

Homework 6 Solutions

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Section 11.4, Problem 1: For the boundary-value problem

$$\begin{aligned} y'' &= -(y')^2 - y + \log x, \\ 1 &\leq x \leq 2, \\ y(1) &= 0, \quad y(2) = \log 2, \end{aligned} \tag{1}$$

write the nonlinear system and formulas for Newton's method.

Solution: We divide $[1, 2]$ into $N + 1$ subintervals whose endpoints are $x_i = 1 + ih$, for $i = 0, 1, \dots, N + 1$, and consider the discretization of the boundary-value problem in (1):

$$y''(x_i) = -(y'(x_i))^2 - y(x_i) + \log x_i. \tag{2}$$

Replacing $y''(x_i)$ and $y'(x_i)$ by appropriate centered difference formulas, equation (2) becomes:

$$\frac{y(x_{i+1}) - 2y(x_i) + y(x_{i-1}))}{h^2} - \frac{h^2}{12}y^{(4)}(\xi_i) = -\left(\frac{y(x_{i+1}) - y(x_{i-1}))}{2h} - \frac{h^2}{6}y'''(\eta_i)\right)^2 - y(x_i) + \log x_i,$$

for some ξ_i and η_i in the interval (x_{i-1}, x_{i+1}) .

The difference method results when the error terms are deleted and the boundary conditions are employed:

$$w_0 = 0, \quad w_{N+1} = \log 2,$$

and

$$-\frac{w_{i+1} - 2w_i + w_{i-1}}{h^2} - \left(\frac{w_{i+1} - w_{i-1}}{2h}\right)^2 - w_i + \log x_i = 0, \tag{3}$$

for each $i = 1, 2, \dots, N$. Multiplying (3) by h^2 , we obtain

$$-w_{i+1} + 2w_i - w_{i-1} - \left(\frac{w_{i+1} - w_{i-1}}{2}\right)^2 - h^2w_i + h^2\log x_i = 0,$$

which can be written as:

$$-w_{i+1} + 2w_i - w_{i-1} - \left(\frac{w_{i+1} - w_{i-1}}{2}\right)^2 - h^2w_i + h^2\log x_i = 0,$$

or

$$-w_{i-1} + 2w_i - w_{i+1} - \frac{1}{4}(w_{i-1}^2 - 2w_{i-1}w_{i+1} + w_{i+1}^2) - h^2w_i + h^2\log x_i = 0.$$

Thus, the $N \times N$ nonlinear system is:

$$\begin{aligned}
-0 + 2w_1 - w_2 - \frac{1}{4}(0^2 - 2 \cdot 0 \cdot w_2 + w_2^2) - h^2 w_1 + h^2 \log x_1 &= 0, \\
-w_1 + 2w_2 - w_3 - \frac{1}{4}(w_1^2 - 2w_1 w_3 + w_3^2) - h^2 w_2 + h^2 \log x_2 &= 0, \\
-w_2 + 2w_3 - w_4 - \frac{1}{4}(w_2^2 - 2w_2 w_4 + w_4^2) - h^2 w_3 + h^2 \log x_3 &= 0, \\
&\vdots \\
-w_{N-2} + 2w_{N-1} - w_N - \frac{1}{4}(w_{N-2}^2 - 2w_{N-2} w_N + w_N^2) - h^2 w_{N-1} + h^2 \log x_{N-1} &= 0, \\
-w_{N-1} + 2w_N - \log 2 - \frac{1}{4}(w_{N-1}^2 - 2w_{N-1} \log 2 + (\log 2)^2) - h^2 w_N + h^2 \log x_N &= 0,
\end{aligned}$$

where we designate the left-hand side of the first equation as $F_1(w_1, \dots, w_N)$, the second equation as $F_2(w_1, \dots, w_N)$, ..., the last equation as $F_N(w_1, \dots, w_N)$. Also, we designate $\vec{F} = (F_1, \dots, F_N)^T$ and $\vec{w} = (w_1, \dots, w_N)^T$.

We use Newton's method for nonlinear systems to approximate the solution to the system $\vec{F}(\vec{w}) = 0$ above. A sequence of iterates $\vec{w}^{(k)} = (w_1^{(k)}, w_2^{(k)}, \dots, w_N^{(k)})^T$ is generated that converges to the solution of this system. The Jacobian matrix J for this system is

