Unsupervised learning

Representation learning

L PCA / kernel PCA

Assumed for Jake

Probabilistic

Probabilistic

Representation learning

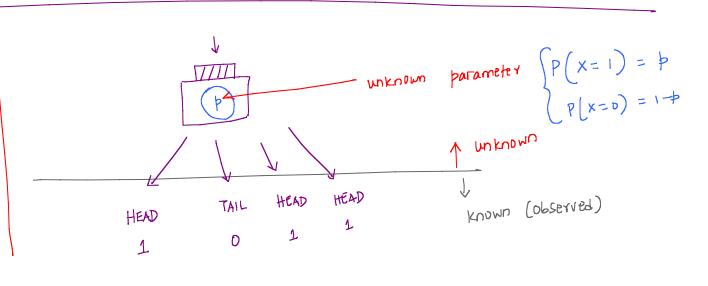
L LLyod's / k-means.

"There is some probabilistic mechanism that generates data about which we don't know "something". Given data, find/estimate what we don't know"

- · OBSERVE data
- · "ASSUME" a model

that generates data

ESTIMATE UNKNOWN
 parameters using data.



ESTIMATE :



ASSUMPTIONS

OBSERVATIONS ARE

- (1) INDEPENDENT
- (1) IDENTICALLY DISTRIBUTED

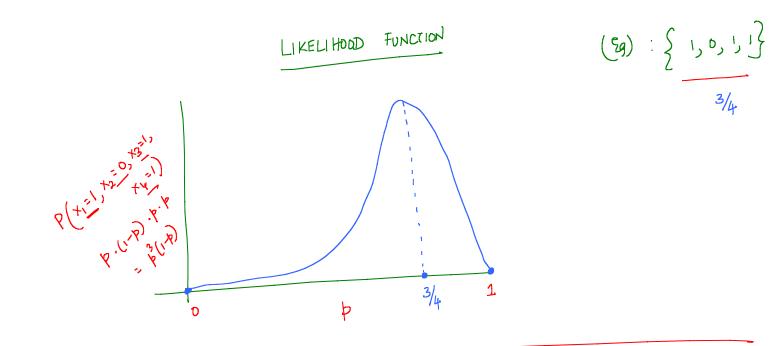
Givess =
$$2/3$$
? Y
= 0.0001? Y
= 0? N
= 1? N

INDEPENDENCE

$$P(x_i/x_j) = P(x_i)$$

$$+ i + j$$

$$P(x_i=1) = P(x_j=1) = P$$
+i,j



FISHERS PRINCIPLE OF MAXIMUM LIKELIHOOD

$$L\left(\frac{p}{p}; \{x_1, x_2, \dots, x_n\}\right) = p\left(\frac{x_1, x_2, \dots, x_n}{p}; \frac{p}{p}\right) \xrightarrow{\text{undexlying parameter.}}$$

$$= p\left(\frac{x_1, p}{p}\right) \cdot p\left(\frac{x_2, p}{p}\right) \cdot \dots \quad p\left(\frac{x_n, p}{p}\right)$$

$$= \prod_{i=1}^{n} \frac{x_i}{p} \cdot \binom{1-x_i}{p} \cdot \binom{$$

=
$$\underset{p}{\operatorname{arg}} \operatorname{max} \sum_{i=1}^{n} \left[x_{i} \log p + (i-x_{i}) \log (i-p) \right]$$

Take derivative of logL(P), Set it to 0 to get

$$\frac{1}{p_{ML}} = \frac{1}{n} \sum_{i=1}^{\infty} x_i$$
 Fraction of 1's

$$Data = \{x_1, \ldots, x_n\}$$
 $x_i \in \mathbb{R}$ $\forall i$

$$X_i \sim Gaussian (A, 6^2)$$
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M-> withour ; 62-> known.

$$L\left(\mathcal{A}_{1}, 6^{2}, \{x_{1}, \dots, x_{n}\}\right) = P\left(x_{1}, \dots, x_{n}; A_{1}, 6^{2}\right)$$

$$= \prod_{i=1}^{n} P\left(x_{i}; A_{1}, 6^{2}\right)$$

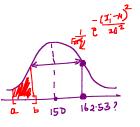
$$\downarrow_{i=1}$$

$$L\left(\mathcal{A}, 6^{2}, \left\{x_{1}, \dots, x_{n}\right\}\right) = \int_{X_{1}, \dots, x_{n}} \left(x_{1}, \dots, x_{n}, x_{n}, x_{n}, x_{n}\right)$$

$$= \frac{1}{\sqrt{1 + \frac{2}{26^2}}} - \frac{2}{\sqrt{1 + \frac{2}{26^2}}}$$

$$= \frac{1}{\sqrt{1 + \frac{2}{26^2}}} = \frac{1}{\sqrt{2\pi 6}} = \frac{2}{\sqrt{26^2}}$$

