

EXTENDING C/C++ FOR PORTABLE SIMD PROGRAMMING

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PROBLEM void mandelbrot(float x0, float y0, float x1, float y1, int width, int height, int max_iter, __m128i output[]) { // outer loopp $_{m128} dx = _{mm_{set1_ps}((x1 - x0) / width);}$ $_{m128} dy = _{mm_{set1_ps((y1 - y0) / height);}$ // for each row for (int j = 0; j < height; ++j) // for each column as vector of length 4 for (int ii = 0; ii < width; ii += 4) __m128i i = _mm_add_epi32(_mm_set1_epi32(ii), _mm_set_epi32(3, 2, 1, 0)); $_{m128}$ $x = _{mm_add_ps(_{mm_set1_ps(x0)}, _{mm_mul_ps(_{mm_cvtepi32_ps(i)}, dx));}$ $_{m128}$ $y = _{mm_add_ps(_{mm_set1_ps(y0)}, _{mm_mul_ps(_{mm_set1_ps((float) j), dy))};$ *output++ = mandel(x, y, max_iter); __m128i mandel(__m128 c_r , __m128 c_i , **int** count) { // inner loop // gets accumulated in each iteration $_{m128} z_r = c_r;$ $_{m128} z_i = c_i;$ // loop count for each program instance $_{m128i} i = _{mm_{set1_{epi32}(0)}}$ while (true) { $_{m128} length = _{mm_add_ps(_{mm_mul_ps(z_r, z_r), _{mm_mul_ps(z_i, z_i));}}$ __m128 mask = _mm_and_ps((__m128) (_mm_cmplt_epi32(i, _mm_set1_epi32(count))), _mm_cmplt_ps(length, _mm_set1_ps(4.f))); if (_mm_movemask_ps(mask) == 0) break; $_{m128 \text{ new_r}} = _{mm_sub_ps(_mm_mul_ps(z_r, z_r), _mm_mul_ps(z_i, z_i));$ $_{m128} \text{ new_i} = _{mm_mul_ps(_mm_set1_ps(2.f), _mm_mul_ps(z_r, z_i));}$ $z_r = _mm_blendv_ps(z_r, _mm_add_ps(c_r, new_r), mask);$ $z_i = _mm_blendv_ps(z_i, _mm_add_ps(c_i, new_i), mask);$ i = _mm_blendv_epi8(i, _mm_add_epi32(i, _mm_set1_epi32(1)), _mm_castps_si128(mask)); // number of iterations for each program instance return i; • Intrinsics are tied to one specific target architecture

- Assembly-like coding style
- Hard to write and debug
- Rewrite your code for each new ISA or extension
- Manual blending/adjustments of the mask
 - Extremely complicated and error-prone when dealing with branches and loops

OTHER SOLUTIONS

Auto-Vectorizer

- Restricted scope of applicability
- Works only for code the auto-vectorizer "understands"

Array Programming (FORTRAN, MATLAB®, Intel® Array Building Blocks, ...)

- Excel in the domain of vector/matrix computations
- Operations on non-primitve types (e.g. vec3) become problematic

