```
# ! ls Datasets/new_test
from google.colab import drive
drive.mount('/content/drive')
```

```
Drive already mounted at /content/drive; to attempt to forcibly
remount, call drive.mount("/content/drive", force_remount=True).
```

```
!ls "/content/drive/My Drive/forest_fire_images/Test_Data"
```

```
Fire  Non_Fire
```

```
import os
import cv2
import numpy as np
from tqdm import tqdm
import matplotlib.pyplot as plt
from sklearn.metrics import confusion_matrix
import itertools

#DATADIR = r'D:\EDU Files\project\fire\MNet_Vgg Fire tuning\
BowFire_Data'
DATADIR = '/content/drive/My Drive/forest_fire_images/Test_Data'
CATEGORIES = ['Fire', 'Non_Fire']

IMG_SIZE = 64
def create_training_data():
    training_data = []
    for category in CATEGORIES:

        path = os.path.join(DATADIR,category)
        class_num = CATEGORIES.index(category)  # get the
classification  (0 or a 1). 0=C 1=O

        for img in tqdm(os.listdir(path)):  # iterate over each image
            try:
                img_array = cv2.imread(os.path.join(path,img))  #
convert to array
                new_array = cv2.resize(img_array, (IMG_SIZE,
IMG_SIZE))  # resize to normalize data size
                training_data.append([new_array, class_num])  # add
this to our training_data
            except Exception as e:  # in the interest in keeping the
output clean...
                pass

    return training_data

training_data = create_training_data()
```

```
100%|██████████| 32/32 [00:10<00:00,  2.93it/s]
100%|██████████| 25/25 [00:08<00:00,  2.96it/s]
```

```
import random
test_image_num=58704
print(len(training_data))
random.shuffle(training_data)
test_labels=np.zeros((test_image_num,1))

c=0
for sample in training_data:
    test_labels[c]=(sample[1])
    c+=1
print(c)
actual_labels=(test_labels.reshape(test_image_num,))
print(actual_labels.shape)
actual_labels.astype(int)
```

```
57
57
(58704,)
```

```
array([0, 1, 1, ..., 0, 0, 0])
```

```
X = []
Y = []

for features,label in training_data:
    X.append(features)
    Y.append(label)

X = np.array(X).reshape(-1, IMG_SIZE, IMG_SIZE, 3)
X = X/255.0
X.shape[1:]

Y = np.array(Y)

!ls "/content/drive/My Drive/TrainedModels"
```

```
Fire-64x64-color-v7.1-soft.h5
```

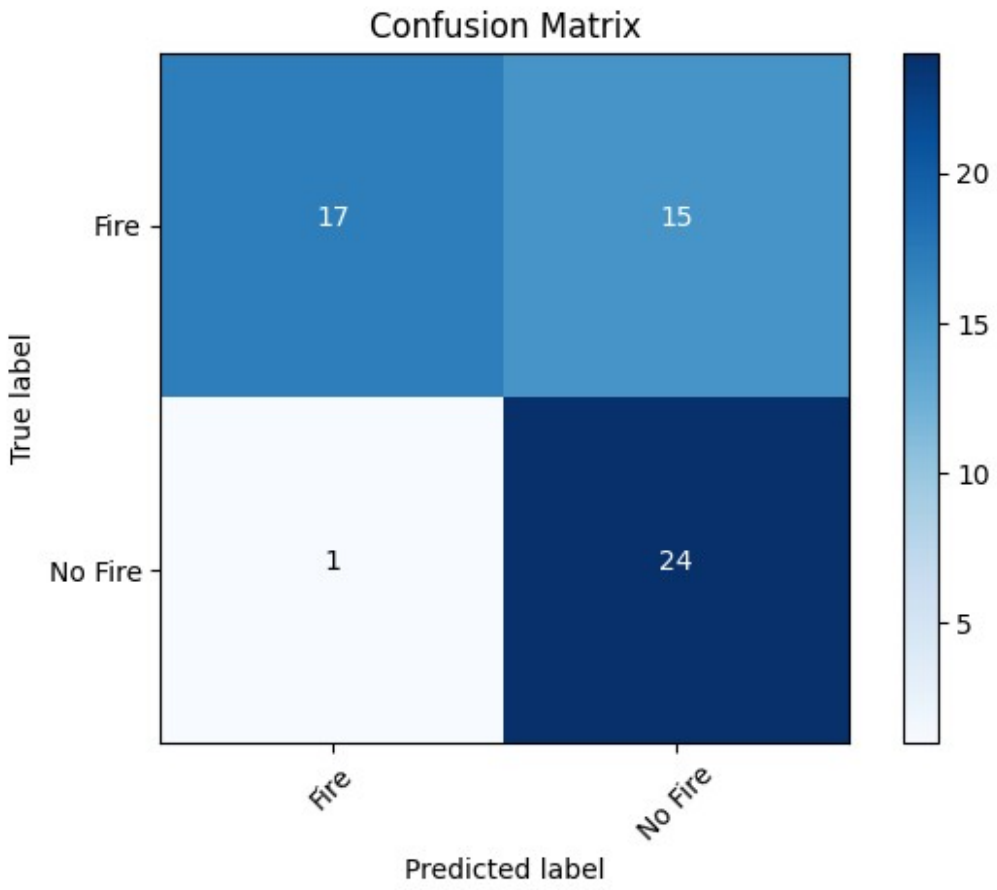
```
from keras.models import load_model
