

# Fundamentals of Control Systems

MECH 420 / ELEC 436

Department of Mechanical Engineering

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Prof. Fathi H. Ghorbel

## 3. Laplace Transform Domain

## MATHEMATICAL BACKGROUND

Mass-spring-damper equation

$$m \frac{d^2 y(t)}{dt^2} + c \frac{dy(t)}{dt} + ky(t) = f(t) + \frac{df(t)}{dt}$$

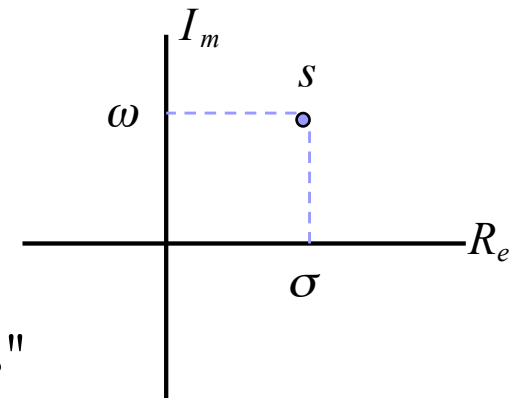
Take Laplace Transform and assume zero initial conditions

$$\frac{Y(s)}{F(s)} = \frac{s + 1}{ms^2 + cs + k} = \frac{\text{Output}}{\text{Input}}$$

# MATHEMATICAL BACKGROUND

## 1. Complex Variables

- $s = \sigma + j\omega$        $\sigma$  : real  
                                  $\omega$  : imaginary



- $G(s)$  is a function of the complex variable "s"  
 $\Rightarrow G(s) = R_e[G(s)] + jI_m[G(s)]$

Analytic function: A function  $G(s)$  of  $s$  is called an analytic function in a region of the  $s$ -plane if  $G(s)$  and all its derivatives (Cauchy-Riemann condition) exist in the region.

$$\text{Ex. } G(s) = \frac{1}{(s+1)(s+2)} \quad G(s) \rightarrow \infty \text{ as } s \rightarrow -2 \text{ and/or } s \rightarrow -1$$

$G(s)$  is analytic at every point in the  $s$ -plane except at  $s = -2$  and  $s = -1$

## Poles of a function of complex variables

$G(s)$ : analytic and single-valued near  $s_i$

$G(s)$  has a pole of order "r" at  $s = s_i$  if

$\lim_{s \rightarrow s_i} [(s - s_i)^r G(s)]$  is finite and nonzero

If  $r = 1$ ,  $s = s_i \leftarrow$  simple pole

$$\text{Ex. } G(s) = \frac{s + 1}{s(s + 10)^2(s + 2)}$$

has: - pole of order 2 @  $s = -10$   
- simple poles @  $s = 0$  and  $s = -2$

## Zeros of a function of complex variables


$G(s)$  analytic @  $s = s_i$

$G(s)$  has a zero of order "r" @  $s = s_i$  if

$\lim_{s \rightarrow s_i} [(s - s_i)^{-r} G(s)]$  is finite and nonzero

$$\text{Ex. } G(s) = \frac{s + 1}{s(s + 10)^2(s + 2)}$$

has: simple zero @  $s = -1$



For a rational function of  $s$ , i.e.  $\frac{\text{Polynomial of } s}{\text{Polynomial of } s} = \frac{Q(s)}{P(s)}$

# of poles = # of zeros

Example :

$$G(s) = \frac{s + 1}{s(s + 10)^2(s + 2)}$$

Poles = 0, -10, -10, -2

Zeros = -1,  $\infty$ ,  $\infty$ ,  $\infty$

$$\left( \lim_{s \rightarrow \infty} G(s) = \lim_{s \rightarrow \infty} \frac{1}{s^3} = 0 \right)$$

## 2. Laplace Transform

$f(t)$  = real function

$$F(s) = \mathcal{L}[f(t)] = \int_0^{\infty} f(t)e^{-st} dt \quad \leftarrow \text{Laplace Transform of } f(t)$$

$$f(t) = \mathcal{L}^{-1}[F(s)] \quad \leftarrow \text{Inverse Laplace Transform}$$

