

EPFL CS439: Optimization for Machine Learning

Note: I am not affiliated with EPFL. These notes are based on the online [course material](#) provided by Prof. Martin Jaggi.

Siddhartha Bhattacharya

January 16, 2025

Contents

0.1	High Level Overview	1
0.1.1	How to Optimize	2
1	Theory of Convex Optimization	2
1.1	Warm-up: Cauchy-Schwarz Inequality	2
1.2	What is Convexity? Convex Sets and Functions	2
1.3	Proving Convexity	3
1.3.1	Solving Convex Optimization – Provably	3
1.4	Characterizations of Convexity	6
1.4.1	Operations that Preserve Convexity	7
1.5	Local Minima are Global Minima	8
1.6	Strict Convexity	9
1.7	Constrained Minimization	9

0.1 High Level Overview

General unconstrained minimization problem:

$$\min_{x \in \mathbb{R}^d} f(x) \quad (1)$$

- $x \in \mathbb{R}^d$ refers to candidate solutions, variables, or parameters. \mathbb{R}^d is the domain.

- $f : \mathbb{R}^d \rightarrow \mathbb{R}$ is the objective function.
- typical assumptions: f is continuous and differentiable.

0.1.1 How to Optimize

Two main steps:

Mathematical Modeling: Defining & modeling the optimization problem.

Computational Optimization: Running an (approximate) optimization algorithm.

1 Theory of Convex Optimization

1.1 Warm-up: Cauchy-Schwarz Inequality

Theorem 1.1 (Cauchy-Schwarz Inequality). *Let $u, v \in \mathbb{R}^d$. Then*

$$\langle u, v \rangle^2 \leq \|u\|^2 \|v\|^2 \quad (2)$$

Equivalently,

$$|\langle u, v \rangle| \leq \|u\| \|v\| \quad (3)$$

where $\langle \cdot, \cdot \rangle$ is the standard Euclidean dot product.

For nonzero u, v , this is equivalent to

$$-1 \leq \frac{\langle u, v \rangle}{\|u\| \|v\|} \leq 1 \quad (4)$$

So, the angle α between u and v is given by $\cos(\alpha) = \frac{\langle u, v \rangle}{\|u\| \|v\|}$. Thus, equality holds in (2) if and only if u and v are scalar multiples of each other.

1.2 What is Convexity? Convex Sets and Functions

Definition 1.2. A set C is a **convex set** if the line segment between any two points of C lies entirely in C . Formally, for any $x, y \in C$ and $0 \leq \lambda \leq 1$, we have

$$\lambda x + (1 - \lambda)y \in C \quad (5)$$

Proposition 1.3. Intersections of convex sets are convex.

Remark 1.4. Unions of convex sets are not necessarily convex.

Proposition 1.5 (later: projections onto convex sets).

$$P_C(x') = \arg \min_{y \in C} \|y - x'\|$$

Definition 1.6. A function $f : \mathbb{R}^d \rightarrow \mathbb{R}$ is a **convex function** if

1. $\text{dom}(f)$ is a convex set
2. for all $x, y \in \text{dom}(f)$ and $0 \leq \lambda \leq 1$, we have

$$f(\lambda x + (1 - \lambda)y) \leq \lambda f(x) + (1 - \lambda)f(y) \quad (6)$$

Geometrically: the line segment connecting $(x, f(x))$ and $(y, f(y))$ lies above the graph of f .

1.3 Proving Convexity

Convex optimization problems are of the form

$$\min f(x) \text{ s.t. } x \in C \quad (7)$$

where both f is a convex function and $C \subseteq \text{dom}(f)$ is a convex set.

Crucial property of convex optimization problems: every local minimum is a global minimum.

