

Ma3 - STAT220 - Sigbjørn Fjelland

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```
library(tinytex)
library(igraph)
```

```
##
## Attaching package: 'igraph'
## The following objects are masked from 'package:stats':
##
##      decompose, spectrum
## The following object is masked from 'package:base':
##
##      union
```

```
library(expm)
```

```
## Loading required package: Matrix
##
## Attaching package: 'expm'
## The following object is masked from 'package:Matrix':
##
##      expm
```

```
library(markovchain)
```

```
## Package:  markovchain
## Version:   0.9.0
## Date:      2022-07-01
## BugReport: https://github.com/spedygiorgio/markovchain/issues
```

```
library(diagram)
```

```
## Loading required package: shape
```

```
library(pracma)
```

```
##
## Attaching package: 'pracma'
## The following objects are masked from 'package:expm':
##
##      expm, logm, sqrtm
## The following objects are masked from 'package:Matrix':
##
##      expm, lu, tril, triu
```

```
set.seed(123)
```

Problem 3.1

a)

$$\begin{aligned}P(X_t = 6) &= \frac{1}{6} \\P(X_1 = 6 \cap X_2 = 6) &= \left(\frac{1}{6}\right)^2 \\&= \frac{1}{36}\end{aligned}$$

b)

Throwing a dice where each throw is independent event with a given p , hence it is a bernoulli trail. The sum of independent bernoulli trail with failures until success is geometric:

$$X \sim ber(p) \Rightarrow \sum X = T_X \sim geom(p)$$

Since we need two equal in this trail we can construct a new compound sequence where two throws are equal. the process will be the same, hence the distributions will be the same, but the probabilitie p will change:

$$\begin{aligned}Y = X^2 &\Rightarrow p_y = P(X \cap X) = p^2 \\Y \sim ber(p^2) &\Rightarrow \sum Y = T_Y \sim geom(p^2)\end{aligned}$$

c)

By def we have that the expected value and variance of an Geometric distribution is:

$$E[T_Y] = \frac{1}{p}$$
$$V[T_Y] = \frac{1-p}{p^2}$$

$$p_y = p^2 = \frac{1}{6^2}$$
$$= \frac{1}{36}$$

```
P.Y <- 1/6^2
```

```
E.T.G <- P.Y^(-1)
```

```
V.T.G <- (1-P.Y) / P.Y^2
```

```
cat('E(T) = ', E.T.G, ' and Var(T) = ', V.T.G)
```

```
## E(T) = 36 and Var(T) = 1260
```

for the exponential distribution (continous analog of Geometric distribution) variance and expectation is:

$$E[T_Y] = \frac{1}{p}$$
$$V[T_Y] = \frac{1}{p^2}$$

which yields the same expectantion and a larger variance:

```
E.T.E <- P.Y^(-1)
```

```
V.T.E <- (1) / P.Y^2
```

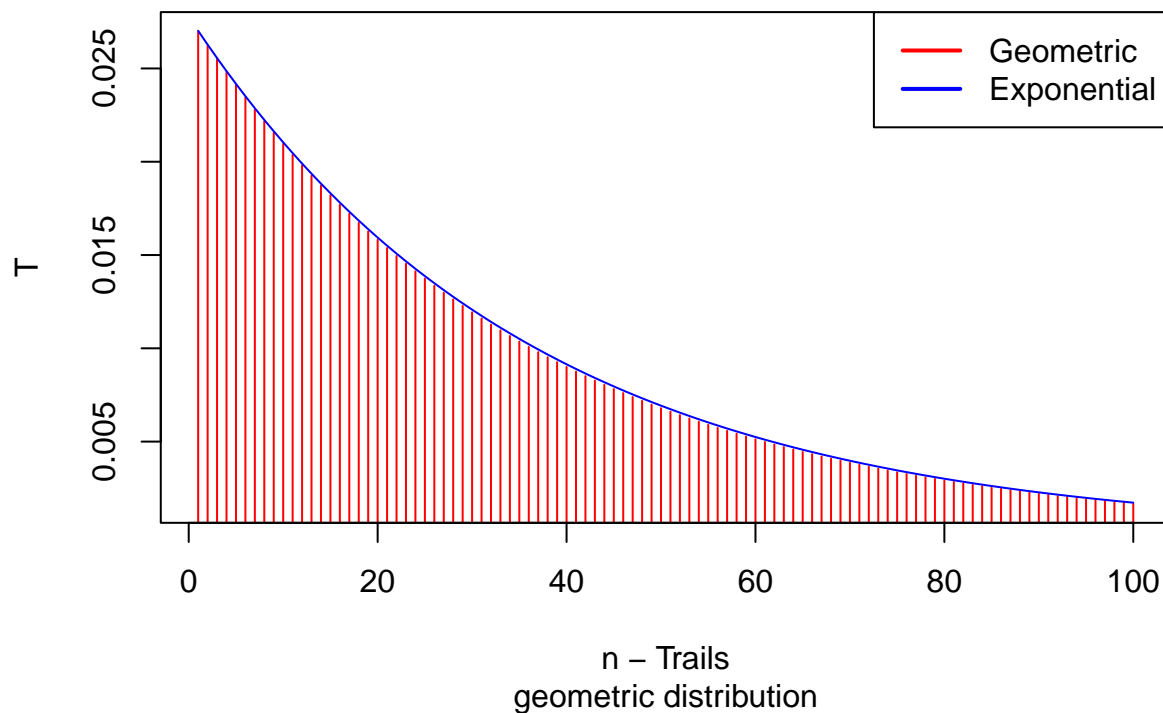
```
cat('E(T) = ', E.T.E, ' and Var(T) = ', V.T.E)
```

