

# Design Principles

## Design Patterns

## Good Practices

Programming Techniques II HS15

# Rule of 5

```
class Foo {  
    Foo(const Foo &) { // copy constructor  
        member = new double[999];  
    }  
    double * member;  
};
```

# Rule of 5


```
class Foo {  
    Foo(const Foo &);           // copy constructor  
    operator=(const Foo &);     // copy assignment operator  
    Foo(Foo &&);               // move constructor  
    operator=(Foo &&);          // move assignment operator  
    ~Foo();                   // destructor  
};
```

Either all of them, or none!


# Auto-generation

	ctor	copy ctor	copy =	move ctor	move =	~dtor
ctor						
copy ctor						
copy =						
move ctor						
move =						
~dtor						

# Auto-generation

	ctor	copy ctor	copy =	move ctor	move =	~dtor
ctor		✓	✓	✓	✓	✓
copy ctor	✓		✓	✗	✗	✓
copy =	✓	✓		✗	✗	✓
move ctor	✓	✗	✗		✗	✓
move =	✓	✗	✗	✗		✓
~dtor	✓	✓	✓	✗	✗	

# Auto-generation

	ctor	copy ctor	copy =	move ctor	move =	~dtor
ctor		✓	✓	✓	✓	✓
copy ctor	✓		✓	✗	✗	✓
copy =	✓	✓		✗	✗	✓
move ctor	✓	✗	✗		✗	✓
move =	✓	✗	✗	✗		✓
~dtor	✓	✓	✓	✗	✗	

# Rule of 5

```
class Abstract {  
    virtual ~Abstract() { }    // allow polymorphism  
};
```

# Rule of 5

```
class Abstract {  
    Abstract(const Abstract &) = default;  
    Abstract & operator=(const Abstract &) & = default;  
    Abstract(Abstract &&) = default;  
    Abstract & operator=(Abstract &&) & = default;  
    virtual ~Abstract() { }  
};
```



# Rule of 5 compromises

- `copy ctor`, `copy =`, `~dtor` → non-movable
- `move ctor`, `move =`, `~dtor` → non-copyable
- implicit `move =` deleted by:

non-static const members, non-static & members,

non-move-assignable members, non-move-assignable base

implicit `move ctor` even more sensitive...

more on that when we discuss move semantics!

# Rule of zero

- Classes with custom rule-of-5 methods deal exclusively with ownership
- memory management follows *single responsibility principle*
  - smart pointers (next week)
- other classes should have no rule-of-5 methods

*“Trust me...”*

~ gcc

Good Design?

**Fragile**

**Hard to  
reuse**

Bad Design?

**Hard to  
understand**

# Open/Closed Principle

```
class Rect {  
    double get_width();  
    double get_height();  
};
```

```
double area(Rect r) {  
    return r.get_width()  
        *r.get_height();  
}
```

# Open/Closed Principle

```
class Rect: public Shape {  
    double get_width();  
    double get_height();  
};  
  
class Circle: public Shape {  
    double get_radius();  
};  
  
double area(Shape s) {  
    if(type(s)==type(Rect))  
        return s.get_width()  
            *s.get_height();  
    if(type(s)==type(Circle))  
        return s.get_radius()  
            *s.get_radius();  
}
```

# Open/Closed Principle

```
class Rect: public Shape {  
    double get_width();  
    double get_height();  
};  
class Circle: public Shape {  
    double get_radius();  
};  
class Triangle: public Shape {  
    // ...  
};
```

```
double area(Shape s) {  
    if(type(s)==type(Rect))  
        return s.get_width()  
            *s.get_height();  
    if(type(s)==type(Circle))  
        return s.get_radius()  
            *s.get_radius();  
    if(type(s)==type(Triangle))  
        // ...  
}
```

# Open/Closed Principle

- code should be *open for extension*, but *closed for modification*

```
class Shape {  
    virtual double get_area() = 0;  
};  
  
double area(Shape s) {  
    return s.get_area();  
}
```



# Single Responsibility

```
class Animal {  
    std::string get_name() const;  
    void run();  
    std::string mate_with(Animal &);  
    void save_to_file(std::string &) const {  
        // open file, write data, close file  
    }  
};
```

- who uses functionality from Animal?
  - a population class, another animal, a save feature, ...

# Single Responsibility

```
class Animal {  
    // ...  
    properties & return_data();  
};  
void save(std::ostream & o,  
          Animal & a) {  
    for(auto p: a.properties) {  
        o << p;  
    }  
}
```

```
void saveHTML(std::ostream  
              & o, Animal & a) {  
    for(auto p: a.properties) {  
        o << "<" << p.tag << ">"  
        << p.content  
        << "</" << p.tag << ">";  
    }  
}
```

# Single Responsibility

- leads to lower coupled design / dependencies
- but... can lead to getter / setter / friend bloat
- how easy is it to give your class a name?
- can you identify subtasks to refactor?

