Lab 1: Basic Implementation of Image Processing

Author: Siddharth Nahar, 2016CSB1043

1. Resize function: Implemented using Backward mapping and two options are provided:

Input Image:



a.Nearest Neigbourhood:



*ScaleX=0.5,ScaleY=0.5,PSNR=30.2672
*Inbuilt=resize(src,dst,Size(),fx

,fy,INTER_NEAREST);

*In inbuilt ,0.5 is rounded to 0 rather than 1 So PSNR is not exact 0.

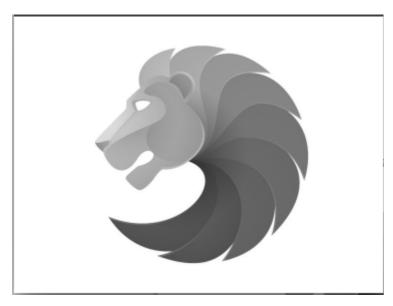
b.Bilinear:

Resize my implementation:



ScaleX = 0.5,ScaleY = 0.5,PSNR=0
Inbuilt=resize(...,INTER LINEAR)

Inbuilt function Output(BILINEAR):



*For Inter cubic PSNR=46.53

*For Bilinear I observed :

a.For Corner Points ,inbuilt not gives same value, it takes only fraction which is effective.

b. Inbuilt floors size if rows*fx is not integer, So PSNR is calculted for 0.5

2.Translate the image:

By Implementation:



Traverse x = 20, y=20;*PSNR = 0,As in case of both forward or backward

Result remains same.

By Inbuilt:

Function = warpAffine(src,dst,m,Size(dst));
m=2*3 matrix of translation

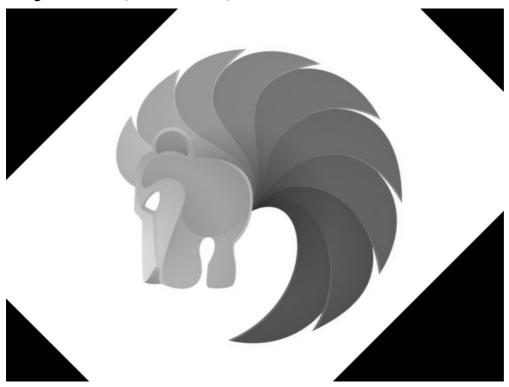
Output:



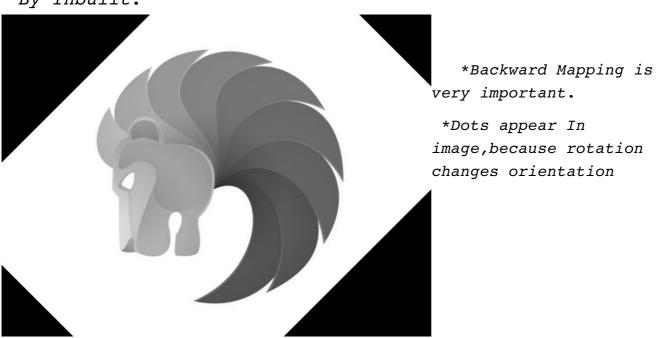
3. Rotation of Image:

By Implemnetation:

Angle = 45, Bilinear, PSNR = 65.5325



By Inbuilt:



*In bilinear implementation, corner cases are considered differently.ex. For only 2 nearest ,it takes interpolation for both then multiply effective ration to result.

4.Shear:

By implementation:

shear x = 0.5, PSNR = 26.452



Inbuilt:



5.Recounstruction with Tie points:

Input Image:

Points of distoted :(13,395),(233,14),(235,523),(455,142)

Point of original: (10,450), (10,10), (266,450), (266,10)



Output Image:

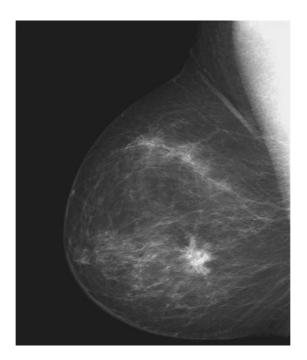


*Kept the size same as Input image.

*It has reconstructed the image which was rotated.

6.Image Negative:

Input Image:



Output Image:

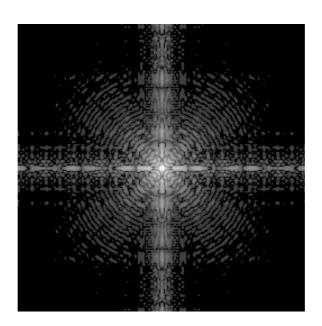


7.Log Transformation:

Input Image:



Output Image:



8. Power Transformation:

Input Image:

Gamma = 3.0



Output Image:



9.PieceWise Linear Transformation:

Input Image:

r1 = rmin, r2 = rmax, s1 = 0, s2 = 255



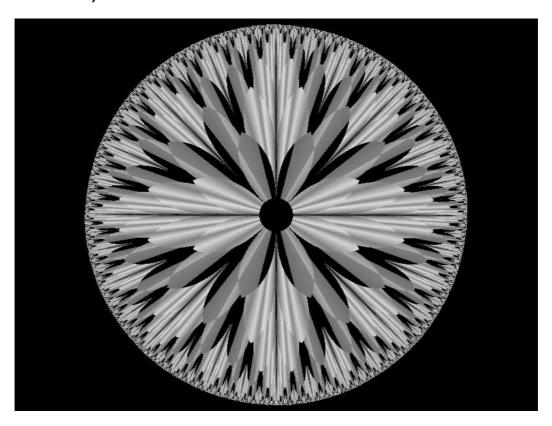
Output Image:



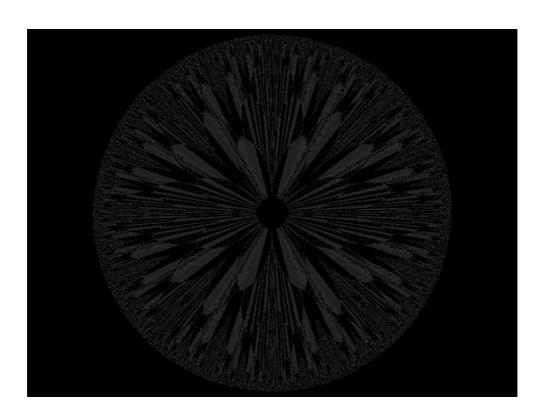
10.BitSlicing Transformation:

Input Image:

Planes = 3,5

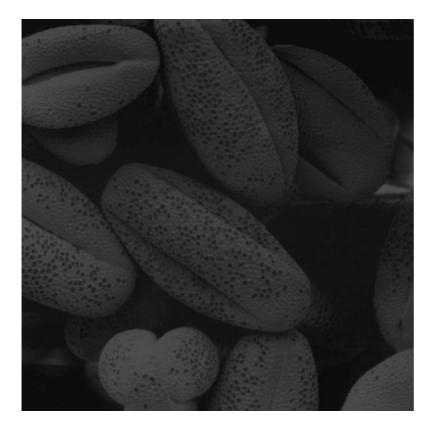


Output Image:



11.Histogram Equalization:

Input Image:



*PSNR = 0;*Normalization used : 255*(y-ymin)/(1-ymin) For more distribution of values *equalizehist(src,dst);

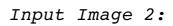
Output Image implementation: Inbuilt Implementation:

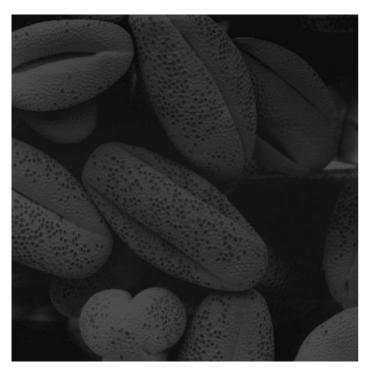


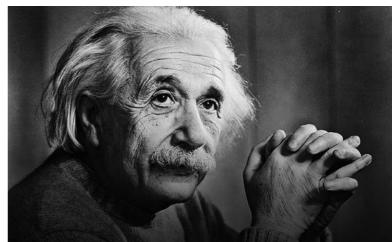


12.Matched Equalization:

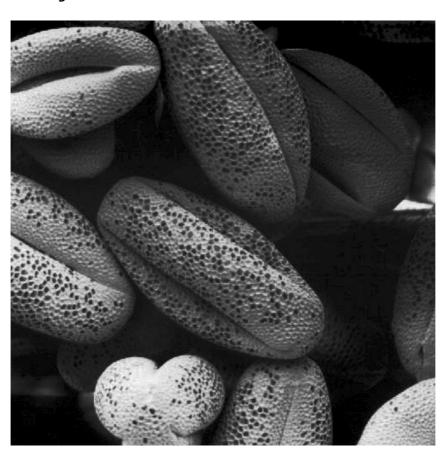
Input Image 1:







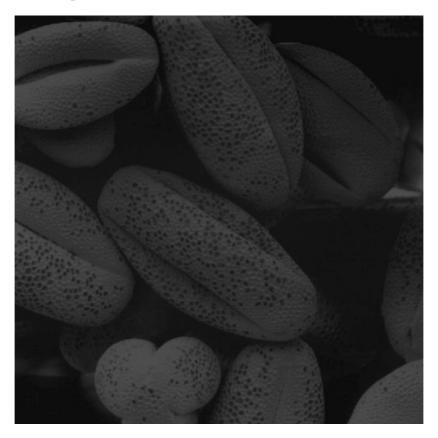
Outptut Image:



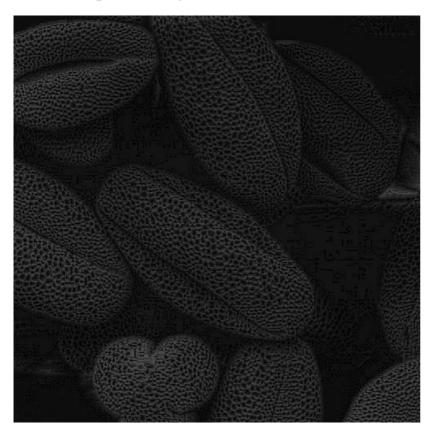
13.Adaptive Histogram Eqalization:

Input Image:

Congruence Square=3



Output Image:



*Use Mirror neighbours
for Locaslized
Equalization
*Used Equalization
in local region of3*3
*Due to small region
Enhancement is not
proper.
*Most effective to

*Most effective to

Enhance regions but time

complexity m2*n2