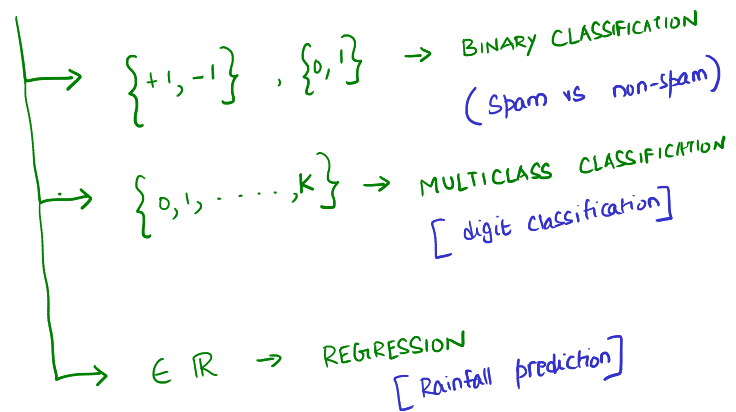


SUPERVISED LEARNING

Input: $\{x_1, \dots, x_n\}$ $x_i \in \mathbb{R}^d$ \leftarrow Features / Attributes
 $\{y_1, \dots, y_n\}$ \leftarrow LABELS (supervision)



REGRESSION

INPUT / TRAINING DATA $\{x_1, \dots, x_n\}$ $x_i \in \mathbb{R}^d$
 $\{y_1, \dots, y_n\}$ $y_i \in \mathbb{R}$

Goal! Learn $f: \mathbb{R}^d \rightarrow \mathbb{R}$

- How do we measure "goodness" of a function $f: \mathbb{R}^d \rightarrow \mathbb{R}$

- $$\text{error}(f) = \sum_{i=1}^n (f(x_i) - y_i)^2$$

- How small can this error be? 0

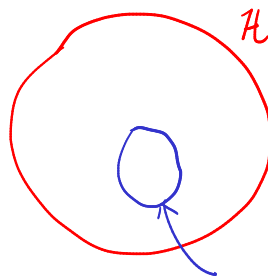
- Which f achieves zero error?

$$f(x_i) = y_i \quad \forall i$$

What is the problem?

- By "memorizing", we can get zero error on training data
- What we care is about test performance.
- Impose "STRUCTURE" to reduce search space.

SIMPLEST STRUCTURE - LINEAR STRUCTURE.



Set of all functions
 $f: \mathbb{R}^d \rightarrow \mathbb{R}$.

$$H_{\text{linear}} = \left\{ \begin{array}{l} f_w: \mathbb{R}^d \rightarrow \mathbb{R} \\ f_w(x) = w^T x \end{array} \right. \text{ s.t. } \left. \begin{array}{l} \text{for} \\ \text{all } w \in \mathbb{R}^d \end{array} \right\}$$

GOAL:

$$\min_{f_w \in H_{\text{linear}}} \sum_{i=1}^n (f_w(x_i) - y_i)^2$$

(or) equivalently -

$$\min_{w \in \mathbb{R}^d} \sum_{i=1}^n (w^T x_i - y_i)^2$$

→ LINEAR REGRESSION

$$\min_{w \in \mathbb{R}^d} \sum_{i=1}^n (w^T x_i - y_i)^2 = \underbrace{\|Xw - y\|_2^2}$$

$$X^T = \begin{bmatrix} x_1 & x_2 & \dots & x_n \end{bmatrix} \begin{bmatrix} 1 \\ w \\ 1 \end{bmatrix} \quad \begin{matrix} n \times d & d \times 1 \end{matrix}$$

$$y = \begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix}_{n \times 1}$$

$$\min_{w \in \mathbb{R}^d} (X^T w - y)^T (X^T w - y)$$

← unconstrained
Quadratic (in w)
Optimisation problem

Solution: Take derivative (gradient) and set to zero.

