

1a)

$$\dot{x} = \alpha x + \beta xy$$

$$\dot{y} = -\gamma y + \delta xy$$

$$\Leftrightarrow H = (bH - b_d H^2 - dH) - iHz$$

$$Z = RD + aI - nZH$$

$$D = dH + dI + nZ - nD$$

$$I = iHz - dI - aI$$

$$H + I + Z + D = bH - b_d H^2$$

$$b, b_d, d, i, r, a, n, z$$

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Modsim V1  
Hæfðe svik  
Vær 1q

1b) initial equation gives start values for other variables.

If there are as many dead, zombies and infected as there are humans, humanity is dead real fast.

If there are no humans, the  $S$ ,  $I$  and  $D$  can only become ~~zombie~~, because no extra input is given to the system (no birth).

1g) Modelica can model flow, and with some input and output code, we would not need to duplicate codes.

1f) The model could for example how many students join and leave a course. Or literally any ecosystem.

$$2a \quad \dot{x} + cx + g\left(1 - \left(\frac{x_0}{x}\right)^k\right) = 0$$

$$\begin{aligned} x_1 &= x \\ \dot{x}_1 &= \dot{x} \end{aligned}$$

$$\ast \quad \dot{x}_1 = x_2$$

$$\dot{x}_2 + cx_2 + g\left(1 - \left(\frac{x_0}{x_1}\right)^k\right) = 0$$

$$\dot{x}_2 = -cx_2 - g\left(1 - \left(\frac{x_0}{x_1}\right)^k\right)$$

b) Euler's method.

$$y_{n+1} = y_n + h f(y_n, t) + \frac{h^2}{2} d f(y_n, t) + \dots + \frac{h^p}{p!} + \frac{d^p f(y_n, t)}{p!} + O(h^{p+1})$$

$$\text{where slope } \frac{y_{n+1} - y_n}{h} = f(y_n, t_n)$$

$$\text{Our slope: } \nabla_x \lambda = \nabla_y \lambda$$



$$2b) \quad Y_{1,n+1} = Y_{1,n} + h Y_{1,n} - Y_{1,n} + Y_{2,n}$$

$$Y_{2,n+1} = Y_{2,n} + h Y_{2,n}$$

$$= Y_{2,n} + h \left( C Y_{2,n} - g \left( 1 - \left( \frac{x_d}{Y_{2,n}} \right)^k \right) \right)$$

2c) Rechnung mit 2. Methode:

$$k_1 = f(Y_n, t_n)$$

$$k_2 = f(Y_n + \frac{1}{3}h k_1, t_n + \frac{1}{3}h)$$

$$\Rightarrow k_1 = \begin{cases} k_{1,1} = Y_2^n \\ k_{1,2} = -C Y_2^n - g \left( 1 - \left( \frac{x_d}{Y_2^n} \right)^k \right) \end{cases}$$

$$k_2 = \begin{cases} k_{2,1} = Y_2^n + \frac{1}{3}h k_1 \\ k_{2,2} = -C \left( Y_2^n + \frac{1}{3}h k_1 \right) - \end{cases}$$

$$-g \left( 1 - \frac{x_d}{Y_1^n + \frac{1}{3}h k_1} \right)$$

2d)

$$0 + 0 + g\left(1 - \left(\frac{x_d}{x}\right)^k\right) = 0$$

$$\Rightarrow 1 - \left(\frac{x_d}{x}\right)^k = 0$$

$$\sqrt[k]{1} = \frac{x_d}{x}$$

$$x_1 = \frac{x_d}{\sqrt[k]{1}} = x_d$$

equilib.  
point

$$\underline{x_2 = 0}$$

$$\begin{pmatrix} \frac{\partial y_1}{\partial y_1} & \frac{\partial y_1}{\partial y_2} \\ \frac{\partial y_2}{\partial y_1} & \frac{\partial y_2}{\partial y_2} \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ -kg \frac{x_d}{y_1} & -c \end{pmatrix}$$

$$\begin{pmatrix} 0 & 1 \\ -kg & -c \end{pmatrix}$$

2e)

