
Noteworthy Framework

Examples & Documentation (Solutions)

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NOTEWORTHY

Preface

Welcome to the **Noteworthy Framework**. This document serves as both a demonstration of the framework's capabilities and a reference for its features.

1 About Noteworthy

Noteworthy is a modular framework for creating beautiful educational documents in Typst. It provides a comprehensive set of tools for:

- **Structured Layouts:** Automated chapters, sections, and covers.
- **Themed Components:** Pre-styled blocks for definitions, theorems, examples, and more.
- **Advanced Plotting:** Integrated 2D and 3D plotting capabilities.
- **Customizable Themes:** A robust theming engine with multiple built-in presets.

2 Using This Guide

Each section of this document demonstrates a specific module of the framework. You can find the source code for these examples in the `content/` directory, which serves as a practical reference for your own documents.

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Noteworthy*

Table of Contents

Chapter 00 *Getting Started*

Chapter 00.01	Welcome	5
Chapter 00.02	Quick Start	6

Chapter 01 *Content Blocks*

Chapter 01.01	Introduction	9
Chapter 01.02	Content Blocks	11
Chapter 01.03	Layout Elements	13

Chapter 02 *Geometry & Visualization*

Chapter 02.01	Introduction	16
Chapter 02.02	Geometry (Geoplot)	18
Chapter 02.03	Vectors (Vectorplot)	24
Chapter 02.04	3D Space (Spaceplot)	27
Chapter 02.05	Custom Plots	29

Chapter 00

Getting Started

Introduction to Noteworthy basics.

Chapter 00.01

Welcome

1 Welcome to Noteworthy

Noteworthy is a powerful Typst template for creating beautiful educational documents with rich content blocks and visualization tools.

1.1 What You'll Learn

This guide covers all Noteworthy-specific features:

DEFINITION | Content Blocks

Semantic containers for definitions, theorems, proofs, examples, solutions, and more.

NOTE | Canvas System

A unified object-oriented plotting system for 2D geometry, vectors, polar plots, and 3D space.

Chapter 00.02

Quick Start

1 Quick Start Guide

Get started with Noteworthy in minutes.

1.1 Block Syntax Overview

All blocks follow the pattern: #blockname("Title")[content]

DEFINITION | Definition Block

Use #definition("Title") [...] for definitions.

THEOREM | Theorem Block

Use #theorem("Title") [...] for theorems.

EQUATION | Equation Block

Use #equation("Title") [...] for named equations:

$$E = mc^2$$

NOTE | Note Block

Use #note("Title") [...] for important notes.

NOTATION | Notation Block

Use #notation("Title") [...] to explain notation.

ANALYSIS | Analysis Block

Use #analysis("Title") [...] for analysis and discussion.

Proof |

Use `#proof[...]` for proofs.

1.2 Proof & Solution Blocks

These blocks have special formatting:

EXAMPLE | Example Block

Use `#example("Title")[...]` for examples.

Solution 1 |

Use `#solution[...]` for solutions. Visibility controlled by `show-solution` config.

NOTE |

Although not mandatory, solutions are suggested to be used inside of example blocks for clarity.

Chapter 01

Content Blocks

Semantic blocks for structuring educational content: definitions, theorems, proofs, examples, and solutions.

Chapter 01.01

Introduction

1 Content Blocks Overview

Noteworthy provides 9 semantic block types for structuring educational content.

1.1 The Block Types

1.1.1 Definition & Theorem

DEFINITION | Limit

The limit of $f(x)$ as x approaches a is L if for every $\varepsilon > 0$ there exists $\delta > 0$ such that $|f(x) - L| < \varepsilon$ whenever $0 < |x - a| < \delta$.

THEOREM | Squeeze Theorem

If $g(x) \leq f(x) \leq h(x)$ for all x near a , and $\lim_{x \rightarrow a} g(x) = \lim_{x \rightarrow a} h(x) = L$, then $\lim_{x \rightarrow a} f(x) = L$.

1.1.2 Equation & Notation

EQUATION | Euler's Identity

$$e^{i\pi} + 1 = 0$$

NOTATION | Big-O Notation

$O(n)$ denotes an upper bound on the growth rate of an algorithm.

1.1.3 Note & Analysis

NOTE | Remember

Limits describe behavior as we approach a point, not necessarily at the point itself.

ANALYSIS | Convergence

The sequence $a_n = \frac{1}{n}$ converges to 0 because for any $\varepsilon > 0$, choosing $N > \frac{1}{\varepsilon}$ ensures $|a_n| < \varepsilon$ for all $n > N$.

Chapter 01.02

Content Blocks

1 Proofs & Solutions

Special blocks for mathematical reasoning and worked examples.

1.1 Proof Block

The `#proof` block automatically adds a QED symbol at the end.

THEOREM | Sum of First n Integers

$$\sum_{k=1}^n k = \frac{n(n+1)}{2}$$

Proof |

Base case: When $n = 1$: $\sum_{k=1}^1 k = 1 = \frac{1 \cdot 2}{2}$. ✓

Inductive step: Assume true for n . Then:

$$\begin{aligned}\sum_{k=1}^{n+1} k &= \sum_{k=1}^n k + (n+1) = \frac{n(n+1)}{2} + (n+1) \\ &= (n+1)\left(\frac{n}{2} + 1\right) = (n+1)\frac{n+2}{2}\end{aligned}$$

Thus true for $n+1$. ∴ By induction, the formula holds for all $n \geq 1$.

1.2 Example & Solution Blocks

EXAMPLE | Derivative of x^3

Find $\frac{d}{dx}x^3$ using the power rule.

Solution 1 |

Using the power rule $\frac{d}{dx}x^n = nx^{n-1}$:

$$\frac{d}{dx}x^3 = 3x^2$$

EXAMPLE | Integration

Evaluate $\int_0^2 x^2 \, dx$.

Solution 1 |

$$\int_0^2 x^2 \, dx = \left[\frac{x^3}{3} \right]_0^2 = \frac{8}{3} - 0 = \frac{8}{3}$$

Chapter 01.03

Layout Elements

1 Layout & Equations

Named equations and layout helpers.

1.1 Named Equations

Use `#equation` for important equations that deserve highlighting:

Equation | Quadratic Formula

$$x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

Equation | Maxwell's Equations

$$\begin{aligned}\nabla \cdot \mathbf{E} &= \frac{\rho}{\epsilon_0} \\ \nabla \cdot \mathbf{B} &= 0 \\ \nabla \times \mathbf{E} &= -\partial \frac{\mathbf{B}}{\partial t} \\ \nabla \times \mathbf{B} &= \mu_0 \mathbf{J} + \mu_0 \epsilon_0 \partial \frac{\mathbf{E}}{\partial t}\end{aligned}$$

Equation | Schrödinger Equation

$$i\hbar \frac{\partial}{\partial t} \Psi = \hat{H} \Psi$$

1.2 Combining Blocks

Blocks work naturally together:

Definition | Eigenvalue

A scalar λ is an eigenvalue of matrix \mathbf{A} if $\mathbf{A}\mathbf{v} = \lambda\mathbf{v}$ for some non-zero vector \mathbf{v} .

