IT UNIVERSITY OF COPENHAGEN

Clustering Player Behaviors in Data Streams with K-Means in Map-Reduce

by

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A thesis submitted in partial fulfillment for the degree of Master of Science in IT

in the Computer Science Software Development and Technology

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April 2013

"Any intelligent fool can make things bigger, more complex, and more violent. It takes a touch of genius – and a lot of courage – to move in the opposite direction."

Albert Einstein

Abstract

The abstract is a short summary of the thesis. It announces in a brief and concise way the scientific goals, methods, and most important results. The chapter "conclusions" is not equivalent to the abstract! Nevertheless, the abstract may contain concluding remarks. The abstract should not be discursive. Hence, it cannot summarize all aspects of the thesis in very detail. Nothing should appear in an abstract that is not also covered in the body of the thesis itself. Hence, the abstract should be the last part of the thesis to be compiled by the author.

A good abstract has the following properties: Comprehensive: All major parts of the main text must also appear in the abstract. Precise: Results, interpretations, and opinions must not differ from the ones in the main text. Avoid even subtle shifts in emphasis. Objective: It may contain evaluative components, but it must not seem judgemental, even if the thesis topic raises controversial issues. Concise: It should only contain the most important results. It should not exceed 300–500 words or about one page. Intelligible: It should only contain widely-used terms. It should not contain equations and citations. Try to avoid symbols and acronyms (or at least explain them). Informative: The reader should be able to quickly evaluate, whether or not the thesis is relevant for his/her work.

An Example: The objective was to determine whether \dots (question/goal). For this purpose, \dots was \dots (methodology). It was found that \dots (results). The results demonstrate that \dots (answer).

Acknowledgements

The acknowledgments and the people to thank go here, don't forget to include your project advisor...

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1.1 Motivation

We live in a time of data, where data is growing at an amazing rate. Data is everywhere around us and companies are generating more and more data. Storing data is cheaper than ever and many smaller and mid-sized companies are buying storage subscriptions at other bigger companies that offer "Storage as a Service" (SaaS). A SaaS company offers e.g. data reliability and durability by storing critical data in multiple facilities and on multiple devices. Having all this data does not give a meaning by itself, it needs to be analysed and interpret to give a business value.

"Information is the oil of the 21st century, and analytics is the combustion engine."

Peter Sondergaard, senior VP at Gartner

The need to analyse all this data have caused many new companies to rise up that are specialised in analysing large quantities of data, extracting knowledge and converting it to a business value. Many of those companies offer "Analytics as a Service" (AaaS) that offer an analytical software to discover trends and unknown patterns in the data.

1.2 Problem Statement

GameAnalytics.com is a cloud hosted service for collecting, analyzing and reporting game metrics. Working with large quantities of game metric data that needs to be analysed and processed efficiently.

A valuable application for GA is to design and implement a scalable streaming version of a clustering algorithm. That can read a large data in mini-batches into memory and cluster the data incrementally.

The goal would be to incrementally find clusters efficiently in a streaming data, showing predominant characteristics of human behavior, e.g. the hardcore players, casual players, people who didn't understand the game, etc.

1.3 Contributions

- Clustering Player Behaviours using Map-Reduce framework
- Software and knowledge to GameAnalytics for further development

1.4 Project Outline

Background Theory

- 2.1 Player Behaviour
- 2.1.1 Game Metric
- 2.1.2 Features
- 2.2 Clustering
- 2.2.1 K-Means
- 2.2.2 Streaming and Data Streams
- 2.3 Map-Reduce and Hadoop

Related and Recent Work

Clustering player behaviors and large data sets have been researched actively in the recent years. In our work we focus on processing a large amount of data of finite length in parallel using k-means in Map-Reduce and incrementally cluster new data sets arriving each day. The behavior of the data can change from day to day like when dealing with an endless stream of data. In subsequent sections some of the recent and related work are given a short introduction.

3.1 Clustering Player Behaviors

Many researches have been done on clustering and predicting player behaviors over the last years to get a better understanding which kind of user behaviors are to be found when playing a game that can be actionable for game developers [1–5]. User behavior analysis has becoming increasingly popular in the recent years because of rise of the free-to-play (F2P) genre games in Facebook and Google Play where populations can be in millions creating complex game interactions [4, 6]. Playing these games are free and many are of persistent nature where the world in the game continues when a player exits. To be profitable these games drive their revenue via micro transactions, e.g. players buying upgrades or virtual items in game for real money [4, 6–8]. Major game publishers have also been collecting and analyzing large scale of behavior telemetry data but details of their methods are kept confidential [9, 10]. Most available research work

is case based where a specific algorithm is applied to a specific game and commercial game data sets has only become accessible recently for academic researchers [10].