We can use the eigenvalues of the linearized  $\tilde{Y}$  to find if Euler is stable; because if we know that

$$|1+n\lambda| \leq 1$$

$$\tilde{Y} = \begin{pmatrix} 0 & 1 \\ -Kg - C & 0 \end{pmatrix} \quad 0 = \det(\lambda - \begin{pmatrix} Kg & C \\ 0 & \lambda + C \end{pmatrix})$$

$$\lambda^2 + \lambda C + Kg = 0$$

$$\lambda = \frac{-C \pm \sqrt{C^2 - 4Kg}}{2} =$$

$$= \frac{0 \pm \sqrt{-4Kg/176}}{2}$$

$\Rightarrow$  imaginary  $\Rightarrow$  Euler not stable for any  $n$ .

$$2e) \text{ ii) } \lambda = \frac{C \pm \sqrt{C^2 - 4Kg}}{2}$$

$$\lambda = \frac{8.927 \pm \sqrt{-14.48}}{2}$$

$\Rightarrow$  still imaginary  
values  $\Rightarrow$  not stable for any  $b$

3a)

$$L \frac{di}{dt} + Ri = u$$

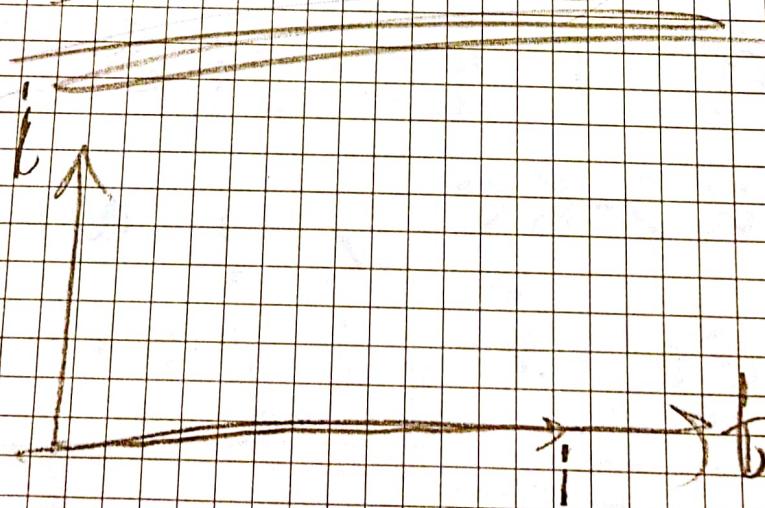
$$\Rightarrow \frac{di}{dt} = -\frac{R}{L}i$$