EQUATION | Characteristic Equation

$$\det(\mathbf{A} - \lambda \mathbf{I}) = 0$$

EXAMPLE | 2×2 Eigenvalues

Find eigenvalues of $\begin{pmatrix} 3 & 1 \\ 0 & 2 \end{pmatrix}$.

Solution 1 |

$$\det\begin{pmatrix} 3 - \lambda & 1 \\ 0 & 2 - \lambda \end{pmatrix} = (3 - \lambda)(2 - \lambda) = 0$$

Thus $\lambda = 3$ or $\lambda = 2$.

Chapter 02

Geometry & Visualization

Powerful plotting system for Euclidean geometry, vectors, and 3D space.

Chapter 02.01

Introduction

1 Canvas System Overview

The Noteworthy canvas system provides unified object-oriented plotting.

1.1 Canvas Types

Noteworthy provides four canvas types:

DEFINITION | cartesian-canvas

Standard 2D Cartesian coordinate system with axes, grids, and labels.

DEFINITION | blank-canvas

Canvas without axes - useful for diagrams and geometric constructions.

DEFINITION | polar-canvas

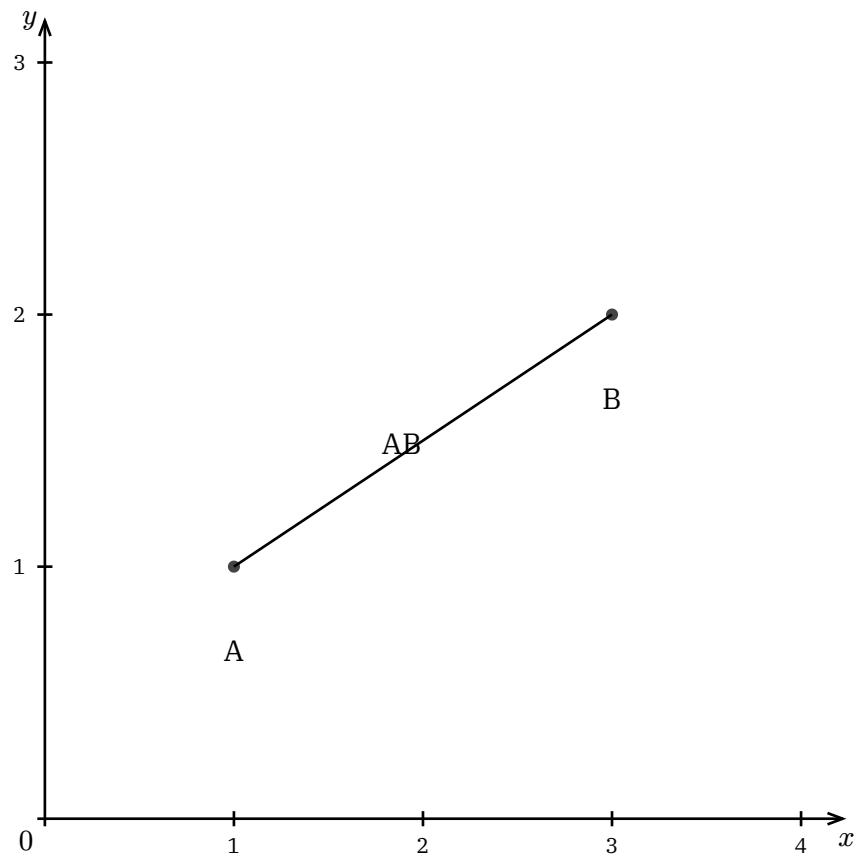
Polar coordinate system for circular plots.

DEFINITION | space-canvas

3D coordinate system with perspective projection.

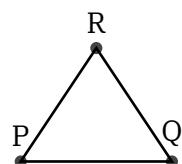
1.2 Basic Example

A simple Cartesian canvas with a point and line:



1.3 Blank Canvas

For diagrams without coordinate axes:



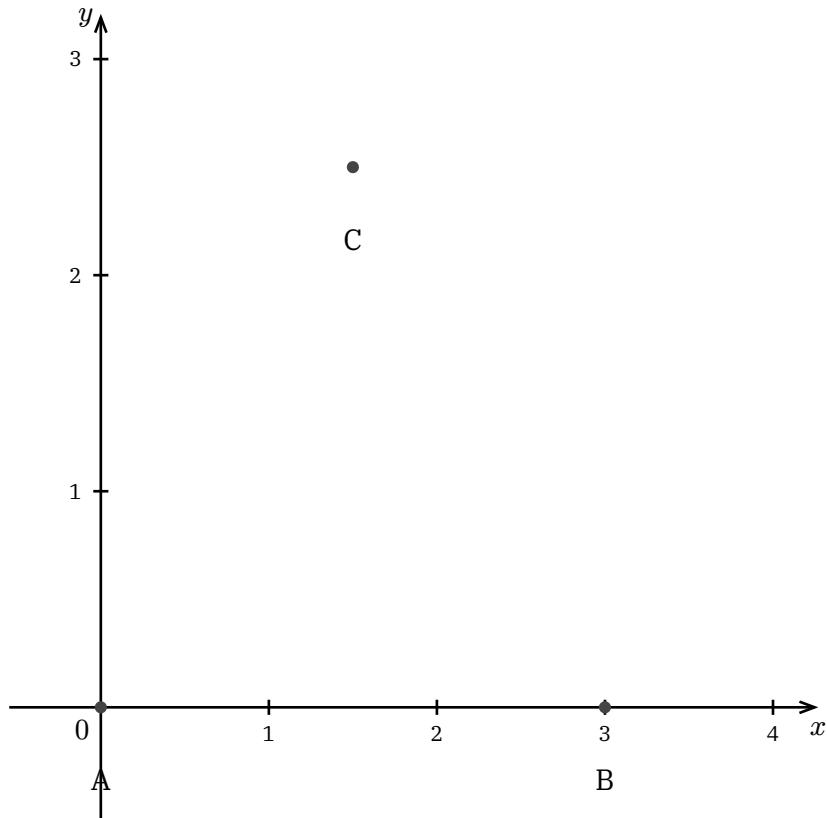
Chapter 02.02

Geometry (Geoplot)

