PyTorch_Basics_Tutorial_final

August 19, 2023

[1]: import numpy as np

```
print(np.__version__)
     import torch
     print(torch.__version__)
     import matplotlib.pylab as plt
    1.23.5
    2.0.1+cu118
    Correlation: PyTorch vs Numpy
[2]: # Create a numpy array of shape (2,3) and print its shape
     numpy_array = np.array([[1,2,3], [4,5,6]])
     print(numpy array.shape)
     # create a tensor of shape (2,3) and print its shape
     torch_tensor = torch.tensor([[1,2,3,], [4,5,6]])
     print(torch_tensor.shape)
    (2, 3)
    torch.Size([2, 3])
[3]: # Generate a random number of shape (3,4) in numpy
     numpy_rand = np.random.rand(3,4)
     print(numpy_rand)
     # Generate a random number of shape (3,4) in PyTorch
     torch rand = torch.rand(3,4)
     print(torch_rand)
    [[0.16217428 0.82824196 0.54467197 0.41789477]
     [0.26921656 0.41767813 0.2164388 0.09966194]
     [0.19866075 0.13359389 0.38171415 0.48985428]]
    tensor([[0.3064, 0.4763, 0.5908, 0.6238],
            [0.8397, 0.1822, 0.4500, 0.2720],
            [0.0799, 0.1624, 0.8114, 0.2577]])
```

```
[4]: # Generate zeros of shape (1,10) in numpy
     numpy_zeros = np.zeros((1,10))
     print(numpy_zeros)
     # Generate zeros of shape (1,10) in torch
     torch_zeros = torch.zeros((1,10))
     print(torch_zeros)
    [[0. 0. 0. 0. 0. 0. 0. 0. 0. 0.]]
    tensor([[0., 0., 0., 0., 0., 0., 0., 0., 0., 0.]])
[5]: # Generate ones of shape (1,7) in numpy
    numpy_ones = np.ones((1,7))
     print(numpy_ones)
     # Generate ones of shape (1,7) in torch
     torch_ones = torch.ones((1,7))
     print(torch_ones)
    [[1. 1. 1. 1. 1. 1. 1.]]
    tensor([[1., 1., 1., 1., 1., 1., 1.]])
[6]: # create a range of values 0 to 10 in numpy
     zero_to_ten_np = np.arange(0,10)
     print(zero_to_ten_np)
     # Create a range of values 0 to 10 in torch
     zero_to_ten_torch = torch.arange(0,10)
     print(zero_to_ten_torch)
    [0 1 2 3 4 5 6 7 8 9]
    tensor([0, 1, 2, 3, 4, 5, 6, 7, 8, 9])
    List/Array/Tensor Manipulation
[7]: int_list = [1,2,3,4,5]
     # Convert a integer list with length 5 to a tensor
     int_tensor = torch.tensor(int_list)
     print(int_tensor.dtype)
    torch.int64
[8]: # Convert a float list with length 5 to a tensor
     float_list = [0.0, 1.0, 2.0, 3.0, 4.0]
     # YOUR CODE STARTS HERE
     floats_to_tensor = torch.tensor(float_list)
     print(floats_to_tensor)
```

```
print(floats_to_tensor.dtype)
#YOUR CODE ENDS HERE

tensor([0., 1., 2., 3., 4.])
torch.float32

[9]: # Convert the integer list to float tensor
old_int_tensor = torch.tensor([0, 1, 2, 3, 4])
# YOUR CODE STARTS HERE
new_float_tensor = old_int_tensor.float()
print(new_float_tensor)
#YOUR CODE ENDS HERE

tensor([0., 1., 2., 3., 4.])
[9]:
```

