

# Learning Adaptive Language Interfaces through Decomposition



Percy Liang

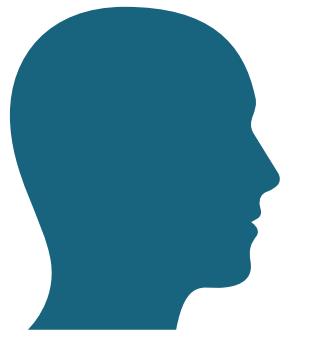


Siddharth Karamcheti



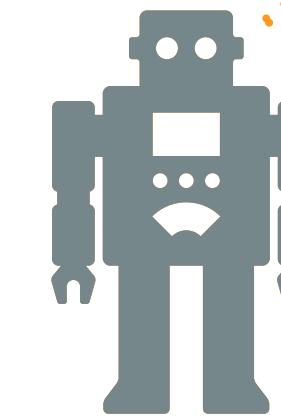
Dorsa Sadigh





“Wash the coffee mug”

I'm sorry - I don't understand!  
Please teach me!



.....  
*What can I do?*  
GOTO Mug;  
PICKUP Mug;  
PUT Mug;  
....

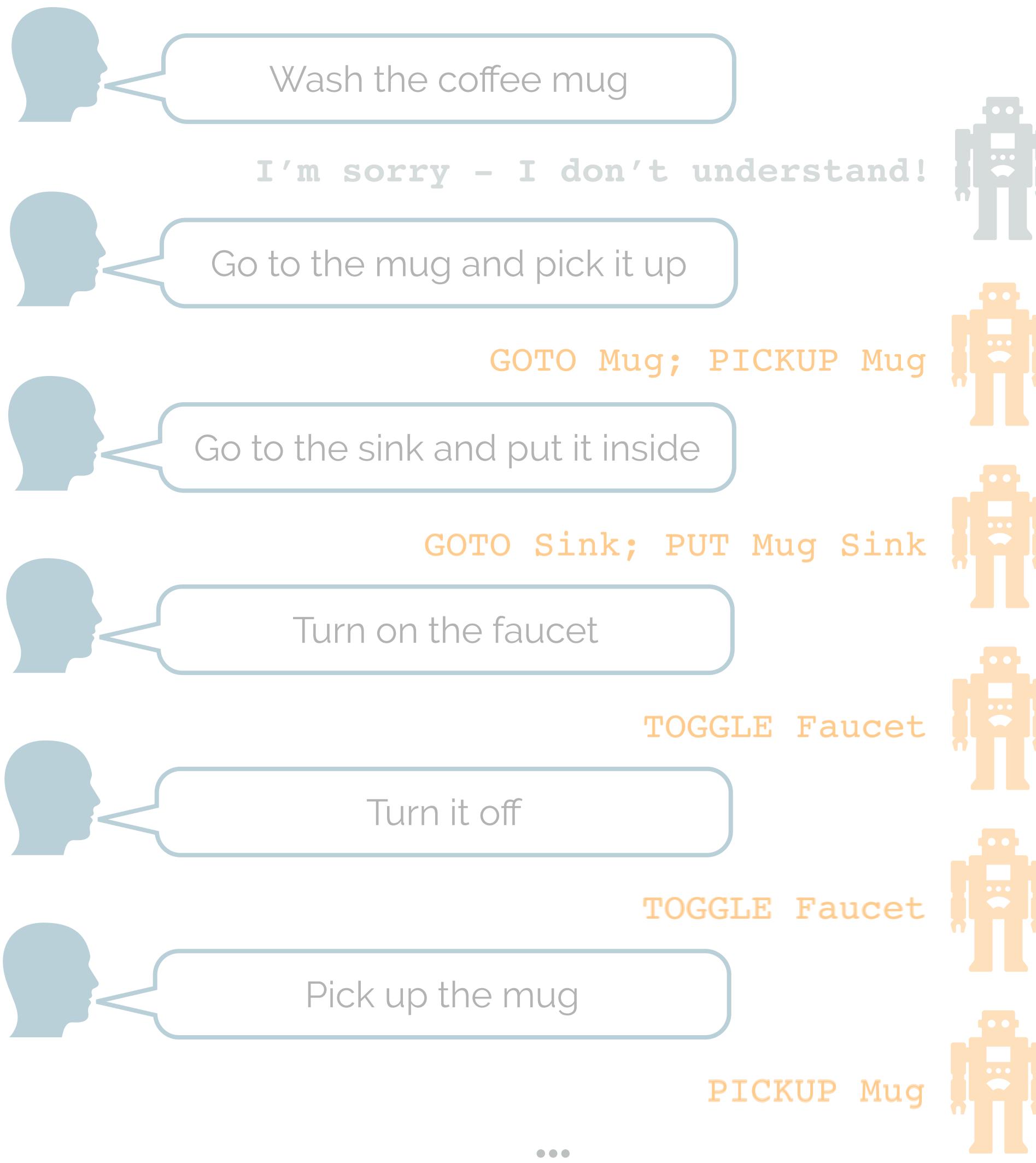
# Learning from Decomposition

## Interaction

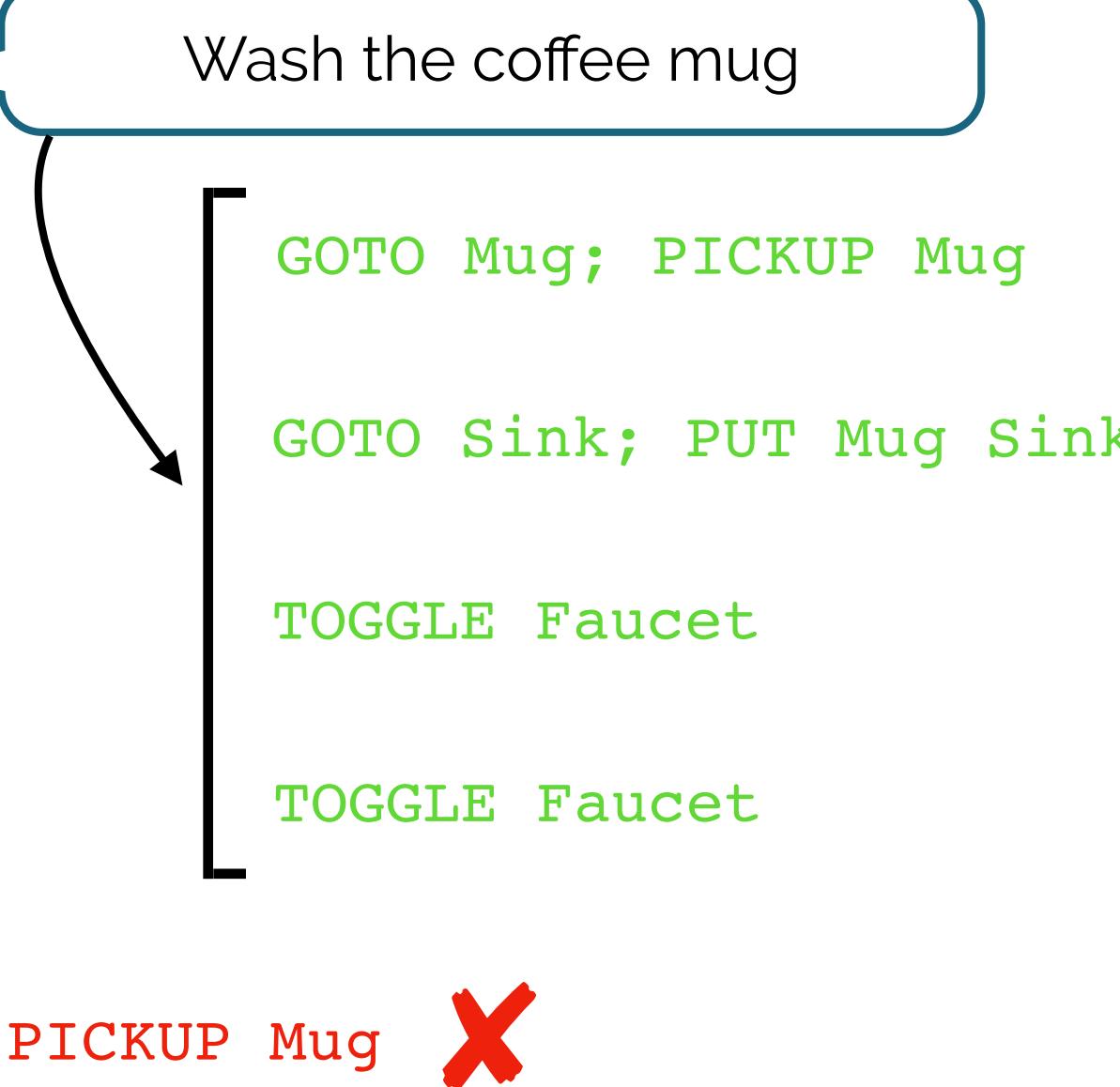


# Learning from Decomposition

## Interaction



## Teaching



Decompose into simpler steps!

# Learning from Decomposition

## Interaction

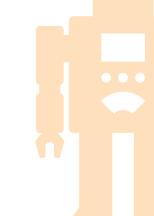
 Wash the coffee mug

 I'm sorry - I don't understand!

 Go to the mug and pick it up

 GOTO Mug; PICKUP Mug

 Go to the sink and put it inside

 GOTO Sink; PUT Mug Sink

 Turn on the faucet

 TOGGLE Faucet

 Turn it off

 TOGGLE Faucet

 Pick up the mug

 PICKUP Mug

## Teaching

 Wash the coffee mug

 GOTO Mug; PICKUP Mug  
GOTO Sink; PUT Mug Sink

 TOGGLE Faucet

 TOGGLE Faucet

 PICKUP Mug 

 Model







Decompose into simpler steps!

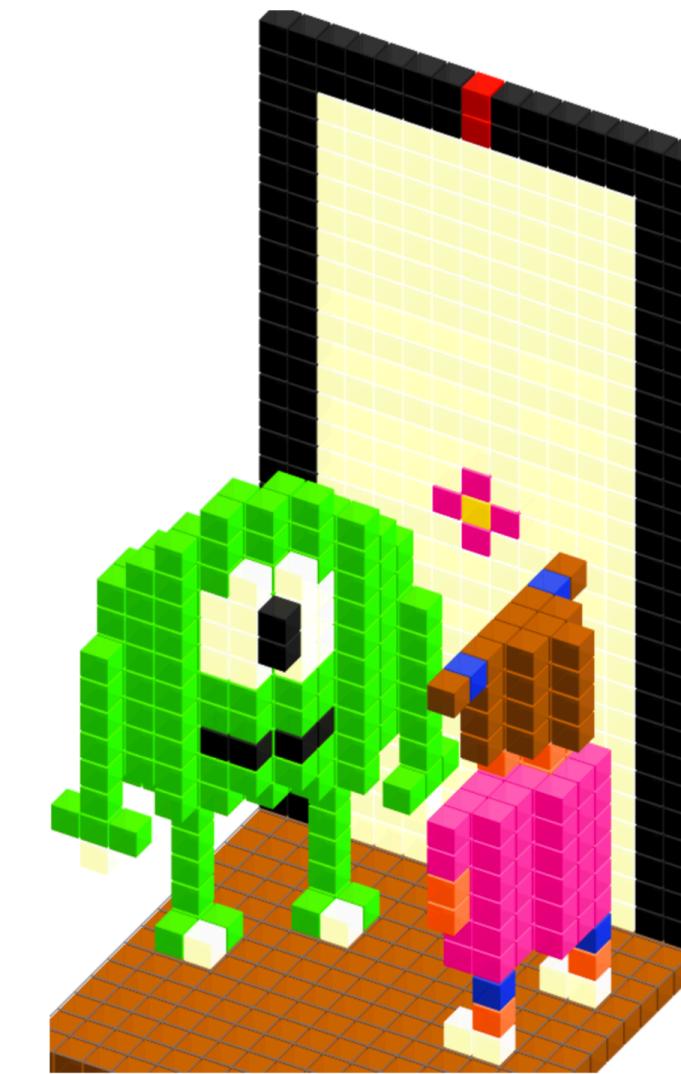
Historical Interaction Data (Single-User)



Online Learning

# Related Work – Semantic Parsing & Interaction

- Closest to our work is Voxelurn [1]
  - Grammar-based semantic parsers:
    - *Reliable one-shot generalization* ✓
    - *Lexical flexibility* ✗
      - “Add palm tree” → “Create a palm tree”
- Separately: Neural sequence-to-sequence models [2, 3].
  - *Lexical flexibility* ✓
  - *Reliable one-shot generalization* [4] ✗



```
def: add palm tree
def: brown trunk height 3
def: add brown top 3 times
      repeat 3 [add brown top]
def: go to top of tree
      select very top of has color brown
def: add leaves here
def: select all sides
      select left or right or front or back
      add green
```

[1] Naturalizing a Programming Language via Interactive Learning — Wang et. al. 2017

[2] Data Recombination for Neural Semantic Parsing — Jia and Liang 2016

[3] From Language to Programs: Bridging Reinforcement Learning and Maximum Marginal Likelihood — Guu et. al. 2017

[4] Six Challenges for Neural Machine Translation — Koehn and Knowles 2017

## **This Work:**

Applies interactive learning from decomposition, and introduces a *neural “exemplar-based” parser* that is *lexically flexible* and can *reliably generalize from limited examples*.

## **Critical Point:**

*Trust during Inference* – Given a novel utterance, output “I don’t understand.”



## **This Work:**

Applies interactive learning from decomposition, and introduces a *neural “exemplar-based” parser* that is *lexically flexible* and can *reliably generalize from limited examples*.

## **Critical Point:**

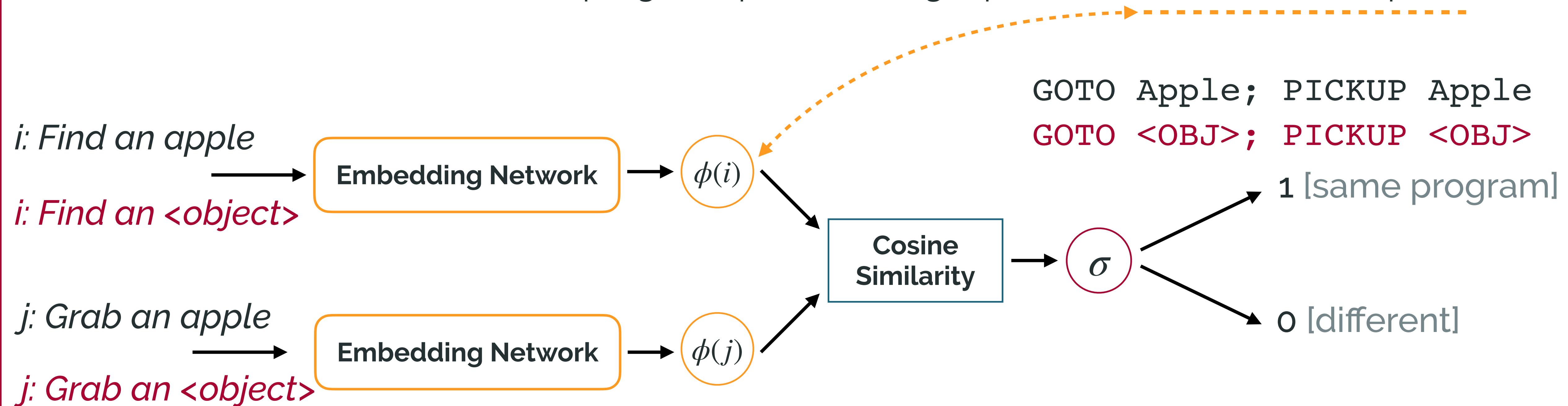
*Trust during Inference* – Given a novel utterance, output “I don’t understand.”

## Roadmap:

1. Exemplar-Based Semantic Parsing
2. Experiments
3. Limitations & Discussion

# Exemplar-Based Semantic Parsing

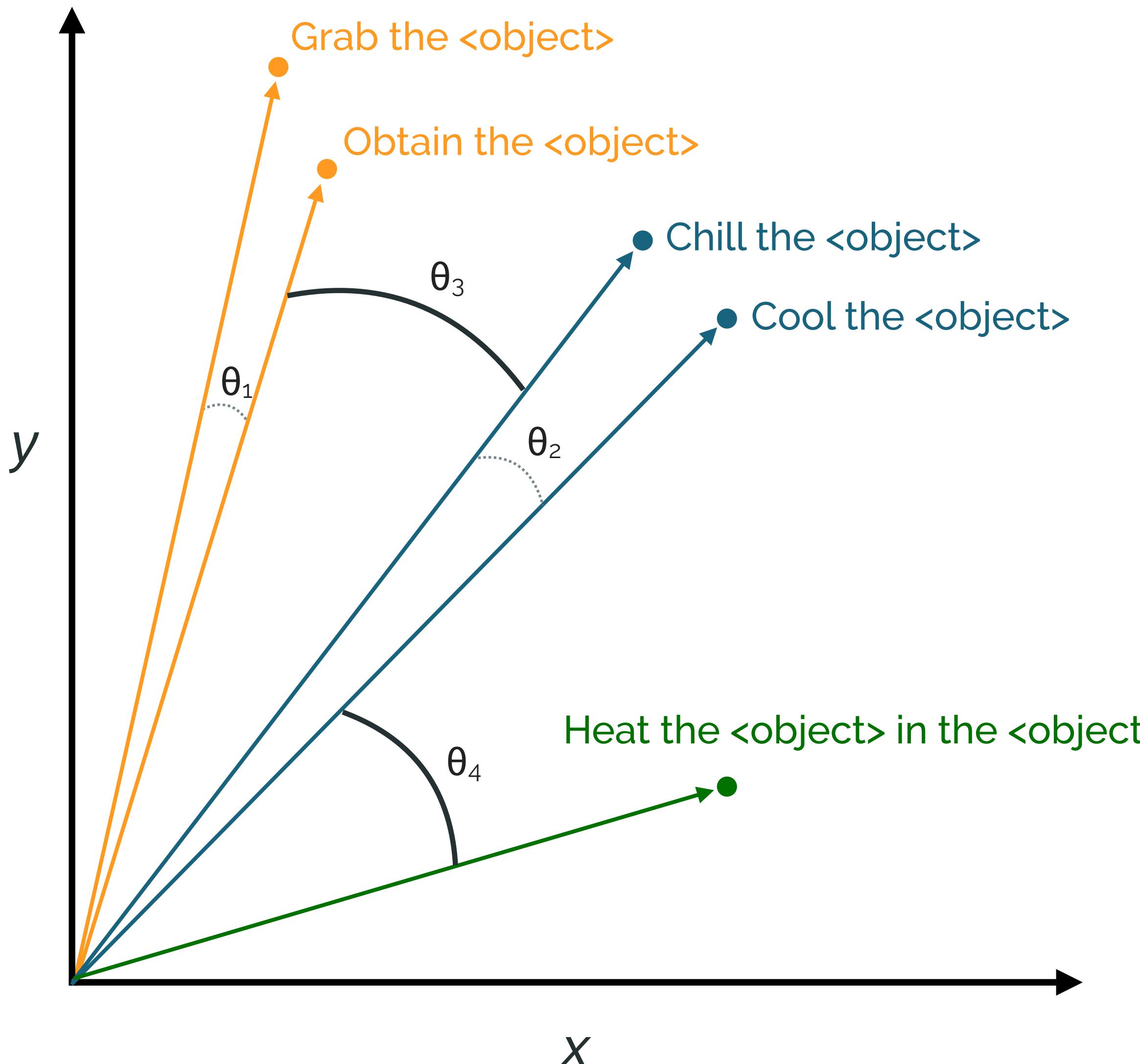
**Overview:** Treat each (utterance, program) pair as a single point in a learned latent space.



**Inference:** Given utterance  $u$ , embed  $u$  and retrieve closest “exemplar.”

**Reliable Generalization:** Decouple “functions”/arguments and operate on “lifted” utterances.

# Trust during Inference



2D Visualization of our learned latent space.

Trust during Inference:

Given a novel utterance, how to output  
“I don’t understand!”

Intuition:

Set a “threshold”  $\tau$  in embedding space!

if **CosineDistance**( $\phi(u)$ ,  $\phi(i)$ )  $\geq \tau$   $\forall_i$   
return “I don’t understand”

## Roadmap:

1. Exemplar-Based Semantic Parsing
2. Experiments
3. Limitations & Discussion

# Environments & Tasks

**Environment:** We use a simplified (2D) version of the AI2-THOR Simulation Environment [1]

**Tasks:** We borrow from ALFRED [2]:

**Pick and Place**

**Examine in Light**

**Nested Pick and Place**

**Pick Two and Place**

**Pick, Heat, and Place**

**Pick, Clean, and Place**

**Pick, Cool, and Place**

**Simple Primitives:**

GOTO (object)

PICKUP (object)

TOGGLE (object)

PUT (object, receptacle)

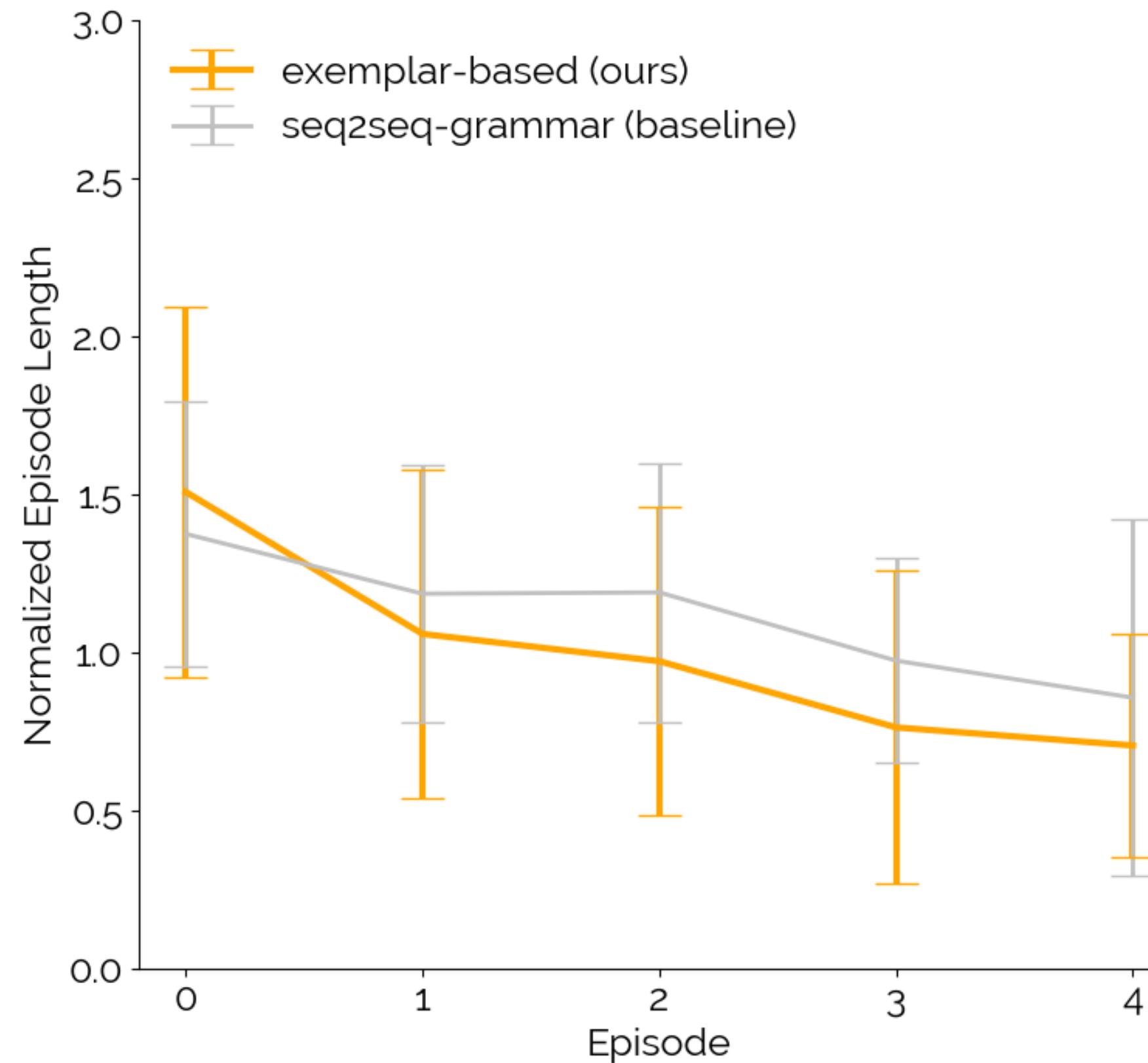
OPEN/CLOSE (receptacle)



[1] AI2-THOR: An Interactive 3D Environment for Visual AI — Kolve et. al. 2017

[2] ALFRED: A Benchmark for Interpreting Grounded Instructions for Everyday Tasks — Shridhar et. al. 2020

# Results – Multi-Task [20 Users x 7 Task Types]



*Normalized Episode Length*

How many utterances does it take a user to complete a task?

(Lower is better!)

## Baseline: Seq2Seq + Backoff Grammar

*Seq2seq models are unpredictable when trained with limited data — leverage backoff grammar:*

- Grammar-based parser for “*simple*” instructions.
- Seq2Seq responsible for “*high-level*” language!

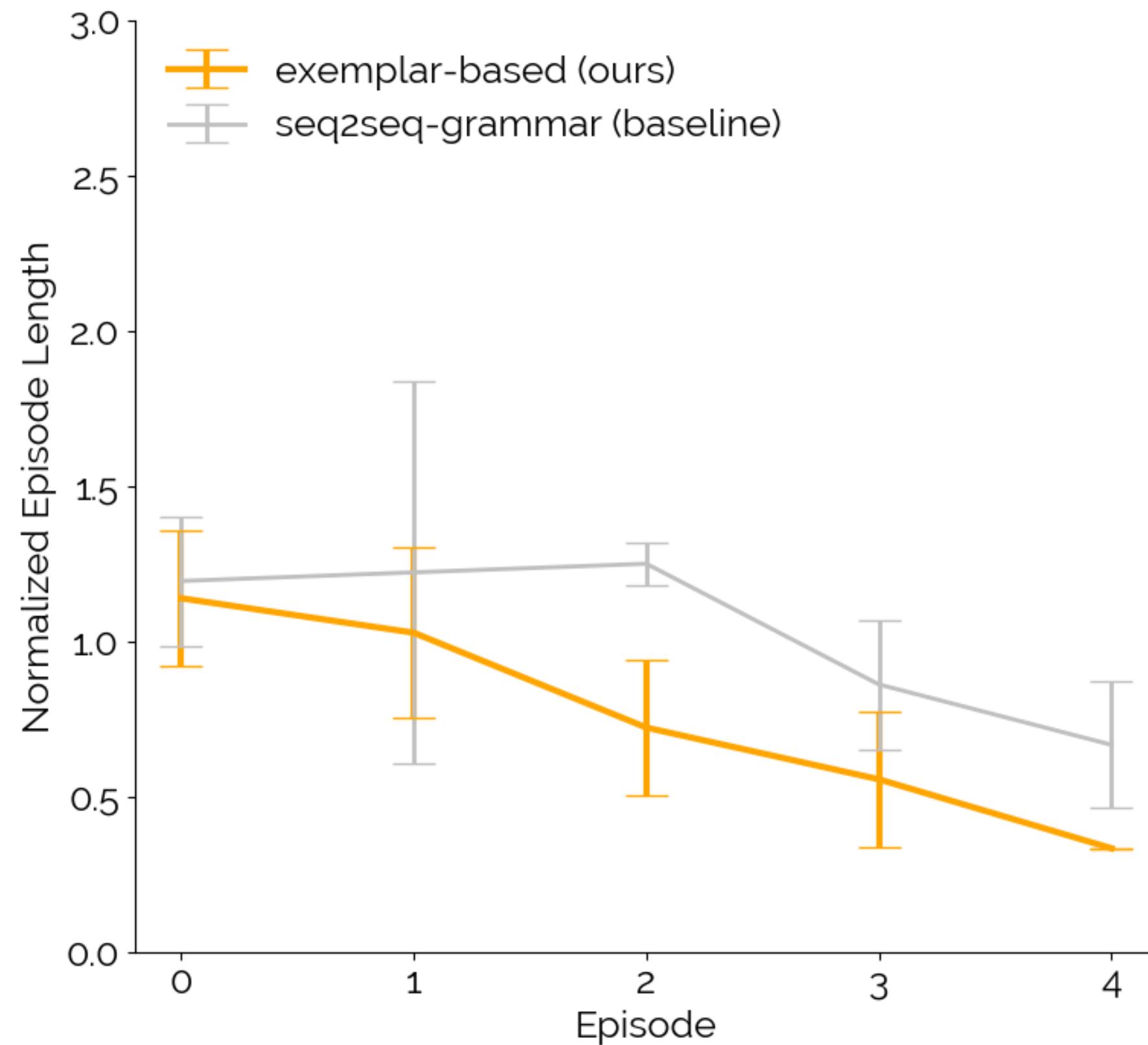
**Takeaway:** Users don’t seem to be *teaching or re-using* new high-level language!

- For seq2seq-grammar baseline →  
*89.9% of all utterances handled by grammar!*

**Users are not incentivized to teach ...**

**... in simple tasks.**

# Results – Pick, Cool, and Place [3 Users]



## *Normalized Episode Length*

How many utterances does it take a user to complete a task?

### Takeaways:

- Normalized Length ~0.3
- Users are able to:
  - Reuse high-level abstractions.
  - Complete tasks in 1/3 of the time!
  - Less reliance on simple utterances.

## Roadmap:

1. Exemplar-Based Semantic Parsing
2. Experiments
3. Limitations & Discussion

# Discussion, Limitations, and Looking Forward

## Towards More Complex Settings

- Simple settings, users take the “shortest path.”
- We need environments where there is a “natural incentive” to teach nested abstractions!
  - Minecraft
  - Cooking (a la EPIC-KITCHENS [1])

## On Trusting Interactive Learning

- What is the system learning?
  - “Wash the mug” → “Wash the countertop?”
- We need tools for *transparency and reliability!*

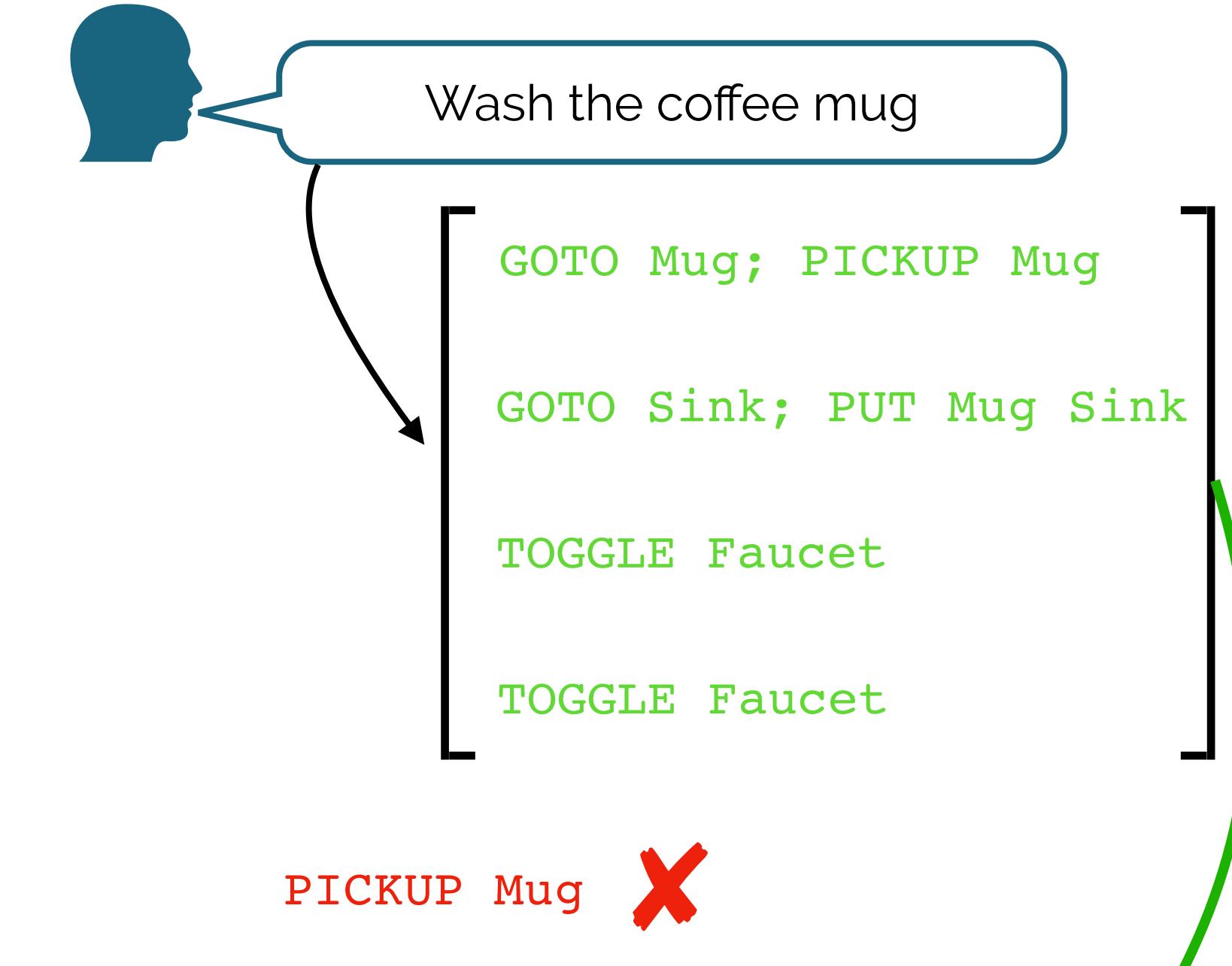


Setup for EPIC-KITCHENS [1], a free-form cooking domain where the use and definition of nested abstractions (“peel the apples,” “make some pie crust”) are naturally incentivized.

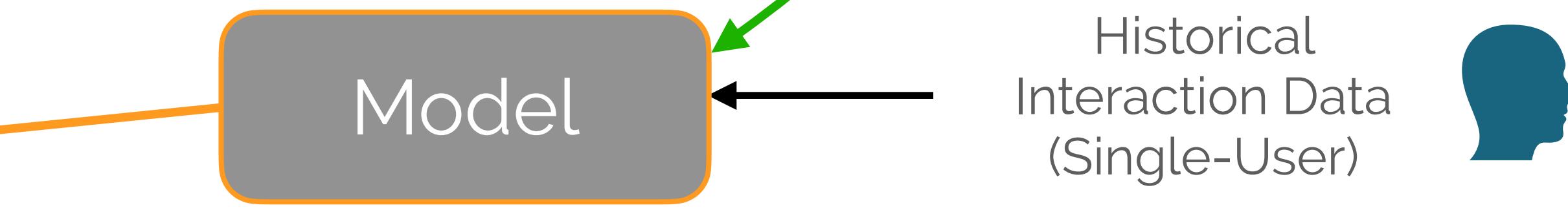
## Interaction



## Teaching



Decompose into simpler steps!



## Online Learning

Thanks so much!

If you have questions/comments/helpful tips, feel free to email me – [skaramchetti@cs.stanford.edu](mailto:skaramchetti@cs.stanford.edu)