```
## E(T) = 36 and Var(T) = 1296
```

d)

```
n<-1:100  
  
T.geom <-dgeom(x = n, prob = P.Y)  
T.exp <- dexp(x = n, rate = P.Y)  
  
plot(T.geom, type = 'h', col='red',xlab = 'n - Trails', ylab = 'T',  
      main='Comparsion geometric/exponential distr.  
      - two dice', sub='geometric distribution')  
lines(T.exp, type = 'l', col='blue')  
legend("topright", col = c("red", "blue"),  
       legend = c("Geometric", "Exponential"), lwd = 2)
```

Comparsion geometric/exponential distr. – two dice



as we see there is a preaty fair chance that we hit withinthe first 10 -20 throws.

e) with three dice the probabilities decrease:

$$P(X_t = 6) = \frac{1}{6}$$

$$P(X_1 = 6 \cap X_2 = 6 \cap X_3 = 6) = \left(\frac{1}{6}\right)^3$$

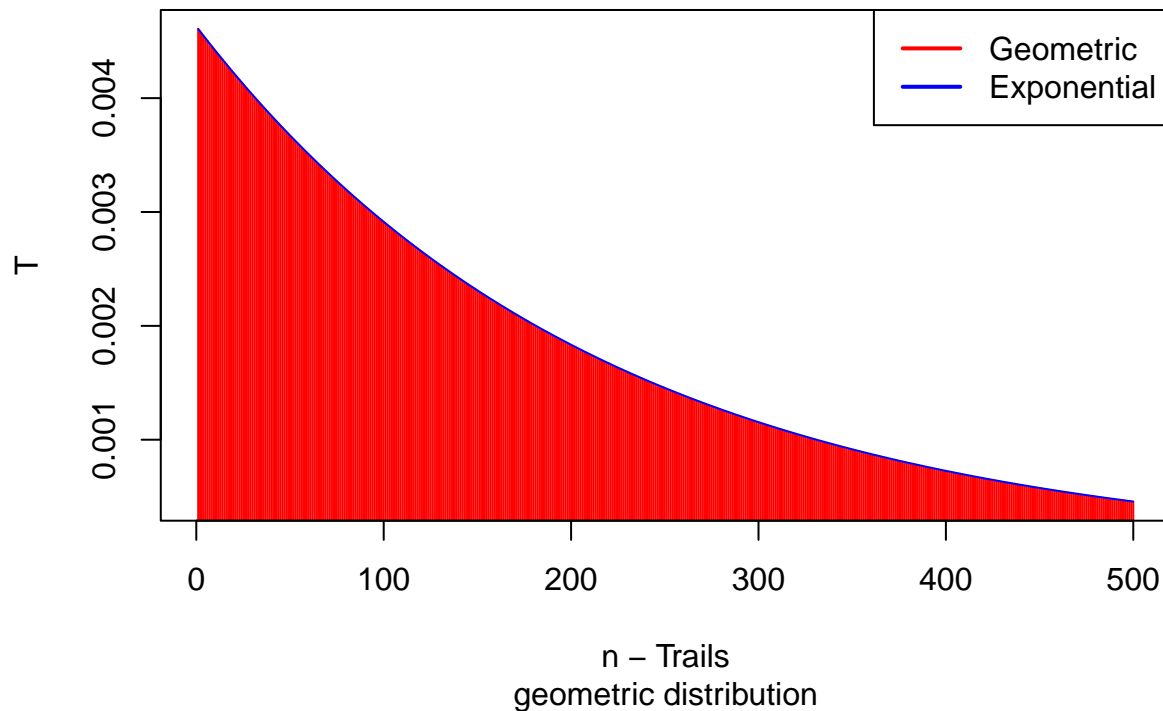
$$= \frac{1}{216}$$