numpy vs. torch * Convert the given numpy array to a torch tensor; And torch tensor to a numpy array

```
[10]: twoD_list = [[11, 12, 13], [21, 22, 23], [31, 32, 33]]
      twoD_numpy = np.asarray(twoD_list)
      print("The numpy array: ", twoD_numpy)
      print("Type : ", twoD_numpy.dtype)
      # Convert numpy array to tensor
      # YOUR CODE STARTS HERE
      twoD_tensor = torch.tensor(twoD_numpy,dtype=float)
      print(twoD_tensor)
      print(twoD tensor.shape)
      twoD_tensor = torch.asarray(twoD_numpy,dtype=float)
      print(twoD_tensor)
      print(twoD_tensor.shape)
      #YOUR CODE ENDS HERE
      print("\nNumpy Array -> Tensor:")
      print("The tensor after converting:", twoD_tensor)
      print("Type after converting: ", twoD_tensor.dtype)
      # Convert torch tensor to numpy array
      # YOUR CODE STARTS HERE
      print("\n\n")
      new_twoD_numpy = twoD_tensor.numpy()
      print(twoD tensor.shape)
      #YOUR CODE ENDS HERE
      print("\nTensor -> Numpy Array:")
```

```
print("Type after converting: ", new_twoD_numpy.dtype)
     The numpy array: [[11 12 13]
      [21 22 23]
      [31 32 33]]
     Type: int64
     tensor([[11., 12., 13.],
             [21., 22., 23.],
             [31., 32., 33.]], dtype=torch.float64)
     torch.Size([3, 3])
     tensor([[11., 12., 13.],
             [21., 22., 23.],
             [31., 32., 33.]], dtype=torch.float64)
     torch.Size([3, 3])
     Numpy Array -> Tensor:
     The tensor after converting: tensor([[11., 12., 13.],
             [21., 22., 23.],
             [31., 32., 33.]], dtype=torch.float64)
     Type after converting: torch.float64
     torch.Size([3, 3])
     Tensor -> Numpy Array:
     The numpy array after converting: [[11. 12. 13.]
      [21. 22. 23.]
      [31. 32. 33.]]
     Type after converting: float64
[10]:
     2D Torch Tensors and 2D numpy arrays
     Access the different elements of the tensor twoD_tensor and numpyarray twoD_numpy.
[11]: # Slice rows 2nd and 3rd row
      # YOUR CODE STARTS HERE
      sliced_tensor = twoD_tensor[1:3, :]
      sliced_numpy = twoD_numpy[1:3, :]
      # YOUR CODE STARTS HERE
      print("Tensor: Result after tensor slicing ", sliced_tensor)
      print("Tensor: Dimension after tensor slicing ", sliced tensor.ndimension())
      print("Numpy: Result after np slicing: ", sliced_numpy)
      print("Numpy: Dimension after np slicing: ", sliced_numpy.ndim)
```

print("The numpy array after converting: ", new_twoD_numpy)

Dot Product

In this task, you will implement the dot product function for numpy arrays & torch tensors.

The dot product (also known as the scalar product or inner product) is the linear combination of the n real components of two vectors.

$$x \cdot y = x_1 y_1 + x_2 y_2 + \dots + x_n y_n$$

Your Task: Implement the functions NUMPY_dot & PYTORCH_dot.

```
[12]: def NUMPY_dot(x, y):
    """
    Dot product of two arrays.

Parameters:
    x (numpy.ndarray): 1-dimensional numpy array.
    y (numpy.ndarray): 1-dimensional numpy array.

Returns:
    numpy.int64: scalar quantity.
    """
    # YOUR CODE STARTS HERE

out = np.dot(x,y)

# YOUR CODE ends HERE

return out
```

```
[13]: def PYTORCH_dot(x, y):
    """
    Dot product of two tensors.

Parameters:
    x (torch.Tensor): 1-dimensional torch tensor.
    y (torch.Tensor): 1-dimensional torch tensor.

Returns:
```

```
torch.int64: scalar quantity.
"""

# YOUR CODE STARTS HERE

out = torch.dot(x,y)

# YOUR CODE ends HERE

return out
```

```
[14]: # TEST cases
    X = np.asarray([1,2,3])
    Y = np.asarray([4,-5,6])
    print(f'NUMPY: Dot product of {X} and {Y} is {NUMPY_dot(X,Y)}')
    assert NUMPY_dot(X,Y)==12

X = torch.from_numpy(X)
    Y = torch.from_numpy(Y)
    print(f'Pytorch: Dot product of {X} and {Y} is {PYTORCH_dot(X,Y)}')
    assert PYTORCH_dot(X,Y).item()==12
```

NUMPY: Dot product of $[1\ 2\ 3]$ and $[\ 4\ -5\ 6]$ is 12 Pytorch: Dot product of tensor($[1,\ 2,\ 3]$) and tensor($[\ 4,\ -5,\ 6]$) is 12

Creating a Tensor & Understanding it

```
[15]: tensor([[[1, 2, 3], [3, 6, 9], [2, 4, 5]]])
```

```
[16]: # print the shape of the above tensor print(tensor.shape)
```

torch.Size([1, 3, 3])

```
[17]: ## Can you correleate it with (batch_size, channels, height, width)?
```

Assuming that we are dealing with a grayscale image (Only 3 dimensions available in the vector, instead of 4), I'd say that batch_size is 1, height and width are 3 units each. And obviously, there is 1 channel.

```
[17]:
```