model = load_model('/content/drive/My Drive/TrainedModels/Fire-64x64-
color-v7.1-soft.h5')

predictions = model.predict(X)
predicted_labels = np.argmax(predictions, axis=1)
predicted_labels = predicted_labels.astype(int)
# syntax outdated, so updated
```

```
2/2 [==============================] - 0s 43ms/step
```

```
def plot_confusion_matrix(cm, classes,
                          normalize=False,
                          title='Confusion matrix',
```

```
                          cmap=plt.cm.Blues):
    """
    This function prints and plots the confusion matrix.
    Normalization can be applied by setting `normalize=True`.
    """
    if normalize:
        cm = cm.astype('float') / cm.sum(axis=1)[:, np.newaxis]
        print("Normalized confusion matrix")
    else:
        print('Confusion matrix, without normalization')

    print(cm)

    plt.imshow(cm, interpolation='nearest', cmap=cmap)
    plt.title(title)
    plt.colorbar()
    tick_marks = np.arange(len(classes))
    plt.xticks(tick_marks, classes, rotation=45)
    plt.yticks(tick_marks, classes)

    fmt = '.2f' if normalize else 'd'
    thresh = cm.max() / 2.
    for i, j in itertools.product(range(cm.shape[0]),
range(cm.shape[1])):
        plt.text(j, i, format(cm[i, j], fmt),
                 horizontalalignment="center",
                 color="white" if cm[i, j] > thresh else "black")

    plt.ylabel('True label')
    plt.xlabel('Predicted label')
    plt.tight_layout()

actual_labels = actual_labels[:len(training_data)]
cm = confusion_matrix(actual_labels, predicted_labels)
#test_batches.class_indices
cm_plot_labels=['Fire','No Fire']
plot_confusion_matrix(cm, cm_plot_labels,title='Confusion Matrix')
```

```
Confusion matrix, without normalization
[[17 15]
 [ 1 24]]
```




```
tp=cm[0][0]
fn=cm[0][1]
fp=cm[1][0]
tn=cm[1][1]
print("tp"+' '+str(tp))
print("fn"+' '+str(fn))
print("fp"+' '+str(fp))
print("tn"+' '+str(tn))
```

```
tp 17
fn 15
fp 1
tn 24
```

```
Recall=tp/(tp+fn)
Precision=tp/(tp+fp)
f_measure= 2*((Precision*Recall)/(Precision+Recall))

print(Precision, Recall, f_measure)
```

```
0.9444444444444444 0.53125 0.6799999999999999
```

```
model.evaluate(X, Y)
```

```
2/2 [==============================] - 0s 43ms/step - loss: 2.0976 - accuracy: 0.7193
```

```
[2.0976366996765137, 0.719298243522644]
```