Hint: PennaLV genome

# Interface Segregation

```
class Animal {  
    virtual void make_child() = 0;  
    // ...  
    virtual wool_t give_wool() = 0;  
    virtual void eat_grass() = 0;  
};  
class Sheep : public Animal {  
    // ...  
    wool_t give_wool() override {  
        // happy shearing  
    }  
};
```

```
class Bear : public Animal {  
    // ...  
    void eat_grass() override {  
  
    }  
}
```



Don't force dependencies on unused interfaces!

# Formal Principles

- SOLID ( single responsibility, open/closed, Liskov substitution, interface segregation, dependency inversion)
- DRY (don't repeat yourself) ↔ WET (we like typing)
- SSOT, KISS, ...

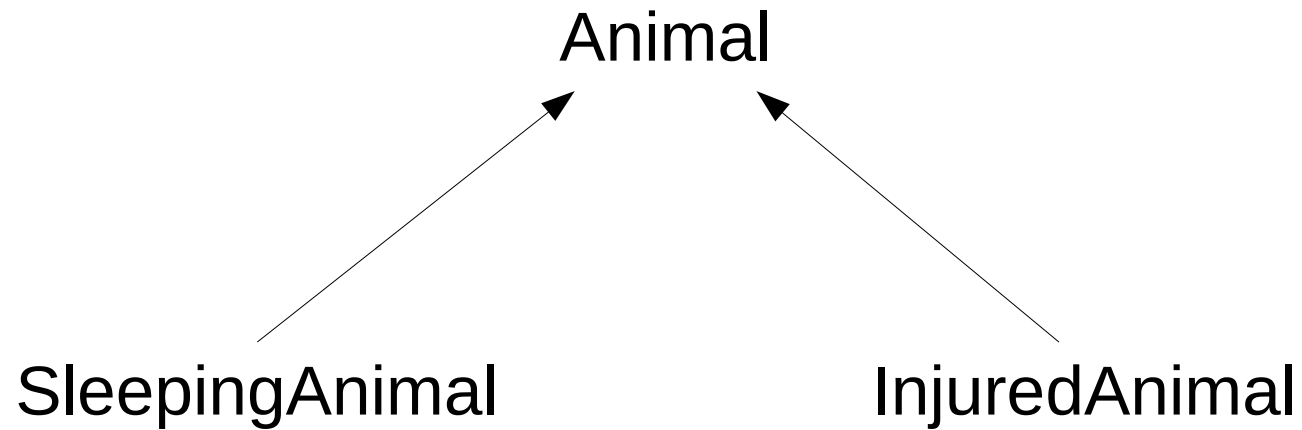
# Factory Pattern

```
class AnimalFactory {  
    static Animal * make_child(int choice) {  
        switch(choice) {  
            Case 0: return new Sheep();  
            Case 1: return new Bear();  
        }  
    }  
};
```

! use smart pointers !

Useful to provide instances to a container or unit test

# Decorator



Adjust existing functionality, interchangeable with base

# Decorator

```
class Animal {  
    virtual void eat() {  
        // with appetite  
    };  
};  
class SleepingInjuredAnimal  
    : public InjuredAnimal  
    , public SleepingAnimal {  
    virtual void eat() {  
        SleepingAnimal::wake_up();  
        InjuredAnimal::eat();  
    }  
};
```

```
class InjuredAnimal : public Animal  
{  
    virtual void eat() {  
        moan();  
        Animal::eat();  
    }  
};  
class SleepingAnimal : public  
Animal {  
    virtual void eat() {  
        wake_up();  
        Animal::eat();  
    }  
};
```

Composition (holding the wrapped class in a member) scales better!



# Recursively Bounded Quantification

# Curiously Recurring Template Pattern (CRTP)

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```
template <class D>
class Base {
    void foo() {
        std::cout << D::x << std::endl;
    }
};

class Derived : public Base<Derived> {
    int x;
};
```

# Curiously Recurring Template Pattern (CRTP)

```
template <class D>
class Base {
    void foo() {
        static_cast<const D*>(this)->foo();
    }
};

class Derived : public Base<Derived> {
    void foo() const {}
};
```

# Curiously Recurring Template Pattern (CRTP)

```
template <class D>
class Base {
    void foo() { /* do something with D members */ }
    int x;
};
class Derived : public Base<Derived> {
};
int main() {
    Derived d;
    d.foo();
    std::cout << d.x << std::endl;
    return 0;
}
```