

A PROJECT REPORT ON

Implementation of Lung Cancer Nodule Detection

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In

COMPUTER ENGINEERING

Of

SAVITRIBAI PHULE PUNE UNIVERSITY

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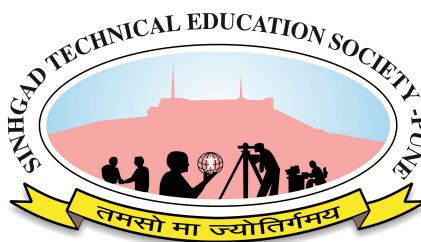
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**SKN SINHGAD INSTITUTE OF TECHNOLOGY AND SCIENCE,
LONAVALA**

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Date:

CERTIFICATE

This is to certify that the project report entitled
“ **Implementation of Lung Cancer Nodule Detection**”

Submitted by

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is a bonafide work carried out by him/her under the supervision of Prof. Neha Jamdar and it is approved for the partial fulfillment of the requirements of Savitribai Phule Pune University, Pune for the award of the degree of Bachelor of Engineering (Computer Engineering) during the year 2017-18.

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Lastly, and the most important, we extend our thanking to our parents and friends who have constantly guided and motivated us to accomplish the task successfully.

Patil Sarang
Maramwar Siddharaj
Gawande Mahesh
Damkondwar Shubham

Abstract

With the recent development of high resolution time-of-flight (TOF) positron emission tomography (PET) and resolution recovery incorporated in the reconstruction algorithm, accurate detection, and quantification of sub-centimeter nodules might become feasible. In this paper, we performed a comprehensive simulation to explore the quantitative accuracy of sub-centimeter nodules using the Otsu, Watershed and GLCM technique. We simulated nodules ranging from 4 to 10 mm in diameter, with 2:1 to 8:1 contrast level, at 1% to 100% (70 million) count-level, and with realistic respiratory motion amplitudes of 5/3, 10/6, and 20/12 mm. Images were reconstructed using motion-compensation ordered subset expectation Otsu thresholding algorithm. The results from this studies were consistent. Segmentation using the watershed transform works better to identify foreground objects and background locations. GLCM feature will be computed from the detected lung nodule in CT image, finally by using machine learning algorithm we detect actual lung cancer nodule.

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Abbreviations

UML

Unified Modeling Language

py

Python

SDLC

Systems development life cycle

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Chapter 1

INTRODUCTION

1.1 Background and Basics

Nowadays the cancer disease patients are increasing rapidly. The main reason behind it that the disease is not detect at early stage. The doctors or any medical consultant can manually analyze the nodule for their CT images. It is not gives the correct diagnosis in the early stage of disease. Sometime it detects in the critical stage. There are many existing system which can work for detecting the lung nodule. So we proposed a system which can predict the lung nodule from the lung CT images by using SVM machine learning algorithm.

1.2 Literature Survey

1. A morphological operation-based approach for Subpleural lung nodule detection from CT images, Rekka Mastouri, Henda Neji, Saoussen Hantous-Zannad, Nawres Khelifa, This paper is focus on an automatic segmentation approach of sub-pleural lung nodules from Computed Tomography (CT) scans based on morphological operations. Because the extraction of sub-pleural nodules is challenging and a computer-aided diagnosis system is, hence, indispensable. The proposed system is divided into three steps: pre-processing, initial detection of sub-pleural lung nodule and post-processing.

2. A Computer Aided Diagnosis for detection and classification of lung nodules, Lakshmi Narayanan A , Prof. Jeeva J.B, The aim of proposed system is to develop an efficient Computer Aided Diagnosis (CAD) for detection of lung nodules from parenchyma region of lung and classify the nodule into either cancerous (Malignant) or non-cancerous (Benign). The proposed system consists of following steps: i) the image taken is enhanced initially and then the region of interest is cropped, where the user can select the area to be cropped. ii) Morphological operation is performed to suppress the blood vessels and enhance the nodules. iii) Nodules are identified by labeling. iv) Features extraction. v) Neural networks are implemented for features classification. The proposed work was able to detect the lung nodule that falls in close proximity to the lung wall. The system is able to achieve an overall accuracy of 92.2%.

3. Automatic lung nodules detection in computed tomography images using nodule filtering and neural networks, A.R. Talebpour, H.R. Hemmati, M. Zarif Hosseinian, The proposed system implements a computer-aided detection (CAD) system that detects small size nodules (larger 3 mm) in High Resolution CT (HRCT) images. It used a cylindrical filter for filtering nodule cases from other objects in images. They use a lung LIDC image database.
4. Lung nodule detection based on 3D convolutional neural networks, Lei Fan, Zhaoqiang Xia, Xiaobiao Zhang, Xiaoyi Feng, This paper proposes a method to detect lung nodule of lung CT images using 3D convolutional neural networks. It combines the traditional morphological preprocessing methods and 3D convolutional neural networks are applied to lung CT images.

1.3 Project Undertaken

1.3.1 Problem Definition

Develop a system that is capable of analyzing CT images of lung nodules using convolutional neural network and providing nodule details for advanced stages of cancer.

1.3.2 Scope Statement

This project applicable to government or private hospitals.

Chapter 2

PROJECT PLANNING AND MANAGEMENT

2.1 Detail System Requirement Specification (SRS)

2.1.1 System Overview

Recently, image processing techniques are widely used in several medical areas for image improvement in earlier detection and treatment stages, where the time factor is very important to discover the abnormality issues in target images, especially in various cancer tumors such as lung cancer, breast cancer. Computer aided segmentation for computed tomography (CT) and magnetic resonance imaging (MRI) are finding the application in computer aided diagnosis, clinical studies, and treatment planning. A new automatic method has been proposed based upon black circular neighborhood algorithm and image processing techniques to extract the nodules. Feature extraction is an important step in algorithms. These separate the area which is then analyzed for detection of nodules to diagnose the disease. Computed tomography (CT), allows effective mapping .CT Image decreases the time complexity. We have used the GLCM Features Which Helps in detection of the nodule .The use of Otsu's Algorithm helps in detection of size and stage of the tumor.

2.1.2 Functional Requirements

- The application is user friendly.
- It provides an easy interface to user.
- The accessibility or response time of the application should be fast.

2.1.3 Non-Functional Requirements

- Interface Requirements: User interface should be simple and easy to understand.
- Performance Requirements: Our system should work properly on large no of users access.

- Software quality attributes such as availability
 - **Reliability** : The system should be reliable i.e there should be machine failure though load comes
 - **Modifiability** : The system should be scalable, rewritable, reusable, and can be updated
 - **Performance** : The performance should be real time and consistent
 - **Security** : The system should be secure i.e one should not be able to hack or change the system until there is no identity
 - **Reusability** : The system should be reusable i.e it can be used by multiple users
 - **Portability** : The system should be portable i.e environment should not matter to it in any situation.
 - **Adaptability** : It should be self adaptable as well as user adaptable

2.2 Project Process Modelling

2.2.1 Waterfall Model

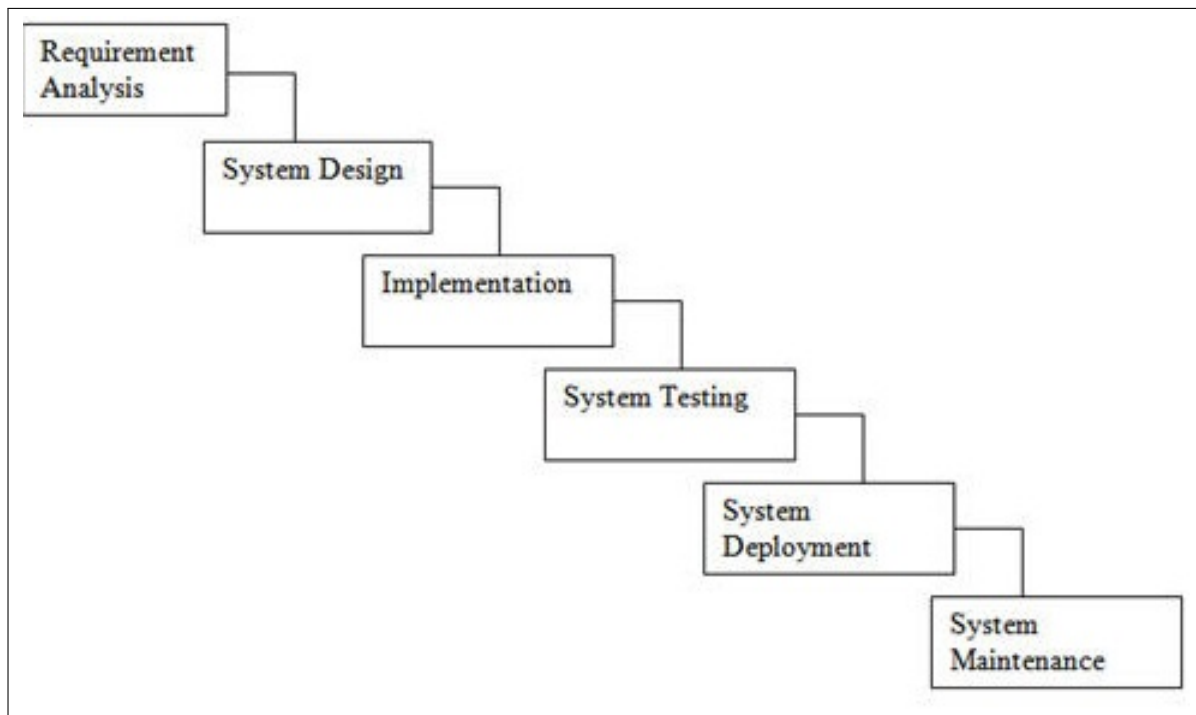


Figure 2.1: Waterfall Model

1. Requirement gathering and analysis:

In this step of waterfall we identify what are various requirements are need for our project such are software and hardware required, database, and interfaces.

2. System Design:

In this system design phase we design the system which is easily understood for end user i.e. user friendly. We design some UML diagrams and data flow diagram to understand the system flow and system module and sequence of execution.

3. Implementation:

In implementation phase of our project we have implemented various module required of successfully getting expected outcome at the different module levels. With inputs from system design, the system is first developed in small programs called units, which are integrated in the next phase. Each unit is developed and tested for its functionality which is referred to as Unit Testing.

4. Testing:

The different test cases are performed to test whether the project module are giving expected outcome in assumed time. All the units developed in the implementation phase are integrated into a system after testing of each unit. Post integration the entire system is tested for any faults and failures.

5. Deployments of System:

Once the functional and non functional testing is done, the product is deployed in the customer environment or released into the market.

6. Maintenance:

There are some issues which come up in the client environment. To fix those issues patches are released. Also to enhance the product some better versions are released. Maintenance is done to deliver these changes in the customer environment. All these phases are cascaded to each other in which progress is seen as flowing steadily downwards like a waterfall through the phases. The next phase is started only after the defined set of goals are achieved for previous phase and it is signed off, so the name "Waterfall Model". In this model phases do not overlap.

2.3 Cost & Efforts Estimates

COCOMO Model:

COCOMO (Constructive Cost Estimation Model) was proposed by Boehm [1981]. According to Boehm, software cost estimation should be done through three stages: Basic COCOMO, Intermediate COCOMO, and Complete COCOMO.

Basic COCOMO Model :

The basic COCOMO model gives an approximate estimate of the project parameters. The basic COCOMO estimation model is given by the following expressions:

$$\text{Effort} = a_1 * (\text{KLOC})^{a_2} \text{ PM}$$

$$T_{\text{dev}} = b_1 \times (\text{Effort})^{b_2} \text{ Months}$$

Where,

1. KLOC is the estimated size of the software product expressed in Kilo Lines of Code,
2. a_1 , a_2 , b_1 , b_2 are constants for each category of software products,
3. T_{dev} is the estimated time to develop the software, expressed in months,
4. Effort is the total effort required to develop the software product, expressed in person months (PMs).

The effort estimation is expressed in units of person-months (PM). It is the area under the person-month plot. It should be carefully noted that an effort of 100 PM does not imply that 100 persons should work for 1 month nor does it imply that 1 person should be employed for 100 months, but it denotes the area under the person-month curve.

Estimation of development effort:

For the three classes of software products, the formulas for estimating the effort based on the code size are shown below:

Organic : $\text{Effort} = 2.4(\text{KLOC})^{1.05} \text{ PM}$

Semi-detached : $\text{Effort} = 3.0(\text{KLOC})^{1.12} \text{ PM}$

Embedded : $\text{Effort} = 3.6(\text{KLOC})^{1.20} \text{ PM}$

Estimation of development time:

For the three classes of software products, the formulas for estimating the development time based on the effort are given below:

Organic : $T_{\text{dev}} = 2.5(\text{Effort})^{0.38} \text{ Months}$

Semi-detached : $T_{\text{dev}} = 2.5(\text{Effort})^{0.35} \text{ Months}$

Embedded : $T_{\text{dev}} = 2.5(\text{Effort})^{0.32} \text{ Months}$

Sr. No.	Month schedule	Phase	Work Status
1.	June-August	Topic searching	Topic Searched
2.	August-September	Topic selection	Topic Selected
3.	August-September	Project confirmation	Project Confirmed
4.	August-September	Literature Survey	Literature Survey Done
5.	September-October	Requirement Analysis	Requirement Analysis Done
6.	September-October	Requirement Gathering	Requirements Gathered
7.	November-December	Designing	Architecture Design
8.	November-December	Designing Test	GUI Tested
9.	November-December	Database Creation	Database Tested
10.	January-February	Coding	Coded Different modules
11.	January-February	Database And Modules Connectivity	Connectivity Done
12.	March	Testing of project	Project Tested
13.	April	Result Analysis	Result Analysis

Table 2.1: Project Scheduling

2.4 Project Scheduling

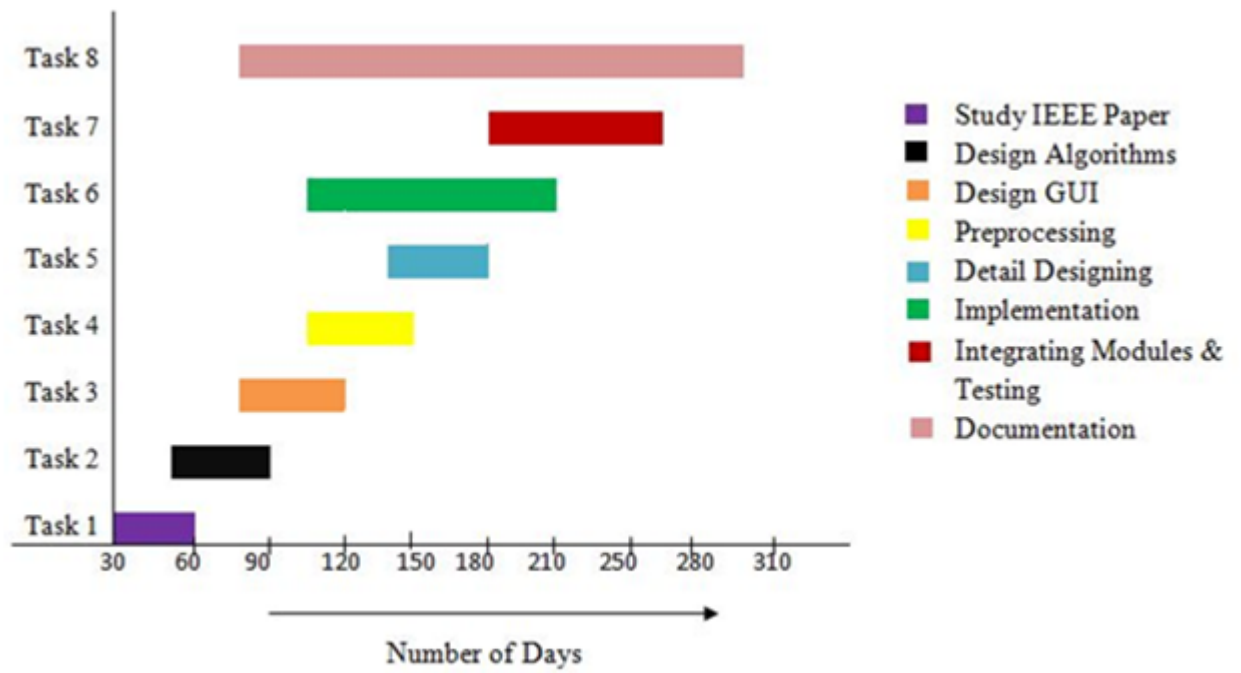


Figure 2.2: Time Line Chart

2.4.1 Time Line Chart

Chapter 3

ANALYSIS & DESIGN

3.1 IDEA Matrix

I	D	E	A
Increase The communication overhead will be increased to bits. We omit a detailed description of the variant scheme due to space limitations	Drive The necessity of Improving system by supporting noisy images	Educate we first preprocess, segmentation, feature extraction on image and then apply classification.	Accelerate We proposed an application to detect lung nodules
Improve The results are improved	Deliver High Performance in terms of machine learning process.	Evaluate Sensitive data being exposed	Associate System is associate with doctors to resolve issue in lungs.
Ignore Giving access to invalid User.	Decrease Chances of losing sensitive data.	Eliminate Noisiness in image.	Avoid Unwanted part of image

Table 3.1: IDEA Matrix

3.2 Mathematical Model

System Description:

$S=\{I,O,F,\text{success},\text{failure}\}$ where,

- I=Input

- O=Output
- F=Functions
- I={U, Li }
U:set of attributes
Li: Lung Images
- Output : Detecting Lung Nodule.
- Functions : {UpImg, Pre-pross, Seg, FE, classify}
 1. UpImg: User can upload Lung Image as a input.
 2. Pre-pross: apply Pre-possessing on image using otsu threshoulding.
 3. Seg: Apply watershed for nodule segmentation.
 4. FE: Feature Extract done using GLCM
 5. Classify: finally using SVM we classify the given image.
- success: Our system predict nodule correctly in very short time.
- failure: If system crashed then can not get the answer.

3.3 Feasibility Analysis

The feasibility of the project is analyzed in this phase and business proposal is put forth with a very general plan for the project and some cost estimates. During system analysis the feasibility study of the proposed system is to be carried out. This is to ensure that the proposed system is not a burden to the company. For feasibility analysis, some understanding of the major requirements for the system is essential.

Three key considerations involved in the feasibility analysis are

- ECONOMICAL FEASIBILITY
- TECHNICAL FEASIBILITY
- SOCIAL FEASIBILITY

1. ECONOMICAL FEASIBILITY

This study is carried out to check the economic impact that the system will have on

the organization. The amount of fund that the company can pour into the research and development of the system is limited. The expenditures must be justified. Thus the developed system as well within the budget and this was achieved because most of the technologies used are freely available. Only the customized products had to be purchased.

Our main goal is to develop our application within 10 months. here we estimate the project cost near to 14,000. So that amount is not grater for any organization to spend on the project.

2. TECHNICAL FEASIBILITY

This study is carried out to check the technical feasibility, that is, the technical requirements of the system. Any system developed must not have a high demand on the available technical resources. This will lead to high demands on the available technical resources. This will lead to high demands being placed on the client. The developed system must have a modest requirement, as only minimal or null changes are required for implementing this system.

In our project we use Lung image dataset we are using for detecting Lung nodule. We use python for developing our project. Here we develop our application on Anaconda IDE.

3. SOCIAL FEASIBILITY

The aspect of study is to check the level of acceptance of the system by the user. This includes the process of training the user to use the system efficiently. The user must not feel threatened by the system, instead must accept it as a necessity. The level of acceptance by the users solely depends on the methods that are employed to educate the user about the system and to make him familiar with it. His level of confidence must be raised so that he is also able to make some constructive criticism, which is welcomed, as he is the final user of the system.

We develop a application that will easy to understand, basically our app use by doctors that identity the Lung nodule by uploading lung image and get result from our application.

3.4 Architecture Diagram

In this system we use Lung image as a input and apply some techniques to identify the nodule of lung. Here first we use Otsu's thresholding method involves iterating through all the possible threshold values and calculating a measure of spread for the pixel levels each side of the threshold, i.e. the pixels that either fall in foreground or background. and then that images are filtered for image segmentation by using watershed algorithm. Segmentation using the watershed transform works better to identify, foreground objects and background locations. By applying GLCM feature that compute from the detected lung nodule in CT image. and finally we apply the SVM machine learning algorithm for detecting nodule of lung.

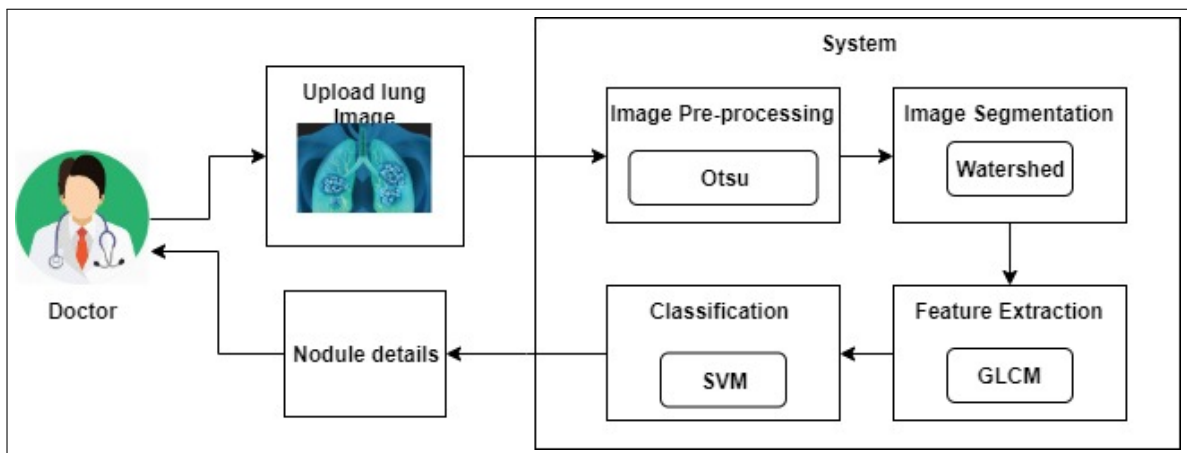


Figure 3.1: System Architecture

3.5 Data Flow Diagrams

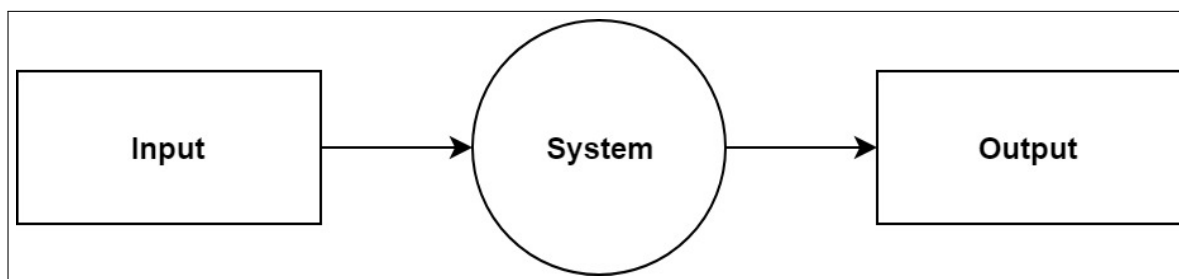


Figure 3.2: Data Flow diagram 0

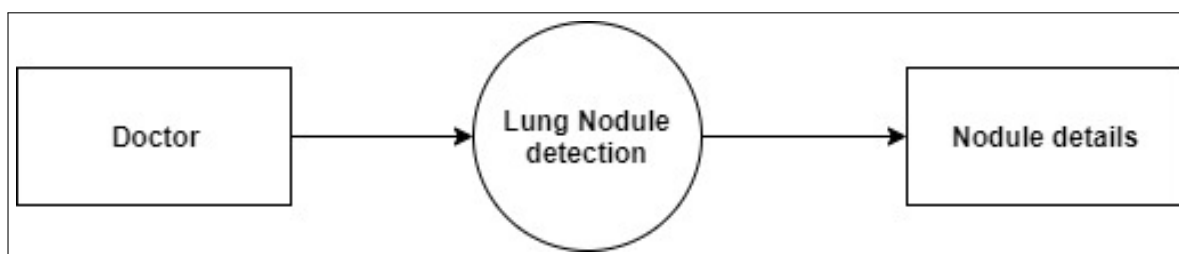


Figure 3.3: Data Flow diagram 1

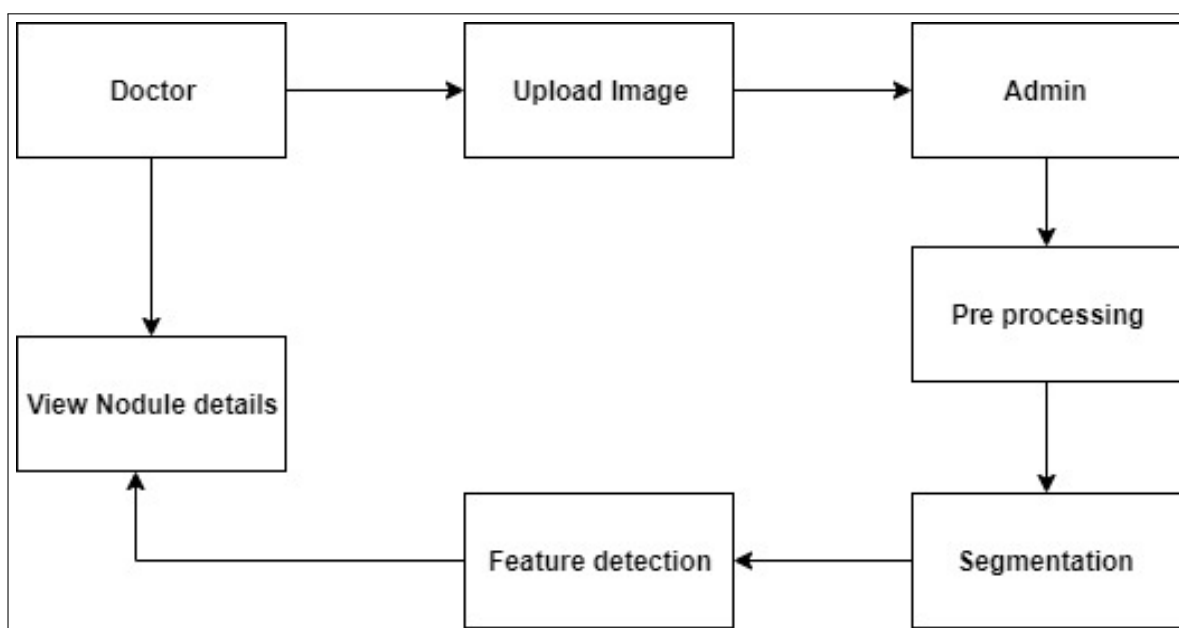


Figure 3.4: Data Flow diagram 2

3.6 ER Diagram

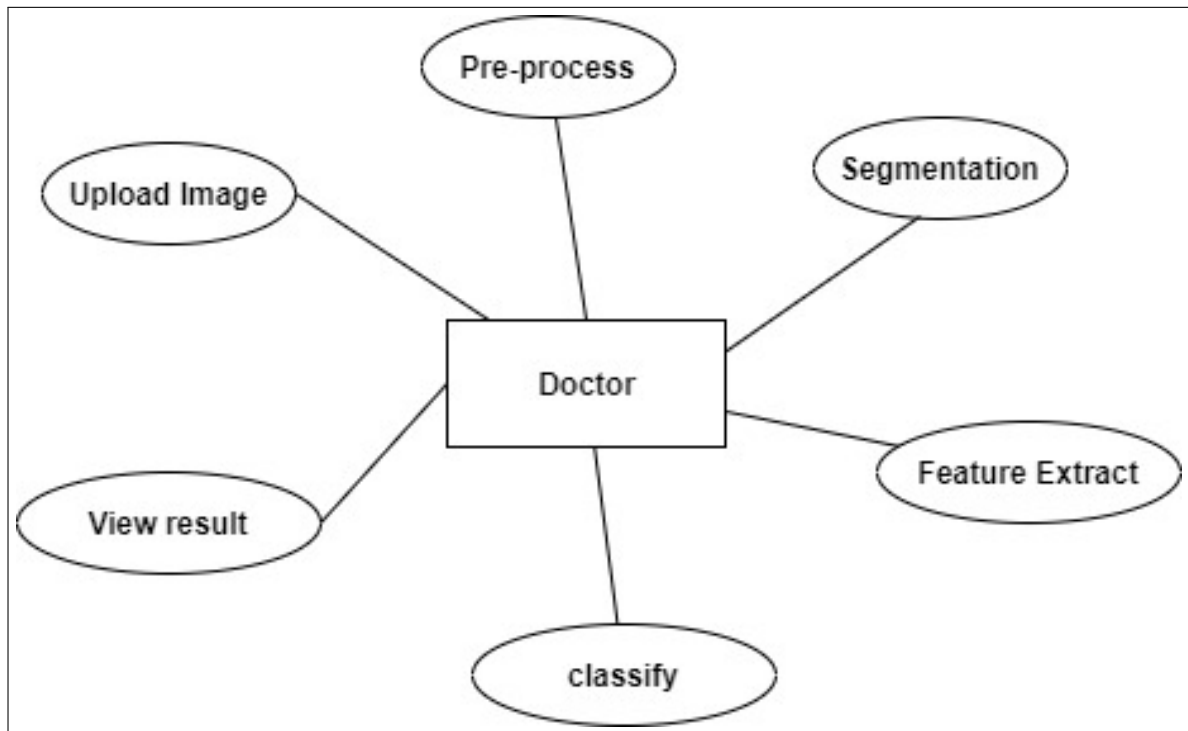


Figure 3.5: ER diagram

3.7 UML Diagrams

3.7.1 Class Diagram

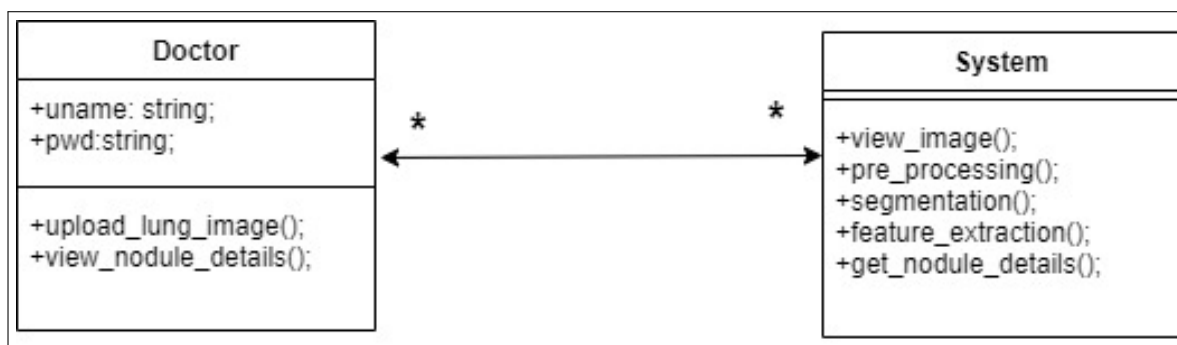


Figure 3.6: Class diagram

3.7.2 Use Case Diagram

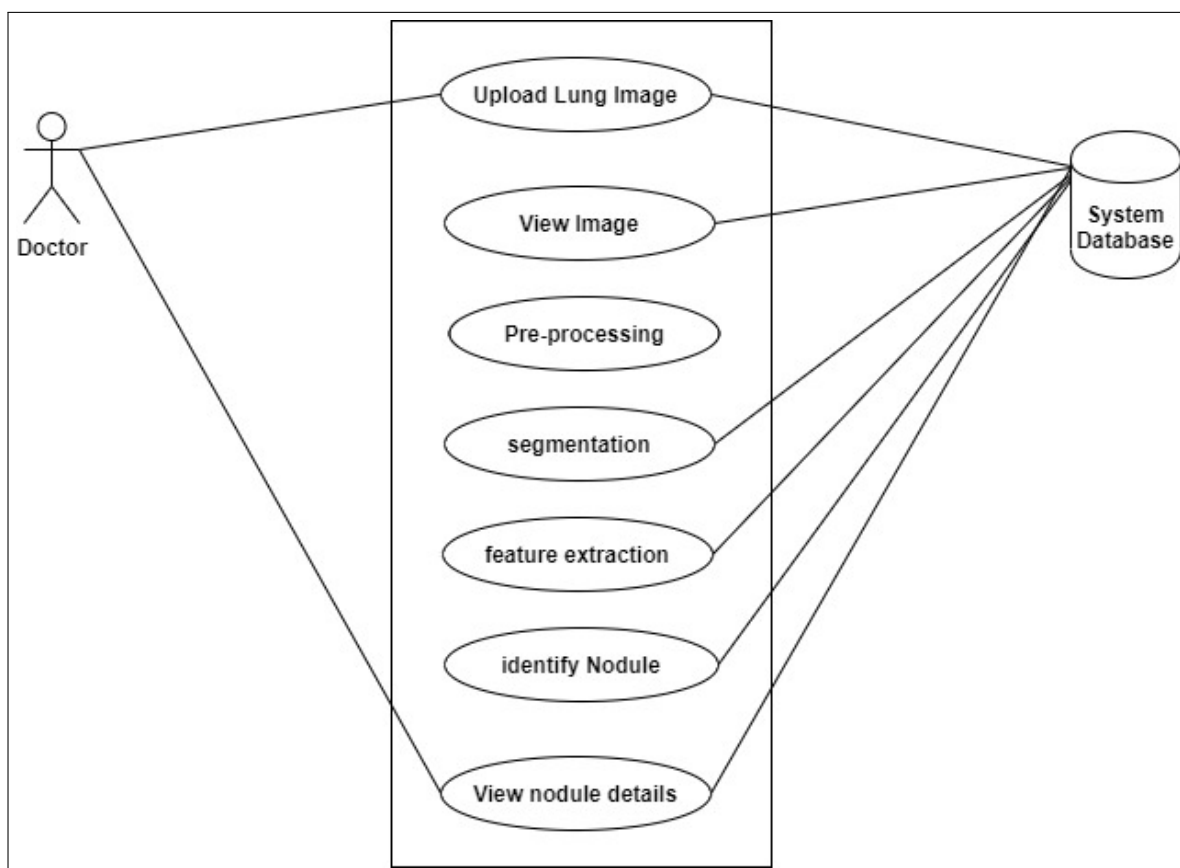


Figure 3.7: Use case diagram

3.7.3 Activity Diagram

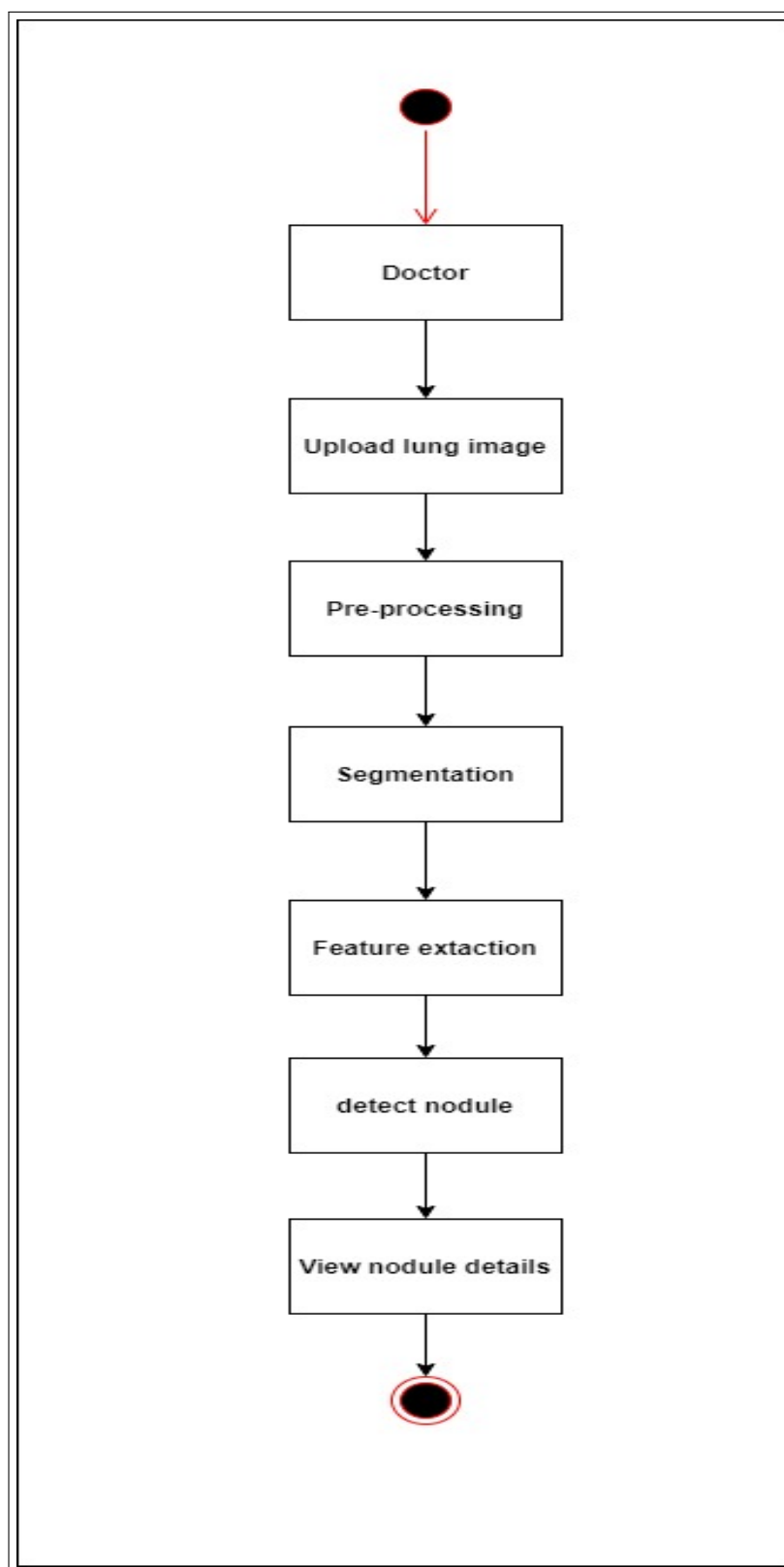


Figure 3.8: Activity diagram

3.7.4 Sequence Diagram

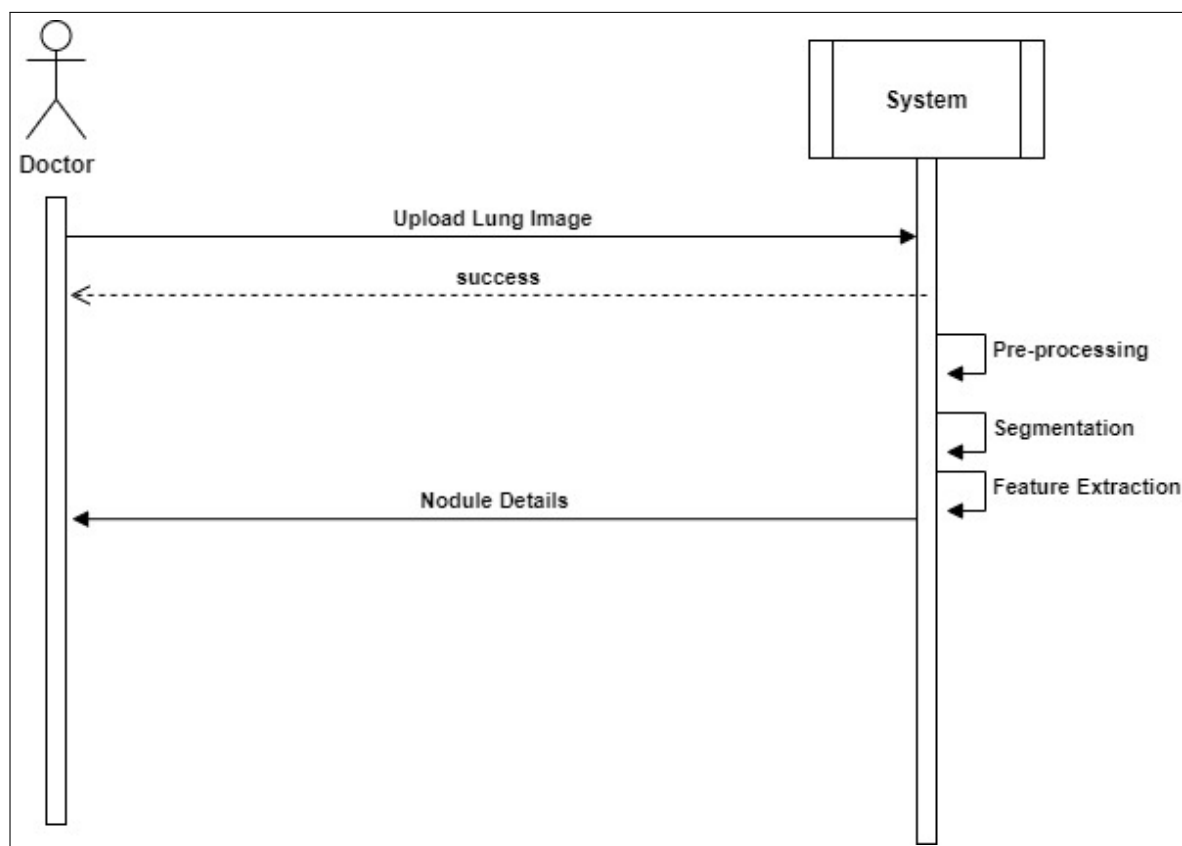


Figure 3.9: Sequence Diagram

3.7.5 State Transition Diagram

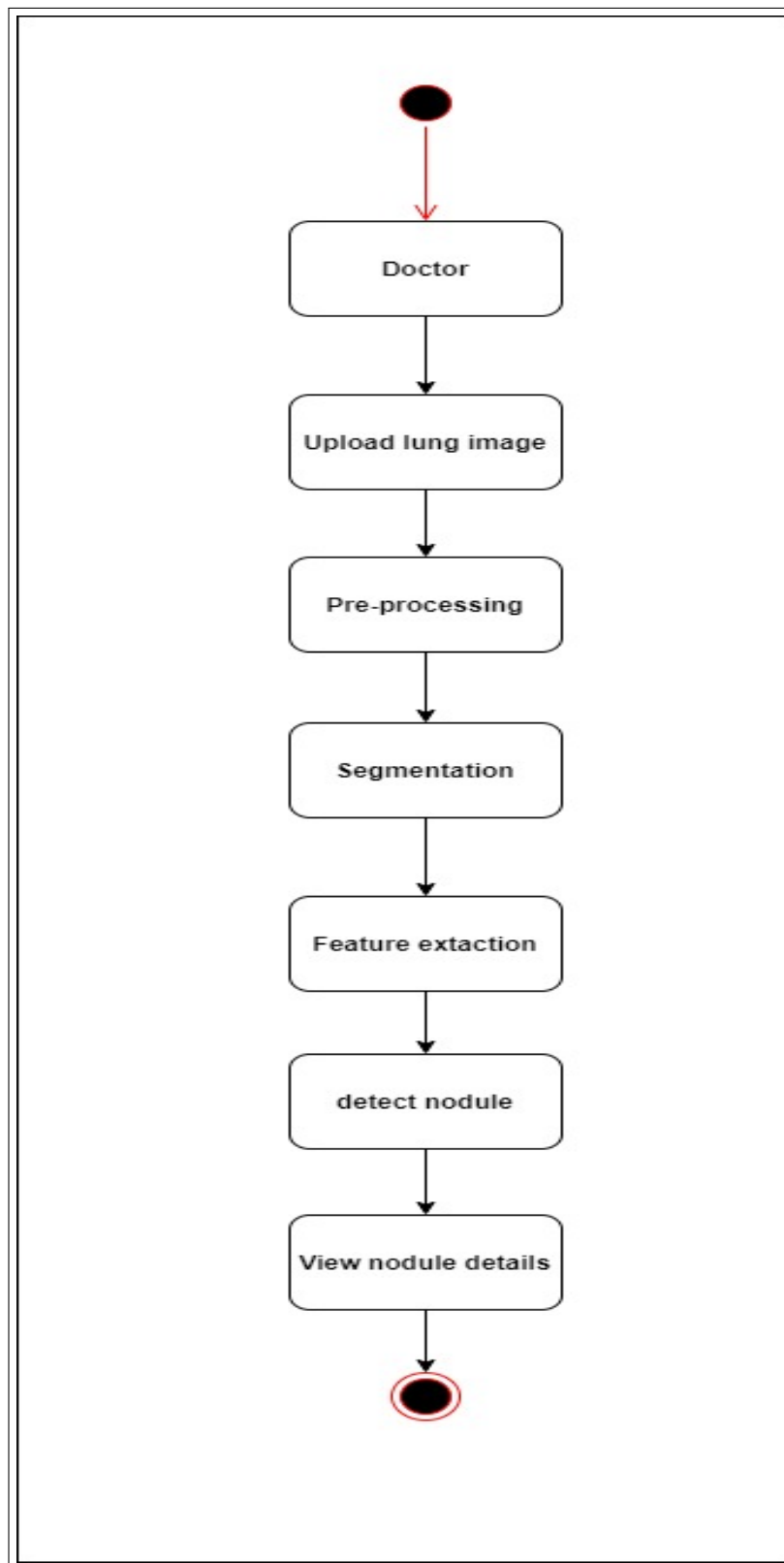


Figure 3.10: State Transition diagram

3.7.6 Component Diagram

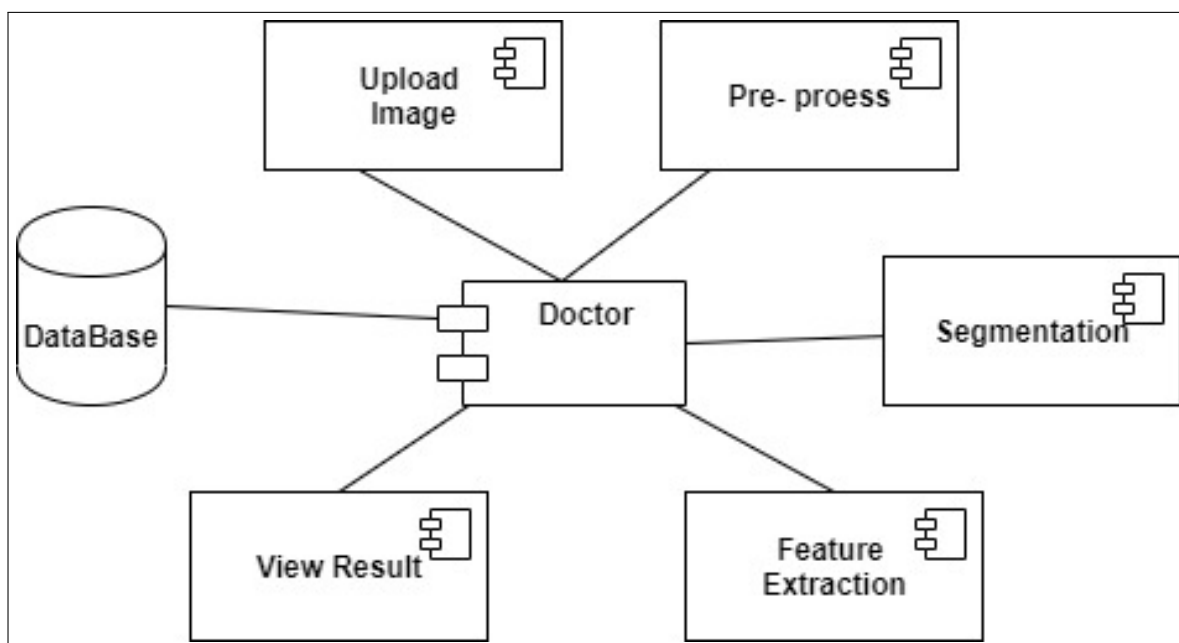


Figure 3.11: Component Diagram

3.7.7 Deployment Diagram

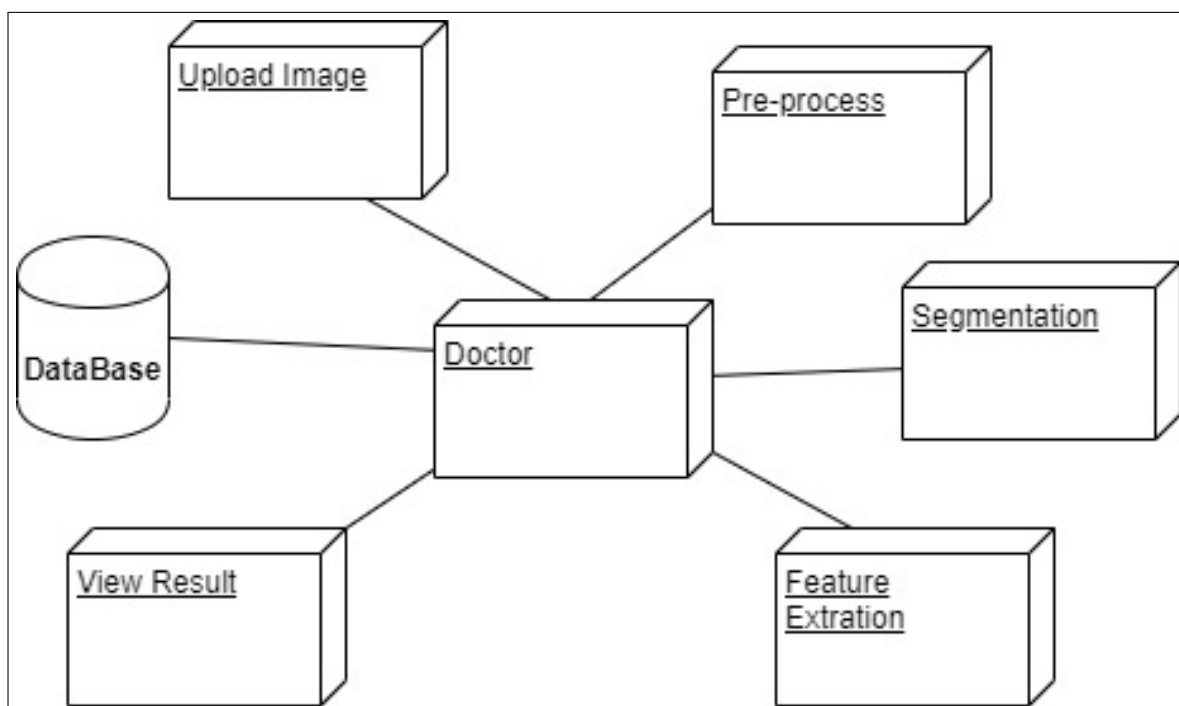


Figure 3.12: Deployment Diagram

Chapter 4

IMPLEMENTATION AND CODING

4.1 Introduction

- Upload lung image
- Preprocessing using Otsu Thresholding
- Segmentation
- Feature Extraction
- Get nodule details.
- View Result Nodule details

4.2 Operational Details

4.2.1 Hardware Resource Requirement

- Hardware : Pentium Dual Core
- Speed : 2.80 GHz
- RAM : 1GB
- Hard Disk : 20 GB

4.2.2 Software Resource Requirement

- Operating System : Windows 7 and above
- Technology : Python
- IDE : Anaconda or Spider

4.3 Code Listing

4.4 Screen Shots

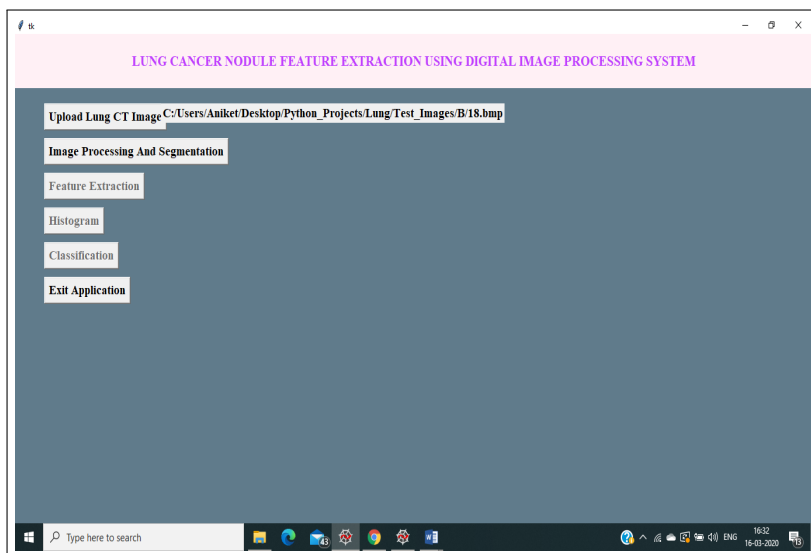


Figure 4.1: Screen Shot 1

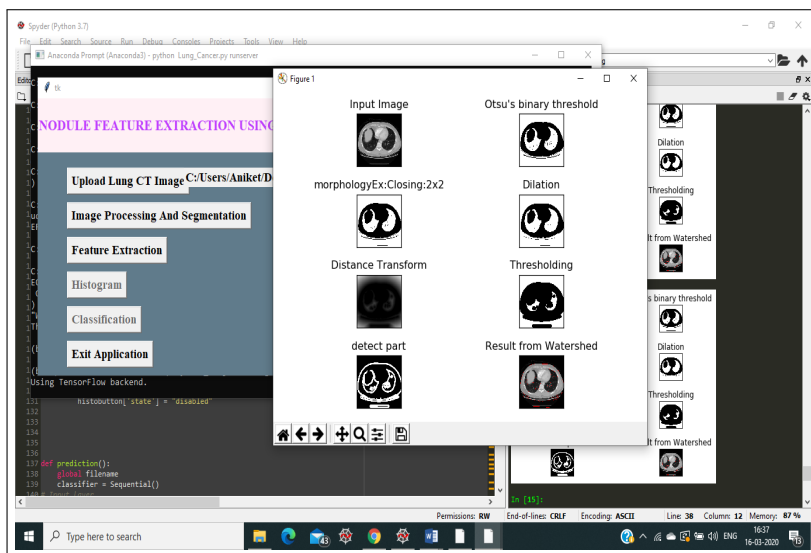


Figure 4.2: Screen Shot 2

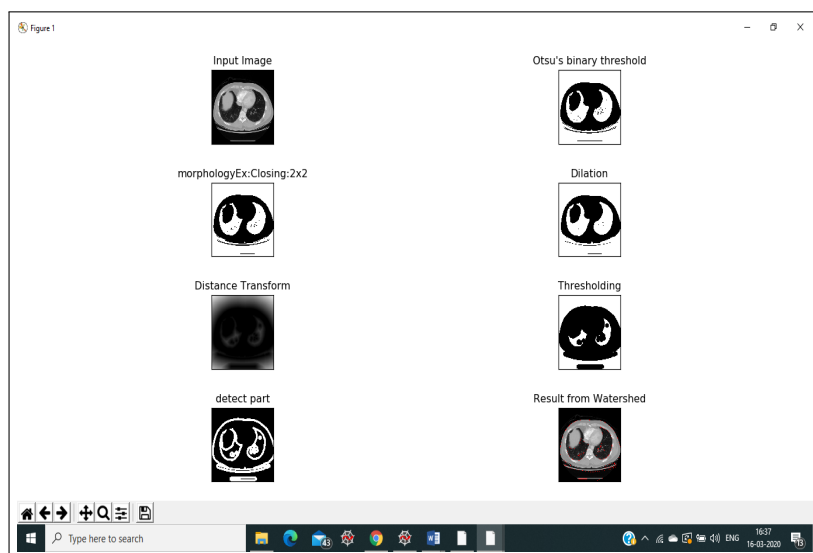


Figure 4.3: Screen Shot 3

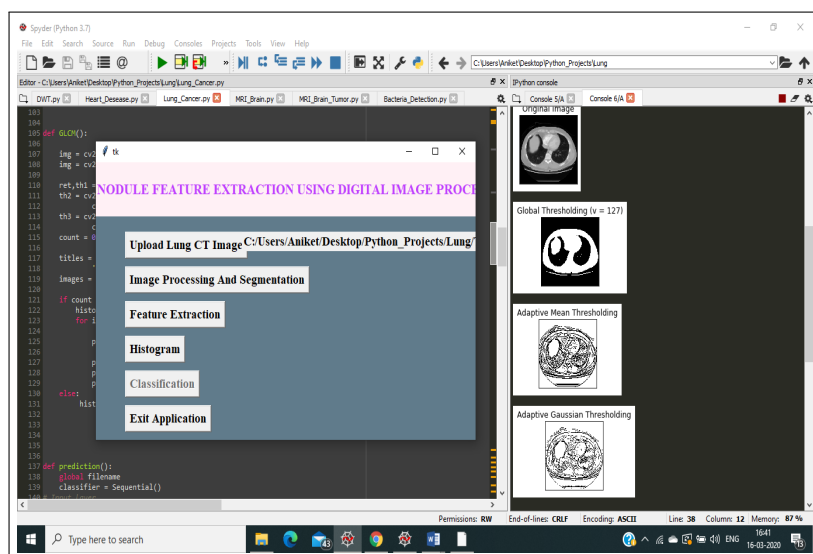


Figure 4.4: Screen Shot 4

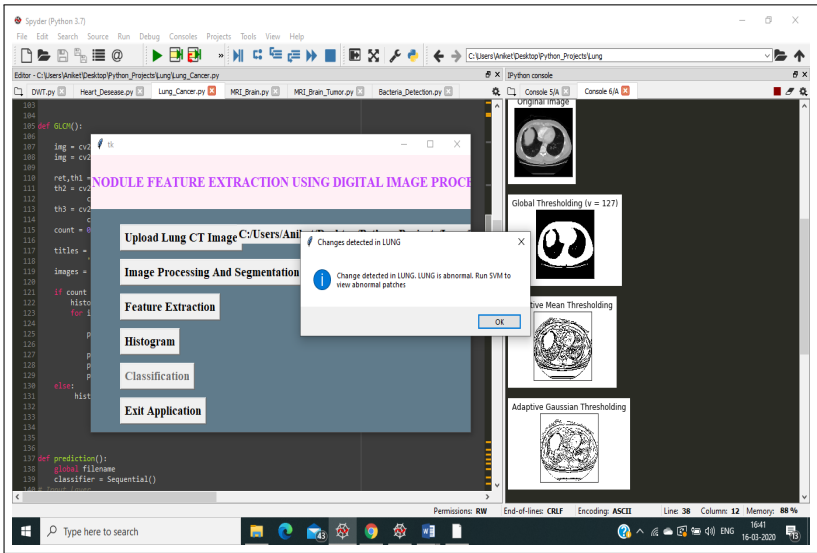


Figure 4.5: Screen Shot 5

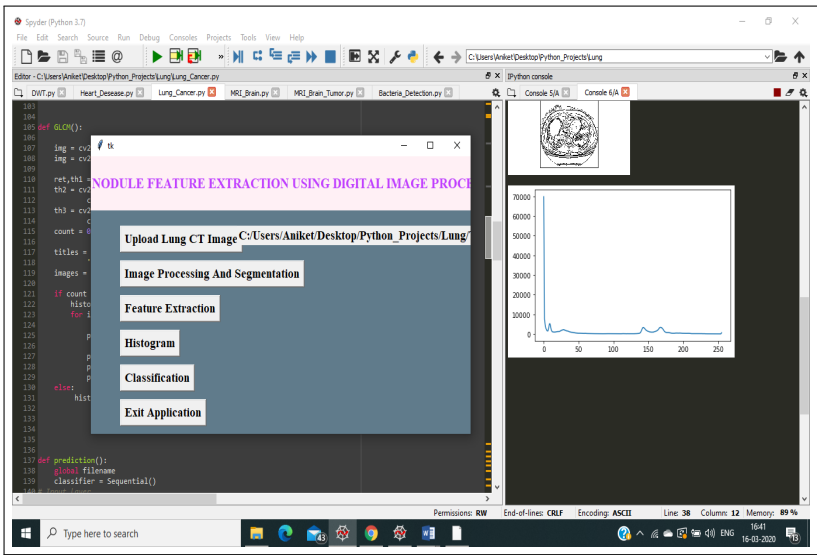


Figure 4.6: Screen Shot 6

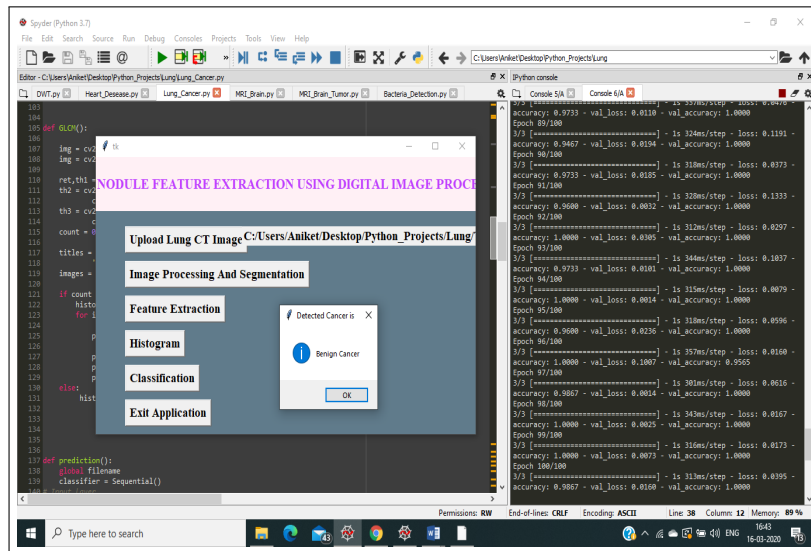


Figure 4.7: Screen Shot 7

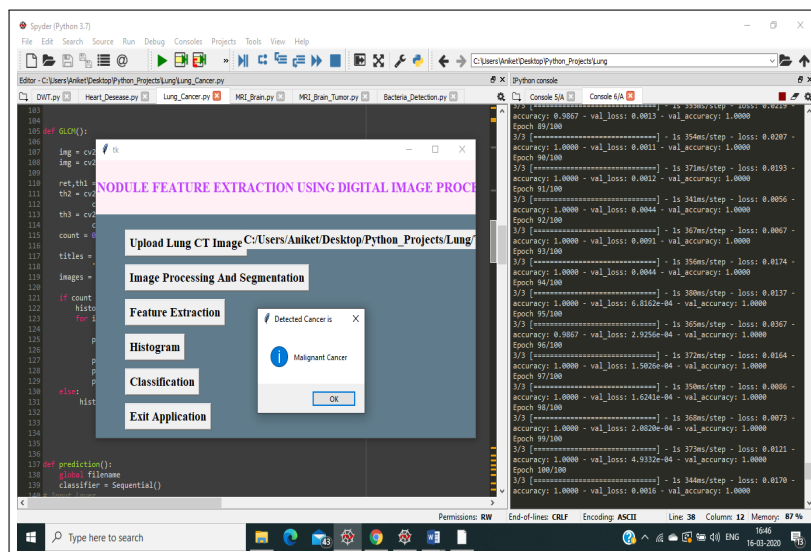


Figure 4.8: Screen Shot 8

Chapter 5

TESTING

5.1 Unit Testing

Unit testing involves the design of test cases that validate that the internal program logic is functioning properly, and that program inputs produce valid outputs. All decision branches and internal code flow should be validated. It is the testing of individual software units of the application. It is done after the completion of an individual unit before integration. This is a structural testing, that relies on knowledge of its construction and is invasive. Unit tests perform basic tests at component level and test a specific business process, application, and/or system configuration. Unit tests ensure that each unique path of a business process performs accurately to the documented specifications and contains clearly defined inputs and expected results.

5.2 Integration Testing

Integration tests are designed to test integrated software components to determine if they actually run as one program. Testing is event driven and is more concerned with the basic outcome of screens or fields. Integration tests demonstrate that although the components were individually satisfactory, as shown by successful unit testing, the combination of components is correct and consistent. Integration testing is specifically aimed at exposing the problems that arise from the combination of components.

5.3 Acceptance Testing

The acceptance test suite is run using predefined acceptance test procedures to direct the testers which data to use, the step-by-step processes to follow and the expected result following execution. The actual results are retained for comparison with the expected results.[7] If the actual results match the expected results for each test case, the test case is said to pass. If the quantity of non-passing test cases does not breach the project's predetermined threshold, the test suite is said to pass. If it does, the system may either be rejected or accepted on conditions previously agreed between the sponsor and the manufacturer.

5.4 Test Cases and Test Results

Test Case	Upload Lung Image
Objective	System user should be upload Lung Image
Result	Upload Lung Image successfully
Test Case	Pre-Process
Objective	Perform Pre-Processing using otsu
Result	Pre-Process perform successfully
Test Case	Segmentation
Objective	Perform segmentation using Watershed
Result	Segmentation perform successfully
Test Case	Extract Feature from Image
Objective	Extract feature using GLCM
Result	Extract Feature successfully
Test Case	Apply SVM
Objective	SVM Apply for classification
Result	Classification done successfully
Test Case	View Result
Objective	Dr should view result correctly
Result	Dr view correct result successfully

Chapter 6

RESULTS AND DISCUSSION

6.1 Main GUI Snapshots

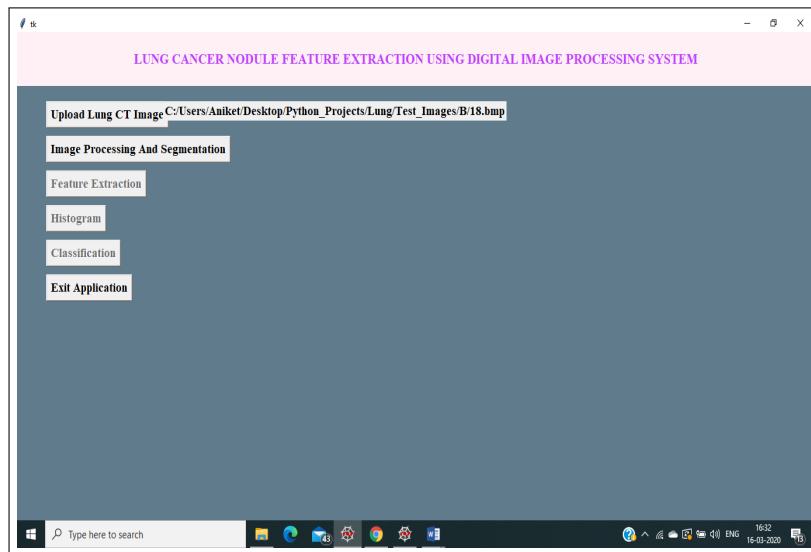


Figure 6.1: Screen Shot 1

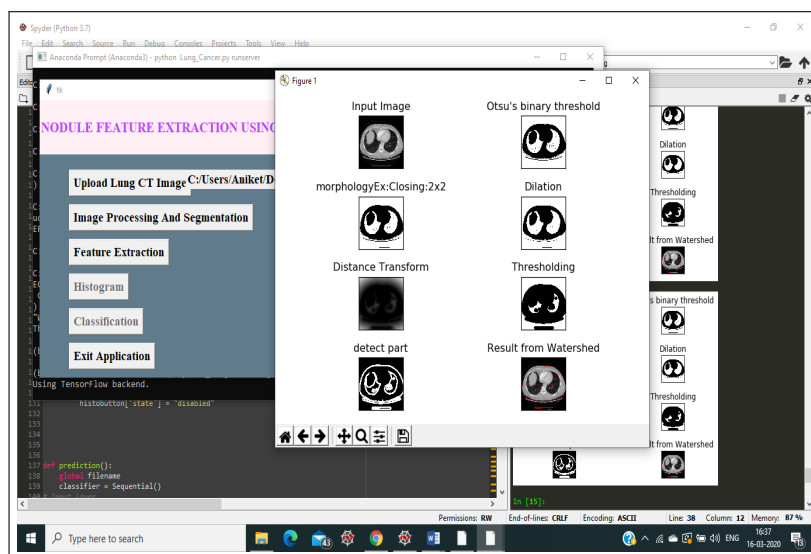


Figure 6.2: Screen Shot 2

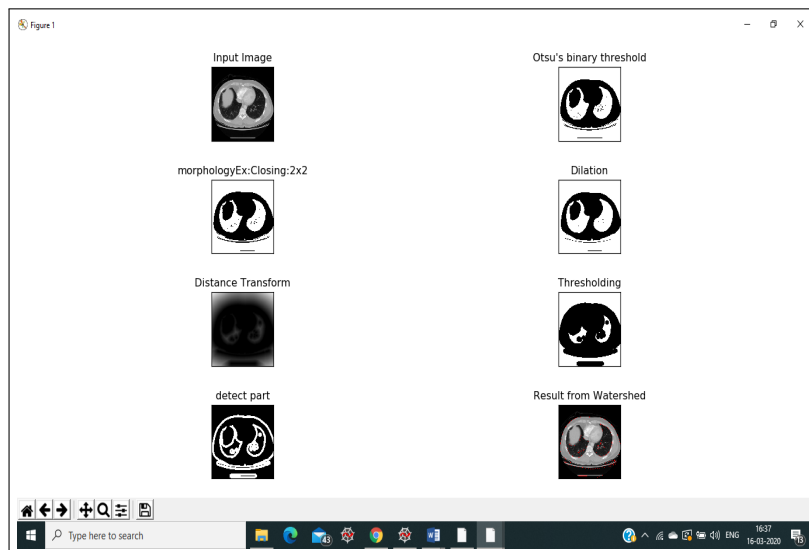


Figure 6.3: Screen Shot 3

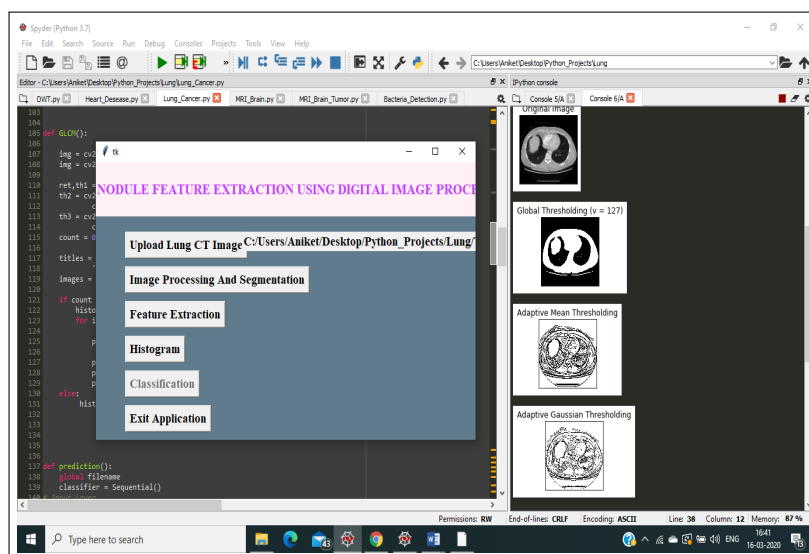


Figure 6.4: Screen Shot 4

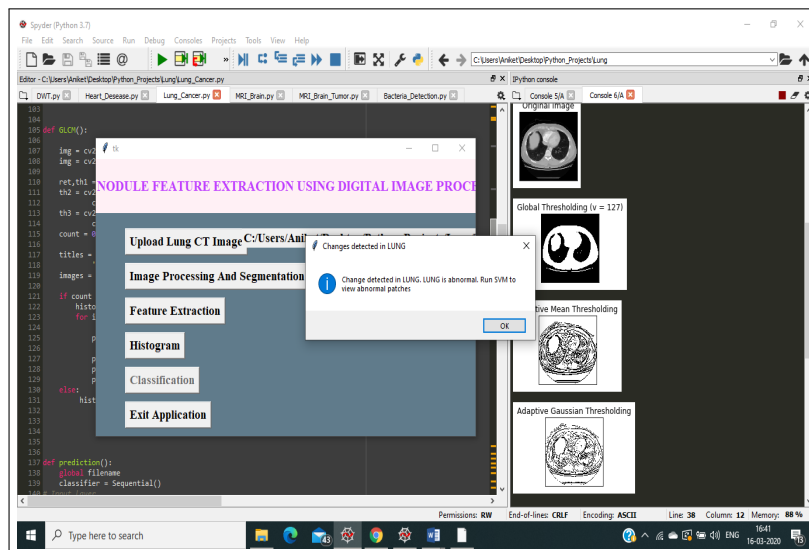


Figure 6.5: Screen Shot 5

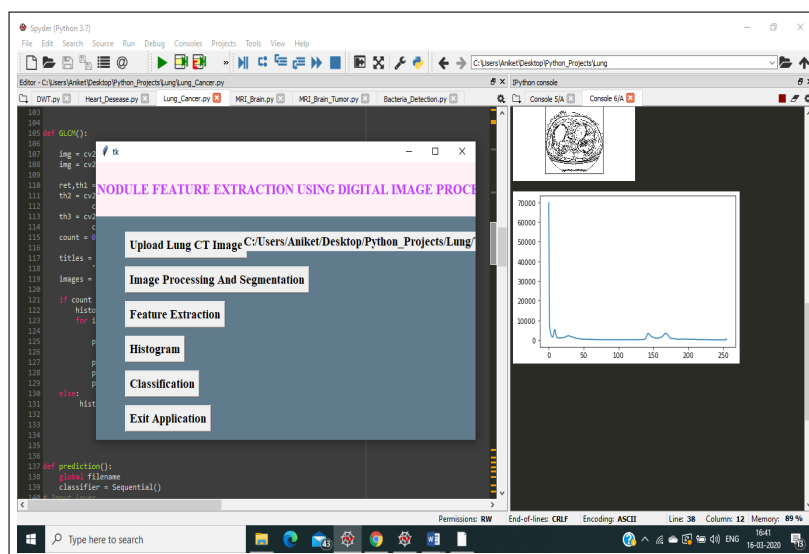


Figure 6.6: Screen Shot 6

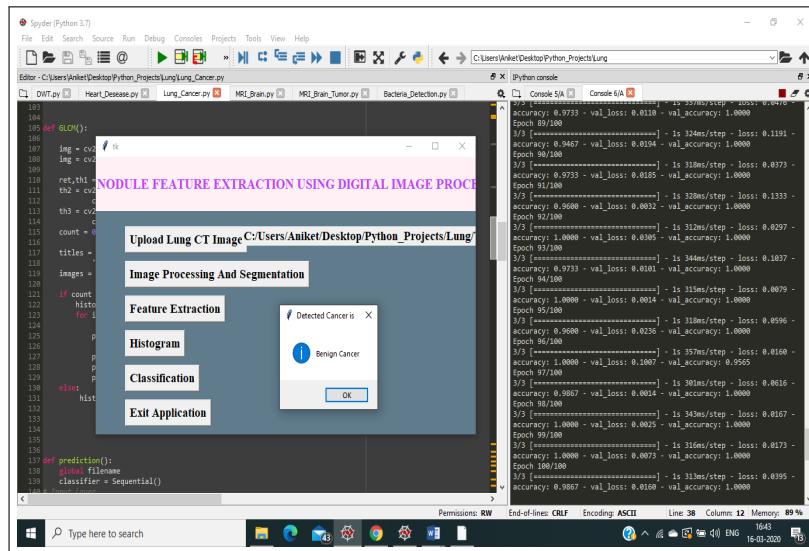


Figure 6.7: Screen Shot 7

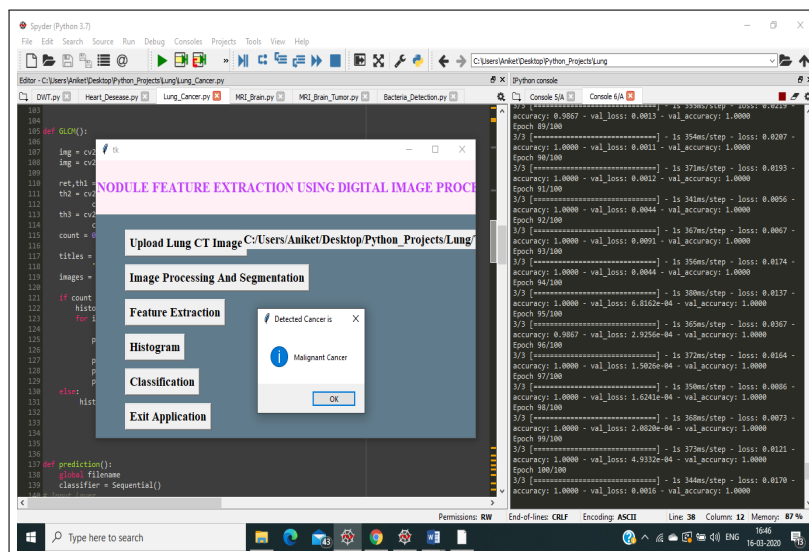


Figure 6.8: Screen Shot 8

6.2 Discussions

Here we detect lung nodule using machine learning techniques. Otsu thresholding used for the pre-processing, watershed use for segmentation and GLCM used for feature extraction and finally get output using SVM Classification.

Chapter 7

Conclusion and Future Work

7.1 Conclusion

Our simulations showed that it is feasible to quantify sub-cm nodules within 20% bias using low-dose PET in the simulation. However, more thorough validations using clinically realistic phantoms should be performed. Reconstruction voxel size of 1 mm is recommended for small nodules. Respiratory motion correction is critical for nodules in the lung and abdomen. this project get accurate nodule size by using Otsu, Watershed, GLCM, and SVM.

7.2 Future Work

In future we would like to apply different techniques an compare them.

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