$$\therefore \frac{dE}{di} = -\frac{R}{L} \frac{di}{dt}$$

$$\frac{dE}{di} = \frac{d}{di} \left( \frac{1}{2} L i^2 \right) = Li$$

$$\Rightarrow \frac{dE}{dt} = -R i^2 \leq 0$$

$\Rightarrow$  stable



$$3b) e = i - i_{ref} \quad \text{if } R > \frac{L}{C}$$

$$E = \frac{1}{2} L e^2$$

$$\frac{de}{dt} = -\frac{R}{L}e - \frac{1}{L}u$$

$$\dot{E} = \frac{de}{dt} \frac{dE}{de} = -Re^2 - eu \quad (0)$$

$\Rightarrow$  now if  $Re^2 = eu$ ,  
the diff between

$i$  and  $i_{ref}$  will go  
to zero

$\Rightarrow$  if  $Re^2 < -eu$

$u > Re$ ,  $i$  will go  
to  $i_{ref}$  when  $t \rightarrow \infty$ ,

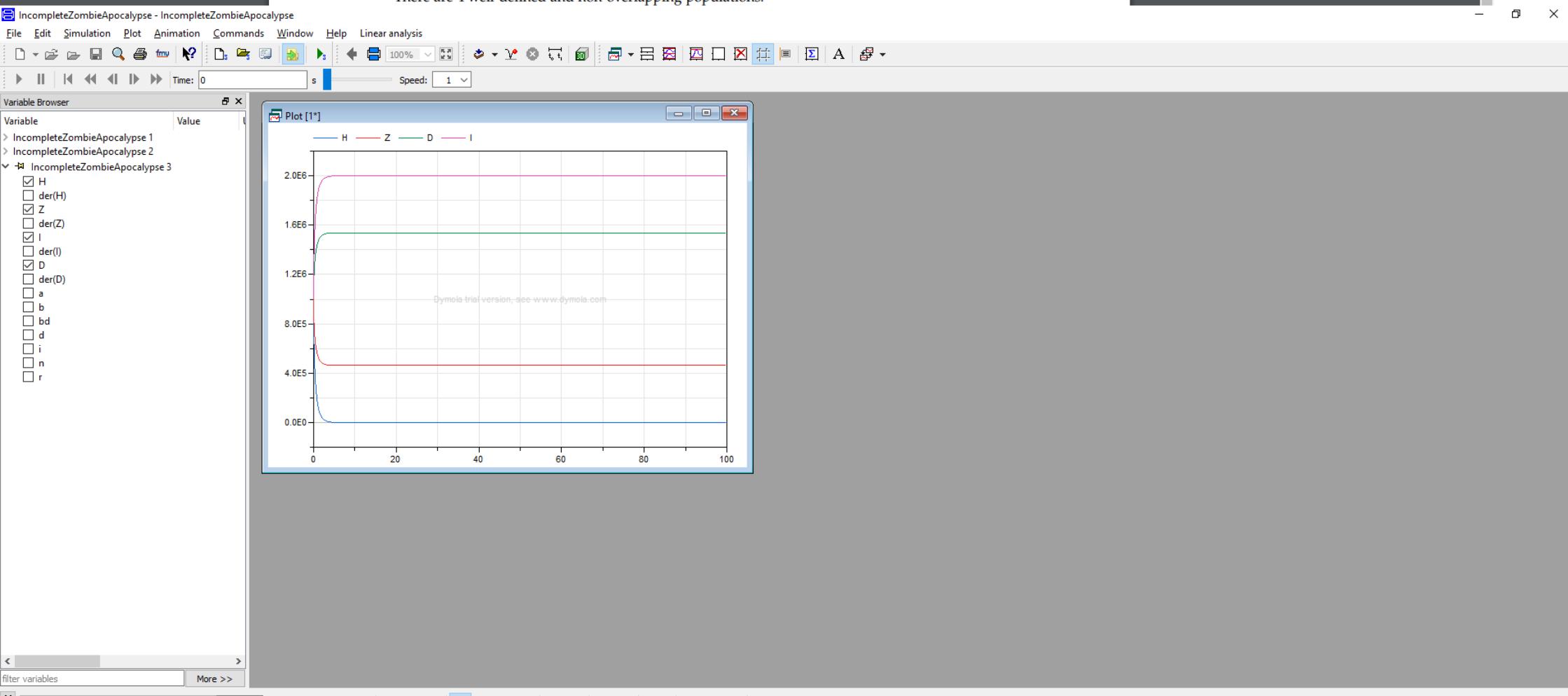


NB: This is a computer exercise, and can therefore be solved in groups of 2 students. If you do so, please write down the name of your group partner in your answer.

The doomsday is upon us!

Zombies have begun to rise from the dead, and violently and indiscriminately kill and infest the living. In order to save humanity, you have to first model and simulate the zombie infestation using the little information available on these abominations.

There are 4 well-defined and non-overlapping populations:



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IncompleteZombieApocalypse - IncompleteZombieApocalypse - [Modelica Text]