$$f(w) = (X^T w - y)^T (X^T w - y)$$

$$\nabla f(w) = 2(X^T X)w - 2(X^T y)$$

Solution satisfies $\boxed{(X^T X)w^* = X^T y}$

OBSERVATION

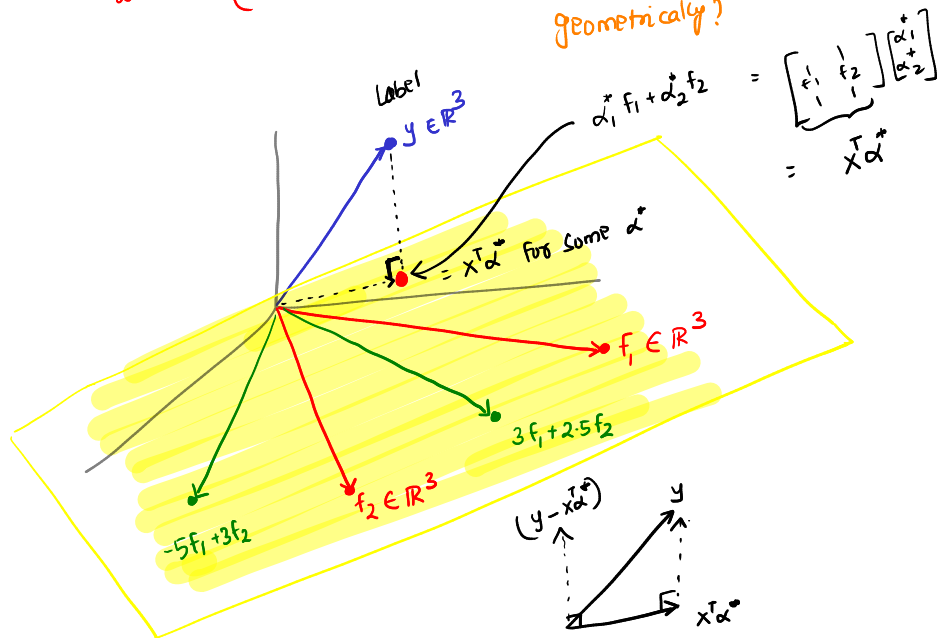
Like PCA, w^* depends on a "Covariance" like matrix. But it also involves y .

$$w^* = (xx^T)^{\dagger} xy \quad \leftarrow \text{Pseudo-inverse.}$$

- Lin reg has closed form solution
- GEOMETRIC VIEW?
- COMPUTATIONAL CONSIDERATIONS?
- NON-LINEAR FEATURE \rightarrow LABEL RELATIONSHIP?
- PROBABILISTIC VIEW?

$w^* = (xx^T)^{\dagger} xy \leftarrow$ How can we interpret this geometrically?

$$\begin{array}{cc} f_1 & f_2 \\ \text{height} & \text{weight} \end{array} \quad \begin{array}{c} x_1 \\ x_2 \\ x_3 \end{array} \begin{bmatrix} | \\ | \\ | \end{bmatrix} \quad \begin{array}{c} y_1 \\ y_2 \\ y_3 \end{array} \begin{bmatrix} | \\ | \\ | \end{bmatrix} \quad \left| \begin{array}{l} d=2 \\ n=3 \end{array} \right.$$



$$(y - x^T \alpha^*)^T (x^T \alpha^*) = 0$$

$$y^T x^T \alpha^* - \alpha^{*T} (xx^T) \alpha^* = 0 \quad \text{--- (1)}$$

Recall, $w^* = (xx^T)^{\dagger} xy$

Substituting $w^* = \alpha^*$ on L.H.S, we get

$$y^T x^T ((xx^T)^{\dagger} xy) - ((xx^T)^{\dagger} xy)^T (xx^T) ((xx^T)^{\dagger} xy)$$

$$= 0 \quad \left[\begin{array}{l} \text{USE} \\ xx^T \text{ is symmetric} \end{array} \right]$$

CONCLUSION:

$X^T w^*$ is the PROJECTION of the Labels onto the Subspace spanned by the features.