```
P.3 <- (1/6)^3
n<-1:500

T.geom <-dgeom(x = n, prob = P.3)
T.exp <- dexp(x = n, rate = P.3)

plot(T.geom, type = 'h', col='red',xlab = 'n - Trails', ylab = 'T',
     main='Comparsion geometric/exponential distr.
     - three dice', sub='geometric distribution')
lines(T.exp, type = 'l', col='blue')
legend("topright", col = c("red", "blue"),
      legend = c("Geometric", "Exponential"), lwd = 2)
```

Comparsion geometric/exponential distr. – three dice



now need significantly many more throws to achieve the goal:

geometric mean and variance:

```
E.T.G <- P.3^(-1)
V.T.G <- (1-P.3) / P.3^2
```

We

```
cat('E(T) = ', E.T.G, ' and Var(T) = ',V.T.G)
```

```
## E(T) = 216 and Var(T) = 46440
```

exponential mean and variance:

```
E.T.Ex <- P.3^(-1)
```

```
V.T.Ex <- (1-P.3) / P.3^2
```

```
cat('E(T) = ', E.T.Ex, ' and Var(T) = ',V.T.Ex)
```

```
## E(T) = 216 and Var(T) = 46440
```

and we can also observe that the variance have converged between the distributions.

Problem 3.2

```
init<-rep(0.25,4)
```

```
S <-c(1:4) # state space
```

```
mP <- matrix(nrow = 4, ncol = 4, dimnames = list(c("00","01","10","11"),
                                                    c("00","01","10","11")))
```

```
mP[1,] <- c(0.62, 0.00, 0.38, 0.00)
```

```
mP[2,] <- c(0.55, 0.00, 0.45, 0.00)
```

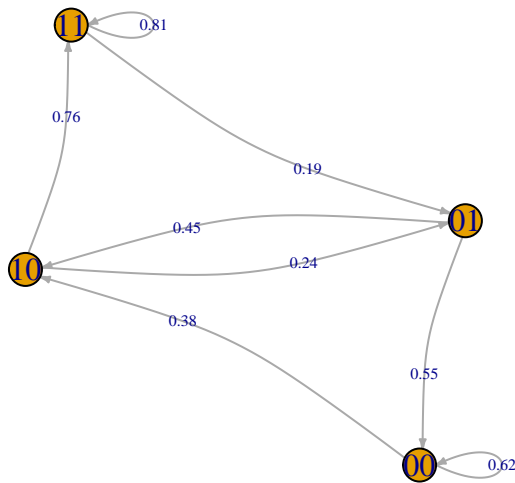
```
mP[3,] <- c(0.00, 0.24, 0.00, 0.76)
```

```
mP[4,] <- c(0.00, 0.19, 0.00, 0.81)
```

```
mP.plot <- graph_from_adjacency_matrix(mP, weighted = "prob")
```

```
E(mP.plot)$prob <- ifelse(is.nan(E(mP.plot)$prob), NA, E(mP.plot)$prob)
```

```
plot(mP.plot, edge.label = round(E(mP.plot)$prob, 2), edge.arrow.size =
     .25, edge.curved=-0.2, edge.label.cex = .5)
```



b)

They should all sum up to one:

```
rowSums(mP)
```

```
## 00 01 10 11
```

```
## 1 1 1 1
```

and they did...

c)

```
set.seed(1234)
```

```
n=365
```

```
rainsim<-function(n){
```

```
  X <- rep(0, n+1)
```

```
  X[1] <- sample(S,1, prob=init )
```

```
  for(k in 2:(n+1)){
```

```
    X[k]<-sample(S,1, prob=mP[X[k-1],] )
```

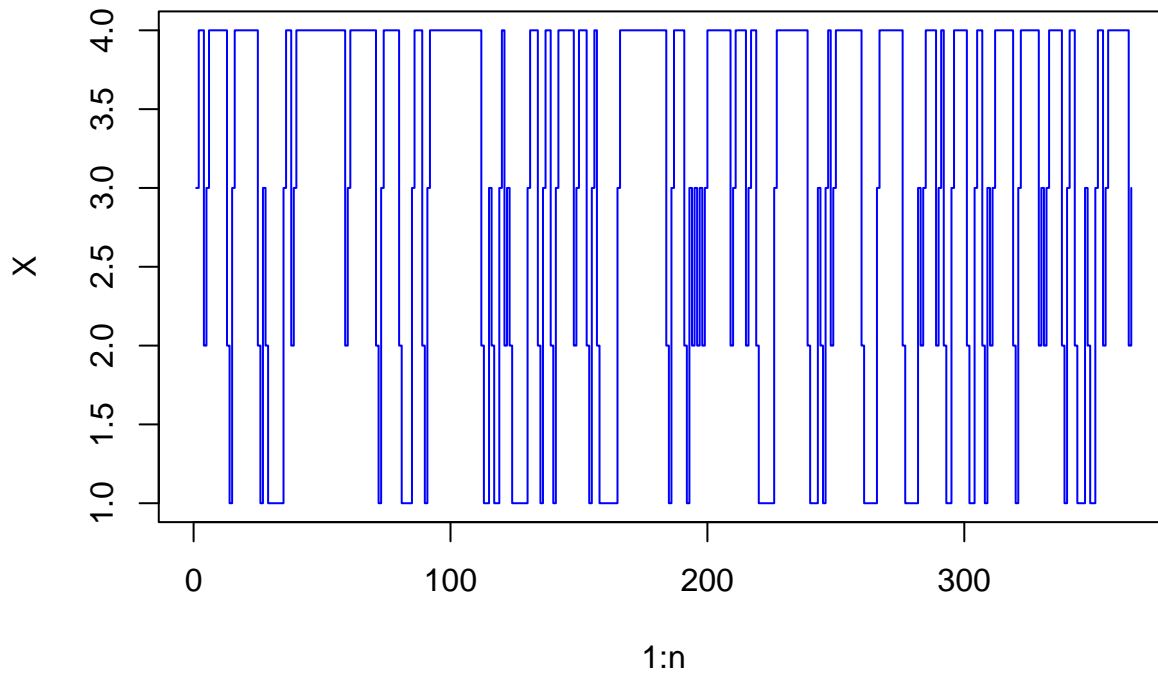
```
  }
```