1.3.1 Solving Convex Optimization – Provably

For convex optimization problems, all algorithms

- coordinate descent, gradient descent, SGD, projected and proximal gradient descent

do converge to the global optimum! (assuming f is differentiable)

Definition 1.7. A **graph** of a function $f : \mathbb{R}^d \rightarrow \mathbb{R}$ is defined as

$$\{(x, f(x)) \in \mathbb{R}^{d+1} \mid x \in \text{dom}(f)\}$$

Definition 1.8. The **epigraph** of a function $f : \mathbb{R}^d \rightarrow \mathbb{R}$ is defined as

$$\text{epi}(f) = \{(x, \alpha) \in \mathbb{R}^{d+1} \mid x \in \text{dom}(f), \alpha \geq f(x)\}$$

Visually, the epigraph is the set of points above the graph of f .

Proposition 1.9. A function $f : \mathbb{R}^d \rightarrow \mathbb{R}$ is convex if and only if its epigraph is a convex set.

Proof. First, let $f : \mathbb{R}^d \rightarrow \mathbb{R}$ be a convex function. Then, for any $x, y \in \text{dom}(f)$ and $0 \leq \lambda \leq 1$, we have

$$f(\lambda x + (1 - \lambda)y) \leq \lambda f(x) + (1 - \lambda)f(y)$$

Thus, for any $(x, \alpha), (y, \beta) \in \text{epi}(f)$ and $0 \leq \lambda \leq 1$, we have

$$f(\lambda x + (1 - \lambda)y) \leq \lambda f(x) + (1 - \lambda)f(y) \leq \lambda \alpha + (1 - \lambda)\beta$$

Therefore, $(\lambda x + (1 - \lambda)y, \lambda \alpha + (1 - \lambda)\beta) \in \text{epi}(f)$, so $\text{epi}(f)$ is convex.

For the converse, suppose that $\text{epi}(f)$ is convex. Let $x, y \in \text{dom}(f)$ and $0 \leq \lambda \leq 1$. We know that $(x, f(x)), (y, f(y)) \in \text{epi}(f)$ by definition of the epigraph (let $\alpha = f(x)$ and $\beta = f(y)$). By the convexity of $\text{epi}(f)$, any convex combination of x, y is also in $\text{epi}(f)$.

So, the convex combination $(\lambda x + (1 - \lambda)y, \lambda f(x) + (1 - \lambda)f(y)) \in \text{epi}(f)$. Therefore, by the definition of $\text{epi}(f)$,

$$f(\lambda x + (1 - \lambda)y) \leq \lambda f(x) + (1 - \lambda)f(y)$$

and thus, f is convex. □

Example 1.10. Examples of convex functions:

- Linear functions: $f(x) = a^T x$
- Affine functions: $f(x) = a^T x + b$
- Exponential functions: $f(x) = e^{ax}$
- Norms: every norm on \mathbb{R}^d is convex

Proof. Proof of convexity of norms:

By the triangle inequality, $\|x + y\| \leq \|x\| + \|y\|$ and homogeneity of a norm,

$\|\lambda x\| = |\lambda| \|x\|$, we have that for any $x, y \in \mathbb{R}^d$ and $0 \leq \lambda \leq 1$,

$$\begin{aligned}\|\lambda x + (1 - \lambda)y\| &\leq \|\lambda x\| + \|(1 - \lambda)y\| \\ &= |\lambda| \|x\| + |1 - \lambda| \|y\| \\ &= \lambda \|x\| + (1 - \lambda) \|y\|\end{aligned}$$

□

Lemma 1.11 (Jensen's Inequality). *Let f be convex, $x_1, \dots, x_m \in \mathbf{dom}(f)$, $\lambda_1, \dots, \lambda_m \in \mathbb{R}_{\geq 0}$ such that $\sum_{i=1}^m \lambda_i = 1$. Then*

$$f\left(\sum_{i=1}^m \lambda_i x_i\right) \leq \sum_{i=1}^m \lambda_i f(x_i) \quad (8)$$