Thurau world of warcraft guilds A work of analyzing social groups in the popular Massively Multiplayer Online Role-Playing Game (MMORPG) World of Warcraft was done by Thurau and Bauckhage [CITE]. They analyzed how groups (guilds) evolve over time from both American and European based guilds. Their paper is the first study analyzing such amount of data in a MMORPG, analyzing large-scale data from 18 million players belonging in 1.4 million groups over a period of 4 years. Convex-Hull Non Negative Matrix Factorization (CH-NMF) technique was applied to the data and the results show that there are no significant cultural difference in formation processes of guilds from either the US or the EU. Interpretability of CH-NMF was more distinguishable and representing archetypal guilds than the more conventional clustering method k-means that represent the cluster centroids with similar characteristic.

Tomb raider Julian + mahlmann

Drachen et al. [5] did a clustering analysis for two major commercial games applied to large-scale of high-dimensionality player behavior telemetry. K-means and Simplex Volume Maximization (SIVM) clustering were applied to the MMORPG Tera and the multi-player first-person shooter strategy game Battlefield: Bad Company 2. SIVM clustering is an adaption of Archetype Analysis (AA) for large-scale data sets to find extreme player behaviors profiles [3, 11]. The authors show the contribution differences from the two algorithms where k-means gives insights into the general distribution of behaviors vs. SIVM showing players with extreme behaviors. The selection of the most important features from the data set were followed by a method suggested by Drachen et al. [12], behavioral profiles were extracted and interpreted in terms of design language [9, 12].

In a recent study by Drachen et al. [13] the authors compare four different popular methods with purpose of clustering player behaviors and develop profiles from large-scale game metric data set from the highly popular commercial MMORPG World of Warcraft. The data set was collected from mining the Warcraft Realms site, recordings of on-line time and what level each player reached for each day in the years 2005-2010 for approx. 70 thousands of players. The authors selected playtime and leveling speed as their behavioral variables to show a measure of the overall player engagement in the

game, where playtime is one of the most important measure for calculating the churn rate (attrition) [7, 8]. Interpretable behaviors profiles where only generated by the k-means and the SIVM algorithm. The SIVM Archetype Analysis algorithm produces however significantly different behaviors that result in easier interpretation of behavior profiles compared to the k-means algorithm where the centroids are overall similar.

3.2 Clustering Large Data

K-means is one of the most studied clustering algorithm out there and is still actively researched. It's a simple algorithm that partition the data into k partitions by minimizing its objective function sum of squared error. From its appearance in a standard algorithm version by Stuart Lloyd in 1982 [14], it has been one of the most popular clustering algorithm to research because of its simplicity. There are many different research areas regarding k-means e.g. manually set the number of k partitions to cluster, initializing the centers of the partitions, dealing with outliers in data and scalability when dataset increases. In recent years k-means has also been very popular algorithm to study in the Map-Reduce framework where the algorithm can easily be applied to cluster large amount of data sets in parallel [15].

Guha et al. [16] designed an algorithm called STREAM that is based on the divideand-conquer strategy and achieves a constant-factor approximation solving the k-median problem (a k-means variant). The algorithm divides the dataset into m pieces of similar sizes. Each of the pieces are independently clustered sequentially and all the centers from all the pieces are then clustered further. They show a new k-median algorithm called LSEARCH that is used by the stream algorithm and is based on local search algorithm solving the facility location problem [17] to solve the k-median problem. Results show that LSEARCH produced better quality clusters than k-means and the hierarchical algorithm BIRCH [18] but took longer to run. In 2009 Ailon et al. [19] extended the the work of Guha et al. introducing an one pass streaming algorithm for k-means with approximation guarantees. Achieving that they introduced a new algorithm called k-means# that builds on the non-streaming algorithm k-means++ by Arthur and Vassilvitskii [20] that is a combined algorithm of seeding the initial centers and running k-means. k-means# provides a bi-criterion (α, β) approximation algorithm by choosing $\alpha * k$ centers with approximation factor β . In the divide-and-conquer strategy they run the k-means# independently on each piece of the data to achieve O(k * log(k)) random centers non-uniformly and use the k-means++ algorithm to find k centers from the intermediate centers from all the pieces of the data set.