```
  X <- X[-1]
```

```
}
X <- rainsim(n)
```

d)

```
plot(1:n, X, type="s", col="blue")
```



e)

```
pi.hat <- as.numeric(table(X)/n)
cat(' Empirical frequency: ', pi.hat)

## Empirical frequency:  0.1863014 0.1232877 0.1260274 0.5643836
```

f)

```
delta = (sum((pi.hat- (pi.hat %*% mP))^2))^0.5
cat(' delta: ', delta)

## delta:  0.01848067
```

g)

The result is a bit weak, probably due to a relatively low “n”.

```
mP %>% 2
```

```
##      00      01      10      11
## 00 0.3844 0.0912 0.2356 0.2888
## 01 0.3410 0.1080 0.2090 0.3420
## 10 0.1320 0.1444 0.1080 0.6156
## 11 0.1045 0.1539 0.0855 0.6561
```

```
m <- 2
while(norm(mP %>% m - mP %>% (m - 1)) > (0.5*10^(-8))) {
  m <- m+1
}
```



```

}

mP_converged <- mP%>%m
mP_converged[1,]

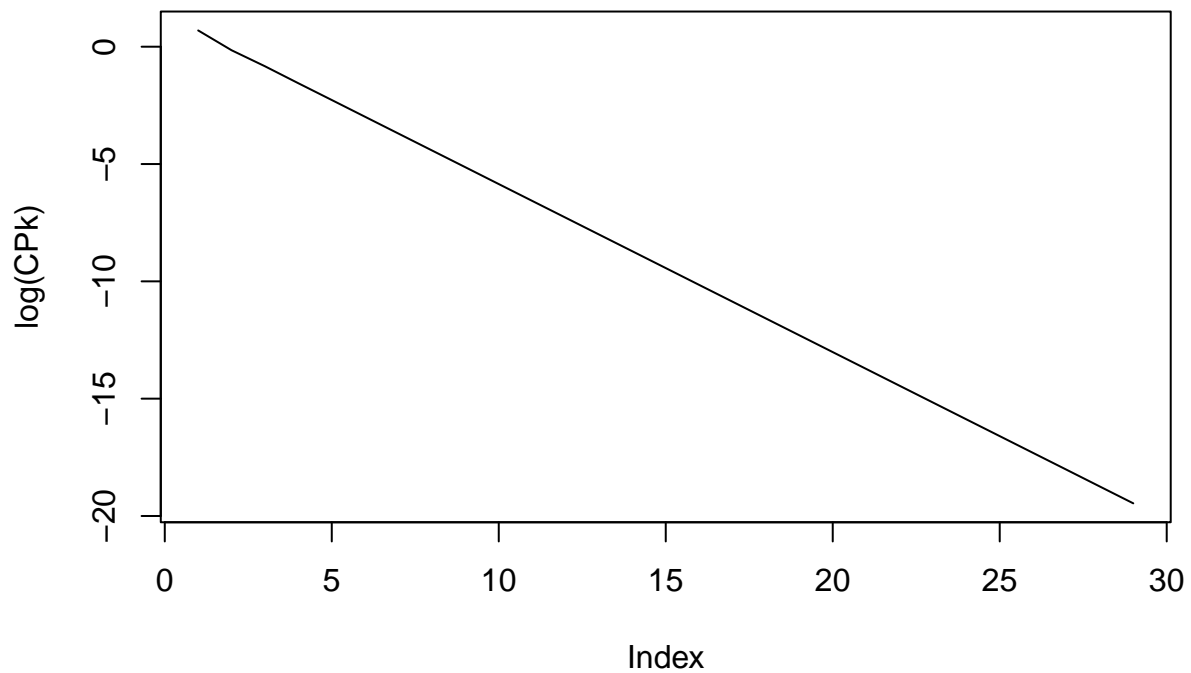
##          00          01          10          11
## 0.1943463 0.1342756 0.1342756 0.5371025

i)

iterations<-c()
CPk <- c()
result <- 10
k<-1
while(result > 0.5*1e-8){
  mP_power_k <- mP%>% k
  sum_l<-c()
  for(i in 1:3){
    for(j in (i+1):4){

      row <- abs(mP_power_k[i, ] - mP_power_k[j, ])
      sum_l <- c(sum_l, sum(row))
    }
  }
  result <- max(sum_l)
  CPk[k] <- result
  k <- k+1
}
plot(log(CPk), type='l')

```

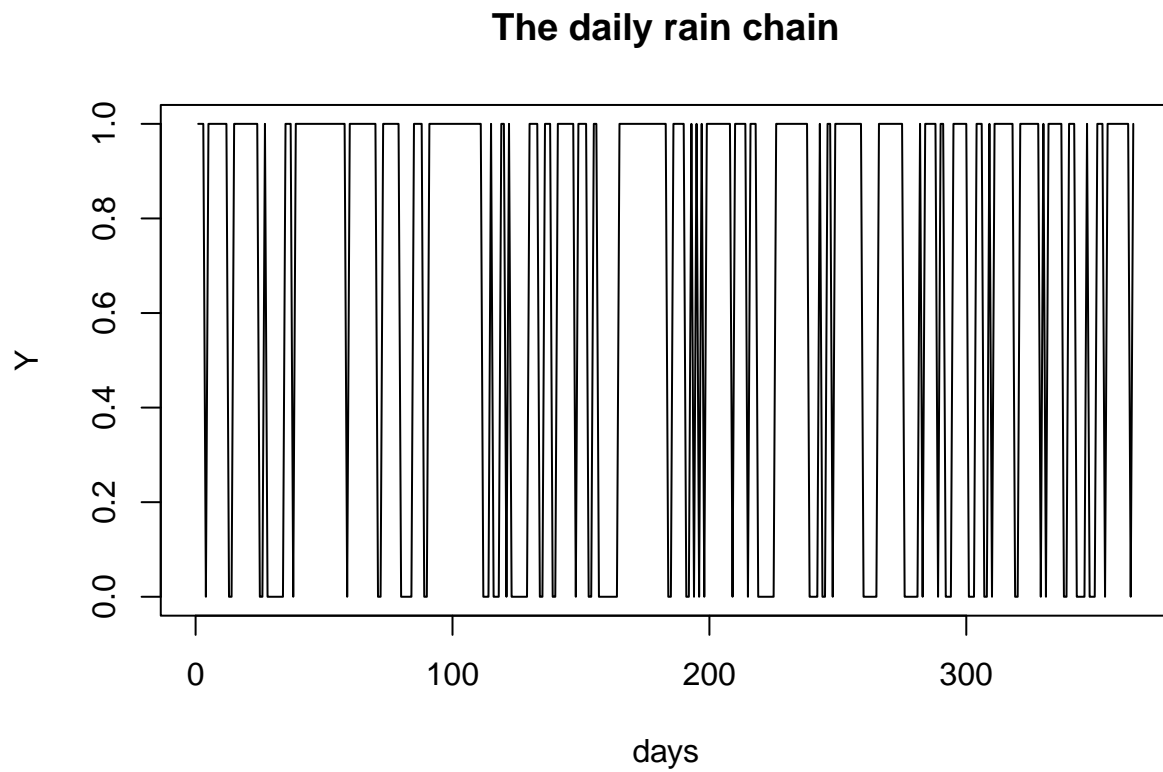