### • Properties:

$$\mathcal{L}[kf(t)] = kF(s) \quad k = \text{constant}$$

$$\mathcal{L}[f_1(t) \pm f_2(t)] = F_1(s) \pm F_2(s)$$

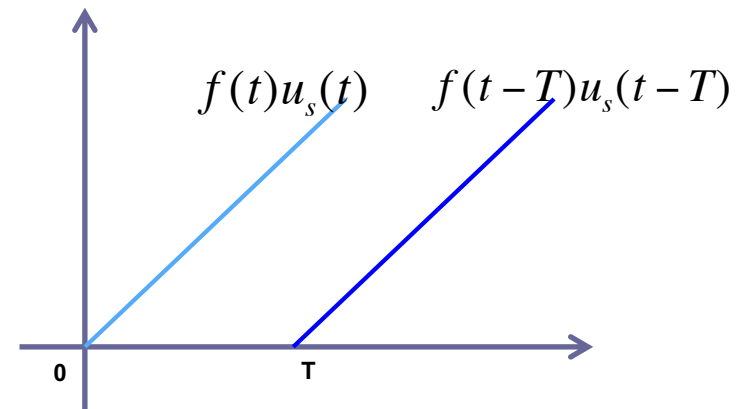
$$\mathcal{L}\left[\frac{d^n f(t)}{dt^n}\right] = s^n F(s) - s^{n-1}f(0) - s^{n-2}\frac{df}{dt}(0) - \dots - \frac{d^{n-1}f(0)}{dt^{n-1}}$$

$$\text{So } \mathcal{L}(\dot{f}) = sF(s) - f(0)$$

$$\mathcal{L}\left[\int_0^{t_1} \int_0^{t_2} \dots \int_0^{t_n} f(\tau) d\tau dt_1 dt_2 \dots dt_{n-1}\right] = \frac{F(s)}{s^n}$$

$$\text{So } \mathcal{L}\left[\int_0^{t_1} f(\tau) d\tau\right] = \frac{F(s)}{s}$$

$$\mathcal{L}[f(t-T)u_s(t-T)] = e^{-Ts}F(s) \quad \text{shift in Time by } T$$



- Property: Initial Value Theorem:

$$\lim_{t \rightarrow 0} f(t) = \lim_{s \rightarrow \infty} sF(s) \quad \text{If the time limit exists}$$

$$e^{-\alpha t} \leftrightarrow \frac{1}{s + \alpha} \quad ; \quad sF(s) = \frac{s}{s + \alpha} = \frac{1}{1 + \frac{\alpha}{s}}$$

- Property: Final Value Theorem:

Provided all of the poles of  $[sF(s)]$  lie strictly in the left half plane

$$\lim_{t \rightarrow \infty} f(t) = \lim_{s \rightarrow 0} sF(s)$$

$$\text{Ex. } F(s) = \frac{5}{s(s+1)} \quad ; \quad sF(s) = \frac{5}{s+1} \Rightarrow \lim_{t \rightarrow \infty} f(t) = \lim_{s \rightarrow 0} sF(s) = 5$$

$$F(s) = \frac{\omega}{s^2 + \omega^2} \quad ; \quad sF(s) = \frac{s\omega}{s^2 + \omega^2} \leftarrow \text{has poles on the imaginary axis}$$

$\Rightarrow$  Final value Thm can not apply. In fact,  $f(t) = \sin(\omega t)$

- Properties-continued

$$\mathcal{L}[e^{\pm \alpha t} f(t)] = F(s \pm \alpha) \quad \leftarrow \text{Complex Shifting}$$

$$\mathcal{L}[\underbrace{f_1(t) * f_2(t)}] = F_1(s)F_2(s) \quad \leftarrow \text{Convolution}$$

$$\int_0^t f_1(\tau) f_2(t - \tau) d\tau = \int_0^t f_2(\tau) f_1(t - \tau) d\tau$$

## Partial-Fraction Expansion

(Useful in inverse Laplace transform)

$$X(s) = \frac{Q(s)}{P(s)}$$

Case 1: All poles are simple and real

$$\begin{aligned} X(s) &= \frac{5s + 3}{(s + 1)(s + 2)(s + 3)} \\ &= \frac{K_1}{s + 1} + \frac{K_2}{s + 2} + \frac{K_3}{s + 3} \end{aligned}$$

$$\begin{aligned} K_1 &= (s + 1)X(s)\big|_{s=-1} \\ &= \frac{5(-1) + 3}{(-1 + 2)(-1 + 3)} = -1 \end{aligned}$$

$$\begin{aligned} K_2 &= (s + 2)X(s)\big|_{s=-2} \\ &= \frac{5(-2) + 3}{(-2 + 2)(-2 + 3)} = 7 \end{aligned}$$

$$\begin{aligned} K_3 &= (s + 3)X(s)\big|_{s=-3} \\ &= \frac{5(-3) + 3}{(-3 + 2)(-3 + 3)} = -6 \end{aligned}$$

