

13 - Relative Motion and The Circular Restricted Three Body Problem

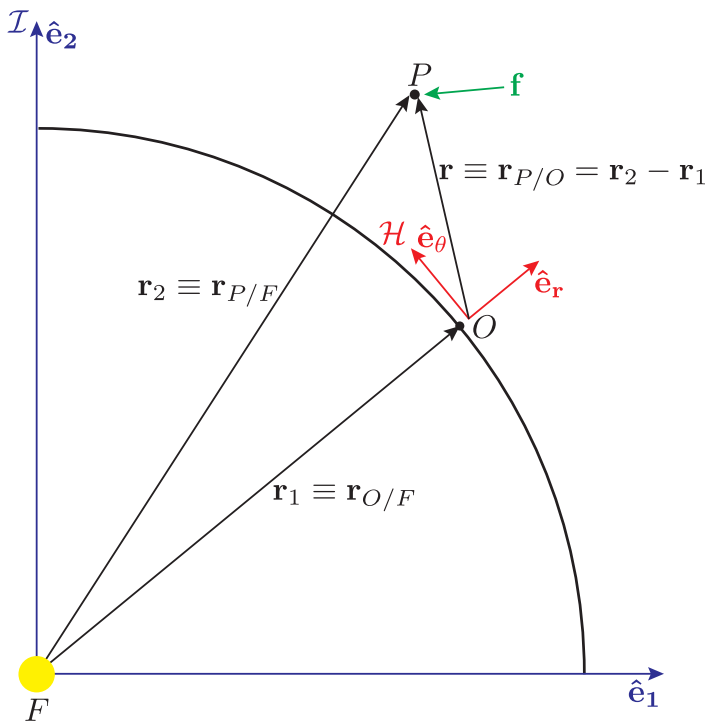
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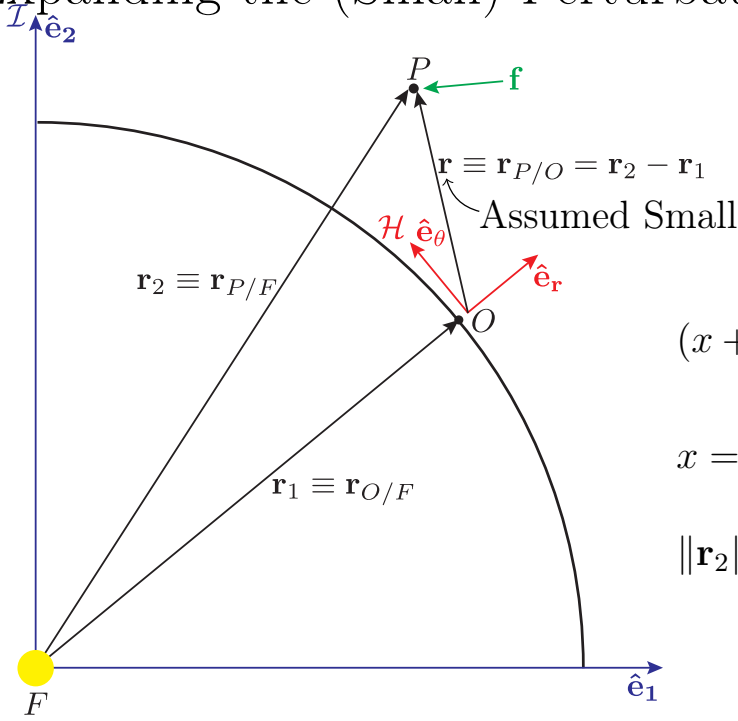
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The Euler-Hill Frame



$$\mathcal{I} \frac{d^2}{dt^2} \mathbf{r} = \frac{\mu}{\|\mathbf{r}_1\|^3} \left(\mathbf{r} - \left(\frac{\|\mathbf{r}_1\|}{\|\mathbf{r}_2\|} \right)^3 \mathbf{r}_2 \right) + \mathbf{f}$$