```

j)
Y<-pmin(pmax(0, X-2),1)

```

```
plot(Y,main= "The daily rain chain",xlab="days", ylab="Y", type = "l")
```



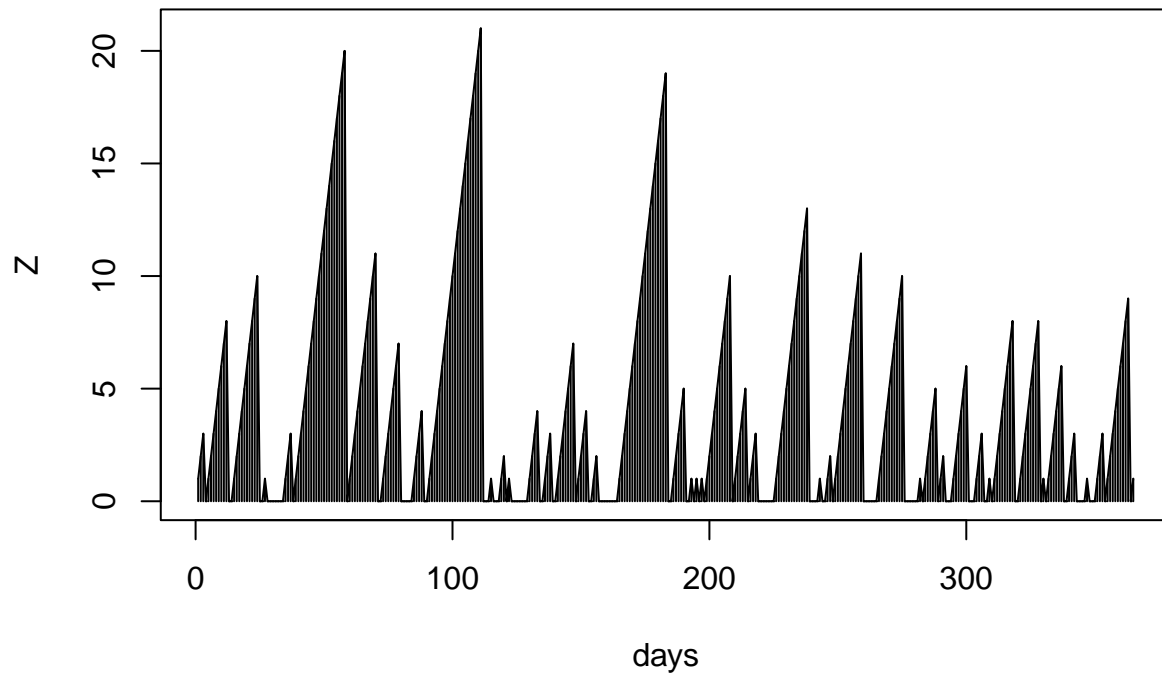
```
k)
n=365

Z<-c(Y[1])

for(t in 2:n){
  Z_t <- (Z[t-1]+1)*Y[t]
  Z <- c(Z,Z_t)
}

plot(y=Z, x=1:n, type='h',xlab='days', main = "one year plot")
lines(y=Z, x=1:n, type='l')
```

one year plot



l)

```
n.50 <- 365*50

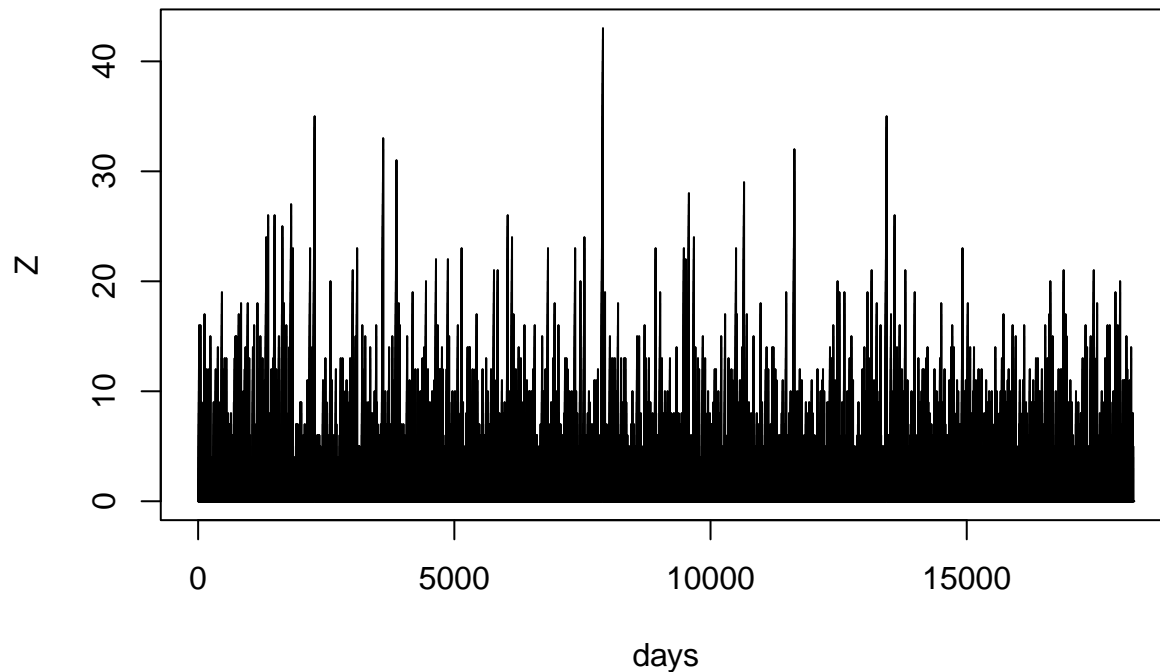
X.365.50 <- rainsim(n=n.50)
Y<-pmin(pmax(0, X.365.50-2),1)

Z<-c(Y[1])

for(t in 2:n.50){
  Z_t <- (Z[t-1]+1)*Y[t]
  Z <- c(Z,Z_t)
}

plot(y=Z, x=1:n.50, type='h', xlab="days", main='50 years plot')
lines(y=Z, x=1:n.50, type='l')
```

50 years plot



m)

```
pi.eigen <- eigen(t(mP))$vectors[, 1] / sum(eigen(t(mP))$vectors[, 1])
```

```
pi.hat.50 <- as.numeric(table(X.365.50)/n.50)
```

```
cat(' Empirical frequency: ' , pi.hat.50)
```

```
## Empirical frequency: 0.1896986 0.1349041 0.1348493 0.5405479
```

we have stationary distribution of P from one year and 50 years

```
pi.hat
```

```
## [1] 0.1863014 0.1232877 0.1260274 0.5643836
```

```
pi.hat.50
```

```
## [1] 0.1896986 0.1349041 0.1348493 0.5405479
```

Given we consider the eigen values as closer to true pi we see that pi obtained from the 50 year sample is significantly more accurate than from one year.

```
pi.hat-pi.eigen
```

```
## [1] -0.008044920 -0.010987947 -0.008248221 0.027281088
```

```
pi.hat.50-pi.eigen
```

```
## [1] -0.0046476596 0.0006284912 0.0005736967 0.0034454717
```

Problem 3.3

a)

```
p <- 0.45
q <- 1-p

N <- 20
n <- 1000

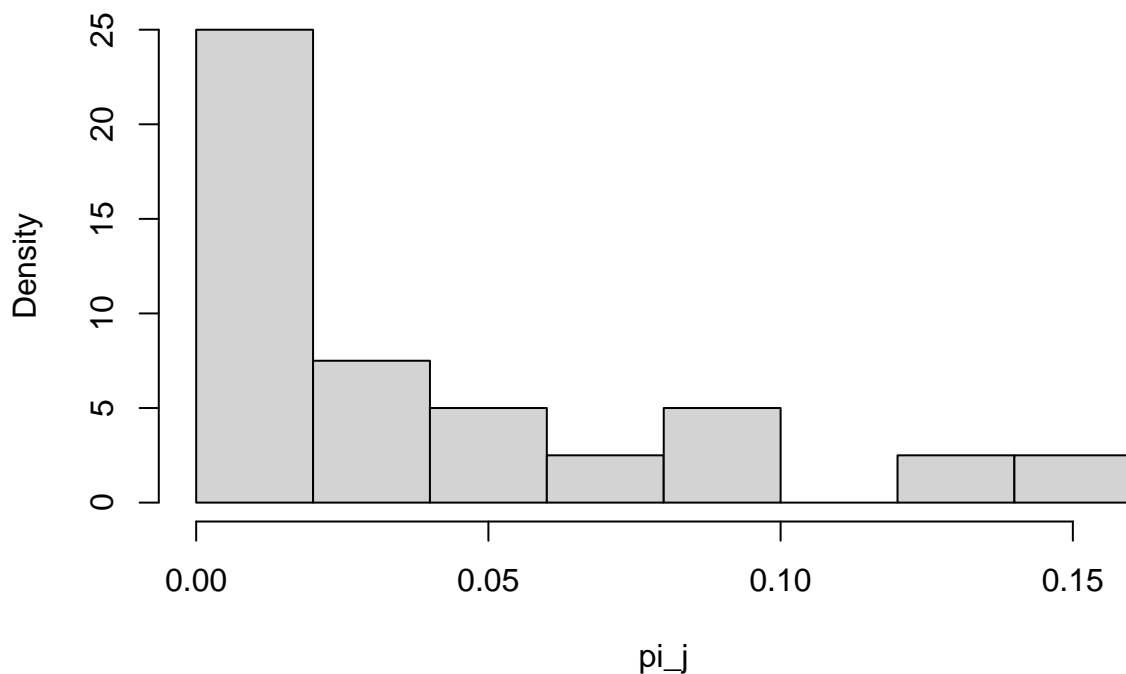
M <- N+1
mP.N <- matrix(0,M,M)
mP.N[1,2] <- 1
mP.N[M,M-1] <- 1
for(i in 2:(M-1)){
  mP.N[i,i-1] <- q
  mP.N[i,i+1] <- p
}

tau <- p/q

pi_0 <- 1-tau
pi_j <- vector(length = N)
pi_j[N] <- (tau)^(N-1)*pi_0
for(j in 1:N-1){
  pi_j[j] <- ((tau)^(j)*pi_0)
}

hist(pi_j, probability = TRUE)
```

Histogram of π_j



c)

