

# Improved Music Feature Learning with Deep Neural Networks

Siddharth Sigtia and Simon Dixon

`{sss31,simond}@qmul.ac.uk`

Centre for Digital Music  
Queen Mary University of London

# Motivation

- Try to learn the most optimal features for a particular task and reduce dependency on hand-crafted features.
- How can we learn features for a particular task?:  
Neural nets with several hidden layers (deep neural networks).
- Can we learn features for MIR tasks with neural nets?:  
Lots of recent evidence suggests yes!



# Can we do better?

- The use of neural networks for supervised learning has come full circle in some ways.
- Unsupervised pre-training is not considered to be necessary for finding good solutions.
- Gradient based optimisers starting with random parameter initialisation provide good results.
- Rectified Linear Units (ReLUs), Dropout, Hessian Free (HF) optimisation, Nesterov's Accelerated Gradient have all been applied to problems in various domains.
- The application of these new techniques to learning features for MIR tasks could provide improvements over existing methods.

# Problem definition

- Learn features for a genre classification task using data from the GTZAN dataset.
- Train a classifier on the learned features and evaluate system performance.
- Inspect if features are general by using the same features on the ISMIR2004 genre dataset.

This area will contain a diagram of the general pipeline

# Contributions Of The Paper

- Evaluate the use of ReLUs as hidden units.
- Use Dropout for regularisation.
- Use HF Optimisation for training sigmoid nets and compare.

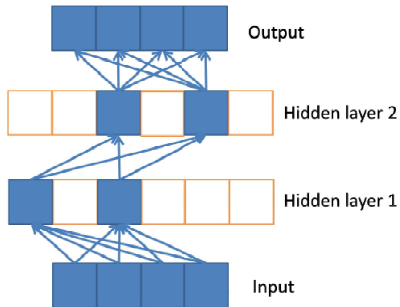
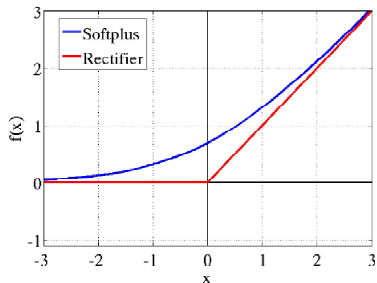
## Hypothesis?

- ReLUs+Dropout eliminate the need for pre-training.
- $\text{Performance}(\text{ReLU}+\text{Dropout}+\text{SGD}) \geq \text{Performance}(\text{sigmoid nets}+\text{SGD})$
- More efficient training of sigmoid nets with HF.

# Feature Extraction

This slide is going to contain a pictorial representation of the feature extraction.

# Rectified Linear Units



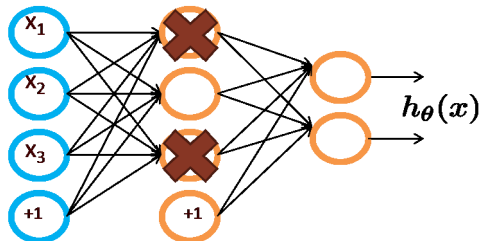
Activation function:  $f(x) = \max(0, x)$



# Useful Properties of ReLUs

- No need for supervised pre-training.
- Hard sparsity in hidden layers.
- Gradients flow easily.
- Error surface is less convoluted w.r.t parameters because of the form of the activation function.

# Dropout



Forward Propagation

$$y^l = \frac{1}{1-p} W^l (r^{l-1} * y^{l-1} + b^l)$$