File Edit Simulation Plot Animation Commands Window Help Linear analysis

Package Browser

Packages

- > Dymola Commands
- > Modelica Reference
- > Modelica
- Unnamed

IncompleteZombieApocalypse

IncompleteZombieApocalypse x +

```
model IncompleteZombieApocalypse "Incomplete zombie apocalypse model"
  // Define types, parameters and variables, as well as start values
  // ...

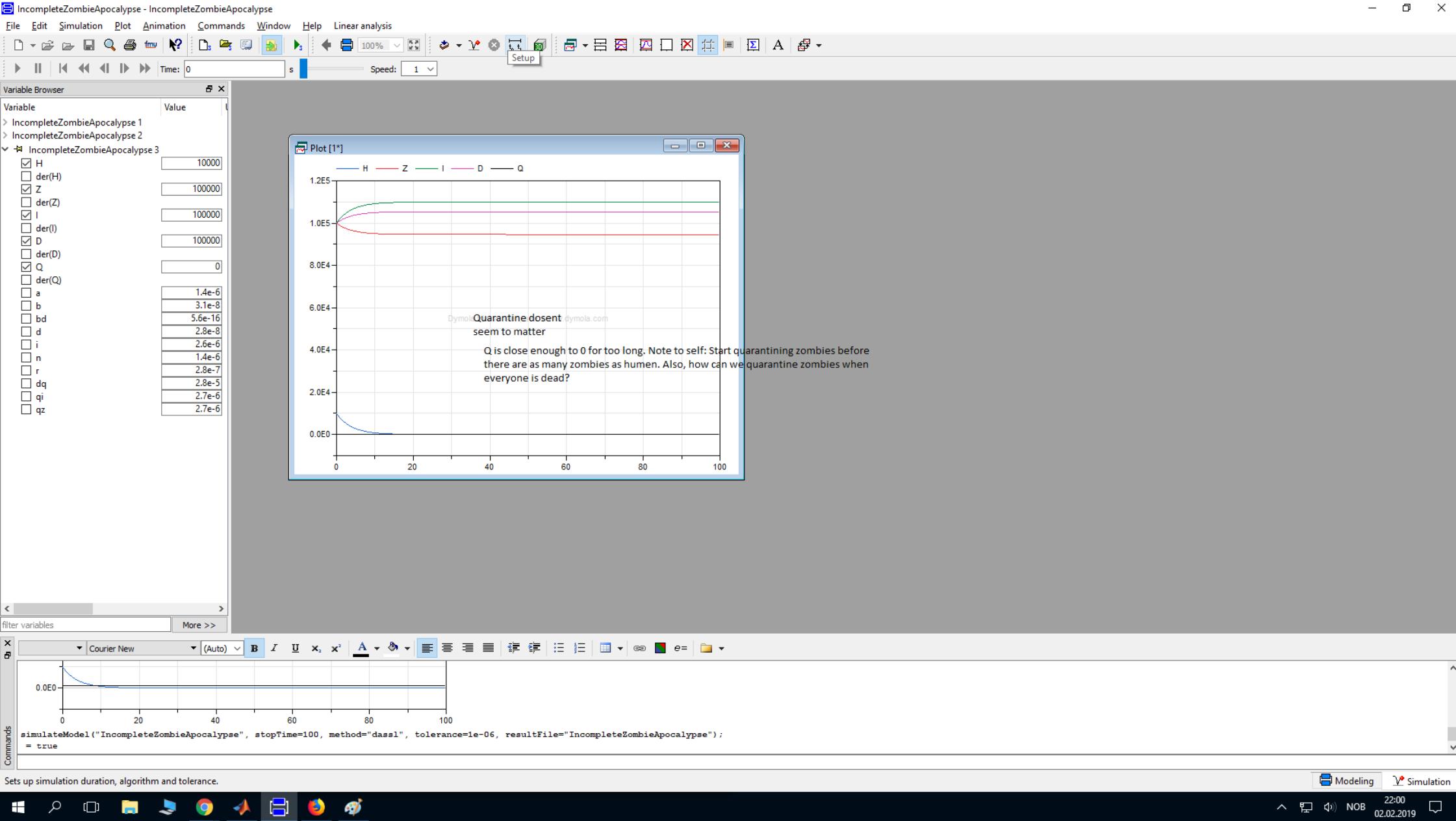
  Real H(start=10^-6);
  Real Z(start=10^-6);
  Real I(start=10^-6);
