

# Learning-Based Compressive MRI <sup>1</sup>

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October 15, 2020

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<sup>1</sup>Gözcü, B., Mahabadi, R.K., Li, Y.H., Ilıcak, E., Çukur, T., Scarlett, J. and Cevher, V., 2018. Learning-based compressive MRI. IEEE transactions on medical imaging, 37(6), pp.1394-1406.

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# Introduction

- A learning-based framework for optimizing MRI subsampling patterns for a specific reconstruction rule and anatomy
- Algorithm searches for a sampling pattern that performs well on average for the signals in the training set
- A novel parameter-free greedy mask selection method
- Can find good sampling patterns for various performance metrics such as PSNR, SSIM, etc.
- Works for broad range of decoders, e.g. basis pursuit<sup>2</sup>, total variation, neural network, BM3D<sup>3</sup>

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<sup>2</sup>D. L. Donoho, "Compressed sensing," IEEE Trans. Inf. Theory, Apr. 2006.

<sup>3</sup>E. M. Eksioglu, "Decoupled algorithm for MRI reconstruction using nonlocal block matching model: BM3D-MRI," J. Math. Imag. Vision 2016.

# Background

## Compressive Sensing Problem

$$\mathbf{b} = \mathbf{P}_{\Omega} \Psi \mathbf{x} + \mathbf{w}$$

where

- $\mathbf{b}$  is the sparse measurement
- $\mathbf{P}_{\Omega} : \mathbb{C}^p \rightarrow \mathbb{C}^n$  is the subsampling operator for sampling pattern/mask  $\Omega$
- $\Psi \in \mathbb{C}^{p \times p}$  is the Fourier Transform operator
- $\mathbf{w} \in \mathbb{C}^n$  is the additive noise

Uses a reconstruction algorithm  $g$  to estimate  $\hat{\mathbf{x}}$  from measurements  $\mathbf{b}$

$$\hat{\mathbf{x}} = g(\Omega, \mathbf{b})$$

# Learning Based Framework

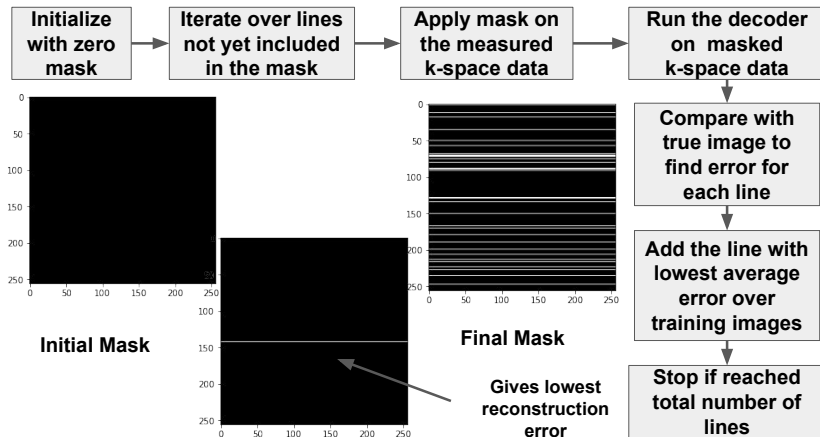
- Access to fully sampled signals  $\mathbf{x}_1, \dots, \mathbf{x}_m$
- Assuming that decoder  $g$  is given (can be arbitrary).
- For a subsampling pattern  $\Omega$ , consider its empirical average performance on the training signals:

$$\frac{1}{m} \sum_{j=1}^m \eta_{\Omega}(\mathbf{x}_j) = \frac{1}{m} \sum_{j=1}^m \eta(\mathbf{x}_j, \hat{\mathbf{x}}_j)$$

where  $\eta$  is the performance measure (e.g. PSNR, SSIM).

- Use greedy algorithm to seek an appropriate maximizer by solving  $\mathbf{b} = \mathbf{P}_{\Omega} \Psi \mathbf{x}$

# Greedy Algorithm: Flow Chart



# Greedy Algorithm: Pseudo Code

**Input:** Training data  $\mathbf{x}_1, \dots, \mathbf{x}_m$ , reconstruction rule  $g$ , sampling set  $\mathcal{S}$ , cost function  $c$ , maximum cost  $\Gamma$

