

MAE 598 Design optimization

HW.1

①

Q2) let x and $b \in \mathbb{R}^n$ be vector and $A \in \mathbb{R}^{n \times n}$ be a square matrix
Define $f: \mathbb{R}^n \rightarrow \mathbb{R}$ as $f(x) = b^T x + x^T A x$

q) what is the gradient and Hessian of $f(x)$ w.r.t x ?

sol) gradient

$$\nabla f(x) = \frac{\partial f(x)}{\partial x}$$

$$\nabla f(x) = \frac{\partial}{\partial x} (b^T x + x^T A x)$$

$$\Rightarrow \frac{\partial b^T x}{\partial x} \Rightarrow \begin{bmatrix} \frac{\partial b^T x}{x_1} \\ \frac{\partial b^T x}{x_2} \\ \vdots \\ \frac{\partial b^T x}{x_n} \end{bmatrix} \Rightarrow \begin{bmatrix} \frac{\partial}{\partial x_1} (b_1 x_1 + b_2 x_2 + \dots + b_n x_n) \\ \vdots \\ \frac{\partial}{\partial x_n} (b_1 x_1 + b_2 x_2 + \dots + b_n x_n) \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} b_1 \\ \vdots \\ b_n \end{bmatrix} = \underline{\underline{b}}$$

$$\Rightarrow x^T A x = \begin{bmatrix} x_1 & \dots & x_n \end{bmatrix} \begin{bmatrix} a_{11} & \dots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{n1} & \dots & a_{nn} \end{bmatrix} \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}$$

$$= \begin{bmatrix} (a_{11}x_1 + \dots + a_{n1}x_n) & \dots & (a_{1n}x_1 + \dots + a_{nn}x_n) \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$$

(2)

$$= \begin{bmatrix} \sum_{i=1}^n a_{i1} x_i & \dots & \sum_{i=1}^n a_{in} x_i \end{bmatrix} \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}$$

$$= x_1 \sum_{i=1}^n a_{i1} x_i + \dots + x_n \sum_{i=1}^n a_{in} x_i$$

$$\Rightarrow \sum_{j=1}^n \sum_{i=1}^n x_i a_{ij} x_j$$

to computing the partial derivative we can simplified the eq as

$$\sum_{i=1}^n (a_{ii} x_i^2 + \sum_{j \neq i} x_i a_{ij} x_j)$$

\Rightarrow for simplicity let consider the k^{th} row and do partial derivative

$$\frac{\partial x^T A x}{\partial x_k} = \frac{\partial}{\partial x_k} \sum_{i=1}^n (a_{ii} x_i^2 + \sum_{j \neq i} x_i a_{ij} x_j)$$

$$\Rightarrow 2a_{kk} x_k + \sum_{j \neq k} x_j a_{jk} + \sum_{j \neq k} a_{kj} x_j$$

we can re-write as

$$\Rightarrow \sum_{j=1}^n x_j a_{jk} + \sum_{j=1}^n a_{kj} x_j$$

convert Back into matrix form

$$\begin{bmatrix} \sum_{j=1}^n x_j a_{j1} \\ \vdots \\ \sum_{j=1}^n x_j a_{jn} \end{bmatrix} + \begin{bmatrix} \sum_{j=1}^n a_{1j} x_j \\ \vdots \\ \sum_{j=1}^n a_{nj} x_j \end{bmatrix}$$

\downarrow
 $A^T x$

\downarrow
 $A x$

$$\Rightarrow (A^T + A) x$$

So $\boxed{\nabla f(x) = b + (A^T + A)x}$ = gradient

\Rightarrow If A is symmetric ($A^T = A$) then $(A^T + A) = (A + A) = 2A$

So $\boxed{\nabla f(x) = b + 2Ax}$ = gradient when A is symmetric

\Rightarrow Hessian matrix

$$\nabla^2 f(x) = \frac{\partial^2 f(x)}{\partial x \partial x^T}$$

Now we know the k^{th} element gradient

$$\boxed{\nabla f(x) = b_k + \sum_{j=1}^n x_j a_{jk} + \sum_{j=1}^n a_{kj} x_j}$$