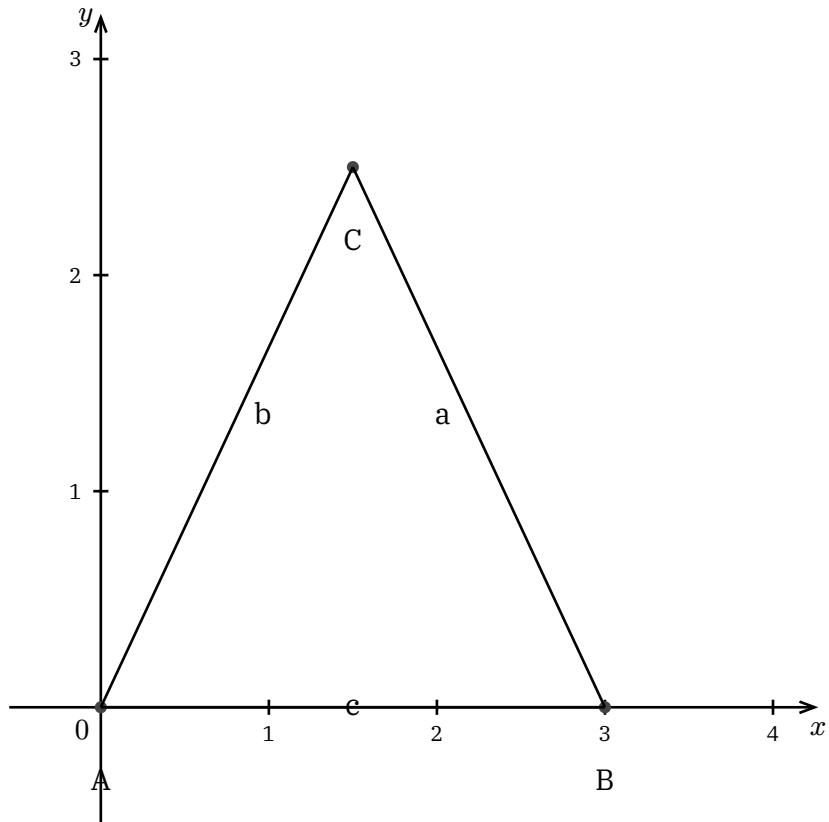
1 Geometry (Geoplot)

Create Euclidean geometry constructions with the geometry object system.