Case 2: Some poles are of multiple order

$$\begin{aligned} X(s) &= \frac{1}{s(s + 1)^3(s + 2)} \\ &= \frac{K_0}{s} + \frac{K_1}{s + 2} + \frac{A_1}{(s + 1)} + \frac{A_2}{(s + 1)^2} + \frac{A_3}{(s + 1)^3} \end{aligned}$$

$$K_0 = sX(s)\big|_{s=0} = \frac{1}{2}$$

$$K_1 = (s + 2)X(s)\big|_{s=-2} = \frac{1}{2}$$

$$A_3 = (s + 1)^3 X(s)\big|_{s=-1} = -1$$

$$A_2 = \frac{d}{ds} [(s + 1)^3 X(s)]\big|_{s=-1} = \frac{d}{ds} \left[ \frac{1}{s(s + 2)} \right]\bigg|_{s=-1} = 0$$

$$A_1 = \frac{1}{2} \frac{d^2}{ds^2} [(s + 1)^3 X(s)]\big|_{s=-1} = \frac{1}{2} \frac{d^2}{ds^2} \left[ \frac{1}{s(s + 2)} \right]\bigg|_{s=-1} = -1$$



### Case 3: Simple complex-conjugate poles

$$X(s) = \frac{\omega_n^2}{s^2 + 2\xi\omega_n s + \omega_n^2}$$

( $\xi, \omega_n$ , s.t poles are complex)

$$X(s) = \frac{K_1}{s + \alpha - j\omega} + \frac{K_2}{s + \alpha + j\omega} \quad ; \quad \alpha = \xi\omega_n \quad ; \quad \omega = \omega_n \sqrt{1 - \xi^2}$$

$$K_1 = (s + \alpha - j\omega)X(s) \Big|_{s = -\alpha + j\omega} = \frac{\omega_n^2}{2j\omega}$$

$$K_2 = (s + \alpha + j\omega)X(s) \Big|_{s = -\alpha - j\omega} = -\frac{\omega_n^2}{2j\omega}$$

### Case 4: General case

*Use intuition*

### Example:

Find the solution  $x(t)$  of  $\ddot{x} + 2\dot{x} + 5x = 3$  ;  $x(0) = 0$ ,  $\dot{x}(0) = 0$

$$s^2 X(s) + 2sX(s) + 5X(s) = \frac{3}{s}$$

$$X(s)[s^2 + 2s + 5] = \frac{3}{s} \Rightarrow X(s) = \frac{3}{s(s^2 + 2s + 5)} = \frac{3}{s[(s+1)^2 + 2^2]}$$

$$\begin{aligned} \text{So } X(s) &= \frac{3}{s[(s+1)^2 + 2^2]} = \frac{A}{s} + \frac{B}{(s+1)^2 + 2^2} = \frac{A[(s+1)^2 + 2^2] + Bs}{s[(s+1)^2 + 2^2]} = \frac{A(s^2 + 2s + 5) + Bs}{s[(s+1)^2 + 2^2]} \\ &= \frac{5A + As^2 + (2A + B)s}{s[(s+1)^2 + 2^2]} \end{aligned}$$

$$3 = 5A \Rightarrow A = \frac{3}{5}$$

$$\frac{3}{5}s^2 + \frac{6}{5}s + Bs = 0 \Rightarrow B = -\frac{3}{5}s - \frac{6}{5} = -\frac{3}{5}(s+2)$$

$$\Rightarrow X(s) = \frac{3}{5} \frac{1}{s} - \frac{3}{5} \frac{s+2}{(s+1)^2 + 2^2} = \frac{3}{5} \frac{1}{s} - \frac{3}{5} \left( \frac{1+s+1}{(s+1)^2 + 2^2} \right) = \frac{3}{5} \frac{1}{s} - \frac{3}{20} \frac{2^2}{(s+1)^2 + 2^2} - \frac{3}{5} \frac{s+1}{(s+1)^2 + 2^2}$$

$$\Rightarrow x(t) = \frac{3}{5} u(t) - \frac{3}{20} e^{-t} \sin 2t - \frac{3}{5} e^{-t} \cos 2t$$