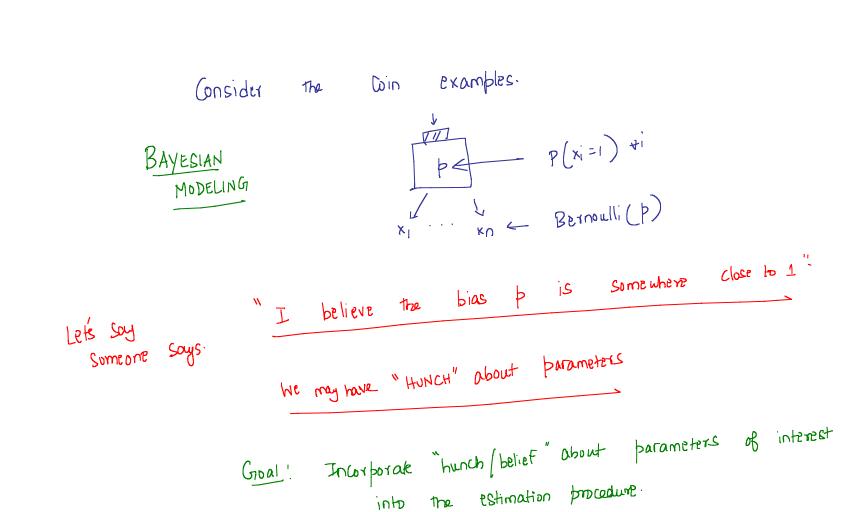
1,= 162.53 CM



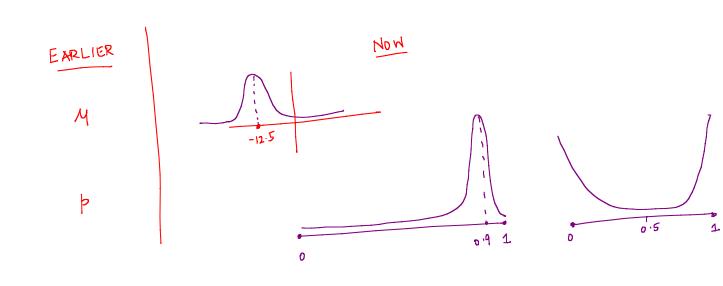
$$\log L\left(M, \delta^{2}, \left\{x_{1}, \dots, x_{n}\right\}\right) = \sum_{i=1}^{n} \left[\log \left(\frac{1}{\sqrt{m} \delta}\right) - \left(\frac{2i - M}{2\delta^{2}}\right)^{2}\right]$$

$$\frac{1}{4}_{ML} = \underset{M}{\operatorname{arg\,max}} \sum_{i=1}^{n} - (x_i - 4)^2$$

$$\frac{1}{M_{ML}} = \frac{1}{L} \sum_{i=1}^{n} x_i$$



APPROACH: Think of the parameter to estimate as a "random" variable.



HUNCH -> Codified using a probability

DATA

UPDATED

HUNCH

Codified using a prob

distribution

P(0)

PRIOR

P(0)

PRIOR

P(0)

PRIOR

POSTERIOR

$$\frac{\text{Bayes law}}{P(A|B)} = \frac{P(B/A) \cdot P(A)}{P(B)}$$

$$A \Rightarrow Parameters \Theta$$

$$B \Rightarrow DATA \left\{x_1, \dots, x_n\right\}$$

$$= \left(P\left(\left\{x_1, \dots, x_n\right\} \middle| \Theta\right)\right) \cdot P\left(\Theta\right)$$

$$P\left(\left\{x_1, \dots, x_n\right\}\right) = \left(P\left(\left\{x_1, \dots, x_n\right\} \middle| \Theta\right)\right) \cdot P\left(\left\{\theta\right\}\right)$$

$$P\left(\left\{x_1, \dots, x_n\right\}\right) = \left(P\left(\left\{x_1, \dots, x_n\right\}\right)\right) \cdot P\left(\left\{\theta\right\}\right)$$

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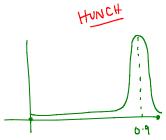
$$P\left(\left\{x_1, \dots, x_n\right\}\right) = \left(P\left(\left\{x_1, \dots, x_n\right\}\right)\right) \cdot P\left(\left\{x_1, \dots, x_n\right\}\right)$$

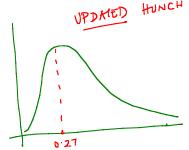
$$P\left(\left\{x_1, \dots, x_n\right\}\right) = \left(P\left(\left\{x_1, \dots, x_n\right\}\right)\right)$$

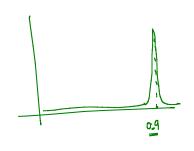
$$P\left(\left\{x_1, \dots, x_n\right\}\right)$$

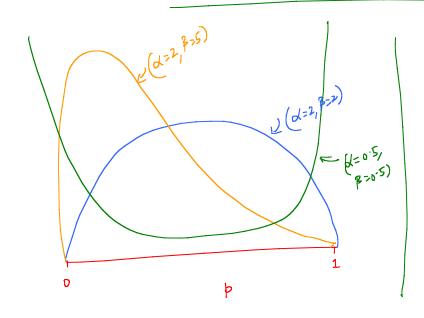
$$P\left(\left\{x_1, \dots, x_n\right\}\right$$

EX AMPLE









PRIOR?
$$P(\theta)$$

$$P(\theta|DMA) \propto P(DMA/\theta) \cdot P(\theta)$$

$$f(\theta) = \frac{1}{p} \left(\frac{1-x_{i}}{p}\right) \cdot \left(\frac{x_{i}}{p} \cdot \frac{1-x_{i}}{p}\right) \cdot \left(\frac{x_{i}}{p} \cdot \frac{x_{i}}{p}\right) \cdot \left(\frac{x_{i}}{p}$$

One possible =
$$\frac{d + n_R}{d + n_R + \beta + n_t} = \frac{d + n_R}{(d + \beta) + n_L}$$

E[Posterior] = E[Beta(d + n_R, \beta + n_t)] = \frac{1}{2}

MAP Estimator - Maximum Aposteriori Estimatori

PMAP