1.1 Points & Labels

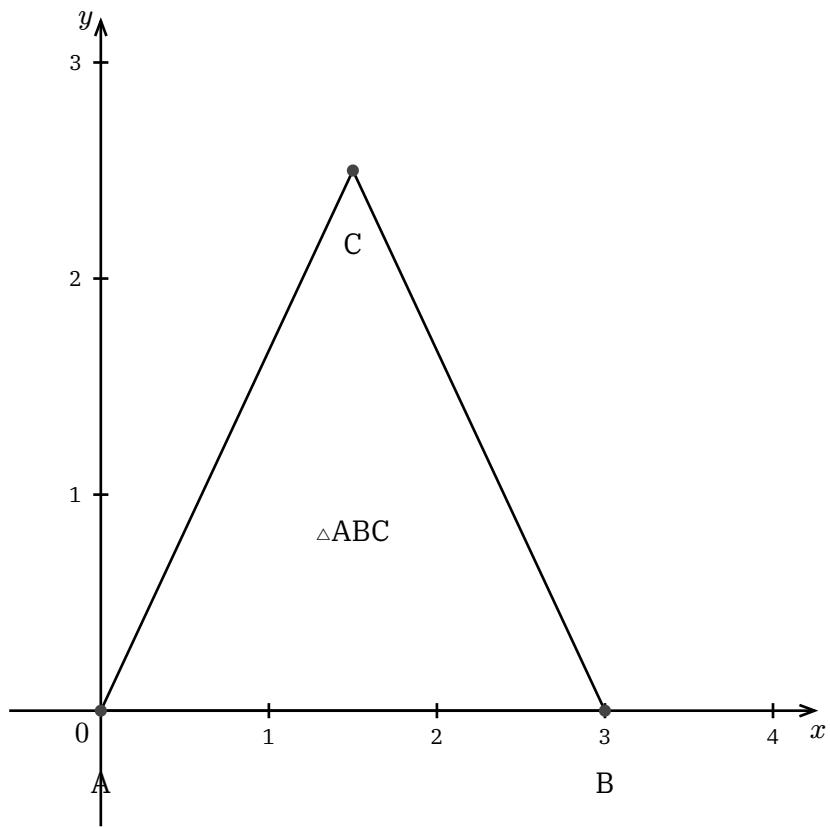


1.2 Lines & Segments

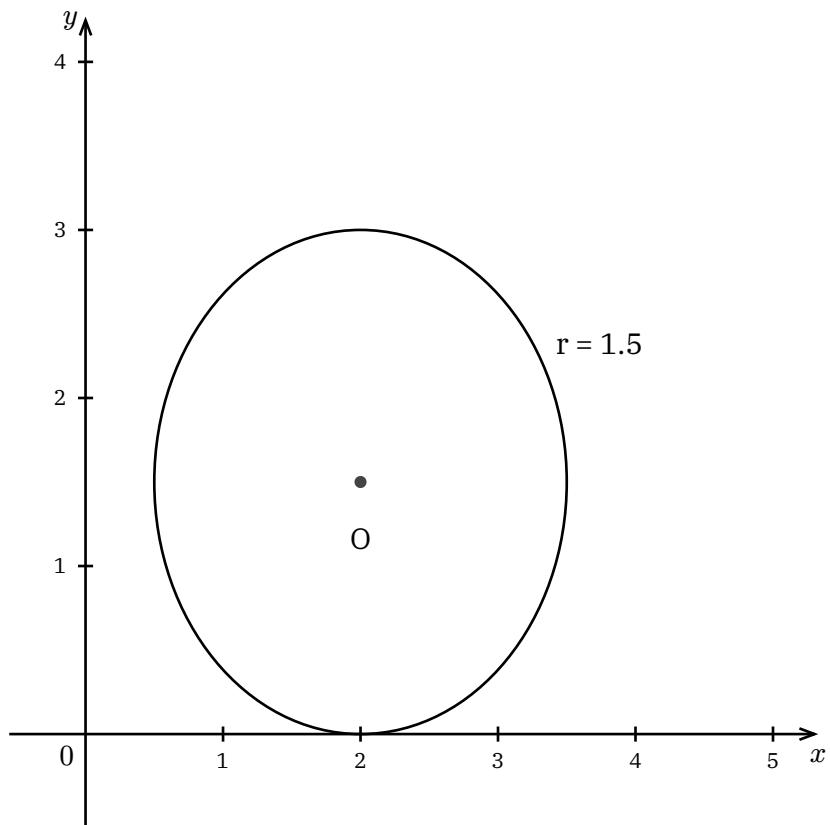


1.3 Triangles

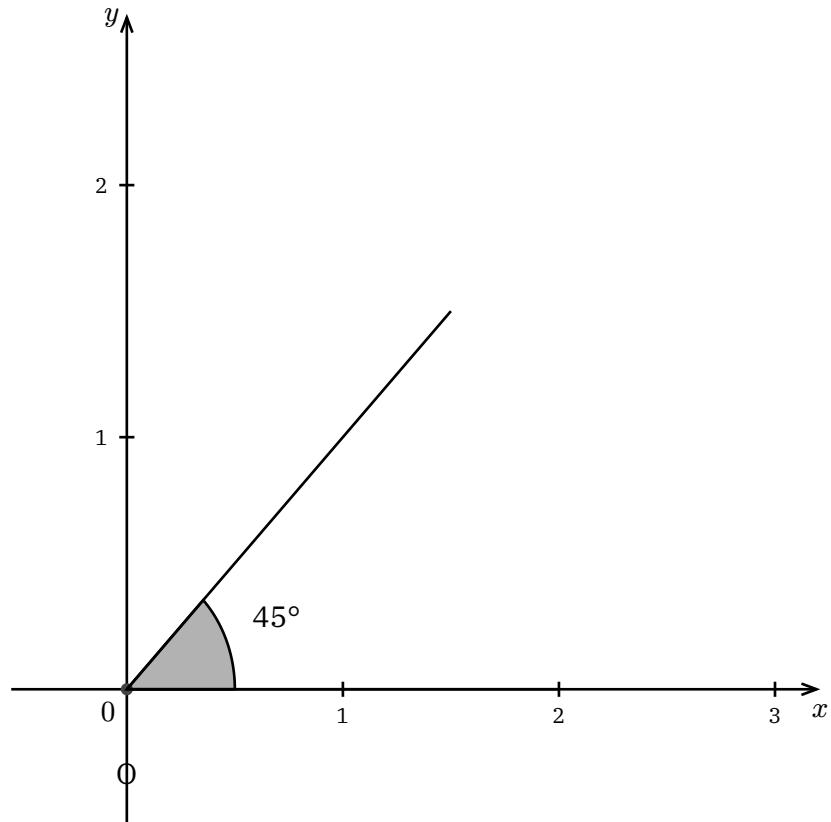
The `triangle` object draws all three sides:



1.4 Circles



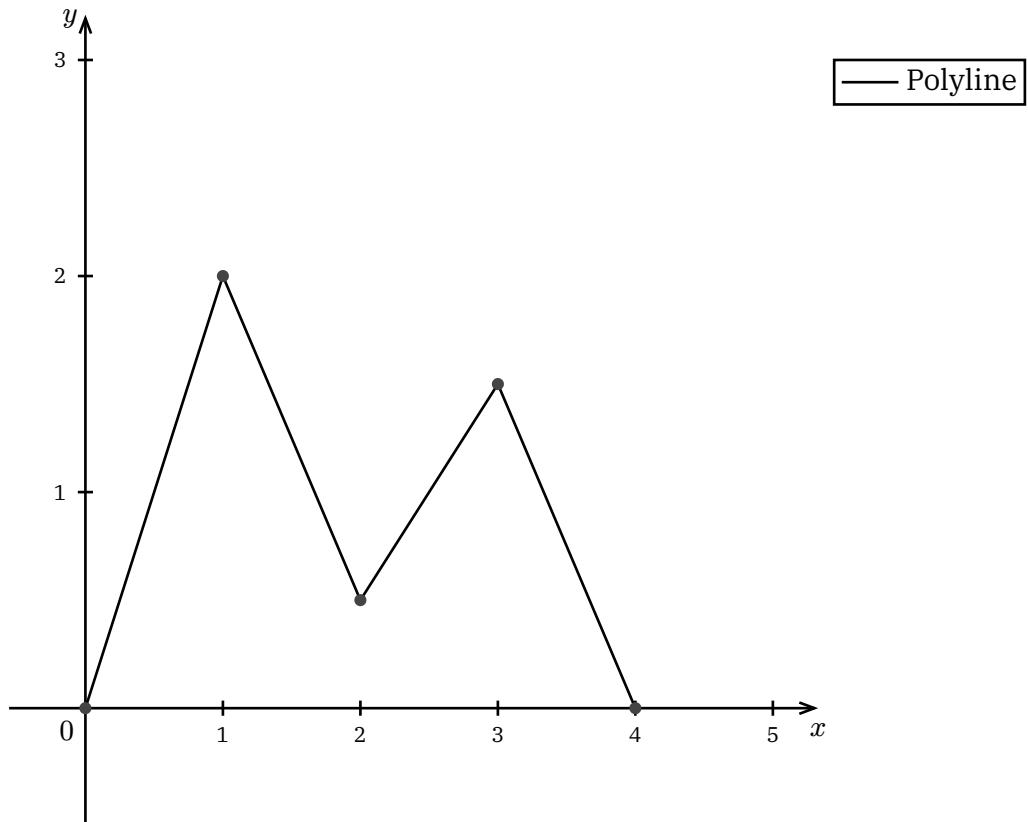
1.5 Angles



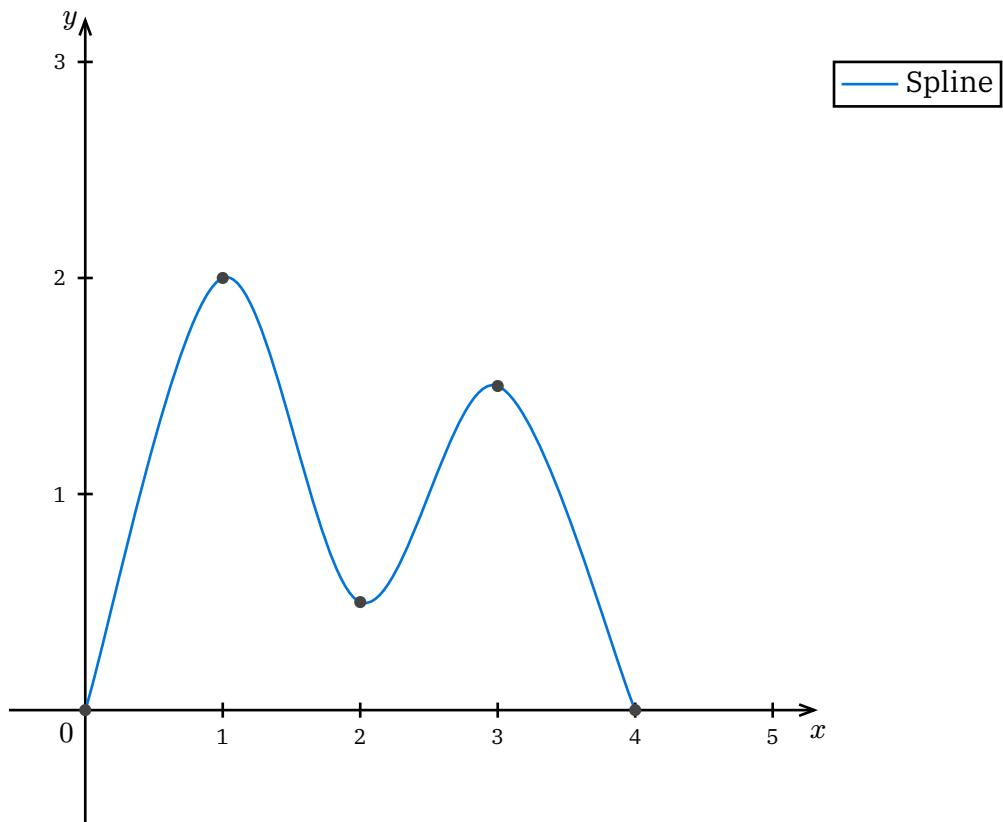
1.6 Curves

Connect points with polylines or smooth splines:

1.6.1 Polyline (curve-through)

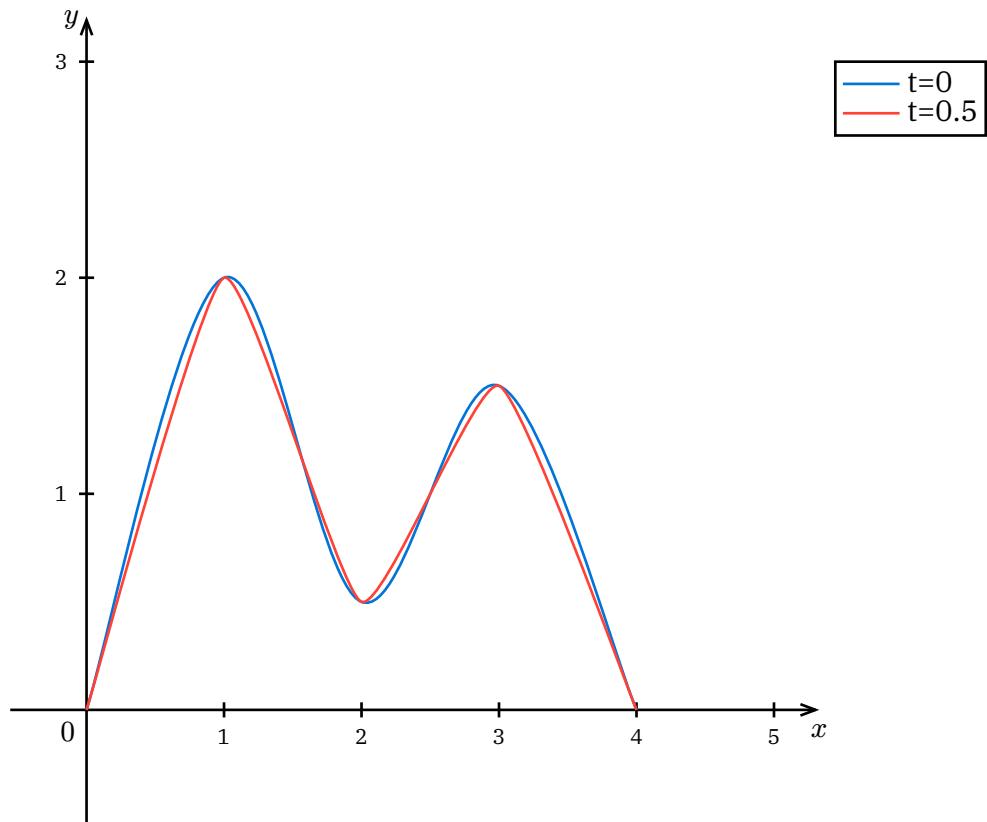


1.6.2 Smooth Spline (smooth-curve)



1.6.3 Tension Control

Higher tension creates tighter curves:



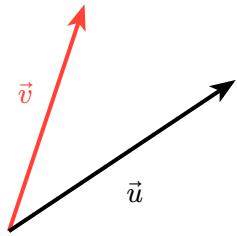
Chapter 02.03

Vectors (Vectorplot)

1 Vectors (Vectorplot)

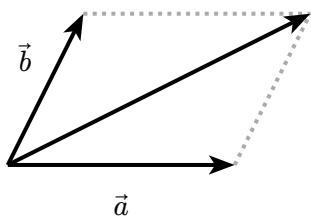
Visualize vectors with automatic scaling and labeling.

1.1 Basic Vectors

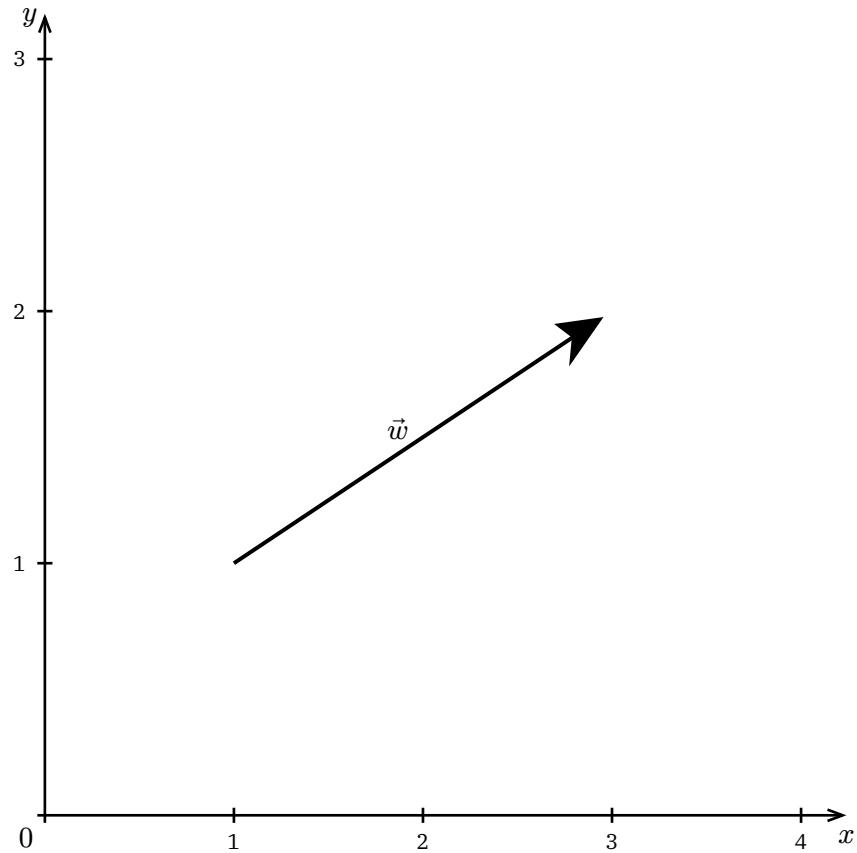


1.2 Vector Addition

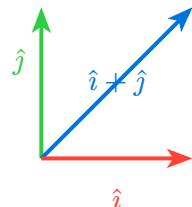
The parallelogram method:



1.3 Vector with Custom Origin

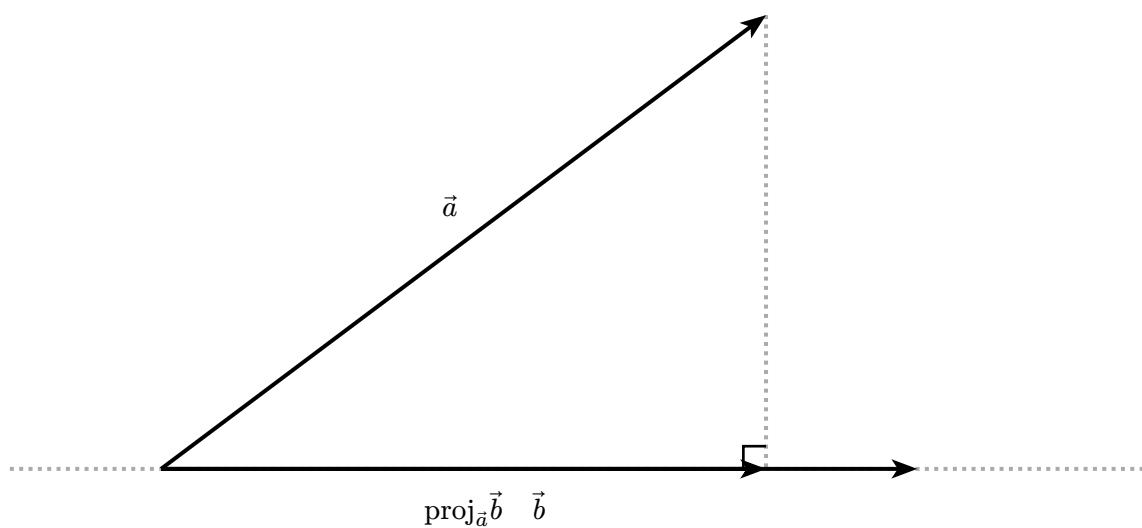


1.4 Multiple Vectors



1.5 Vector Projection

Project vector \vec{a} onto \vec{b} :



NOTE | Vector Notation

Vectors are defined by `vector(dx, dy, ...)` where `dx` and `dy` are the components.

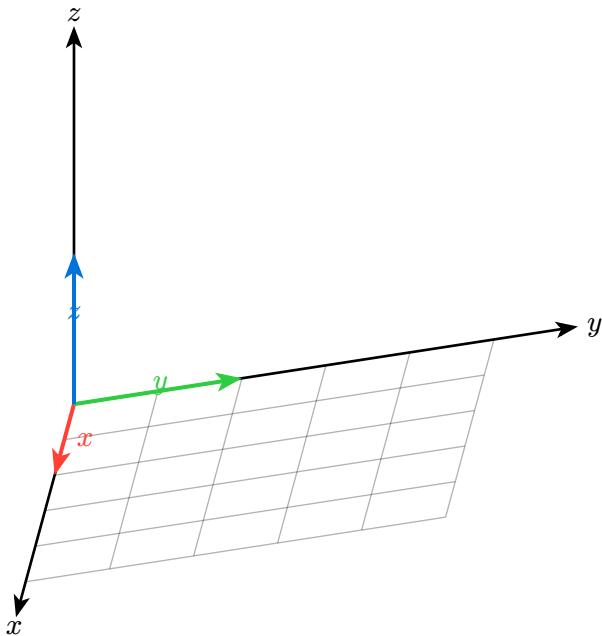
Chapter 02.04

3D Space (*Spaceplot*)

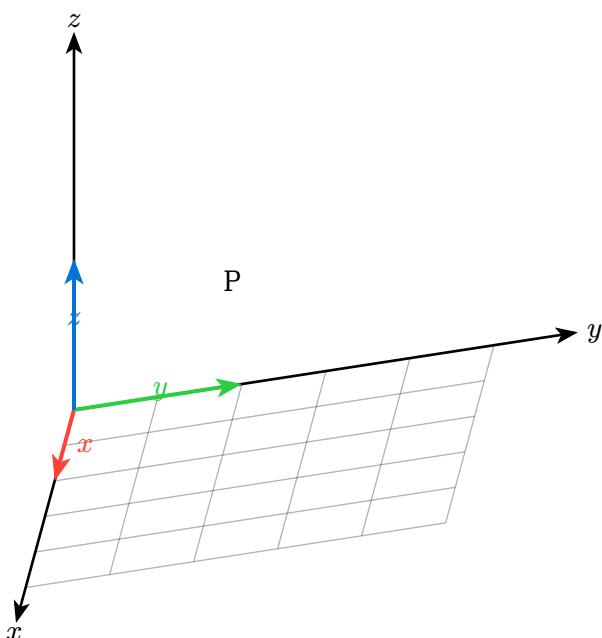
1 3D Space (*Spaceplot*)

Render 3D scenes with perspective projection.