Proof. First, since f is convex, we have that for any $x, y \in \mathbf{dom}(f)$ and $0 \leq \lambda \leq 1$,

$$f(\lambda x + (1 - \lambda)y) \leq \lambda f(x) + (1 - \lambda)f(y)$$

We proceed by induction. For the ‘base case’, let $k = 2$ and $0 \leq \lambda_1, \lambda_2 \leq 1$ such that $\lambda_1 + \lambda_2 = 1$. Note that this implies $\lambda_2 = 1 - \lambda_1$.

$$\begin{aligned}f\left(\sum_{i=1}^2 \lambda_i x_i\right) &= f(\lambda_1 x_1 + \lambda_2 x_2) \\ &= f(\lambda_1 x_1 + (1 - \lambda_1)x_2)\end{aligned}$$

Next, since f is convex,

$$f(\lambda_1 x_1 + (1 - \lambda_1)x_2) \leq \lambda_1 f(x_1) + (1 - \lambda_1)f(x_2)$$

Now, substituting $\lambda_2 = (1 - \lambda_1)$, we get that

$$f(\lambda_1 x_1 + \lambda_2 x_2) \leq \lambda_1 f(x_1) + \lambda_2 f(x_2)$$

So, (8) holds for $k = 2$. Now, suppose for induction that (8) holds for an arbitrary $k \geq 2$. We show that it holds for $k + 1$. Let $1 = \sum_{i=1}^{k+1} \lambda_i$. If we let $\beta = \sum_{i=1}^k \lambda_i$, then $\lambda_{k+1} = 1 - \beta$. Using this, we can rewrite the convex

combination $\sum_{i=1}^{k+1} \lambda_i x_i$ as:

$$\begin{aligned} \sum_{i=1}^{k+1} \lambda_i x_i &= \beta \left(\sum_{i=1}^k \frac{\lambda_i}{\beta} x_i \right) + \lambda_{k+1} x_{k+1} \\ &= \beta \left(\sum_{i=1}^k \frac{\lambda_i}{\beta} x_i \right) + (1 - \beta) x_{k+1} \end{aligned}$$

And since f is convex,

$$f \left(\beta \left(\sum_{i=1}^k \frac{\lambda_i}{\beta} x_i \right) + (1 - \beta) x_{k+1} \right) \leq \beta f \left(\sum_{i=1}^k \frac{\lambda_i}{\beta} x_i \right) + (1 - \beta) f(x_{k+1})$$

And by inductive hypothesis on the first k terms, we know that $f \left(\sum_{i=1}^k \frac{\lambda_i}{\beta} x_i \right) \leq \sum_{i=1}^k \frac{\lambda_i}{\beta} f(x_i)$, which is a valid convex combination, since we defined $\beta = \sum_{i=1}^k \lambda_i$, implying that $\sum_{i=1}^k \frac{\lambda_i}{\beta} = \frac{\sum_{i=1}^k \lambda_i}{\beta} = \frac{\beta}{\beta} = 1$.

Thus,

$$\beta f \left(\sum_{i=1}^k \frac{\lambda_i}{\beta} x_i \right) + (1 - \beta) f(x_{k+1}) \leq \beta \left(\sum_{i=1}^k \frac{\lambda_i}{\beta} f(x_i) \right) + (1 - \beta) f(x_{k+1})$$

And by the definition of the convex combination, $\beta \left(\sum_{i=1}^k \frac{\lambda_i}{\beta} f(x_i) \right) + (1 - \beta) f(x_{k+1}) = \sum_{i=1}^{k+1} \lambda_i f(x_i)$, we are done. \square

Remark 1.12. For $m = 2$, Jensen's inequality reduces to the definition of convexity. Jensen's inequality is a general definition for convex combinations of any number of points in the domain.

Lemma 1.13. *Let f be convex and suppose that $\mathbf{dom}(f)$ is open. Then f is continuous.*

1.4 Characterizations of Convexity

Definition 1.14 (Differentiable Functions). Graph of the affine function $f(x) + \nabla f(x)^T(y - x)$ is a tangent hyperplan to the graph of f at $(x, f(x))$.