  Real D(start=10^-6);

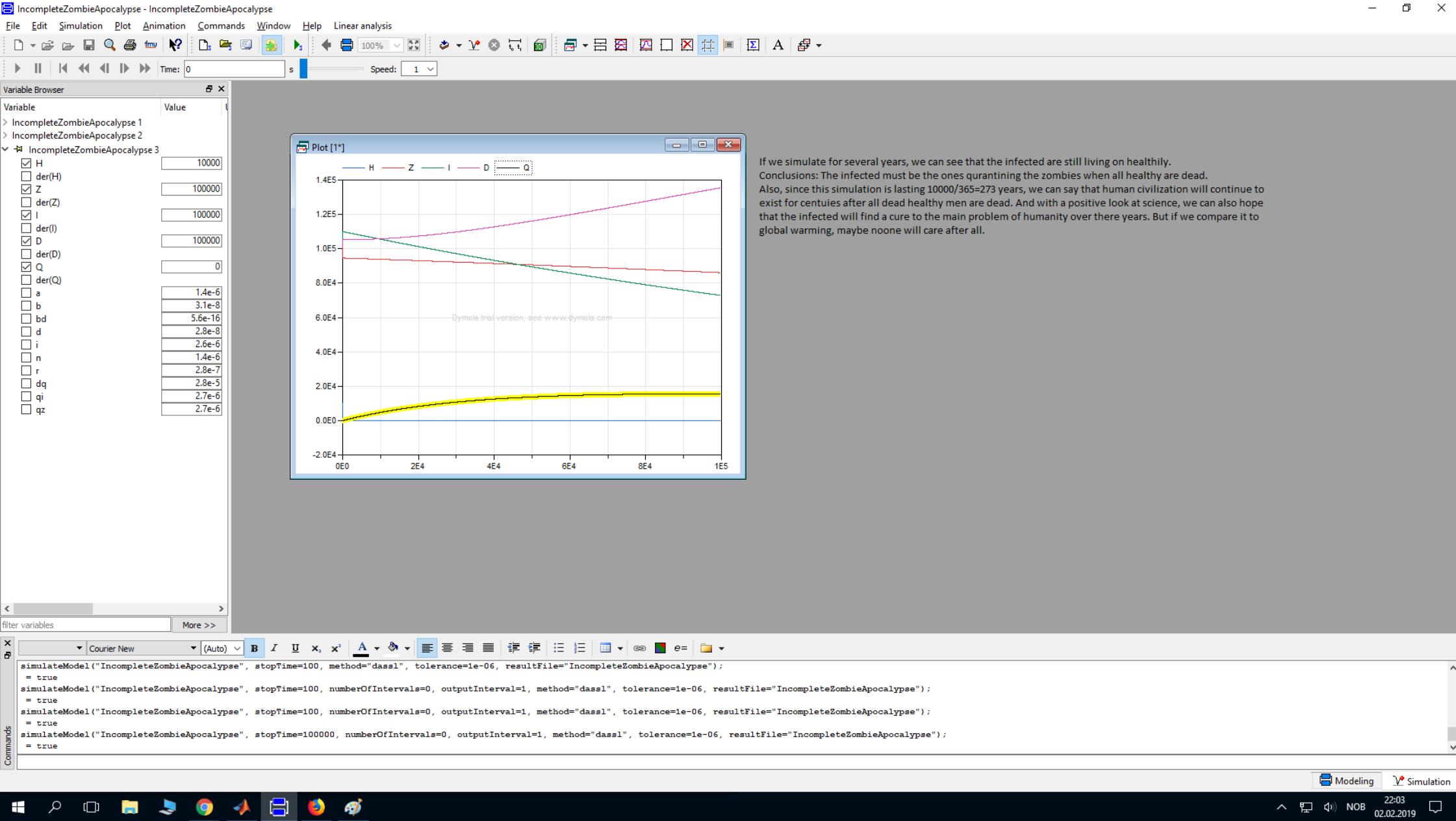
  parameter Real a=1.4*10^(-6);
  parameter Real b=3.1*10^(-8);
  parameter Real bd=5.6*10^(-16);
  parameter Real d=2.8*10^(-8);
  parameter Real i=2.6*10^(-6);
  parameter Real n=1.4*10^(-6);
  parameter Real r=2.8*10^(-7);

  equation
    der(H)=b*H-bd*H^2-d*I*H-i*H*Z;
    der(Z)=r*D+a*I-n*Z*H;
    der(D)=d*H+d*I+n*Z*H-r*D;
    der(I)=i*H^2-d*I-a*I;
    //der(H)+der(Z)+der(D)+der(I)=b*H-bd*H^2;
    0
  end IncompleteZombieApocalypse;
```

