$$\begin{split} 1. & \qquad \hat{u} = \frac{1}{\sqrt{2^2 + 1^2}} \left< 2, -1 \right> = \left< \frac{2}{\sqrt{5}}, -\frac{1}{\sqrt{5}} \right> \\ & \qquad \hat{v} = \frac{1}{\sqrt{1^2 + 3^2}} \left< 1, 3 \right> = \left< \frac{1}{\sqrt{10}}, \frac{3}{\sqrt{10}} \right> \\ & \qquad \hat{w} = \frac{1}{\sqrt{1^2 + 1^2 + 1^2}} \left< -1, -1, -1 \right> = \left< \frac{-1}{\sqrt{3}}, \frac{-1}{\sqrt{3}}, \frac{-1}{\sqrt{3}} \right> \\ & \qquad \vec{r} = \left< \frac{1}{\sqrt{10} - \frac{1}{\sqrt{3}}, \frac{3}{\sqrt{10}}} - \frac{1}{\sqrt{3}, \frac{-1}{\sqrt{3}}} \right> = \left< \frac{\sqrt{3} - \sqrt{10}}{\sqrt{30}}, \frac{3\sqrt{3} - \sqrt{10}}{\sqrt{30}}, \frac{-\sqrt{10}}{\sqrt{30}} \right>. \\ & \qquad \text{Hence } |\vec{r}^2| = \frac{3 + 10 - 2\sqrt{30} + 27 + 10 - 6\sqrt{30} + 10}{30} = \frac{60 - 8\sqrt{30}}{30} = \frac{30 - 4\sqrt{30}}{15}. \text{ Thus,} \\ & \qquad \hat{r} = \frac{\vec{r}}{|\vec{r}|} = \sqrt{\frac{30 - 4\sqrt{30}}{15}} \left< \frac{\sqrt{3} - \sqrt{10}}{\sqrt{30}}, \frac{3\sqrt{3} - \sqrt{10}}{\sqrt{30}}, \frac{-\sqrt{10}}{\sqrt{30}} \right> \end{split}$$

2. (a)
$$\begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_n \end{bmatrix} \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix} = \sum_{i=1}^n a_i b_i.$$

Assume $\vec{a} = \langle a_1, a_2, ..., a_n \rangle$, $\vec{b} = \langle b_1, b_2, ..., b_n \rangle$ and $\vec{c} = \langle c_1, c_2, ..., c_n \rangle$. Then,

(b)
$$\vec{a}.(\alpha \vec{b}) = \langle a_1, a_2, ..., a_n \rangle \cdot \langle \alpha b_1, \alpha b_2, ..., \alpha b_n \rangle$$

$$= \sum_{i=1}^n a_i \alpha b_i = \alpha \sum_{i=1}^n a_i b_i = \alpha \left(\langle a_1, a_2, ..., a_n \rangle \cdot \langle b_1, b_2, ..., b_n \rangle \right) = \alpha \left(\vec{a} \cdot \vec{b} \right)$$

(c)
$$\vec{a} \cdot (\vec{b} + \vec{c}) = \langle a_1, a_2, ..., a_n \rangle \cdot \langle b_1 + c_1, b_2 + c_2, ..., b_n + c_n \rangle$$

$$= \sum_{i=1}^n a_i (b_i + c_i) = \sum_{i=1}^n a_i b_i + \sum_{i=1}^n a_i c_i$$

$$= \langle a_1, a_2, ..., a_n \rangle \cdot \langle b_1, b_2, ..., b_n \rangle + \langle a_1, a_2, ..., a_n \rangle \cdot \langle c_1, c_2, ..., c_n \rangle = \vec{a} \cdot \vec{b} + \vec{a} \cdot \vec{c}$$

3. (a) Suppose $\vec{p} = \langle x_p, y_p, z_p \rangle$ where $x_p, y_p, z_p \in \mathbb{R}$. Since \vec{p} is a point in \mathcal{P} , x_p, y_p and z_p satisfy equation:

$$3x_p - 2y_p + z_p = 4$$

Hence $\vec{p} \cdot \langle 3, -2, 1 \rangle = \langle x_p, y_p, z_p \rangle \cdot \langle 3, -2, 1 \rangle = 3x_p - 2y_p + z_p = 4$.

(b) Plane \mathcal{Q} is a translation of plane \mathcal{P} in y-direction 1 unit. Hence it has equation 3x - 2(y-1) + z = 4, or equivalently

$$3x - 2y + z = 2$$

Similar to part(a), $\vec{q} \cdot \langle 3, -2, 1 \rangle = 2$.

4. (a) Write $a \begin{bmatrix} 3 \\ 1 \end{bmatrix} + b \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 107 \\ 64 \end{bmatrix}$ $(a, b \in \mathbb{R})$.

We do row reduction to augmented matrix to find solution for above equation:

$$\begin{bmatrix} 3 & 1 & 107 \\ 1 & 2 & 64 \end{bmatrix} \xrightarrow{(1)-3(2)} \begin{bmatrix} 0 & -5 & -85 \\ 1 & 2 & 64 \end{bmatrix} \xrightarrow{\frac{-1}{5}(1)} \begin{bmatrix} 0 & 1 & 17 \\ 1 & 2 & 64 \end{bmatrix} \xrightarrow{(2)-2(1)} \begin{bmatrix} 0 & 1 & 17 \\ 1 & 0 & 30 \end{bmatrix}$$

Hence a = 30, b = 17.

(b) We want to solve for $a, b \in \mathbb{R}$ in the equation $a \begin{bmatrix} 3 \\ 1 \end{bmatrix} + b \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} -99 \\ -100 \end{bmatrix}$. We do row reduction to augmented matrix to find solution for above equation:

$$\begin{bmatrix} 3 & 1 & -99 \\ 1 & 2 & -100 \end{bmatrix} \xrightarrow{(1)-3(2)} \begin{bmatrix} 0 & -5 & 201 \\ 1 & 2 & -100 \end{bmatrix} \xrightarrow{\frac{-1}{5}(1)} \begin{bmatrix} 0 & 1 & \frac{-201}{5} \\ 1 & 2 & -100 \end{bmatrix} \xrightarrow{(2)-2(1)} \begin{bmatrix} 0 & 1 & \frac{-201}{5} \\ 1 & 0 & \frac{-98}{5} \end{bmatrix}$$

Thus $a = \frac{-98}{5}$ and $b = \frac{-201}{5}$.

(c) Let
$$\vec{u} = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$$
, $\vec{b} = \begin{bmatrix} 2 \\ 0 \\ 0 \end{bmatrix}$, and $\vec{c} = \begin{bmatrix} 0 \\ 0 \\ -1 \end{bmatrix}$. A linear combination of $\vec{u}, \vec{v}, \vec{w}$ has the form $a\vec{u} + b\vec{v} + c\vec{w} = \begin{bmatrix} a+2b \\ 0 \\ a-c \end{bmatrix}$. The resulting vector has the form $\begin{bmatrix} x \\ 0 \\ z \end{bmatrix}$ where $x, z \in \mathbb{R}$.

In fact any vector of that form is a linear combination of \vec{u}, \vec{v} and \vec{w} . It is because for any $x, z \in \mathbb{R}$, the system of equation

$$\begin{cases} a + 2b = x \\ a - c = z \end{cases}$$

always has solution
$$\begin{cases} a = 0 \\ b = \frac{x}{2} \\ c = -z \end{cases}$$