Expanding the (Small) Perturbation



$$\mathcal{I} \frac{d^2}{dt^2} \mathbf{r} = \underbrace{\frac{\mu}{\|\mathbf{r}_1\|^3}}_{n^2} \left(\mathbf{r} - \left(\frac{\|\mathbf{r}_1\|}{\|\mathbf{r}_2\|} \right)^3 \mathbf{r}_2 \right) + \mathbf{f}$$

$$\|\mathbf{r}_2\|^{-3} \approx [(\mathbf{r}_1 + \mathbf{r}) \cdot (\mathbf{r}_1 + \mathbf{r})]^{-\frac{3}{2}}$$

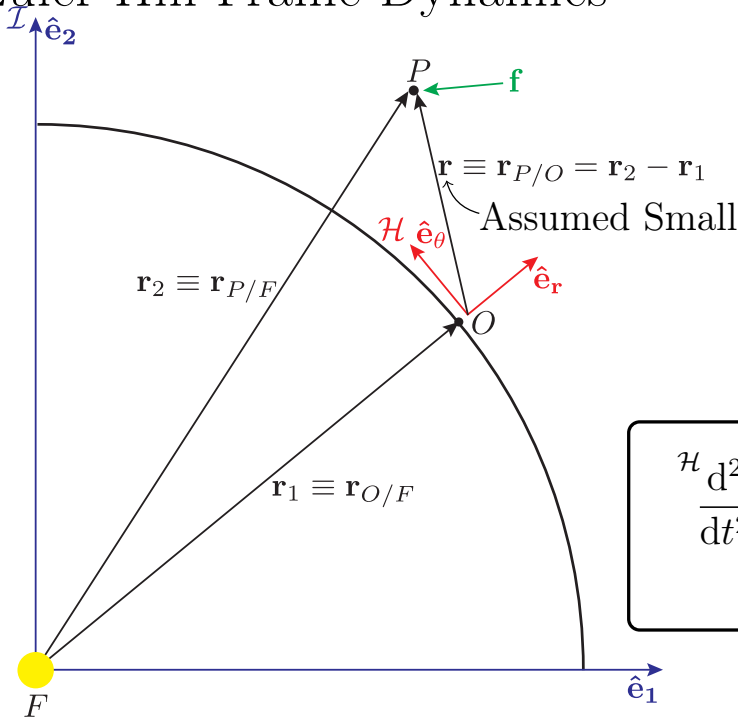
$$(x + y)^r = \sum_{k=0}^{\infty} \binom{r}{k} x^{r-k} y^k = x^r + r x^{r-1} y + \dots$$

$$x = \|\mathbf{r}_1\|^2 \quad y = 2\mathbf{r} \cdot \mathbf{r}_1 + \|\mathbf{r}\|^2 \quad r = -\frac{3}{2}$$

$$\|\mathbf{r}_2\|^{-3} = \|\mathbf{r}_1\|^{-3} \left(1 - \frac{3}{2} \left(\frac{2\mathbf{r} \cdot \mathbf{r}_1}{\|\mathbf{r}_1\|^2} \right) + \mathcal{O}(\mathbf{r}^2) \right)$$

$$\mathcal{I} \frac{d^2}{dt^2} \mathbf{r} \approx n^2 \left(-\mathbf{r} + 3 \frac{\mathbf{r}_1 \cdot \mathbf{r}}{\|\mathbf{r}_1\|^2} \mathbf{r}_1 \right) + \mathbf{f}$$

Euler-Hill Frame Dynamics



$$\mathcal{I} \frac{d^2}{dt^2} \mathbf{r} = \underbrace{\frac{\mu}{\|\mathbf{r}_1\|^3}}_{n^2} \left(\mathbf{r} - \left(\frac{\|\mathbf{r}_1\|}{\|\mathbf{r}_2\|} \right)^3 \mathbf{r}_2 \right) + \mathbf{f}$$

$$\approx n^2 \left(-\mathbf{r} + 3 \frac{\mathbf{r}_1 \cdot \mathbf{r}}{\|\mathbf{r}_1\|^2} \mathbf{r}_1 \right) + \mathbf{f}$$