Component Browser

IncompleteZombieApocalypse





The quarantined approach only seems to delay the inevitable. Luckily, news of a cure for "zombieism" arrive. This treatment converts zombies and infected individuals to healthy individuals: If the individual was infected, it returns back to its healthy human form; and if it was resurrected from the dead, it returns to its healthy human form before death. Note however that this treatment does not provide immunity, i.e. individuals that are given the treatment may be converted to zombies in the future.

In order to model the effects of the cure, add the following changes to the previous model:

- Quarantine is no longer needed, i.e. the population  $Q$  is no longer part of the model.
- Zombies and infected individuals move to the healthy population with rate  $c > 0$ .

(e) Model the new dynamics of the populations  $H$ ,  $I$ ,  $Z$  and  $D$ .

(f) Extend the Modelica model from part c. to represent the new system  $[H, I, Z, D]^T$ . Do not change the parameter values for  $a$ ,  $b$ ,  $b_d$ ,  $d$ ,  $i$ ,  $n$  and  $r$ , and do not change the start values for  $H$ ,  $I$ ,  $Z$  and  $D$ . Furthermore, use the parameter value  $c = 2.7 \cdot 10^{-3}$ .

Simulate the new model for 100 days. Add the Modelica model and a plot with the obtained results for all the populations to your answer. What is the stationary value of  $H$ ? Comment on the results.

*Hint: Not sure about the stationary value of  $H$ ? Simulate the model for some years.*

Your are a champion of humanity! But before you can relax and think back with pride of the many lives your work saved, there is still one task to do: to clean up your code.

(g) Explain how you would use the language features of Modelica to reduce the amount of repeated code in the 3 models developed in parts (b), (d) and (f).

Feel free to rewrite the model codes so that the number of repeated code lines is minimized. If you do so, you only need to add the newest versions of the model codes to your answer. However, no code implementation is needed to solve this task.

A zombie outbreak is of course an unrealistic scenario if taken literally. However, the structure of the models developed here can be used for real-life applications.

(h) Give some examples of such applications.

**Problem 2 (Euler's method, linearization, stability. 25%)**

In this problem we will study the system

```

model IncompleteZombieApocalypse "Incomplete zombie apocalypse model"
  // Define types, parameters and variables, as well as start values
  // ...

  Real H(start=10^6);
  Real Z(start=10^6);
  Real I(start=10^6);
  Real D(start=10^6);
  Real Q;

  parameter Real a=1.4*10^(-6);
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  parameter Real i=2.6*10^(-6);
  parameter Real n=1.4*10^(-6);
  parameter Real r=2.8*10^(-7);
  parameter Real dq=2.8*10^(-5);
  parameter Real q1=2.7*10^(-6);
  parameter Real qz=2.7*10^(-6);

equation
  der(H)=b*H-bd*H^2-d*H-i*H*Z;
  der(Z)=r*D+a*I-n*Z*H-qz*Z;
  der(D)=d*H+d*I+n*Z*H-r*D+dq*Q;
  der(I)=i*H*Z-d*I-a*I-q1*I;
  der(Q)=qz*Z*q1*I-dq*Q;
  //der(H)+der(Z)+der(D)+der(I)=b*H-bd*H^2;
end IncompleteZombieApocalypse;

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    der(Z)=r*D+a*I-n*Z*H-c;
    der(D)=d*H+d*I+n*Z*H-r*D;
    der(I)=i*H*Z-d*I-a*I-c*I;

    //der(H)+der(Z)+der(D)+der(I)=b*H-bd*H^2;
    //B
  end IncompleteZombieApocalypse;
```

