In [134	import random
	<pre>import numpy as np from utils.data_utils import load_CIFAR10 import matplotlib.pyplot as plt %matplotlib inline %load_ext autoreload %autoreload 2 def rel_error(x, y): """ returns relative error """ return np.max(np.abs(x - y) / (np.maximum(1e-8, np.abs(x) + np.abs(y)))) The autoreload extension is already loaded. To reload it, use:</pre>
In [135 In [136	Toy example Before loading CIFAR-10, there will be a toy example to test your implementation of the forward and backward pass from nndl.neural_net import TwoLayerNet
	<pre># Note that we set the random seed for repeatable experiments. input_size = 4 hidden_size = 10 num_classes = 3 num_inputs = 5 def init_toy_model(): np.random.seed(0) return TwoLayerNet(input_size, hidden_size, num_classes, std=1e-1) def init_toy_data(): return toy_data():</pre>
In [137	<pre>np.random.seed(1) X = 10 * np.random.randn(num_inputs, input_size) y = np.array([0, 1, 2, 2, 1]) return X, y net = init_toy_model() X, y = init_toy_data() Compute forward pass scores ## Implement the forward pass of the neural network.</pre>
	<pre># Note, there is a statement if y is None: return scores, which is why # the following call will calculate the scores. scores = net.loss(X) print('Your scores:') print(scores) print() print('correct scores:') correct_scores = np.asarray([</pre>
	[-0.38172726, 0.10835902, -0.17328274], [-0.64417314, -0.18886813, -0.41106892]]) print(correct_scores) print() # The difference should be very small. We get < 1e-7 print('Difference between your scores and correct scores:') print(np.sum(np.abs(scores - correct_scores))) Your scores: [[-1.07260209 0.05083871 -0.87253915] [-2.02778743 -0.10832494 -1.52641362] [-0.74325008 0.15350725 -0.30572548]
	[-0.74225908 0.15259725 -0.39578548] [-0.38172726 0.10835902 -0.17328274] [-0.64417314 -0.18886813 -0.41106892]] correct scores: [[-1.07260209 0.05083871 -0.87253915] [-2.02778743 -0.10832494 -1.52641362] [-0.74225908 0.15259725 -0.39578548] [-0.38172726 0.10835902 -0.17328274] [-0.64417314 -0.18886813 -0.41106892]] Difference between your scores and correct scores: 3.3812311957259755e-08
In [139	<pre>loss, _ = het.loss(x, y, reg=0.05) correct_loss = 1.071696123862817 # should be very small, we get < 1e-12 print("Loss:", loss) print('Difference between your loss and correct loss:') print(np.sum(np.abs(loss - correct_loss)))</pre>
In [140	Loss: 1.071696123862817 Difference between your loss and correct loss: 0.0 Backward pass Implements the backwards pass of the neural network. Check your gradients with the gradient check utilities provided. from utils.gradient_check import eval_numerical_gradient # Use numeric gradient checking to check your implementation of the backward pass. # If your implementation is correct, the difference between the numeric and
	<pre># analytic gradients should be less than 1e-8 for each of W1, W2, b1, and b2. loss, grads = net.loss(X, y, reg=0.05) # these should all be less than 1e-8 or so for param_name in grads: f = lambda W: net.loss(X, y, reg=0.05)[0] param_grad_num = eval_numerical_gradient(f, net.params[param_name], verbose=False) print('{} max relative error: {}'.format(param_name, rel_error(param_grad_num, grads[param_name]))) W2 max relative error: 2.9632233460136427e-10 b2 max relative error: 1.2482633693659668e-09</pre>
In [141	W1 max relative error: 1.28328951808708e-09 b1 max relative error: 3.172680285697327e-09 Training the network Implement neural_net.train() to train the network via stochastic gradient descent, much like the softmax.