```
P_AA <-mP.N[1:20, 1:20]
I <- diag(N)
I_AA<-c(rep(1,N))
mu <- inv(I-P_AA)%*%I_AA
mu
```

```
##           [,1]
## [1,] 2489.6052
## [2,] 2488.6052
## [3,] 2485.1608
## [4,] 2478.7287
## [5,] 2468.6450
## [6,] 2454.0983
## [7,] 2434.0967
## [8,] 2407.4282
## [9,] 2372.6111
## [10,] 2327.8346
## [11,] 2270.8856
## [12,] 2199.0590
## [13,] 2109.0487
## [14,] 1996.8139
## [15,] 1857.4159
## [16,] 1684.8182
## [17,] 1471.6433
## [18,] 1208.8740
## [19,] 885.4893
## [20,] 488.0191
```

Problem 3.4

a)

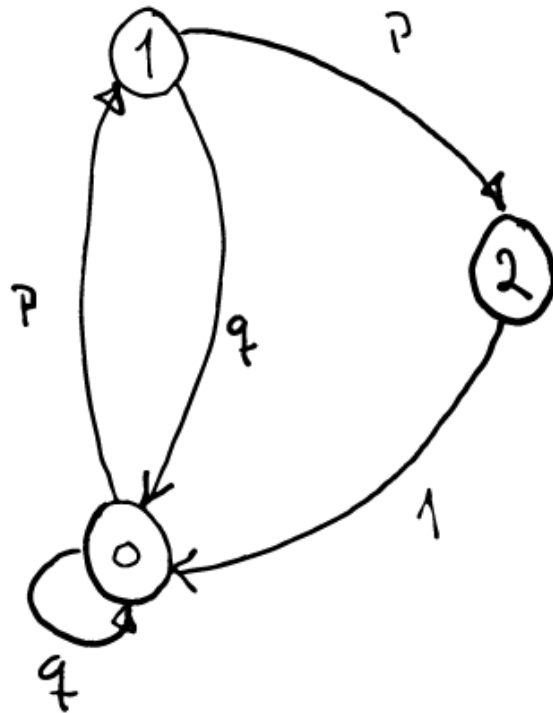


Figure 1: Matrix P illustrated

b)

$$\begin{aligned}f_{00} &= P_0(X_1|X_0) \cdot P_1(X_2|X_1) \cdot P_2(X_0|X_2) \\&= p \cdot p \cdot 1 \\&= \underline{p^2}\end{aligned}$$

since

$$\begin{aligned}0 &\rightarrow 0 \\0 &\rightarrow 1 \rightarrow 0 \\0 &\rightarrow 1 \rightarrow 2 \rightarrow 0\end{aligned}$$

hence $P_0(S_0 < 3) = 1$ and return time is $0 \leq 3$

c)

$$\det(P - \lambda I) = 0$$

$$[\pi_0, \pi_1, \pi_2] \cdot \begin{bmatrix} q & p & 0 \\ q & 0 & p \\ 1 & 0 & 0 \end{bmatrix} = \begin{bmatrix} \pi_0 \\ \pi_1 \\ \pi_2 \end{bmatrix}$$

$$q\pi_0 + \pi_1 = \pi_0 \tag{1}$$

$$q\pi_0 + p\pi_2 = \pi_1 \tag{2}$$

$$\pi_0 = \pi_2 \tag{3}$$

$$\pi_0 + \pi_1 + \pi_2 = 1 \tag{4}$$

by substituting 3 into 2:

$$q\pi_0 + p\pi_0 = \pi_1 \Rightarrow \pi_0(p + q) = \pi_1 \tag{5}$$

and the result of these combination:

$$\pi_0 + \pi_0(p + q) + \pi_0 = 1$$

$$\pi_0(1 + (p + q) + 1) = 1$$

$$\pi_0 = \frac{1}{\underline{p + q + 2}}$$

$$\pi_1 = \frac{(p + q)}{\underline{p + q + 2}}$$

$$\pi_2 = \pi_0 = \frac{1}{\underline{p + q + 2}}$$

- d) We know the unique $\vec{\pi}$ and that $p \in (0, 1)$ and $q = 1 - p$ hence $p + q = 1$. The chain is also positive recurrent

$$\begin{aligned} E[S_0] &= \frac{1}{\pi_0} \\ &= \frac{1}{(p + q + 2)^{-1}} \\ &= p + q + 2 = 1 + 2 = \underline{3} \end{aligned}$$

- e) No it is not bounded due to:

$$P(x_1 = 0 | X_0 = 0) > 0$$

there is always a chance that it can stop in State “0”, however the expectation is equal for S_2 as S_0 since:

$$\begin{aligned} \pi_0 &= \pi_2 \\ \Rightarrow \frac{1}{\pi_2} &= \frac{1}{\pi_2} \\ &= \frac{1}{(p + q + 2)^{-1}} = \underline{3} \end{aligned}$$