Nonlinear Methods: Classification

Signal Data Science

Previously, we considered nonlinear *regression* techniques. Next, we'll move to briefly covering nonlinear *classification* techniques, allowing us to improve upon logistic regression via more sophisticated and general methods. The theory of some of the classification techniques used in this assignment is discussed in *Notes on Classification Theory*; feel free to back to those notes as you work through the exercises below.

The field of nonlinear techniques is *very* vast and wide. As with the nonlinear regression assignment, you should be constantly referring to textbooks and online resources to clarify details and to improve your own understanding and intuition. The lesson below is designed to *guide* you in the correct directions, and the goal is not to speedily finish the exercises but rather to use them as prompts for your curiosity and as sources of further directions of intellectual exploration.

Getting started

We will use a combination of simulated and real data to explore classification techniques in R.

First, we can write some utility functions to generate our simulated data. For simplicity, we will restrict attention to the 2-dimensional unit square ($x \in [0,1]$, $y \in [0,1]$).

- Write a function lin_pair(m, b, label) that takes in integers m, b, and label and returns two numerics c(x, y) satisfying the following criteria:
 - Both x and y should be between 0 and 1.
 - If label is set to 1, then y must be greater than m*x + b. Conversely, if label is set to -1, then y must be less than m*x + b.

You can think of the function $lin_pair(m, b, label)$ as picking a point in the unit square *uniformly randomly* from the region falling above or below the line y = mx + b.

• Plot the points you get from running lin_pair() multiple times with m=2 and b=-0.3. Verify that the resulting plot resembles the image below.

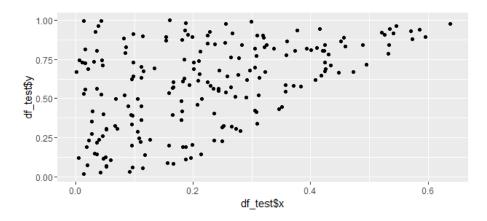


Figure 1: The results of plotting 200 randomly generated points in the unit square falling above the line y = 2x - 0.3.

We can also extend the same methodology to generate data falling above or below a *quadratic* curve (which will be more difficult to classify).

• Write a function quad_pair(a, b, c, label) which does the same thing for the quadratic parabola $y = a(x - b)^2 + c$. Verify that it works as desired by plotting the results.

We will also use the *Iris* flower data set, which was introduced by the statistician Ronald Fisher expressly for the purpose of demonstrating the usage of linear discriminant analysis for classification of different *Iris* species (*Iris setosa*, *Iris virginica*, and *Iris versicolor*).



Figure 2: A specimen of Iris versicolor.

The Iris dataset is a default variable in base R.

- Set df_iris = iris to copy the *Iris* dataset to a different variable. Call ?iris and read the *Description* section of the documentation.
- There are 4 different numeric variables in the *Iris* dataset, yielding $\binom{4}{2} = 6$ different pairs of these variables. Plot each pair of variables on a scatterplot with the points colored according to their species. For example, the code for plotting sepal width against sepal length should look like this:

```
ggplot(df_iris,
  aes(Sepal.Length, Sepal.Width, color=Species))
  + geom_point()
```

Which pairs of variables are easy to separate? Which pairs of variables are more difficult to separate?

Finally, we will look at a dataset containing the results of chemical analysis on wines grown in the same region of Italy but from 3 different cultivars. The data are available in the wine-cultivars datasets folder and also online at the UCI Machine Learning Repository.

- Load the wine dataset in wine.data and read the documentation in wine.names.
- Use aggregate() to view the mean value of each predictor variable for each the three different wine cultivars. (You'll have to set FUN=mean and convert the vector of class labels to a *list* before passing it into the by parameter.)

Discriminant analysis

As an example of generative binary classifiers, we will first consider the field of discriminant analysis, comprising linear discriminant analysis (LDA) and quadratic discriminant analysis (QDA). Both of these methods assume *a priori* that the two classes are generated from multivariate normal distributions. QDA allows the two distributions to have different covariances and thereby attempts to separate a *quadric* (high-dimensional quadratic) surface separating the two classes, whereas LDA makes the additional simplifying assumption of equal covariances and consequently attempts to constructs a *linear* separating hyperplane.

Simulated data analysis

We'll first look at how LDA and QDA perform on simulated data.

- Generate 200 data points, 100 of which fall above the line y = 0.75x + 0.05 and 100 of which fall below the line y = 0.75x 0.1, along with a vector of class labels (taking on the values 1 and -1). Use qplot() to plot a scatterplot of the data, passing in the class labels to the color parameter.
- Do the same with 100 data points falling above the parabola y = 4(x 0.5) + 0.4 and 100 data points falling below the parabola y = 4(x 0.5) + 0.38.

partimat() (from the klaR package) can be used to graph the decision boundary resulting from LDA or QDA. It accepts a *data frame* of predictors as its first argument, a *factor* of class labels as its second argument, and a method parameter which should be set to either "lda" or "qda".

