$$\omega^{\dagger} = \widetilde{\omega}_{ML} \leftarrow \text{Max likelihood.} = (xx^{\dagger})xy_{\text{random}}$$

$$y|_{x} = \overline{M}x + \underline{\epsilon} \longrightarrow N(0,6^{2}) \qquad \left\{ (x_{1},y_{1}), \dots (x_{n},y_{n}) \right\}$$

$$N(\overline{M}x,6^{2}) \qquad \overline{M}x_{1}+\epsilon_{1}$$

$$\overline{M} \in \mathbb{R}^{d} \qquad \widehat{M}_{ML} \in \mathbb{R}^{d}$$

Want a way to understand how good WAL is in estimating W

Mean Squared 
$$\rightarrow \mathbb{E}\left[\|\widehat{\mathcal{H}}_{ML} - \mathcal{H}\|^2\right] = 6^2 \cdot \operatorname{trace}\left(\left(xx^{T}\right)^{-1}\right)$$

over randomness

in  $\mathcal{Y}$ 

$$A = \begin{bmatrix} a_1 & a_2 \\ & a_d \end{bmatrix}$$

$$(\pi(A) = \sum_{i=1}^{d} a_i = \sum_{i=1}^{d} \lambda_i$$

Eigenvalues of  $(xx^{\frac{1}{2}})$  be  $\{\lambda_1, \ldots, \lambda_d\}$ Let Eigenvalue of  $(xx^{\frac{1}{2}})^{-1}$  where  $\{\frac{1}{\lambda_1}, \dots, \frac{1}{\lambda_d}\}$ 

Mean squerror 
$$(\hat{a}_{HL})$$

$$\mathbb{E}\left(\|\hat{a}_{HL} - w\|^2\right) = 6^2 \left(\sum_{i=1}^d \frac{1}{\lambda_i}\right)$$

For some matrix 
$$A_{i}$$
 let Eigen values be  $\{\lambda_{i}, \dots, \lambda_{d}\}$ .

What are Eigenvalues of  $A+\lambda I$ ?  $\{\lambda_{i}+\lambda_{i}, \dots, \lambda_{d}+\lambda_{d}\}$ 

$$= \lambda_{i}v_{i}+\lambda v_{i}$$

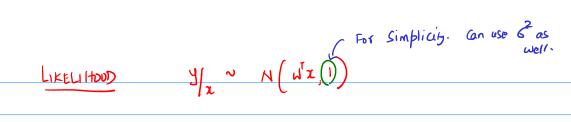
$$= (x_{i}x_{i}+\lambda v_{i})$$

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$$= (x_{i}x_{i}+\lambda v_{i})$$

## EXISTENCE Thm : (Informal) In practice, find & by CROSS VALIDATION RAIN SET VALIDATION SET 80% 20% TRAIN SET · Train on the training Set and Check For emor on Validation spy. · Pick & that gives least emor. K-FOLD CROSS VALIDATION · Train on folds FK {F<sub>12</sub>... F<sub>i-13</sub>, F<sub>i-13</sub>... Fk} · Validate on Fi · Pick & that gives least average error-LEAVE ONE DUT CROSS VALIDATION $\hat{W}_{\text{rew}} = (xx^{\tau} + \lambda z)^{-1} xy$ Is there an alternate way to understand I'me? BAYESIAN MODELING NEED A PRIOR on ω i.e., P(ω)



$$P(\omega \mid \{k_1, y_1) \cdots \mid k_n, y_n\}) \propto P(\{k_1, y_1), \cdots, \{k_n, y_n\}, \cdots, \{k_n, y_n\}\}) \times P(\omega)$$

How will the MAP estimate look like?

$$\hat{\omega}_{\text{mAP}} = \min_{\omega} \frac{1}{2} \underbrace{\frac{\sum_{i=1}^{n} (y_i - \omega x_i)^2}{\sum_{i=1}^{n} (y_i - \omega x_i)^2} + \frac{1}{2} \|\omega\|^2}_{\text{f}(\omega)}$$

Take gradient, Set it to 0 to solve for wimap.

