# Multivariate Linear Regression

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#### June 2021

### Multiple Features

- Notation usage
  - -n number of features
  - -m number of training examples
  - $-x^{(i)}$  input features of ith training example -> is a vector with dimension n
  - $-x_i^{(i)}$  number of feature j in ith training example
- Hypothesis is of the form  $h_{\theta}(x) = \theta_0 + \theta_1 x_1 + ... + \theta_n x_n$ 
  - Define  $x_0 := 1$  as coefficient of  $\theta_0$

\* Let 
$$x = \begin{bmatrix} x_0 \\ \vdots \\ x_n \end{bmatrix}$$
 and  $\theta = \begin{bmatrix} \theta_0 \\ \vdots \\ \theta_n \end{bmatrix}$ 

- \* Both are in  $\mathbb{R}^{n+1}$
- Thus  $h_{\theta}(x) = \theta^T x$  where  $\theta$  is transposed to allow multiplication with matrix x

## Gradient descent with multiple features

- Let  $\theta$  be the n+1-dimensional parameter vector
- $\begin{array}{l} \bullet \ \ \text{Perform} \ \theta_j := \theta_j \alpha \frac{1}{m} \sum_{i=1}^m \left( h_\theta \left( x^{(i)} \right) y^{(i)} \right) x_j^{(i)} \\ \ \ \text{Simultaneous update of} \ \theta_j \ \text{for} \ j = 0, \dots, n \end{array}$

repeat until convergence:

$$\begin{aligned} & \theta_0 \coloneqq \theta_0 - \alpha \frac{1}{m} \sum_{i=1}^m \left( h_\theta \left( x^{(i)} \right) - y^{(i)} \right) \cdot x_0^{(i)} \\ & \theta_1 \coloneqq \theta_1 - \alpha \frac{1}{m} \sum_{i=1}^m \left( h_\theta \left( x^{(i)} \right) - y^{(i)} \right) \cdot x_1^{(i)} \\ & \theta_2 \coloneqq \theta_2 - \alpha \frac{1}{m} \sum_{i=1}^m \left( h_\theta \left( x^{(i)} \right) - y^{(i)} \right) \cdot x_2^{(i)} \end{aligned}$$

# Feature Scaling

- Make sure features are on similar scale or interval
  - Contours will become more like circles -> gradient descent is less complicated
- Get feature into approx.  $-1 \le x_i \le 1$  range
- Mean normalization
  - Replace  $x_i$  with  $x_i \mu_i$  to make features have an approximately zero mean (except  $x_0 = 1$ )
- Thus formula for feature scaling with mean normalization is  $x_i \to \frac{x_i \mu_i}{s_i}$  where  $s_i$  can be range of values in training set or the std. dev

# Learning rate

• Debugging gradient descent

- Plot  $\min J(\theta)$  as gradient descent runs over # of iterations
- Should show decrease as iterations progress
- Automatic convergence test
  - Ex: Declare convergence if  $J(\theta)$  decreases by less than  $10^{-3}$  in 1 iteration
- For sufficient small  $\alpha J(\theta)$  decreases on every iteration
  - If too small -> slow to converge

### Features and Polynomial Regression

- Can define a feature in terms of others -> combining features
- Fitting polynomial model
  - Define each feature to be square, cubed, etc.
  - Apply regular linear Regression
  - Feature scaling is important -> exponential values increase scale

### Normal Equation

- Method to solve for  $\theta_0, \dots, \theta_n$  through derivative of J with respect to  $\theta_j$ , set to 0, and minimization
- Construct a design matrix X that is of dimension  $m \times (n+1)$  and contains all of the training data Each feature vector  $x^{(i)} \in \mathbb{R}^{n+1}$  is transposed to constitute a row of X
- Construct vector y which contains the result/expected output and is m-dimensional
- Optimum  $\theta$  is given by  $(X^TX)^{-1}X^Ty$
- Feature scaling not required
- Gradient descent comparison
  - Gradient descent -> need to choose  $\alpha$  and needs mamy iterations
    - \* Works well for a large n
  - Normal equation -> no need to choose  $\alpha$  and don't need to iterate
    - \* Slow if n is very large -> need to compute  $(X^TX)^{-1}$ )
      - · Inversion is  $O(n^3)$
- $X^TX$  can be noninvertible
  - pinv works regardless of invertibility and inv will throw error in octave
  - Redundant features (i.e. linear dependence)
  - Too many features means  $m \leq n$