Use partimat() to run both LDA and QDA on both datasets. Interpret
the results.

Multiclass classification

The theoretical framework of LDA and QDA can easily be extended to *multiclass classification*, which we will briefly illustrate with the wine cultivars dataset. For this, we'll run LDA directly via lda() (in the MASS package).

• Use lda() to make a classification model for the three different wine cultivars in terms of the chemical properties of the sampled wines.

Multiclass LDA classifies points by producing *linear discriminant functions* and calculating the values of those discriminant functions at data points. Each discriminant function will classify a data point as "class X" or "not class X" depending on the sign of the function at that point (whether the associated value is positive or negative). As such, for a dataset with k classes, we calculate k-1 different discriminant functions.

Use predict() on the result of lda() with no additional arguments.
The result of predict() stores the values of the discriminant functions
evaluated on the training data in the variable \$x. For each of the two
discriminant variables, pass in its values along with the true class labels
to ldahist(). Interpret the results.

However, LDA also lends itself to a very nice *geometric* interpretation. It can be thought of as a generative dimensionality reduction technique where p features are *projected* onto a (k-1)-dimensional space. Recall that LDA assumes that each class of the data is generated from a multivariate normal distribution—the projections are thus calculated such that in the reduced-dimensional space, the variance within each class is *minimized* while the distances between the means of the assumed distributions are *maximized*.

 Plot the values of the two discriminant functions against each other for the wine cultivars dataset, coloring the points according to their true classification. Compare this to a plot of the first two *principal components* of the wine cultivars dataset, again with the points colored according to their classification. Interpret the results.

Although LDA and QDA work well when the data approximately satisfy the assumptions which are made by the underlying generative models, they fail to work well in more complex situations where those assumptions are violated. For example, if the real distributions of the data are *very* non-Gaussian, both LDA and QDA will fail. In addition, even if the data *are* generated in a Gaussian fashion, LDA will perform very poorly if the distributions differ in their variances instead of in their means. The weaknesses of discriminant analysis methods lead us naturally toward the question: how strong can we make a classifier without invoking *any* generative assumptions?

Briefly read this StackExchange answer on visualizing the class boundaries
of LDA applied to the *Iris* dataset.

Perceptrons

We will move to consideration of purely *predictive* methods—algorithms which do not posit any underlying generative model and simply aim to separate two classes of data as well as possible. In particular, we will first look at the famous *perceptron algorithm*, one of the first and simplest purely predictive classification techniques developed. It was developed in 1957 at the Cornell Aeronautical Laboratory by Frank Rosenblatt, who initially caused quite a stir in the media with his controversial statements about his hardware implementation of the perceptron; indeed, *The New York Times* reported the machine to be "the embryo of an electronic computer that [the Navy] expects will be able to walk, talk, see, write, reproduce itself and be conscious of its existence".

Regrettably, the perceptron method was not *that* powerful, but it performed well at standard classification tasks nevertheless. For labeled training data in n-dimensional space, the perceptron algorithm will attempt to construct an (n-1)-dimensional hyperplane which separates the two classes. Although the perceptron is a *linear* method, we present it here for two reasons: first, it is historically illuminating and enjoyable to code yourself; second, its drawbacks will provide us with the motivation behind the development of much more sophisticated, modern techniques.

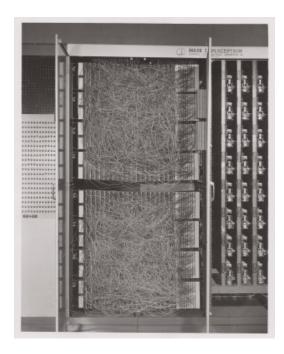


Figure 3: The first (hardware) implementation of the perceptron algorithm, called the Mark I Perceptron.

Regarding the perceptron's advantages, Vapnik writes:

By the time the Perceptron was introduced, classical discriminant analysis based on Gaussian distribution functions had been studied in great detail. [...]

[T]o construct this model using classical methods requires the estimation of about $0.5n^2$ parameters where n is the dimensionality of the space. Roughly speaking, to estimate one parameter of the model requires C examples. Therefore to solve the ten-digit recognition problem using the classical technique one needs $\approx 10(400)^2 C$ examples. The Perceptron used only 512.

This shocked theorists. It looked as if the classical statistical approach failed to overcome the curse of dimensionality in a situation where a heuristic method that minimized the empirical loss easily overcame this curse.

Here, we will explore the strengths of the perception in some simpler contexts.