**Output:** Sampling pattern  $\Omega$

- 1  $\Omega \leftarrow \emptyset$
- 2 **while**  $c(\Omega) \leq \Gamma$  **do**
- 3   **for**  $S \in \mathcal{S}$  such that  $c(\Omega \cup S) \leq \Gamma$  **do**
- 4      $\Omega' = \Omega \cup S$
- 5     For each  $j$ , set  $\mathbf{b}_j \leftarrow \mathbf{P}_{\Omega'} \Psi \mathbf{x}_j$ ,  $\hat{\mathbf{x}}_j \rightarrow g(\Omega', \mathbf{b}_j)$
- 6      $\eta(\Omega') \leftarrow \frac{1}{m} \sum_{j=1}^m \eta(\mathbf{x}_j, \hat{\mathbf{x}}_j)$
- 7      $\Omega \leftarrow \Omega \cup S^*$ , where

$$S^* = \arg \max_{S: c(\Omega \cup S) \leq \Gamma} \frac{\eta(\Omega \cup S) - \eta(\Omega)}{c(\Omega \cup S) - c(\Omega)}$$

- 8 **return**  $\Omega$

# Noisy Setting

Acquired noisy signal given by

$$\mathbf{b} = \mathbf{P}_{\Omega} \Psi \mathbf{x} + \mathbf{w}$$

Learning algorithm have access to only noisy training signals

$$\mathbf{z}_j = \mathbf{x}_j + \mathbf{v}_j, \quad j = 1, \dots, m$$

Can get reduced noise using a denoiser  $\xi(\mathbf{z}) = \mathbf{x}_j + \tilde{\mathbf{v}}_j$

Selection rule now becomes

$$\hat{\Omega} = \arg \max_{\Omega \in \mathcal{A}} \frac{1}{m} \sum_{j=1}^m \eta(\mathbf{x}_j + \tilde{\mathbf{v}}_j, \hat{\mathbf{x}}(\mathbf{P}_{\Omega} \Psi(\mathbf{x}_j + \mathbf{v}_j)))$$

with  $\hat{\mathbf{x}} = g(\Omega, \mathbf{b})$  from the reconstruction algorithm.



# Learning-based approach outperforms the baselines

TABLE I

PSNR AND SSIM PERFORMANCES AVERAGED ON 60 TEST SLICES AT 25% SUBSAMPLING RATE. THE ENTRIES WHERE THE LEARNING IS MATCHED TO THE DECODER AND PERFORMANCE MEASURE ARE SHOWN IN BOLD.

Mask \ Decoder	TV	BP	BM3D	NN
Coherence-based	30.76	31.48	30.04	32.02
Single-image	32.79	33.32	32.42	33.67
TV-greedy	<b>34.84</b>	36.08	35.95	36.04
BP-greedy	34.76	<b>36.16</b>	36.11	36.17
BM3D-greedy	34.77	36.04	<b>36.19</b>	35.92
NN-greedy	34.81	36.05	36.16	<b>36.36</b>
Low Pass	31.96	32.41	32.59	32.59

Mask \ Decoder	TV	BP	BM3D	NN
Coherence-based	0.832	0.85	0.822	0.798
Single-image	0.876	0.889	0.879	0.854
TV-greedy	0.907	0.922	0.921	0.869
BP-greedy	0.906	0.923	0.921	0.859
BM3D-greedy	0.906	0.922	0.922	0.909
NN-greedy	0.907	0.923	0.923	0.925
Low Pass	0.876	0.888	0.893	0.893

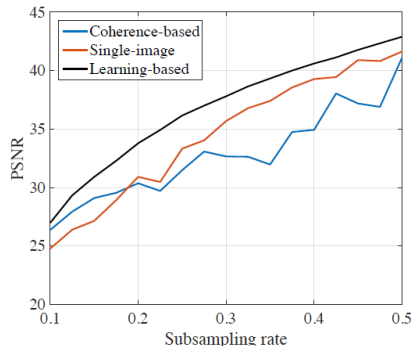
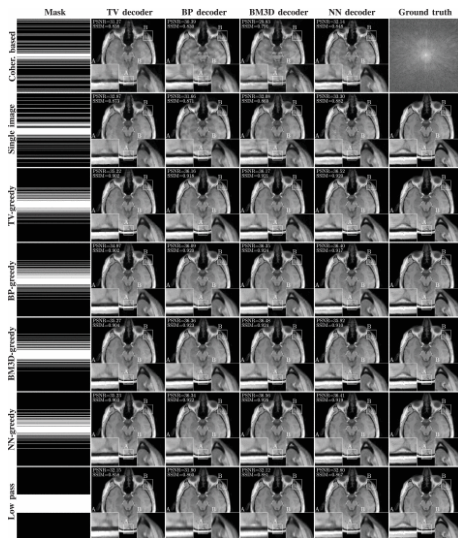


Fig. 1. PSNR as a function of subsampling rates with BP reconstruction.

# Reconstruction Examples



# Observation

- Greedy masks outperform the the low pass mask as well, in terms of PSNR, SSIM and also visual quality,
- Offer sharper images with less aliasing artefacts by balancing between low and high frequency components.
- Pure low-pass mask introduces strong blurring
- Baseline masks (coherence-based<sup>4</sup> and single image<sup>5</sup>) cause highly visible aliasing due to suboptimal sampling across low to intermediate frequencies.

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<sup>4</sup>M. Lustig, D. Donoho, and J. M. Pauly, "Sparse MRI: The application of compressed sensing for rapid MR imaging," Magn. Reson. Med., 2007.

<sup>5</sup>J. Vellagoundar and R. R. Machireddy, "A robust adaptive sampling method for faster acquisition of MR images," Magnetic resonance imaging, 2015.

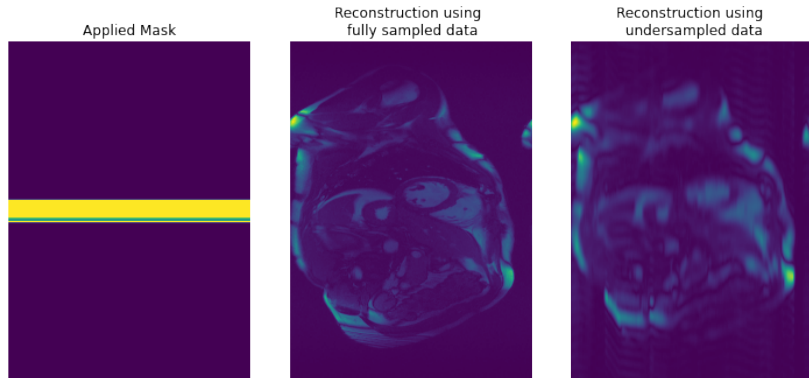
# Testing on OCMR dataset <sup>6</sup>

Parameter	Value
Data	Cardiac
Image Size	$512 \times 208$
No. of coils	18
No. of lines in Mask	32
Performance Metric	Mean Squared Error
Decoder	Inverse FFT + Sum of Squares

Table: Simulation Parameters

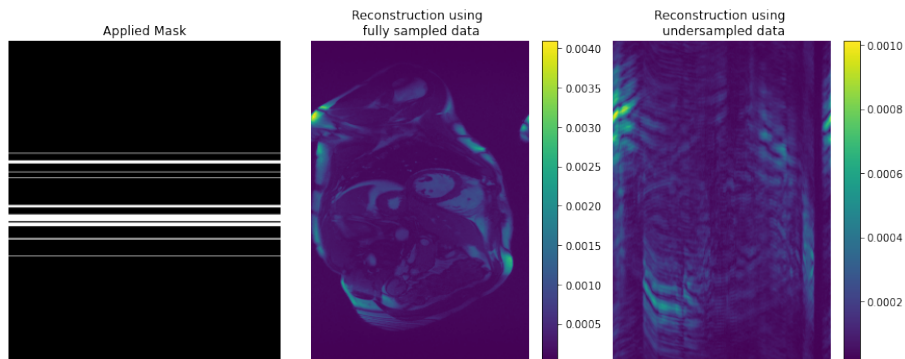
<sup>6</sup>Chen, Chong, et al. "OCMR (v1. 0)–Open-Access Multi-Coil k-Space Dataset for Cardiovascular Magnetic Resonance Imaging." arXiv e-prints. (2020): arXiv-2008.   

# Performance Metric: L2-Norm of the Error



**Figure:** Reconstruction using greedy algorithm with mask of 32 lines tested on fully sampled OCMR data

# Performance Metric: L1-Norm of the Error



**Figure:** Reconstruction using greedy algorithm with mask of 32 lines tested on fully sampled OCMR data

# Conclusion

- A versatile learning-based framework for selecting masks for compressive MRI.
- Provides improved performance on realworld data sets for a variety of reconstruction methods (statistical learning theory).
- Framework suited to general decoders, hence can be used for new reconstruction methods that are yet to be discovered.
- Focused on 1D subsampling for 2D MRI, 2D subsampling (via horizontal and vertical lines) for 2D MRI, and 1D subsampling for 3D MRI,
- Challenge with 3D MRI, since the candidate set is large.