Tensor Datatypes

```
[18]: # Default datatype for tensors is float32
      float_32_tensor = torch.tensor([3.0, 6.0, 9.0],
                                     dtype=None, # defaults to None, which is torch.
       →float32 or whatever datatype is passed
                                     device=None, # defaults to None, which uses the
       ⇔default tensor type
                                     requires_grad=False) # if True, operations⊔
       →performed on the tensor are recorded
      float_32_tensor.shape, float_32_tensor.dtype, float_32_tensor.device
[18]: (torch.Size([3]), torch.float32, device(type='cpu'))
[18]:
     Getting information from tensors
[19]: # Create a tensor
      some_tensor = torch.rand(3, 4)
      # Find out details about it
      print(some_tensor)
      print(f"Shape of tensor: {some_tensor.shape}")
      print(f"Datatype of tensor: {some_tensor.dtype}")
      print(f"Device tensor is stored on: {some_tensor.device}") # will default to CPU
     tensor([[4.8862e-01, 9.3175e-01, 3.6153e-01, 3.8928e-04],
             [8.1481e-01, 4.4611e-01, 2.0216e-01, 1.5740e-01],
             [9.6129e-01, 5.6293e-01, 8.4194e-01, 4.4290e-01]])
     Shape of tensor: torch.Size([3, 4])
     Datatype of tensor: torch.float32
     Device tensor is stored on: cpu
     Common Errors * Data type mismatch * Shape mismatch * Variable device mismatch
     Basics tensor operations
[20]: tensor = torch.tensor([1, 2, 3])
      # multiply tensor by 20
      tensor_mul = torch.mul(tensor, 20)
      print(tensor_mul)
      # add 13 to each element of the tensor
      tensor_add = torch.add(tensor, 13)
      print(tensor add)
     tensor([20, 40, 60])
```

tensor([14, 15, 16])

```
[21]: |\#built-in\ functions\ like\ torch.mul() (short for multiplication) and torch.add()
     →to perform basic operations.
     #torch.mm() which is a short for torch.matmul()
[22]: matrix1 = torch.tensor([[1, 2],
                         [3, 4]])
     matrix2 = torch.tensor([[5, 6],
                         [7, 8]])
     tensor_mm = torch.mm(matrix1, matrix2)
     print(tensor_mm)
     tensor_matmul = torch.matmul(matrix1, matrix2)
     print(tensor_matmul)
     print(tensor_mm.all() == tensor_matmul.all())
    tensor([[19, 22],
           [43, 50]])
    tensor([[19, 22],
           [43, 50]])
    tensor(True)
    Change tensor datatype
[23]: # Create a tensor and check its datatype
     tensor = torch.arange(10., 100., 10.)
     tensor.dtype
[23]: torch.float32
[24]: # Create a float16 tensor
     tensor_float16 = tensor.type(torch.float16)
     tensor_float16
[24]: tensor([10., 20., 30., 40., 50., 60., 70., 80., 90.], dtype=torch.float16)
    GPU
[25]: import torch
     !nvidia-smi
    Sat Aug 19 17:34:55 2023
    +----+
    | NVIDIA-SMI 525.105.17 | Driver Version: 525.105.17 | CUDA Version: 12.0
    |-----
                    Persistence-M| Bus-Id
    | GPU Name
                                            Disp.A | Volatile Uncorr. ECC |
    | Fan Temp Perf Pwr:Usage/Cap| Memory-Usage | GPU-Util Compute M. |
                                                  1
                                                               MIG M.
```

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                                                                0% Default |
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                                           OMiB / 15360MiB |
                                                                             N/A |
     | Processes:
       GPU
            GI
                 CI
                            PID Type Process name
                                                                      GPU Memory |
             ID
                                                                      Usage
       No running processes found
[26]: torch.cuda.is_available()
[26]: True
[27]: # Set device type
     device = "cuda" if torch.cuda.is_available() else "cpu"
     device
[27]: 'cuda'
[28]: torch.cuda.device_count()
[28]: 1
[29]: # Create tensor (default on CPU)
     tensor = torch.tensor([1, 2, 3])
     # Tensor not on GPU
     print(tensor, tensor.device)
     # Move tensor to GPU (if available)
     tensor_on_gpu = tensor.to(device)
     tensor_on_gpu
     tensor([1, 2, 3]) cpu
[29]: tensor([1, 2, 3], device='cuda:0')
[30]: # copy the tensor back to cpu
     tensor_back_on_cpu = tensor_on_gpu.cpu().numpy()
     tensor_back_on_cpu
[30]: array([1, 2, 3])
     ** Computer Vision/ Imaging Related Pytorch library**
```

[30]:			

Image credit: https://www.learnpytorch.io/03_pytorch_computer_vision/