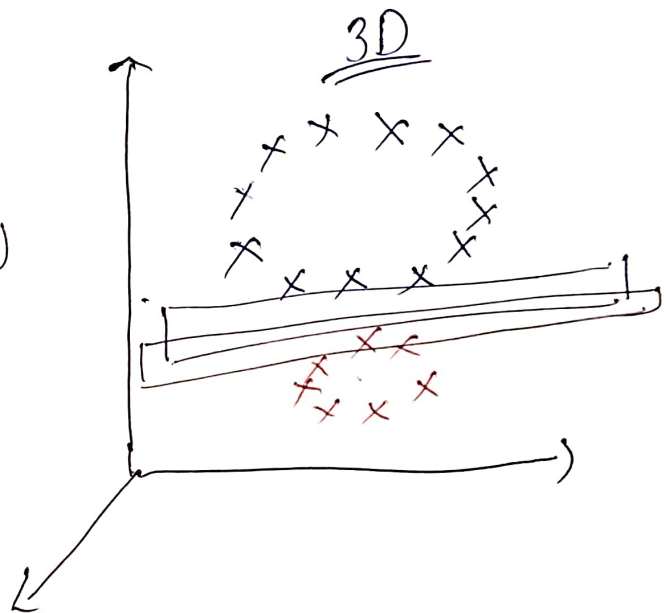


Kernel  
↓  
Linear SVC

kernel = linear.



→



Types

- ① polynomial kernel
- ② RBF Kernel (default)
- ③ sigmoid kernel.
- ④ Linear (~~default~~)