Generating data

First, we will generate linearly separable data to use with a perceptron.

- Generate 1000 data points falling above the line 1.5x + 0.2 and 1000 data points falling below the line 1.5x + 0.05, binding them into the same matrix.
- Create a labels vector where the *i*th entry is 1 or -1 according to whether
 the *i*th data point in the matrix was generated with label=1 or label=-1.
 Graph the results with qplot(), using the color=labels parameter to
 color the points.
- Add a column to your matrix of data consisting purely of 1s. The perceptron algorithm needs this to work properly; it serves as an "intercept term" that allows the separating hyperplane it generates to be shifted up or down instead of being necessarily centered at 0.

Implementing a perceptron

For each point \mathbf{x}_i , the perceptron algorithm forms an augmented point $\mathbf{x}_i' = (\mathbf{x}, 1)$. The algorithm proceeds to work by updating a vector of *weights* \mathbf{w} step-by-step as it iterates over the augmented data points, adjusting the weights whenever it encounters a training point which it misclassifies. To perform classification, it looks at the *sign* of $\mathbf{w} \cdot \mathbf{x}_i'$, classfiying positive results as 1 and negative results as -1.

- Write a function dot(x, y) which computes the dot product between the vectors x and y, denoted as $x \cdot y$. It is equal to the sum of $x_1y_1 + x_2y_2 + \cdots + x_ny_n$.
- Write a function perceptron(xs, y, w, rate, seed) following these specifications:
 - Take as input a matrix of data xs, a vector of labels (1 or -1) y, a vector of weights w, a learning rate rate, and a random seed seed. Set the seed to 'seed.
 - Iterate over the rows of xs in random order. For each row xi, do the following: Compute the dot product between xi and w. The classification of xi, according to the perceptron, is the sign() of the dot product. If the classification is a false negative, update w by adding rate*xi, and if the classification is a false positive, update w by subtracting rate*xi.
 - Return the calculated weights after the iterations finish.

Congratulations: you have successfully implemented one of the classic algorithms of machine learning. It even counts as a neural network (with a single neuron)!

Visualizing your results

The weights of the perceptron parametrize a *line* given by w[1]*x + w[2]*y + w[3] = 0. This is called the *decision boundary*. Intuitively, the vector w, if we ignore its last entry, is a vector which is *perpendicular* to the separating hyperplane.

- What are the slope and *y*-intercept of this line in terms of the components of w? (Recall that a slope of a line y = mx + b is given by m with the *y*-intercept at (0,b).)
- Write a function perceptron_plot(xs, y, w) which uses qplot() to
 plot the data in xs colored according to the labels in y and adds on
 a geom_abline(intercept=..., slope=...) term to overlay the line
 parametrized by w on the scatterplot of data.
- Repeatedly run perceptron() on your generated data with rate=1 and seed=6 until the output weights converge. You should initialize the weights vector to rep(0, 3) and then pass in the output of the first perceptron() call as the initial weights of the next. After each individual to perceptron(), use perceptron_plot() to plot your intermedate results.

A perceptron is *guaranteed to converge* to a line which fully separates two class *if* the two classes are linearly separable. If a perceptron converges to a solution, that means that it will correctly classify *all* of the training data. As such, once a convergent solution for w is reached, further calls of perceptron() will leave w unchanged. In the following exercises, we will explore the convergence properties of the perceptron.

- Write a function perceptron_conv() which takes in the same arguments as perceptron() aside from w. It should run perceptron() repeatedly until the solution converges, returning a list with the final weights.
- Set the seed to 1 and plot the decision boundary which percept ron_conv() gives you for your output. Try setting the seed to integers from 2 to 10 as well and plot each result. How much variation do you observe? What if you only use a dataset of 20 points (generated in the same fashion) rather than a dataset of 2000?
- Write a function perceptron_time(xs, y, rate) which runs perceptron_conv() 10 times, with the random seed set to 1 through 100, and times each iteration with the tictoc package. It should return the average time elapsed over the 100 iterations. Use perceptron_time() to

explore how the average convergence time varies for both your large and small simulated datasets as you vary the rate parameter over the range 10^seq(-1, 2, length.out=20).

As you can see, the perceptron algorithm typically works pretty well. Unfortunately, despite its advantages, the standard perceptron cannot classify data which are *not* linearly separable—the algorithm will simply not converge.

- Verify that the perceptron algorithm does not converge on a dataset which
 is not linearly separable by using quad_pair() to create a dataset of two
 linearly nonseparable classes and passing it into perceptron() repeatedly.
 (Remember to add on the column of 1s.)
- Restrict the *Iris* dataset to the sepal length and sepal width variables. Plot
 the data and restrict to the two species which are *not* linearly separable
 from one another. What happens when you run perceptron_conv() to
 classify those two species? Plot the "solution" returned by the perceptron
 for some intuition.