$$\begin{aligned} \mathcal{H} \frac{d^2}{dt^2} \mathbf{r} = & -2n \hat{\mathbf{e}}_3 \times \frac{\mathcal{H} d}{dt} \mathbf{r} - n^2 (\hat{\mathbf{e}}_3 \times (\hat{\mathbf{e}}_3 \times \mathbf{r})) \\ & - n^2 (\mathbf{r} - 3(\hat{\mathbf{e}}_r \cdot \mathbf{r}) \hat{\mathbf{e}}_r) + \mathbf{f} \end{aligned}$$

Euler-Hill/Clohessy-Wiltshire Equations

$$\begin{bmatrix} \ddot{x} \\ \ddot{y} \\ \ddot{z} \end{bmatrix}_{\mathcal{H}} = \underbrace{\begin{bmatrix} 2n\dot{y} \\ -2n\dot{x} \\ 0 \end{bmatrix}_{\mathcal{H}} + \begin{bmatrix} n^2x \\ n^2y \\ 0 \end{bmatrix}_{\mathcal{H}}}_{\text{Rotating Frame}} - \underbrace{\begin{bmatrix} n^2x \\ n^2y \\ n^2z \end{bmatrix}_{\mathcal{H}} + \begin{bmatrix} 3n^2x \\ 0 \\ 0 \end{bmatrix}_{\mathcal{H}}}_{\text{Gravity Perturbations}} + \underbrace{[\mathbf{f}]_{\mathcal{H}}}_{\text{Other Perturbations}}$$

$$\ddot{x} - 2n\dot{y} - 3n^2x = \mathbf{f} \cdot \hat{\mathbf{e}}_r \triangleq f_x$$

$$\ddot{y} + 2n\dot{x} = \mathbf{f} \cdot \hat{\mathbf{e}}_\theta \triangleq f_y$$