Another approach is using a coreset by selecting a weighted subset from the original data set such that by running any k-means algorithm on the subset will give near similar results to running k-means on the original data set. Ackermann et al. [21] introduce a new algorithm called StreamKM++ that uses k-means++ algorithm from Arthur et al. [20] to solve k-means on the subset and the also design a new data structure called coreset tree to speed up the time for the sampling in the center initialization. StreamKM++ is a streaming version of k-means++ to cluster large data sets. Their approach was shown to be on par with LSEARCH algorithm in cluster quality but outperformed BIRCH by factor of 2. A recent work by Shindler et al. [22] proposed an algorithm called Fast streaming k-means based on the online facility location algorithm [23] and extends the work of Braverman et al. [24] proving a faster running time and a better approximation factor. Their algorithm outperformed both work of Ailon et al. [19] and Ackermann et al. [21] mentioned above.

Clustering data streams of an unknown length, evolving over time [25, 26] are challenging where it is not possible to access historic data points because of the amount of data arriving continuously. Aggarwal et al. [27] proposed a well-known stream clustering framework called CluStream for clustering large evolving data streams and is guided by application-centered requirements. CluStream has an online component that maintains snapshots of statistical information about micro-clusters (a.k.a. cluster feature vector [18]) in a pyramidal time window and an offline component that uses the compact intermediate summary statistics from the micro-clusters to find higher level k clusters using k-means, in a time horizon defined by an analyst. The authors proposed also a new high-dimensional, data stream clustering algorithm called HPStream that is highly scalable [28]. HPStream uses projected clustering [29], which can determine clusters for a subset of dimensions, to data streams and a new data structure called fading cluster structure that allows historical and current data to integrate nicely with a user-specified fading factor. Zhou et al. [30] presented a clustering algorithm called SWClustering that clusters evolving data streams over sliding windows to be able to analyze also the evolution of the individual clusters by eliminating influence by historic data points while the new data points arrive. The Authors show that the CluStream algorithm is more sensitive to influences of outdated data and is less efficient.

Processing large of amount of data efficiently using parallel processing is an active research and gain much of popularity when the Google's MapReduce programming model was introduced by Dean and Ghemawat [15] that allows researchers easily to create highly scalable and fault tolerance algorithms by just implementing a Map and a Reduce function. Zhao et al. [31] implemented a parallel version of k-means (PKMeans) in MapReduce framework and show that their algorithm can effectively run on large data sets. They designed the Map function to calculate the closest cluster centroid for each point at a time and output a < key, value > pair where key is the closest cluster centroid id and value is the data point. After each map task they apply a combiner function called Combine that is executed on the same machine as the Map function. The Combine function partly sum the values of the data points assigned to the same cluster and outputs a $\langle key, value \rangle$ pair where key is the id of the cluster centroid and the value is comprised of the sum values and the number of data points in that cluster. Using a combiner reduces the amount of intermediate information that is processed and sent over the network to the Reduce task [15, 31]. Then the Reduce function sums up all the intermediate sub sum values from all the combiners and calculates the new centers for the next MapReduce iteration.

To overcome the sensibility of k-means to outliers in data, Li et al. [32] proposed an algorithm called MBK-means using the ensemble learning method called Bagging [33], generating k new data sets from the original data set with replacement sampling. For each of the new data set the k-means is run using the MapReduce framework until convergence then finally the k sets of k centroids are merged to form the final k centroids.

Many extensions on the traditional MapReduce framework have been proposed to support algorithms running iteratively [34–39] and incrementally [39–41] efficiently. The incremental MapReduce frameworks are interesting and relates to our work since we are incrementally clustering data but the use of these frameworks is not in this study.

3.2.1 Related work vs the study

Our work is most similar to PKMeans [31] described above, a parallel k-means implementation in MapReduce using a Combine function to reduce the intermediate data sent between the mappers and the reducers. We implement a parallel k-means algorithm in MapReduce so that each Map function efficiently calculates the distance to nearest cluster centers by calculating the distance matrix between all data points and the cluster centers instead of processing each data point separately. We show the algorithm in application where it incrementally clusters player behaviors where theoretically large data sets arrive daily. In our work we show k-means is a good approach to provide insights into the general distribution of behaviors in a game, work of Drachen et al. [5, 13] relates to ours when selecting and building features from user telemetry and extracting behavioral profiles by analyzing the centroids (basis vectors) in k-means. We will also experiment clustering a data stream that could theoretically change from day to day and discuss future work.

Methodology

- 4.1 Game Events Data
- 4.1.1 Building Features
- 4.2 K-Means in Map-Reduce
- 4.2.1 Euclidean distance
- 4.2.2 Normalized Histograms
- 4.3 Experimental Set-Up

Results and Discussion

- 5.1 Results
- 5.2 Discussion

Conclusions

Appendix A

Appendix Title Here

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