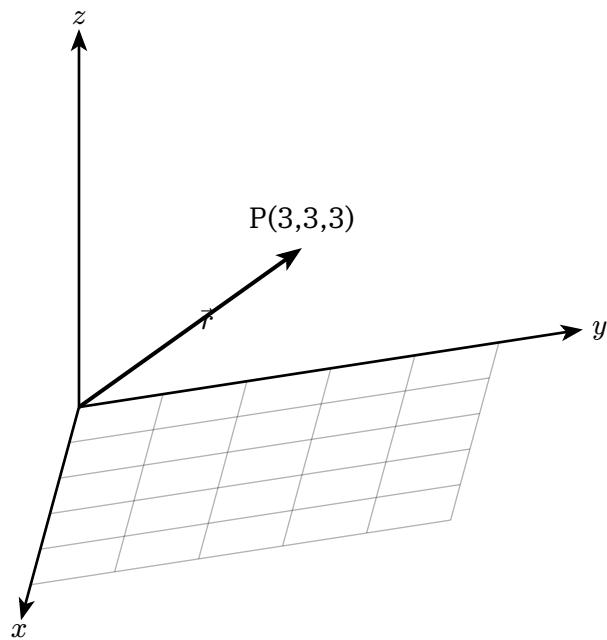
1.1 Coordinate Axes



1.2 3D Points

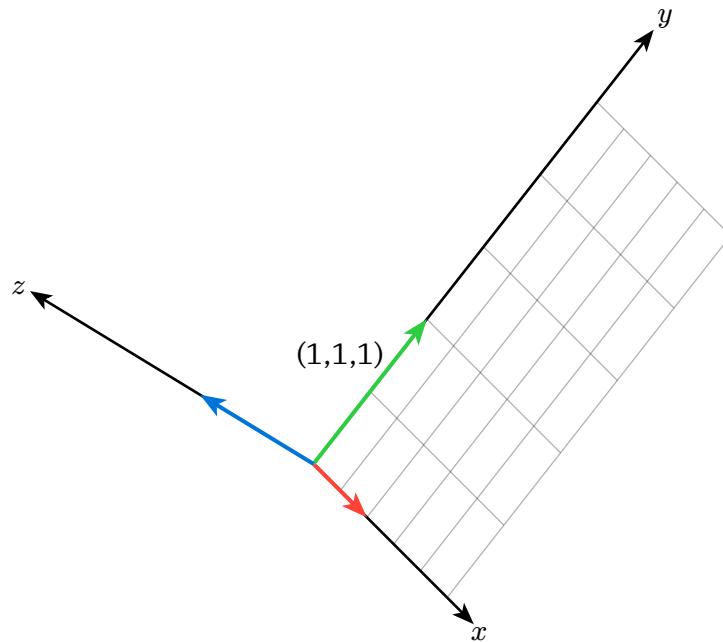


1.3 3D Vectors



1.4 Custom View Angles

Change perspective with the `view` parameter:



NOTE | View Angle

The `view` parameter takes rotation angles for each axis to control the 3D projection.

Chapter 02.05

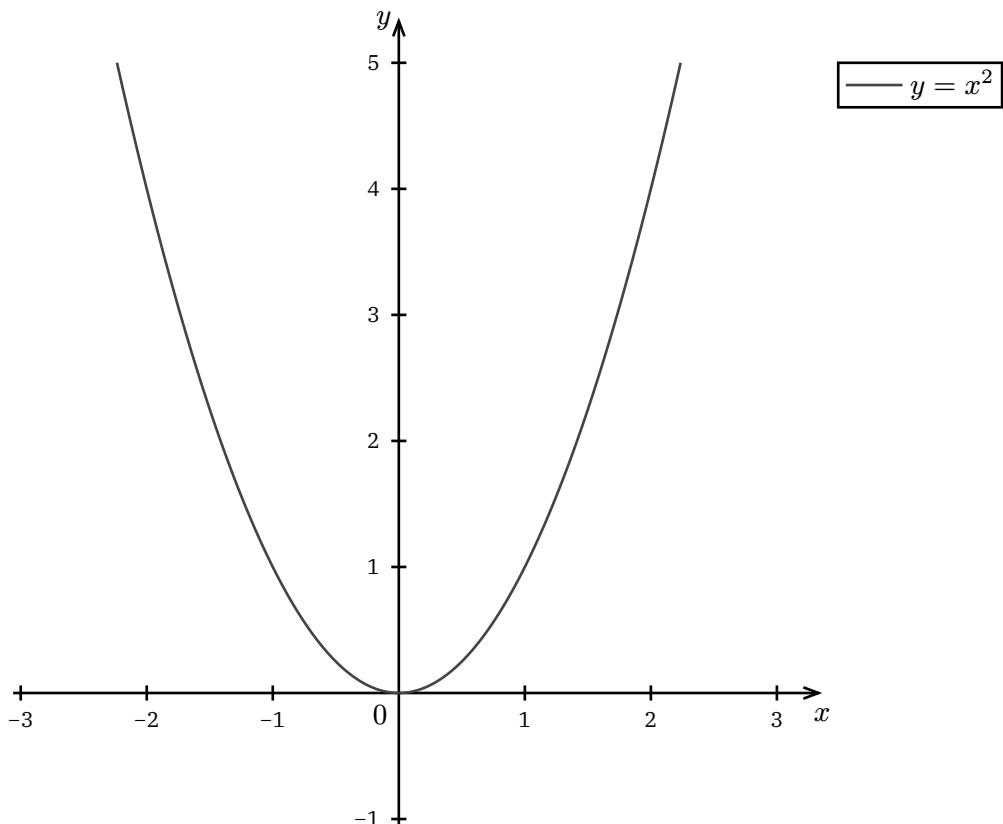
Custom Plots

1 Data Visualization

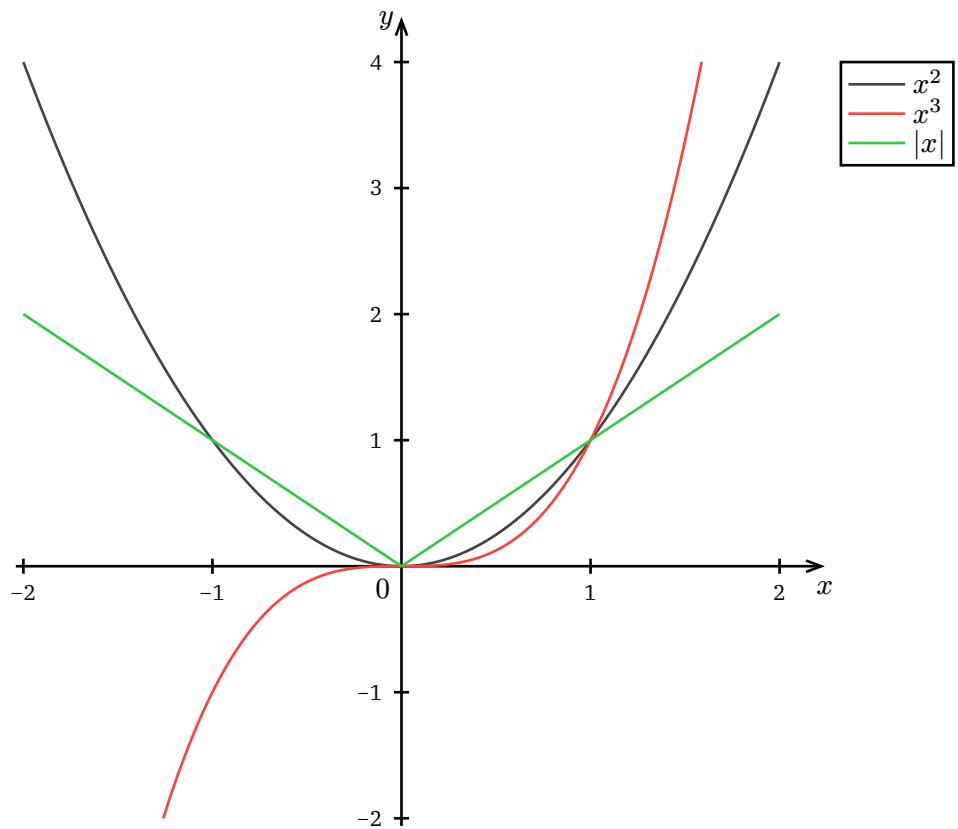
Function plotting and data series.