$$\ddot{z} + n^2z = \mathbf{f} \cdot \hat{\mathbf{e}}_3 \triangleq f_z$$

Natural Motion

$$\ddot{x} - 2n\dot{y} - 3n^2x = 0$$

$$\ddot{y} + 2n\dot{x} = 0$$

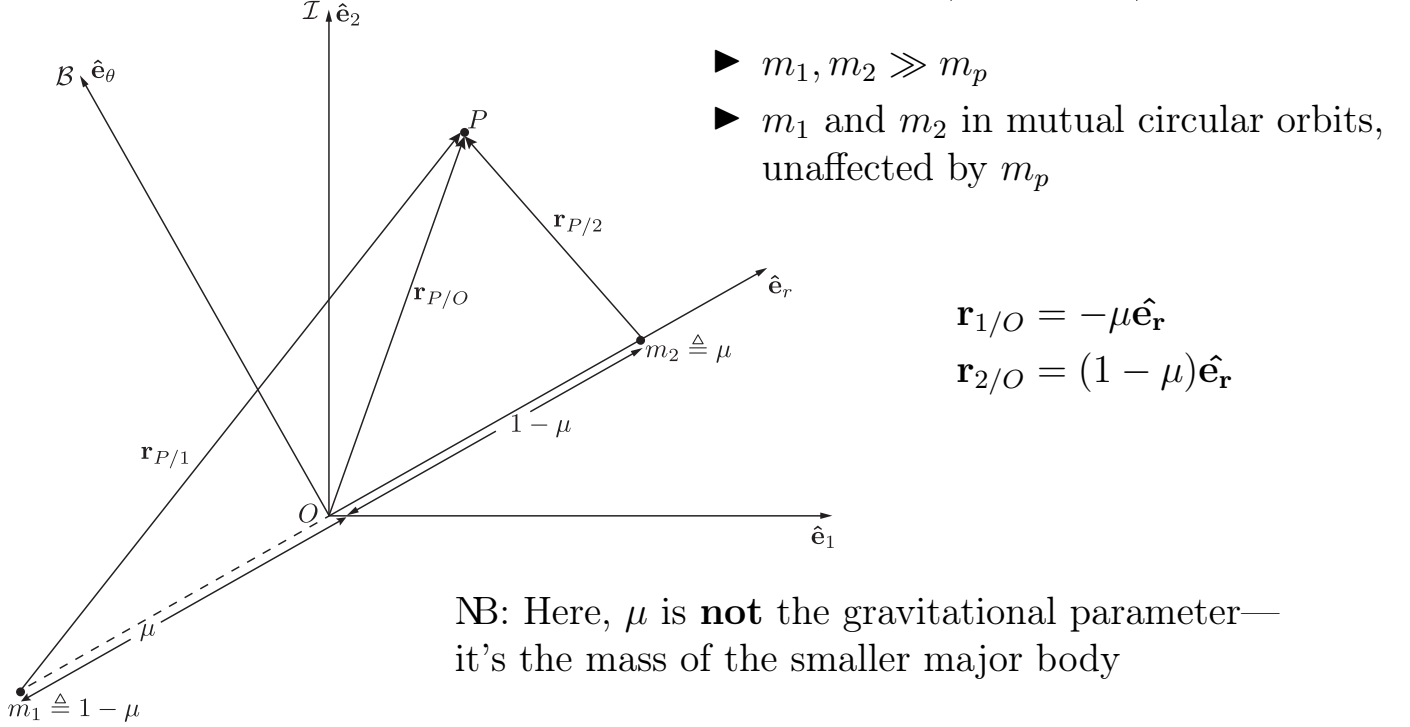
$$\ddot{z} + n^2z = 0$$

$$x(t) = 4x_0 - 3x_0 \cos(nt) + \frac{\dot{x}_0}{n} \sin(nt) + 2\frac{\dot{y}_0}{n} - 2\frac{\dot{y}_0 \cos(nt)}{n}$$

$$y(t) = -6x_0nt + 6x_0 \sin(nt) + 2 \cos(nt) \frac{\dot{x}_0}{n} - 2\frac{\dot{x}_0}{n} + \frac{\dot{y}_0}{n} (4 \sin(nt) - 3nt) + y_0$$

$$z(t) = z_0 \cos(nt) + \frac{\dot{z}_0}{n} \sin(nt)$$

The Circular Restricted 3-Body Problem (CR3BP)



CR3BP Dynamics

$$\mathbf{F}_P = -\frac{Gm_1m_P}{\|\mathbf{r}_{P/1}\|^3}\mathbf{r}_{P/1} - \frac{Gm_2m_P}{\|\mathbf{r}_{P/2}\|^3}\mathbf{r}_{P/2}$$

$$\mathcal{I}_{\omega}^{\mathcal{B}} = n\hat{\mathbf{e}}_3 = \hat{\mathbf{e}}_3$$

$${}^{\mathcal{B}}\mathbf{a}_{P/O} + 2\hat{\mathbf{e}}_3 \times {}^{\mathcal{B}}\mathbf{v}_{P/O} + \hat{\mathbf{e}}_3 \times (\hat{\mathbf{e}}_3 \times \mathbf{r}_{P/O}) = -G \left(\frac{m_1}{\|\mathbf{r}_{P/1}\|^3} \mathbf{r}_{P/1} + \frac{m_2}{\|\mathbf{r}_{P/2}\|^3} \mathbf{r}_{P/2} \right)$$

$$\mathbf{F}_P = -\nabla V$$

$$V = - \left(\frac{1 - \mu}{r_1} + \frac{\mu}{r_2} \right)$$

$$r_1 \triangleq \|\mathbf{r}_{P/1}\| = \sqrt{(x + \mu)^2 + y^2 + z^2}$$

$$r_2 \triangleq \|\mathbf{r}_{P/2}\| = \sqrt{(x - (1 - \mu))^2 + y^2 + z^2}$$

$$\begin{aligned} \ddot{x} - 2\dot{y} - x &= -\frac{\partial V}{\partial x} \\ \ddot{y} + 2\dot{x} - y &= -\frac{\partial V}{\partial y} \\ \ddot{z} &= -\frac{\partial V}{\partial z} \end{aligned}$$

A New Potential

$$\text{Define : } U \triangleq -\frac{1}{2}(x^2 + y^2) - \left(\frac{1-\mu}{r_1} + \frac{\mu}{r_2} \right)$$

$$\left. \begin{aligned} \ddot{x} - 2\dot{y} - x &= -\frac{\partial V}{\partial x} \\ \ddot{y} + 2\dot{x} - y &= -\frac{\partial V}{\partial y} \\ \ddot{z} &= -\frac{\partial V}{\partial z} \end{aligned} \right\} \Rightarrow$$

$$\boxed{\begin{aligned} \ddot{x} &= -\frac{\partial U}{\partial x} + 2\dot{y} \\ \ddot{y} &= -\frac{\partial U}{\partial y} - 2\dot{x} \\ \ddot{z} &= -\frac{\partial U}{\partial z} \end{aligned}}$$

$$\text{NB: } \frac{1}{2} \frac{d}{dt} (\dot{x}^2 + \dot{y}^2 + \dot{z}^2) = -\frac{dU}{dt}$$

The Jacobi Constant

$$\frac{1}{2} (\mathcal{B}_{\mathbf{v}_{P/O}} \cdot \mathcal{B}_{\mathbf{v}_{P/O}}) + U(x, y, z) = C \triangleq \text{Jacobi Constant}$$

$$\mathcal{B}_{\mathbf{v}_{P/O}} = \mathcal{I}_{\mathbf{v}_{P/O}} - \hat{\mathbf{e}}_3 \times \mathbf{r}_{P/O}$$

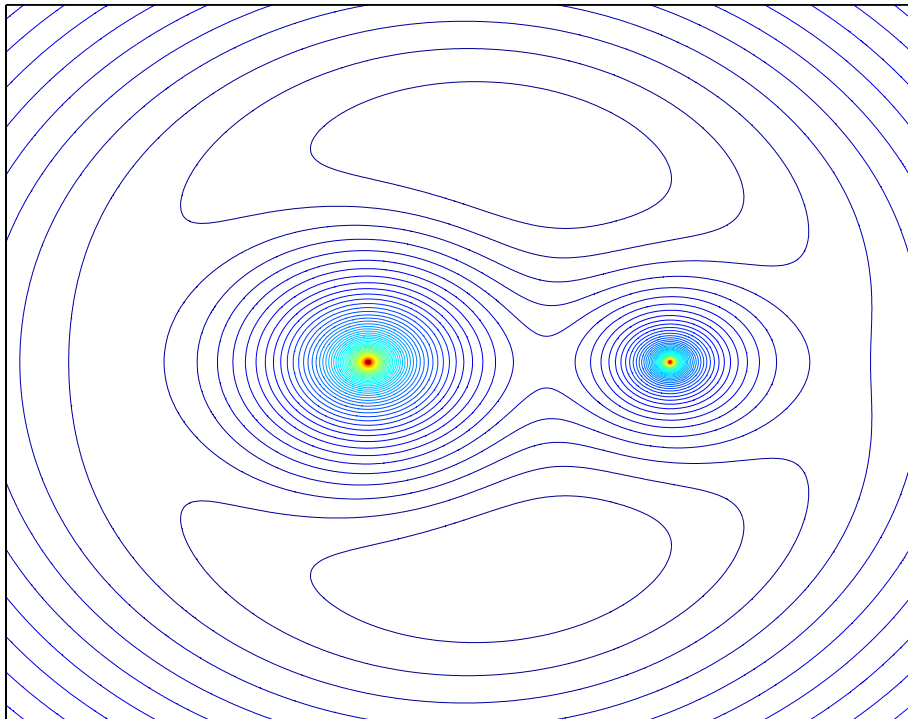
$$\underbrace{\frac{1}{2} (\mathcal{I}_{\mathbf{v}_{P/O}} \cdot \mathcal{I}_{\mathbf{v}_{P/O}})}_{\text{KE+PE}} - \left(\frac{1-\mu}{r_1} + \frac{\mu}{r_2} \right) - \underbrace{\mathcal{I}_{\mathbf{v}_{P/O}} \cdot (\hat{\mathbf{e}}_3 \times \mathbf{r}_{P/O})}_{\hat{\mathbf{e}}_3 \cdot (\mathbf{r}_{P/O} \times \mathcal{I}_{\mathbf{v}_{P/O}}) = \hat{\mathbf{e}}_3 \cdot \mathcal{I}_{\mathbf{h}_{P/O}}} = C$$

$$\boxed{E - h \cos(I) = C}$$

Set by initial conditions

Total Energy of Mass P Angular Momentum of Mass P Angle between orbit of mass P and $\hat{\mathbf{e}}_1 - \hat{\mathbf{e}}_2$ plane

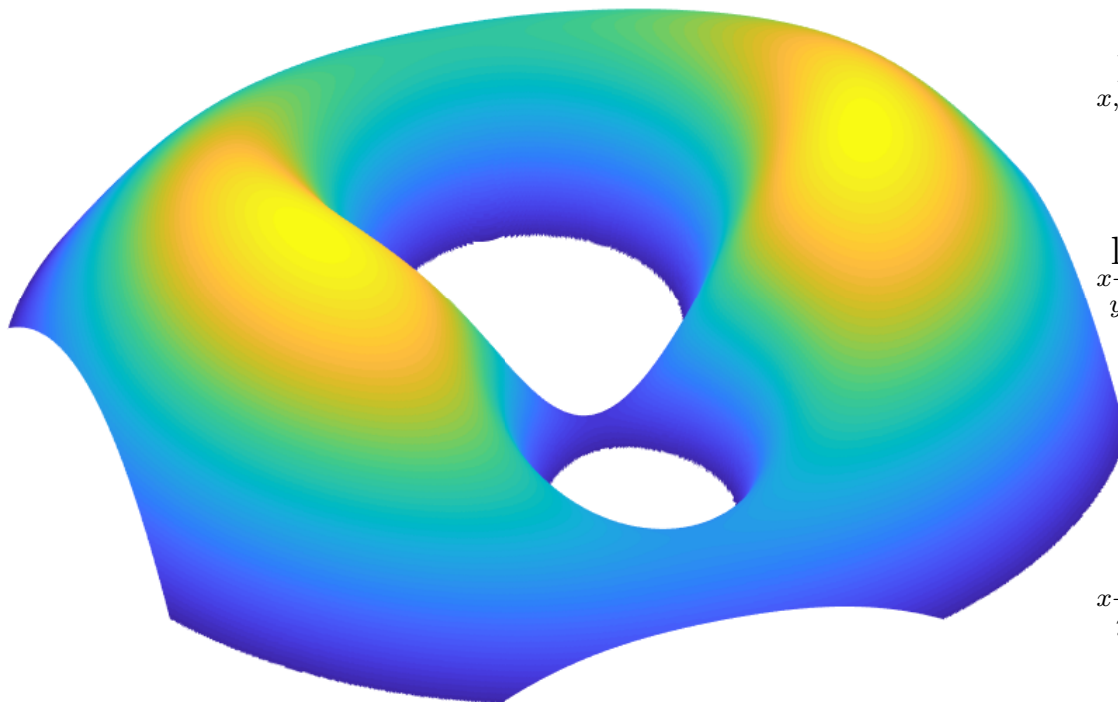
Hill Curves ($\mu = 0.3$)



$$U(x, y) = U(x, -y)$$

$$U(x, y) \neq U(-x, y)$$

Hill Curves ($\mu = 0.3$)



$$\lim_{x, y \rightarrow \infty} U = -\frac{x^2 + y^2}{2}$$

$$\lim_{\substack{x \rightarrow -\mu \\ y \rightarrow 0}} U = -\frac{1 - \mu}{r_1}$$

$$\lim_{\substack{x \rightarrow 1 - \mu \\ y \rightarrow 0}} U = -\frac{\mu}{r_2}$$