So second partial derivative for k^{th} row

$$\nabla^2 f(x) = 0 + a_{k'k} + a_{kk'}$$

which mean that

$$\nabla^2 f(x) = \begin{bmatrix} a_{11} + a_{11} & a_{21} + a_{12} & \dots & a_{n1} + a_{1n} \\ \vdots & \ddots & \ddots & \vdots \\ a_{1n} + a_{n1} & \ddots & \ddots & \ddots \\ \ddots & \ddots & \ddots & a_{nn} + a_{nn} \end{bmatrix}$$

$$\boxed{\nabla^2 f(x) = A + A^T}$$
 = Hessian

If A is symmetric

then $\boxed{\nabla^2 f(x) = 2A}$ = Hessian

b) Derive the first and second order Taylor's approximation of $f(x)$ at $x=0$, Are these approximation exact

(1)

\Rightarrow 1st order

$$f(x) = f(x_0) + \left. \frac{\partial f}{\partial x} \right|_{x_0} (x - x_0)$$

$$\Rightarrow f(x) \approx f(x_0) + \nabla f \Big|_{x_0}^T (x - x_0)$$

$$\Rightarrow 0 + b^T x_0 + x_0^T A x_0 + (b + (A^T + A)x_0)^T (x_0 - x_0)$$

$$= 0 + b^T x$$

$$\boxed{= b^T x}$$

2nd order

$$f(x) \approx f(x_0) + \nabla f \Big|_{x_0}^T (x - x_0) + \frac{1}{2} (x - x_0)^T H \Big|_{x_0} (x - x_0)$$

$$\Rightarrow 0 + b^T x + \frac{1}{2} x^T (A + A^T) x$$

$$\boxed{\Rightarrow b^T x + \frac{1}{2} x^T (A + A^T) x}$$

\exists A is symmetric

$$\boxed{= b^T x + \frac{1}{2} x^T (2A) x}$$

\Rightarrow these approximation are not exact as we increased the order we will get more closer value with less error.

c) what are the necessary and sufficient condition for A to be positive definite?

(5)

→ Since $A \in \mathbb{R}^{n \times n}$; so the necessary and sufficient condition for A to be positive definite is

→ All the eigen value of A must be ~~greater than~~ Positive

$$\lambda > 0$$

→ $x^T A x > 0$ for all x [other than - zero vector]

→ All upper left determinants must be > 0 .

d) what are the necessary and sufficient condition for A to have full rank

→ The $|A| \neq 0$. { Determinant of A $\neq 0$. }

↳ All rows are linearly independent

e) If there exist $y \in \mathbb{R}^n$ and $y \neq 0$ such that $A^T y = 0$ then what are the condition on b for $Ax = b$ to have solution for x

$$A^T y = 0 \quad \therefore y \in N(A^T)$$

$$Ax = b$$

~~$(A^T y)^T = 0^T \Rightarrow y^T A = 0^T$~~

mean $b \in C(A)$

$\therefore y$ is perpendicular to b.

$$x^T (A^T y) = 0 \Rightarrow (Ax)^T y = 0 \Rightarrow$$

$$b^T y = 0$$

23) Due to the Recent Formulate an optimization problem to determine the minimum grocery cost to satisfy the Nutrition need. (6)

Example matrix

unit price	Nutrition $\rightarrow y_1, y_2, \dots, y_j, \dots, y_M$					
	Food \downarrow					
c_1	f_1	a_{11}	a_{12}	\dots	a_{1n}	
c_2	f_2	a_{21}	a_{22}	\dots	a_{2n}	
\vdots	\vdots	\vdots	\vdots	\vdots	\vdots	
c_j	f_j	\vdots	\vdots	a_{ij}	\vdots	
\vdots	\vdots	\vdots	\vdots	\vdots	\vdots	
c_N	f_N	a_{N1}	a_{N2}	\dots	a_{Nn}	

\Rightarrow objective function \Rightarrow minimize the cost

$$= \min \sum_{i=1}^N f_i c_i$$

Constraints : $\sum_{i=1}^N f_i a_{ij} \geq b_j \Rightarrow \sum_{i=1}^N f_i a_{ij} - b_j \geq 0$
for all $j=1, 2, \dots, M$

$$f_i \geq 0$$