Lemma 1.15 (First-order Characterization of Convexity). *Suppose that $\mathbf{dom}(f)$*

is open and f is differentiable; in particular, the gradient (vector of partial derivatives)

$$\nabla f(x) := \left[\frac{\partial f}{\partial x_1}(x), \dots, \frac{\partial f}{\partial x_d}(x) \right]$$

exists at every point $x \in \mathbf{dom}(f)$. Then f is convex if and only if $\mathbf{dom}(f)$ is convex and

$$f(y) \geq f(x) + \nabla f(x)^T(y - x) \quad (9)$$

holds for all $x, y \in \mathbf{dom}(f)$.

Lemma 1.16 (Second-order Characterization of Convexity). *Suppose that $\mathbf{dom}(f)$ is open and f is twice differentiable; In particular, the Hessian (matrix of second partial derivatives)*

$$\nabla^2 f(x) := \begin{bmatrix} \frac{\partial^2 f}{\partial x_1^2}(x) & \cdots & \frac{\partial^2 f}{\partial x_1 \partial x_d}(x) \\ \vdots & \ddots & \vdots \\ \frac{\partial^2 f}{\partial x_d \partial x_1}(x) & \cdots & \frac{\partial^2 f}{\partial x_d^2}(x) \end{bmatrix}$$

exists at every point $x \in \mathbf{dom}(f)$ and is symmetric. Then f is convex if and only if for all $x \in \mathbf{dom}(f)$, we have

$$\nabla^2 f(x) \succeq 0 \text{ i.e. } \nabla^2 f(x) \text{ is positive semidefinite} \quad (10)$$

Recall that a matrix A is positive semidefinite if for all $z \in \mathbb{R}^d$, we have $z^T A z \geq 0$.

Connection to positive operators. Let us regard the hessian matrix A as the matrix representation of a linear operator $T \in \mathcal{L}(V)$, i.e. $A = M(T, B)$ for some basis B of \mathbb{R}^d . Then, f is convex if and only if T is a positive operator, i.e. $\langle Tx, x \rangle \geq 0$ for all $x \in \mathbb{R}^d$ and T is self adjoint (by definition of the Hessian). So, $\langle Tx, x \rangle = x^T A x$.

Example 1.17. Let $f(x_1, x_2) = x_1^2 + x_2^2$. Then, $\nabla^2 f(x) = \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix}$. Which is positive semidefinite, so f is convex.

1.4.1 Operations that Preserve Convexity

Lemma 1.18. *Let f_1, f_2, \dots, f_m be convex functions and $\lambda_1, \dots, \lambda_m \in \mathbb{R}_+$. Then $f := \sum_{i=1}^m \lambda_i f_i$ is convex on $\mathbf{dom}(f) := \bigcap_{i=1}^m \mathbf{dom}(f_i)$.*

Lemma 1.19. Let f be a convex function with $\mathbf{dom}(f) \subseteq \mathbb{R}^d$ and let $g : \mathbb{R}^m \rightarrow \mathbb{R}^d$ be an affine function, meaning that $g(x) = Ax + b$ for some matrix $A \in \mathbb{R}^{d \times m}$ and $b \in \mathbb{R}^d$. Then the function $f \circ g$ (that maps $x \rightarrow f(Ax + b)$) is convex on $\mathbf{dom}(f \circ g) := \{x \in \mathbb{R}^m : g(x) \in \mathbf{dom}(f)\}$.

1.5 Local Minima are Global Minima

Definition 1.20. A **local minimum** of $f : \mathbf{dom}(f) \rightarrow \mathbb{R}$ is a point x such that there exists $\epsilon > 0$ with

$$f(x) \leq f(y) \forall y \in \mathbf{dom}(f) \text{ satisfying } \|y - x\| \leq \epsilon \quad (11)$$

Lemma 1.21. Let x^* be a local minimum of a convex function $f : \mathbf{dom}(f) \rightarrow \mathbb{R}$. Then x^* is a global minimum, meaning that $f(x^*) \leq f(y) \forall y \in \mathbf{dom}(f)$.

Proof. Let x^* be a local minimum to a convex function f . Then suppose for contradiction that there exists another $y \in \mathbf{dom}(f)$ such that $f(y) < f(x^*)$.

Then let $y' = \lambda y + (1 - \lambda)x^*$ for some $0 < \lambda < 1$. Since $f(y) < f(x^*)$, it follows that $\lambda f(y) + (1 - \lambda)f(x^*) < f(x^*)$, so $f(y') < f(x^*)$. Now we show that y' is within the ϵ -neighborhood of x^* . Recall that by the definition of a local minimum, there exists $\epsilon > 0$ such that $f(x^*) \leq f(x) \forall x \in \mathbf{dom}(f)$ satisfying $\|x - x^*\| \leq \epsilon$.

For any $\epsilon > 0$, we may choose a small enough λ such that $\|y' - x^*\| \leq \epsilon$. First, let us expand the norm of $y' - x^*$:

$$\begin{aligned} \|y' - x^*\| &= \|\lambda y + (1 - \lambda)x^* - x^*\| \\ &= \|\lambda y - \lambda x^*\| \\ &= \lambda \|y - x^*\| \end{aligned}$$

Now, if we let $\lambda = \frac{\epsilon}{\|y - x^*\|} > 0$ (since $y \neq x^*$), then

$$\begin{aligned} \|y' - x^*\| &= \frac{\epsilon}{\|y - x^*\|} \|y - x^*\| \\ &= \epsilon \end{aligned}$$

Thus, $f(y') \leq f(x^*)$ and $\|y' - x^*\| \leq \epsilon$, which contradicts the assumption that x^* is a local minimum. \square

Lemma 1.22 (Critical Points are Global Minima). *Suppose that f is convex and differentiable over an open domain $\mathbf{dom}(f)$. Let $x \in \mathbf{dom}(f)$. If $\nabla f(x) = 0$ (**critical point**), then x is the global minimum.*

Proof. Suppose that $\nabla f(x) = 0$. According to the lemma on the first-order characterization of convexity, we have that

$$f(y) \geq f(x) + \nabla f(x)^T(y - x) = f(x)$$

for all $y \in \mathbf{dom}(f)$. Thus, x is a global minimum. \square

1.6 Strict Convexity

Definition 1.23. A function $f : \mathbf{dom}(f) \rightarrow \mathbb{R}$ is **strictly convex** if for all $x \neq y \in \mathbf{dom}(f)$ and all $\lambda \in (0, 1)$, we have

$$f(\lambda x + (1 - \lambda)y) < \lambda f(x) + (1 - \lambda)f(y) \quad (12)$$

This differs from the definition of convexity in that the inequality is strict.

Lemma 1.24. *If f is strictly convex, then f has at most one global minimum.*

1.7 Constrained Minimization

Definition 1.25. Let $f : \mathbf{dom}(f) \rightarrow \mathbb{R}$ be convex and let $X \subseteq \mathbf{dom}(f)$ denote the constraint (or feasible) set. be a convex set. A point $x \in X$ is a **minimizer** of f **over** X if

$$f(x) \leq f(y) \forall y \in X$$

Lemma 1.26. *Suppose that $f : \mathbf{dom}(f) \rightarrow \mathbb{R}$ is convex and differentiable over an open domain $\mathbf{dom}(f) \subseteq \mathbb{R}^d$, and let $X \subseteq \mathbf{dom}(f)$ be a convex set. A point $x^* \in X$ is a **minimizer of f over X** if and only if*

$$\nabla f(x^*)^T(x - x^*) \geq 0 \quad \forall x \in X \quad (13)$$