1.1 Function Graphs

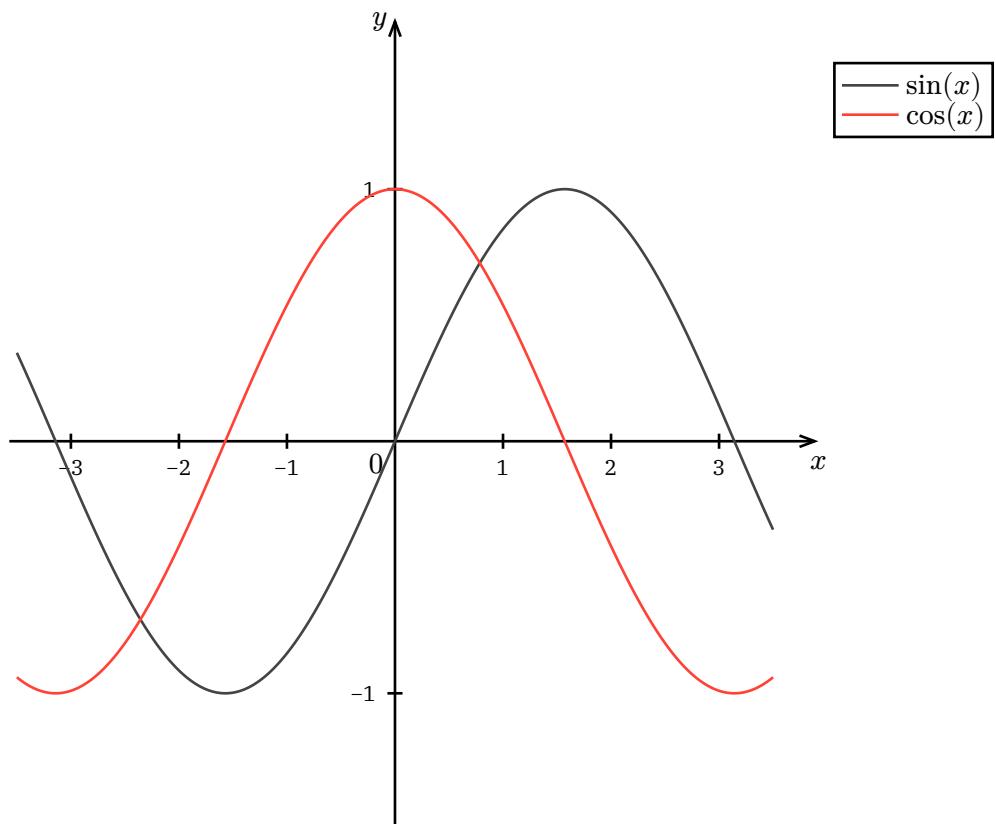
Plot mathematical functions with graph:



1.2 Multiple Functions

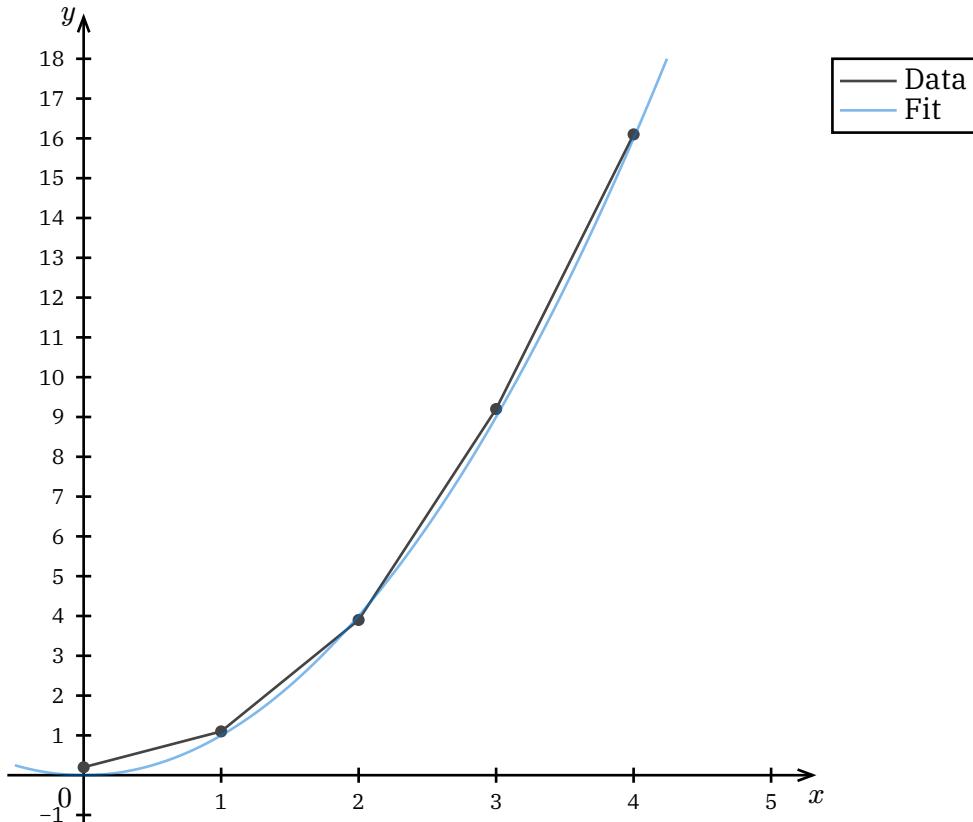


1.3 Trigonometric Functions



1.4 Data Series

Plot data points from arrays:



NOTE | Data Series

Use `data-series(data, plot-type: "scatter" | "line" | "both")` to plot data points.

1.5 CSV Data

Load data from CSV files:

```
#let my-data = csv-series(  
  read("path/to/data.csv"),  
  plot-type: "scatter",  
  has-header: true,  
)
```

This can be then used to draw the data series:

