

# TDT4205 Problem Set 4

## Spring 2017

Answers are to be submitted through *It's Learning*, by Mar. 14<sup>th</sup>, 20:00.  
**This problem set is graded, and counts for a total of 10% of the final mark**

### 1 Theory

#### 1.1 10%

Translate the following VSL program into a three-address code (TAC) representation. (Use the function's argument names as placeholders for its arguments' locations.)

```
FUNC main()
BEGIN
    RETURN axpy(2,3,4)
END
```

```
FUNC axpy(a,x,y)
BEGIN
    VAR r1, r2
    r1 := a * x
    r2 := r1 + y
    RETURN r2
END
```

#### 1.2 10%

Suggest a stack frame layout for the **axpy** function on a machine which passes arguments via the run-time stack, and briefly explain the role of each element in your layout.  
(You may use the x86 convention covered in lecture, but it is not required.)

#### 1.3 5%

Show the state of the run-time stack at the point of execution where **axpy** is about to return.

## 2 Programming

Given the provided program archive `ps4_skeleton.tgz`,

### 2.1 15%

Implement the function `find_globals` in `ir.c`, to populate the global symbol table with

1. Global variables (5%)
2. Functions (10%)

### 2.2 45%

Implement the function `bind_names` in `ir.c`, to populate local symbol tables with

1. Parameters (15%)
2. Local variables (15%)

and link the entry pointers in its syntax tree nodes to their appropriate symbols. (15%)

### 2.3 10%

Extend `bind_names` to create a global table of strings.

### 2.4 5%

Implement the function `destroy_symtab`, to remove dynamically allocated symbol table data at the end of compilation.

Details on the function of these implementations are given in the accompanying recitation slide set.