## Classification

- Is a discrete categorization of an output variable, e.g.  $y \in \{0, 1\}$ 
  - Can also have multiple classes, so some set  $S \mid len(S) > 2$
- Linear regression -> threshold classifier output
  - E.g. if  $h_{\theta}(x) \ge 0.5 \text{ do } y = 1 \text{ else } y = 0$
  - However is not effective when there are > 2 clusters -> DNU
- Classification y = 0 or y = 1
  - $-0 \le h_{\theta}(x) \le 1$
  - Binary classification

## Hypothesis Representation

- Need  $0 \le h_{\theta}(x) \le 1$
- $h\theta_0(x) = g(\theta^T x)$  where  $g = \frac{1}{1+e^{-z}}$  is the sigmoid = logistical function and  $z = \theta^T x$  $-h_{\theta}(x) = \frac{1}{1 + e^{-\theta^T x}}$
- Interpretation
  - $-h_{\theta}(x)$  is estimated probability that y=1 on input x
  - $-h_{\theta}(x) = P(y=1|x;\theta)$  is probability of y=1 given x parameterized by  $\theta$ 
    - \* Due to total sum probability ->  $P(y = 0|x;\theta) = 1 P(y = 1|x;\theta)$

## Decision Boundary

- Prediction boundary If  $h_{\theta}(x) \geq 0.5$  do y = 1 else y = 0
  - Thus  $y = 0 \implies \theta^T x < 0$  and  $y = 1 \implies \theta^T x \ge 0$
  - Graph the equation  $\theta_0 + \theta_1 x_1 + ... + \theta_n x_n \ge 0$  (higher order planes of  $\mathbb{R}^{n+1}$ )
- Nonlinear decision boundaries

  - Have polynomial terms in features Ex.  $-1 + x_1^2 + x_2^2 \ge 0 \implies$  unit circle

## Logistic cost function

- Setup/prime
  - Training set  $S = \{(x^{(1)}, y^{(1)}), (x^{(2)}, y^{(2)}), \dots, (x^{(m)}, y^{(m)})\}$ 
    - \* m examples
  - A feature vector  $x \in \begin{bmatrix} x_0 \\ x_1 \\ \vdots \\ x_n \end{bmatrix}$
- $Cost(h_{\theta}(x), y) = \frac{1}{2}(h_{\theta}(x) y)^{2}$ 
  - Is non-convex many local extrema which may hinder gradient descent
- Cost function for logistic regression

$$\boxed{ \operatorname{Cost} \left( h_{\theta}(x), y \right) = \left\{ \begin{aligned} -\log \left( h_{\theta}(x) \right) & \text{if } y = 1 \\ -\log \left( 1 - h_{\theta}(x) \right) & \text{if } y = 0 \end{aligned} \right. }$$

- Cost function behavior
  - Cost is 0 if  $y = 1, h_{\theta}(x) = 1$
  - As  $h_{\theta}(x) \to 0$ , Cost  $\to \infty$
  - If  $h_{\theta}(x) = 0$  but y = 1, then learning algorithm penalized heavily