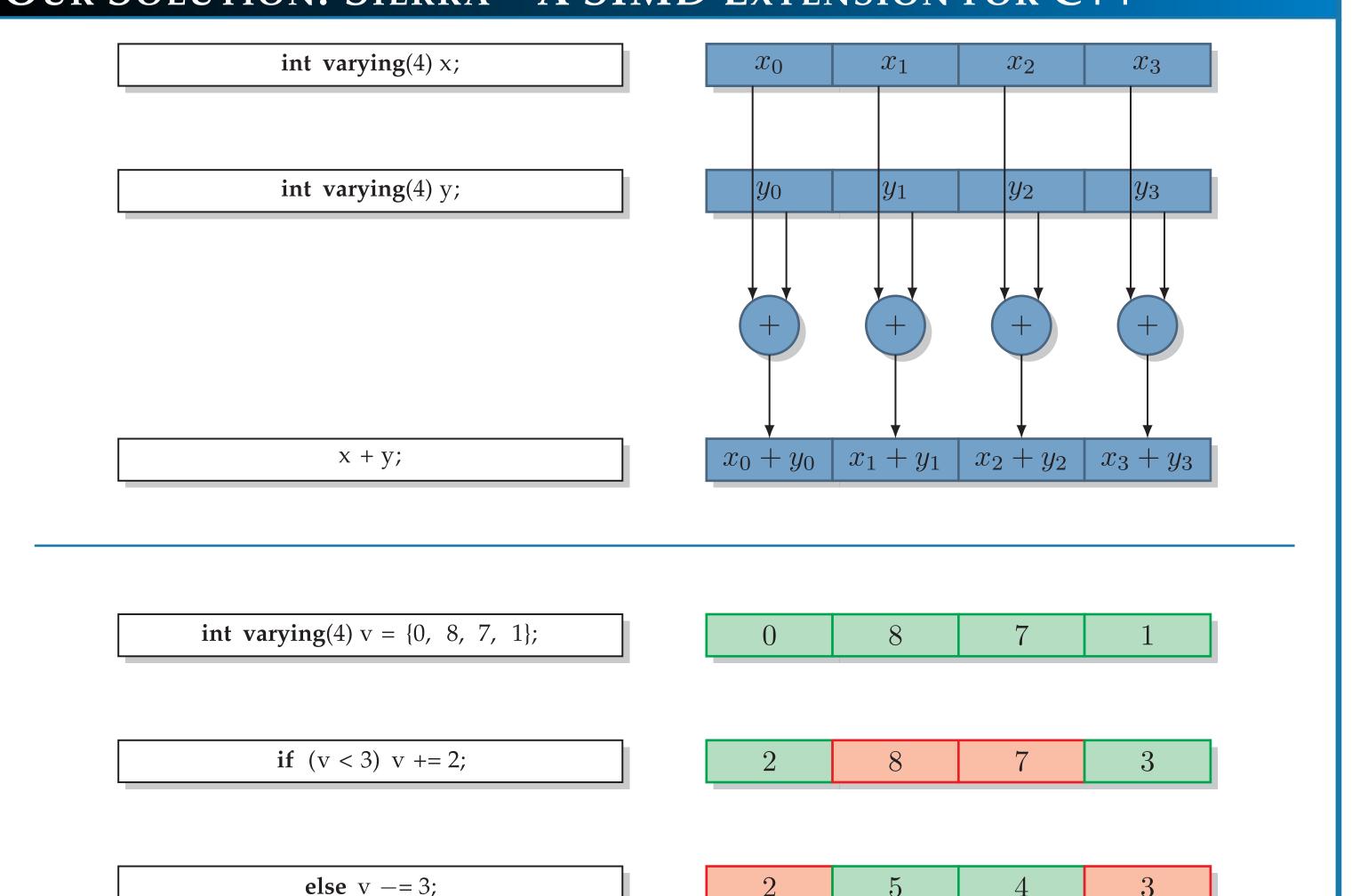
OpenCL

- Special kernel language necessary
- Fixed vectorization length
- Lack of uniform variables (important for performance on the CPU)
- Cross-lane computations tricky (barriers)

ispc[2]/IVL[1]

- Special kernel language necessary
- Fixed vectorization length per translation unit

OUR SOLUTION: SIERRA – A SIMD EXTENSION FOR C++



POLYMORPHIC MANDELBROT



```
template < int L > // outer loop
void mandelbrot(float x0, float y0, float x1, float y1,
                int width, int height, int max_iter, int varying(L)* output)
    float dx = (x1 - x0) / width;
    float dy = (y1 - y0) / height;
    // for each row
    for (int j = 0; j < height; ++j)
       // for each column as vector of length L
        for (int i = 0; i < width; i += L) {
            // pixel coords to coords in mandelbrot set
            float varying(L) x = x0 + (i + seq(L)) * dx;
            float varying(L) y = y0 + j * dy;
            *output++ = mandel < L > (x, y, max_iter);
template<int L> // inner loop
int varying(L) mandel(float varying(L) c_r, float varying(L) c_i, int count) {
   // gets accumulated in each iteration
    float varying(L) z_r = c_r;
    float varying(L) z_i = c_i;
    // loop count for each program instance
    int varying (L) i = 0;
    while ((i < count) & (z_r * z_r + z_i * z_i < 4.f)) 
        float varying(L) new_r = z_r*z_r - z_i*z_i;
        float varying(L) new_i = 2.f * z_r * z_i;
        z_r = c_r + new_r;
        z_i = c_i + new_i;
        ++i;
  // number of iterations for each program instance
  return i;
```

INSTANTIATE OPTIMIZED VARIANTS FROM SINGLE TEMPLATE

```
mandelbrot< 1>(/*...*/); // scalar
mandelbrot< 4>(/*...*/); // SSE
mandelbrot< 8>(/*...*/); // AVX or double-pumped SSE
mandelbrot<16>(/*...*/); // double-pumped AVX
```

FUTURE WORK: VARYING STRUCTS AND VECTOR POLYMORPHISM

```
struct vec3 { float x, y, z; };
float dot(vec3 a, vec3 b) { return a.x*b.x + a.y*b.y + a.z*b.z; }

vec3 varying(4) a;
vec3 uniform b;
// spmd(1) float varying(4) dot(vec3 varying(4), vec3 uniform);
float varying(4) c = dot(a, b);
if (a.x < b)
    // spmd(4) float varying(4) dot(vec3 uniform, vec3 varying(4);
    float varying(4) d = dot(b, a);</pre>
```

SUMMARY

- A SIMD extension for C++
- One language, no special kernel language needed
- Use the full power of C++ in your SIMD code
- Mix different vectorization lengths in the same code

REFERENCES

- [1] R. Leißa, S. Hack, and I. Wald. Extending a C-like Language for Portable SIMD Programming. In *PPoPP*, 2012.
- [2] M. Pharr and W. R. Mark. ispc: A SPMD Compiler for High-Performance CPU Programming. In *InPar*, 2012.