If the data points are iterated over in the same order each time, the weights will eventually *cycle* in the case of nonseparability, but detecting a cycle can take a long time if the sample size is large.

Also, as you have seen, when it *does* converge, the perceptron's solution is highly dependent upon choice of random seed. When the training data are linearly separable *and* there exists a "gap" or "margin" between them, there are infinitely many possible choices of a valid decision boundary. We will see later how to resolve these problems.

 Read more about the fascinating history of perceptrons in the Wikipedia article for Minsky and Papert's book titled Perceptrons: an introduction to computational geometry.

Support vector machines

Support vector machines are implemented in R as svm() in the e1071 package. When you call svm() in the following exercises, you should always specify kernel="linear", because svm() defaults to using a *radial* kernel. (We will discuss kernel methods later.)

- Return to the linearly separable data with 2000 points which you initially used for the perceptron. Convert the matrix into a dataframe, add on a column with the class labels (which should be ± 1), and convert the class label column into a factor. Name the columns of your dataframe appropriately.
- Run svm() on your data to predict class label from x and y coordinates.
 Visualize the resulting model with plot(fit, df). The points marked

with an "X" are the support vectors of the corresponding maximum-margin hyperplane.

- Vary the cost parameter of svm() from 0.1 all the way to much higher values. Each time, plot the resulting SVM fit. Interpret the results.
- Generate 40 data points, where 20 of them fall above $y = 3(x 0.5)^2 + 0.55$ and the other 20 fall below $y = 3(x 0.5)^2 + 0.4$. Plot the data. (If you want a better visualization of what the class boundaries are like, plot the result with 2000 points.) Turn your matrix of data into a dataframe and add a column with class labels; turn the class label column into a factor.
- Try classifying the data with a linear SVM. How well does it work? How
 does the hyperplane change as you vary C?
- How well can a linear SVM separate data when each class is drawn from
 a different multivariate normal distribution? Try it for both distributions
 which have means close to each other and distributions with have means
 far away from each other.

Having used SVMs to classify some data, it may not yet be entirely clear why support vector machines receive so much attention. Is the support vector machine not simply a slightly better version of the perceptron? Is it not also almost entirely reliant upon the data being approximately linearly separable? In the next section, you will see how we can cleverly overcome these challenges.

 Our current formulation of support vector machines only supports binary classification. How would you use a SVM for multiclass classification? Come up with at least one plausible method.

Nonlinear kernels for SVMs

The svm() function supports "radial", "polynomial", and "sigmoid" as arguments for its kernel parameter. The documentation describes how to set the hyperparameters corresponding to each type of kernel.

- Try using a radial kernel SVM with different costs and values for σ on both the linearly separable and the quadratically separable data, plotting the results of each fit. How does the best value of σ vary with the sample size?
- Are there sample sizes for which a linear kernel can do better than a radial kernel?
- Write better versions of lin_pair() and quad_pair() that return points in p-dimensional space for a specified value of p. (You will need to pass in parameters which define a (p-1) dimensional hyperplane or quadric surface and then check which side of the surface a generated point is on.) When p is much greater than the number of data points, how does the

performance of a linear kernel compare to the performance of a radial kernel?

• Just for fun, try to use the polynomial and sigmoid kernels to classify the data and see how well they do.

Other methods

TODO

svm regression

The only remaining major class of machine learning techniques we have remaining to discuss is the field of *deep learning and neural networks*. That topic is complex, broad, and deep, so it will be treated on its on in a future lesson.

k-Nearest Neighbors

k-Nearest Neighbors classification works in precisely the way one would expect it to work: for any given point to classify, the algorithm looks at the nearest *k* points in the training set and finds the most common class among those *k* points. That class is the prediction result.

Although *k*-NN works well when there is enough data to capture, at a very fine-grained level, all of the detailed structure in the data, prediction is slow (because it depends on searching through the *entire* training set for every single prediction) and *k*-NN has difficulty with higher-dimensional data (because distance metrics stop working well at very high dimensions).

Decision tree methods

TODO

Choosing a classifier

TODO

These three papers perform various empirical comparisons of classifier methods:

- 1. Caruana and Niculescu-Mizil (2008), An Empirical Comparison of Supervised Learning Algorithms
- 2. Caruana *et al.* (2008), An Empirical Evaluation of Supervised Learning in High Dimensions

3. Fernández-Delgado (2014), Do we Need Hundreds of Classifiers to Solve Real World Classification Problems?

The third paper is particularly informative, being a comparison of 179 different classifiers from 17 families. There is also a follow-up from the authors about the performance of gradient boosted trees (omitted in the original study).

Closing notes

TODO