	<pre>print('Final training loss: ', stats['loss_history'][-1]) # plot the loss history plt.plot(stats['loss_history']) plt.xlabel('iteration') plt.ylabel('training loss') plt.title('Training Loss history') plt.show()</pre> Final training loss: 0.014497864587765906 Training Loss history
	1.0 - 0.8 - SSO Dujuin 0.6 - 0.4 - 0.2 -
In [143	Classify CIFAR-10 Do classification on the CIFAR-10 dataset. from utils.data_utils import load_CIFAR10
	<pre>def get_CIFAR10_data(num_training=49000, num_validation=1000, num_test=1000): """ Load the CIFAR-10 dataset from disk and perform preprocessing to prepare it for the two-layer neural net classifier. """ # Load the raw CIFAR-10 data cifar10_dir = 'cifar-10-batches-py' X_train, y_train, X_test, y_test = load_CIFAR10(cifar10_dir) # Subsample the data mask = list(range(num_training, num_training + num_validation)) X_val = X_train[mask]</pre>
	<pre>y_val = y_train[mask] mask = list(range(num_training)) X_train = X_train[mask] y_train = y_train[mask] mask = list(range(num_test)) X_test = X_test[mask] y_test = y_test[mask] # Normalize the data: subtract the mean image mean_image = np.mean(X_train, axis=0) X_train -= mean_image X_val -= mean_image</pre>
	<pre>X_test -= mean_image # Reshape data to rows X_train = X_train.reshape(num_training, -1) X_val = X_val.reshape(num_validation, -1) X_test = X_test.reshape(num_test, -1) return X_train, y_train, X_val, y_val, X_test, y_test # Invoke the above function to get our data. X_train, y_train, X_val, y_val, X_test, y_test = get_CIFAR10_data()</pre>
	<pre>print('Train data shape: ', X_train.shape) print('Train labels shape: ', y_train.shape) print('Validation data shape: ', X_val.shape) print('Validation labels shape: ', y_val.shape) print('Test data shape: ', X_test.shape) Train data shape: (49000, 3072) Train labels shape: (49000,) Validation data shape: (1000, 3072) Validation labels shape: (1000,) Test data shape: (1000, 3072)</pre>
In [144	<pre>Test labels shape: (1000,) Running SGD If your implementation is correct, you should see a validation accuracy of around 28-29%. input_size = 32 * 32 * 3 hidden_size = 50 num_classes = 10 net = TwoLayerNet(input_size, hidden_size, num_classes) # Train the network</pre>
	<pre>stats = net.train(X_train, y_train, X_val, y_val,</pre>
	<pre>iteration 0 / 1000: loss 2.302757518613176 iteration 100 / 1000: loss 2.302120159207236 iteration 200 / 1000: loss 2.2956136007408703 iteration 300 / 1000: loss 2.2518259043164135 iteration 400 / 1000: loss 2.188995235046776 iteration 500 / 1000: loss 2.1162527791897747 iteration 600 / 1000: loss 2.064670827698217 iteration 700 / 1000: loss 1.9901688623083942 iteration 800 / 1000: loss 2.002827640124685 iteration 900 / 1000: loss 1.9465176817856495 Validation accuracy: 0.283</pre>
In [145	Questions: The training accuracy isn't great. (1) What are some of the reasons why this is the case? Take the following cell to do some analyses and then report your answers in the cell following the one below. (2) How should you fix the problems you identified in (1)? stats['train_acc_history']
In [148	[0.095, 0.15, 0.25, 0.25, 0.315] stats['val_acc_history'] [0.115, 0.177, 0.208, 0.26, 0.285] # ===================================
	<pre># Do some debugging to gain some insight into why the optimization # isn't great. # ====================================</pre>
	<pre>fig, ax = plt.subplots() plt.plot(stats['train_acc_history'], label='training') plt.plot(stats['val_acc_history'], label='validation') legend = ax.legend(loc='upper center', shadow=True) frame = legend.get_frame() frame.set_facecolor('0.80') plt.title('History of classification accuracy') plt.xlabel('Epoch') plt.ylabel('Clasification accuracy') plt.legend(loc='lower right') plt.legend(loc='lower right') plt.gcf().set_size_inches(15, 12)</pre>
	plt.gcf().set_size_inches(15, 12) plt.show() # ===================================
	22-
	21-
	2.0 -
	19 - 0 200 400 600 800 1000 History of classification accuracy
	0.30 -
	0.25 - Ozorozo
	0.15
	Answers: (1) From the first plot, we can say that the Loss for the first 200 iterations is the same and does not decrease. Post that, we can observe that the Loss decreases linearly which suggests that the Learning Rate used is not large enough. Secondly, from the
	Accuracy plot, we observe that for the first 1000 iterations, both the training and validation accuracy seems to increase and do not converge. This might suggest that we need to increase the number of iterations to make the model converge. (2) The Learning Rate must be increased to ensure the Loss drops exponentially rather than Linearly. Also, the number of iterations must be increased to ensure model covergence. Optimize the neural network Use the following part of the Jupyter notebook to optimize your hyperparameters on the validation set. Store your nets as best_net.
In [150	<pre>best_net = None # store the best model into this # ===================================</pre>
	<pre># # Note, you need to use the same network structure (keep hidden_size = 50)! # ====================================</pre>
	<pre>reg=0.55) y_train_pred = net.predict(X_train) acc_train = np.mean(y_train == y_train_pred) y_val_pred = net.predict(X_val) acc_val = np.mean(y_val == y_val_pred) results[lr] = (acc_train, acc_val) if best_acc < acc_val:</pre>
	<pre>best_acc = acc_val best_net = net</pre>
	<pre>best_net = net # Print out results for lr in sorted(results): train_acc, val_acc = results[lr] print ('Learning rates: %e Train accuracy: %f Validation accuracy: %f' % (lr, train_acc, val_acc)) print ('Best validation accuracy: %f' % best_acc) # Plot the loss function and train / validation accuracies plt.plot(stats['loss_history']) plt.title('Training Loss History') plt.xlabel('Iteration')</pre>
	<pre>best_net = net # Print out results for lr in sorted(results): train_acc, val_acc = results[lr] print ('Learning rates: %e Train accuracy: %f Validation accuracy: %f' % (lr, train_acc, val_acc)) print ('Best validation accuracy: %f' % best_acc) # Plot the loss function and train / validation accuracies plt.plot(stats['loss_history']) plt.title('Training Loss History') plt.xlabel('Iteration') plt.ylabel('Training Loss') plt.show() plt.plot(stats['train_acc_history']) plt.plot(stats['train_acc_history']) plt.title('Classification Accuracy History') plt.xlabel('Iteration') plt.xlabel('Accuracy') plt.xlabel('Accuracy') plt.xlabel('Accuracy') plt.xlabel('Accuracy') plt.xlabel('Accuracy')</pre>
	<pre>best_net = net # Frint out results for 1r in sorted(results): train_acc, val_acc = results[1r] print ('Learning rates: %e Train accuracy: %f Validation accuracy: %f' % (lr, train_acc, val_acc)) print ('Best validation accuracy: %f' % best_acc) # Flot the loss function and train / validation accuracies plt.plot(stats['loss history']) plt.title('Training Loss History') plt.vlabel('Iteration') plt.ylabel('Iteration') plt.plot(stats['val_acc_history']) plt.plot(stats['val_acc_history']) plt.plot(stats['val_acc_history']) plt.plot(stats['val_acc_history']) plt.ylabel('Iteration') plt.ylabel('Accuracy') plt.ylabel('Accuracy') plt.show() # FND YOUR CODE HERE #</pre>
	<pre>best_net = net # Print out results for lr in sorted(results): train_acc, val_acc = results[lr] print ('Learning rates: %e Train accuracy: %f Validation accuracy: %f' % (lr, train_acc, val_acc)) print ('Best validation accuracy: %f' % best_acc) # Plot the loss function and train / validation accuracies plt.plot(stats['loss_history']) plt.title('Training_Loss History') plt.xlabel('Iteration') plt.ylabel('Iteration') plt.ylabel('Training_Loss') plt.show() # Plot (stats['val_acc_history']) plt.title('Classification Accuracy History') plt.xlabel('Accuracy') plt.xlabel('Accuracy') plt.ylabel('Accuracy') plt.ylabel('Accuracy'</pre>
	best_net = net # Frint our results for it is northed(*emilis): train_acc, val_acc = results[ir] print ('Rest validation accuracy: %f' % best_acc) # Flot the loss function and train / validation accuracy # Elect the loss function and train / validation accuracy plt_plot(state('loss history') plt.vitele('Training loss History') plt.vitele('Training loss') plt.vite
	Described Table # Brint Out results # From the Americal Control Cont
In [156	nonlymen =
In [156	body for a continuous production of the conti
In [156	but but described and conditional control of the property of t
In [156	State of the control
In [156	Service and response to the control of the control
In [156	From proceedings and the term streaming of calibration accounts; bit is the anomalous calibration of the calibration accounts; bit is the anomalous calibration of the calibration accounts; bit is the anomalous calibration of the calibration accounts; bit is the ca
In [156	months of the control
In [156	## Colon and Process of Colon
In []:	The control of the co
In []:	The company of the co
In []:	The part of the control of the contr
In []:	The part of the control of the contr
In []:	Service and an experiment of the
	The control of the co
In [152	The control of the co
In []: In [152	The control of the co
In [152 In [153	Contained and the contained an
In []: In [152	Contained and the contained an
In []: In [152	The control of the co
In []: In [152	The control of the co
In []: In [152	The control of the co
In [152	The control of the co
In []: In [152	The control of the co
In []: In [152	The control of the co
In []: In [153	The control of the co
In []: In [152	The control of the co
In []: In [152	The control of the co
In []: In [152	The control of the co

	network. Inputs: - X: Input - y: Vector an intege is not pa instead r - reg: Regu Returns: If y is Non the score f If y is not - loss: Los samples grads: Di with resp """ # Unpack va W1, b1 = se W2, b2 = se N, D = X.sh # Compute t scores = No # "YOUR CODE # Calcula # should # there s # The out # use a f # =======	e: The dimension D of the input data. e: The number of neurons H in the hi e: The number of classes C. = {} 'W1'] = std * np.random.randn(hidden size) 'W2'] = np.zeros(hidden_size) 'W2'] = std * np.random.randn(output size) X, y=None, reg=0.0): loss and gradients for a two layer f	dden layersize, input_size) _size, hidden_size)	
Service Servic	- loss: Los samples grads: Di with resp """ # Unpack va W1, b1 = se W2, b2 = se N, D = X.sh # Compute t scores = No. # ======= # YOUR CODE # Calcula # should # there s # The out # use a f # =======	data of shape (N, D). Each X[i] is a of training labels. y[i] is the labe in the range 0 <= y[i] < C. This passed then we only return scores, and eturn the loss and gradients. Larization strength.	training sample. l for X[i], and each y[i] rameter is optional; if i if it is passed then we	.t
A CONTROLLED CONTROLLE	<pre># YOUR CODE # Calcula # should # there s # The out # use a f # =======</pre>	ctionary mapping parameter names to go to the loss function; has the same riables from the params dictionary of params['W1'], self.params['b1'] of params['W2'], self.params['b2'] of params['W2'], self.params['b2'] of params['w2'], self.params['b2'] of params['w2'], self.params['w2']	radients of those paramet	
For all and property and the parties allow pages and a page and a street and a common and a comm	H1 = relu(X)	HERE: The the output scores of the neural news (N, C). As stated in the description and the neural news (N, C). As stated in the description and the neural news (N, C). As stated in the description and the neural news (N, C) and the news (N, C) and the neural news (N, C) and the news (N, C) and the news (N, C) and the neural news (N, C) and t	twork. The result on for this class, econd FC layer. put scores. Do not ====================================	
and the control of th	<pre># END YOUR # ====================================</pre>	TODE HERE Togets are not given then jump out, we see the see	"re done"	
The control of the co	<pre># total 1 # loss by # ======= # scores is class_prob = prob_correc log_loss = sum_log_los loss = sum_ frob_norm_w frob_norm_w</pre>	num_examples by num_classes np.exp(scores)/np.sum(np.exp(scores) np.log(prob_corest_y) np.log(prob_correct_y) np.log(prob_correct_y) np.sum(log_loss) nog_loss/N np.sum(W1**2) np.sum(W2**2)	he regularization	
Control of the Cont	reg_w1 = 0. reg_w2 = 0. regularized loss += reg #reg_loss = #loss = (np) # ======== # END YOUR	<pre>#reg*frob_norm_w1 #reg*frob_norm_w2 loss = reg_w1 + reg_w2 dlarized_loss 0.5 * reg * (np.linalg.norm(W1, 'fro sum(-np.log(np.exp(scores[np.arange()</pre>	N), y]) / np.sum(np.exp(s	
config. 1921 — substantiable, process, and substantial config. 1921 — subst	<pre># ======= # YOUR CODE # Impleme # weights # diction # W1, and # ======== update_scor update_scor update_scor</pre>	HERE: Int the backward pass. Compute the de and the biases. Store the results in ary. e.g., grads['W1'] should store be of the same size as W1.	rivatives of the n the grads the gradient for	
# SEE TOWN COME MEMBER ***COMMAND COME MEMBER ***COM	<pre>grads['b2'] dH2 = np.do dLdA = dH2 dLdA[H1 <= grads['W1'] grads['b1']</pre>	<pre>= np.sum(update_scores, axis=0) c(update_scores, W2) 0] = 0 = np.dot(dLdA.T, X) = np.sum(dLdA, axis=0) += reg * W2</pre>		
set & heavy area camed (More Double) plongly techniqued. - K voll & namey crossy of chapt (Mivel) of diving vollations dute. - K voll & namey crossy of chapt (Mivel) of diving vollations dute. - K voll & namey crossy of chapt (Mivel) of diving vollations dute. - K voll & namey crossy of chapt (Mivel) of vollation dute on the control of the contr	# END YOUR # ======= return loss lef train(sel lea reg bat """ Train this	grads f, X, y, X_val, y_val, ming_rate=1e-3, learning_rate_decay= ele-5, num_iters=100, ch_size=200, verbose=False):	# 0.95,	
# Young color mass: * Consequence and admitted to be permitting better give semples conduct, * Consequence and admitted to permitting better give semples conduct, * Company or and mass of the color	- X: A nump - y: A nump X[i] has - X_val: A - y_val: A - learning - learning after eac - reg: Scal - num_iters - batch_siz - verbose: """ num_train = iterations # Use SGD t loss_histor train_acc_h val_acc_his for it in n X_batch =	<pre>varray f shape (N,) giving training tabel c, where 0 <= c < C. numpy array of shape (N_val, D) giving numpy array of shape (N_val,) giving tate: Scalar giving learning rate for tate_decay: Scalar giving factor used n epoch. It giving regularization strength. Number of steps to take when optimi tate: Number of training examples to use toolean; if true print progress durin the example of the parameters in self.mod to a coptimize the parameters</pre>	<pre>labels; y[i] = c means th g validation data. validation labels. optimization. to decay the learning ra zing. per step. g optimization.</pre> e, 1)	
Jose, Totalogy, Special Costs (Special Special Special Costs) (Special Speci	# ====== # YOUR CO # Creat # ====== random_in X_batch = y_batch = # ====== # END YOU	DE HERE: e a minibatch by sampling batch_size dices = np.random.choice(np.arange(nu X[random_indices] y[random_indices]	samples randomly. m_train), batch_size)	
seif.params('bi') += -learning_rate * grads('bi') \$	<pre>loss, gra loss_hist # ====== # YOUR CO # Perfo # all p # ====== self.para; self.para;</pre>	As = self.loss(X_batch, y=y_batch, repry.append(loss) DE HERE: The a gradient descent step using the arameters (i.e., W1, W2, b1, and b2). The arameters is ['W2'] += -learning_rate * grads['Was['W1'] += -learning_rate * grads['Was['W1'] += -learning_rate * grads['Was['W1'] += -learning_rate * grads['W1'] += -learn	g=reg) # minibatch to update ===================================	
train_acc_history.append(train_acc) val_acc_history.append(val_acc) * Decay learning rate learning_rate *= learning_rate_decay return [''cas history': loss history, ''rain_acc_history': train_acc_history, ''val_acc_history': val_acc_history, ''val_acc_history': val_acc_history, *** *** *** *** *** *** ***	# ====== # END YOU # ====== if verbos print(' # Every e if it % i # Check train_a	as['b1'] += -learning_rate * grads['b CODE HERE and it % 100 == 0: teration {} / {}: loss {}'.format(it) coch, check train and val accuracy and erations_per_epoch == 0: accuracy cc = (self.predict(X_batch) == y_batc	1']## , num_iters, loss)) d decay learning rate. h).mean()	
<pre>data points. Por each data point we predict scores for each of the C classes, and assign each data point to the class with the highest score. Inputs: - X: A numpy array of shape (N, D) giving N D-dimensional data points to classify. Returns: - y_pred: A numpy array of shape (N,) giving predicted labels for each of the elements of X. For all i, y_pred[i] = c means that X[i] is predicted to have class c, where 0 <= c < C. """ y_pred = None #</pre>	<pre>train_a val_acc # Decay learnin return { 'loss_his 'train_ac 'val_acc_ } ef predict(s</pre>	<pre>cc_history.append(train_acc) history.append(val_acc) learning rate g_rate *= learning_rate_decay cory': loss_history, c_history': train_acc_history, history': val_acc_history,</pre>		
<pre># YOUR CODE HERE: # Predict the class given the input data. #</pre>	<pre>data points classes, an Inputs: - X: A nump classify. Returns: - y_pred: A the eleme to have c """</pre>	For each data point we predict scord assign each data point to the class array of shape (N, D) giving N D-di numpy array of shape (N,) giving predicts of X. For all i, y_pred[i] = c metass c, where 0 <= c < C.	es for each of the C with the highest score. mensional data points to dicted labels for each of	
<pre>#apply softmax softmax = np.exp(H2)/np.sum(np.exp(H2), axis=1, keepdims=True) for i in range(num_examples): max_index = np.argmax(softmax[i]) y_pred[i] = max_index # ===================================</pre>	<pre># YOUR CODE # Predict # ======= num_example y_pred = np H1_preact = #apply RELU H1 = np.ma #second lay</pre>	<pre>HERE: the class given the input data. s = X.shape[0] empty((num_examples,), dtype=int) np.dot(X, self.params['W1'].T) + sel simum(0, H1_preact) er</pre>	f.params['b1']	
	<pre>#apply soft softmax = n; for i in ra max_ind y_pred[# ====================================</pre>	nax o.exp(H2)/np.sum(np.exp(H2), axis=1, nge(num_examples): ex = np.argmax(softmax[i]) nge(num_examples): ex = np.argmax(softmax[i]) nge(num_examples): ex = np.argmax(softmax[i])	keepdims= True)	