$$J(w_1, \dots, w_N) = \begin{bmatrix} \frac{\partial F_1}{\partial w_1} & \frac{\partial F_1}{\partial w_2} & \frac{\partial F_1}{\partial w_3} & \dots & \frac{\partial F_1}{\partial w_N} \\ \frac{\partial F_2}{\partial w_1} & \frac{\partial F_2}{\partial w_2} & \frac{\partial F_2}{\partial w_3} & \dots & \frac{\partial F_2}{\partial w_N} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ \frac{\partial F_{N-1}}{\partial w_1} & \frac{\partial F_{N-1}}{\partial w_2} & \frac{\partial F_{N-1}}{\partial w_3} & \dots & \frac{\partial F_{N-1}}{\partial w_N} \\ \frac{\partial F_N}{\partial w_1} & \frac{\partial F_N}{\partial w_2} & \frac{\partial F_N}{\partial w_3} & \dots & \frac{\partial F_N}{\partial w_N} \end{bmatrix}$$

$$= \begin{bmatrix} 2 - h^2 & -1 + \frac{1}{2} \cdot 0 - \frac{1}{2} w_2 & 0 & \dots & 0 \\ -1 - \frac{1}{2} w_1 + \frac{1}{2} w_3 & 2 - h^2 & -1 + \frac{1}{2} w_1 - \frac{1}{2} w_3 & \ddots & \vdots \\ 0 & & & & \vdots \\ \vdots & & & \ddots & \vdots \\ \vdots & & & & 0 \\ \vdots & \ddots & -1 - \frac{1}{2} w_{N-2} + \frac{1}{2} w_N & 2 - h^2 & -1 + \frac{1}{2} w_{N-2} - \frac{1}{2} w_N \\ 0 & 0 & 0 & \dots & 2 - h^2 \end{bmatrix}.$$

We can now use the Newton's method for nonlinear systems

$$\vec{w}^{(k)} = \vec{w}^{(k-1)} - J^{-1}(\vec{w}^{(k-1)}) \vec{F}(\vec{w}^{(k-1)}).$$

Section 7.1, Problem 1: Find $\|\mathbf{x}\|_\infty$ and $\|\mathbf{x}\|_2$ for the following vectors:

a) $\mathbf{x} = (3, -4, 0, \frac{3}{2})^T$;

c) $\mathbf{x} = (\sin k, \cos k, 2^k)^T$ for a fixed positive integer k .

Solution: The L_∞ and L_2 norms for the vector $\mathbf{x} = (x_1, x_2, \dots, x_n)^T$ are defined by

$$\|\mathbf{x}\|_\infty = \max_{1 \leq i \leq n} |x_i|,$$

$$\|\mathbf{x}\|_2 = \left\{ \sum_{i=1}^n x_i^2 \right\}^{\frac{1}{2}}.$$

a) For $\mathbf{x} = (3, -4, 0, \frac{3}{2})^T$:

$$\|\mathbf{x}\|_\infty = \max \left\{ |3|, |-4|, |0|, \left| \frac{3}{2} \right| \right\} = 4,$$

$$\|\mathbf{x}\|_2 = \sqrt{3^2 + (-4)^2 + 0^2 + \left(\frac{3}{2}\right)^2} = 5.22015325.$$

c) For $\mathbf{x} = (\sin k, \cos k, 2^k)^T$, k is a positive integer :

$$\|\mathbf{x}\|_\infty = \max \{ |\sin k|, |\cos k|, |2^k| \} = 2^k,$$

$$\|\mathbf{x}\|_2 = \sqrt{\sin^2 k + \cos^2 k + (2^k)^2} = \sqrt{1 + 4^k}.$$

Section 7.1, Problem 2(a): Verify that the function $\|\cdot\|_1$, defined on \mathbb{R}^n by

$$\|\mathbf{x}\|_1 = \sum_{i=1}^n |x_i|,$$

is a norm on \mathbb{R}^n .

Solution:

(i) For all $\mathbf{x} \in \mathbb{R}^n$,

$$\|\mathbf{x}\|_1 = \sum_{i=1}^n |x_i| \geq 0. \quad \checkmark$$

(ii) If $\mathbf{x} = \mathbf{0}$, then

$$\|\mathbf{x}\|_1 = \sum_{i=1}^n |x_i| = \sum_{i=1}^n 0 = 0. \quad \checkmark$$

If $\|\mathbf{x}\|_1 = 0$, we have $\sum_{i=1}^n |x_i| = 0$, and thus, $\mathbf{x} = \mathbf{0}$. \checkmark

(iii) For all $\alpha \in \mathbb{R}$ and $\mathbf{x} \in \mathbb{R}^n$,

$$\|\alpha \mathbf{x}\|_1 = \sum_{i=1}^n |\alpha x_i| = \sum_{i=1}^n |\alpha| |x_i| = |\alpha| \sum_{i=1}^n |x_i| = |\alpha| \|\mathbf{x}\|_1. \quad \checkmark$$

(iii) For all $\mathbf{x}, \mathbf{y} \in \mathbb{R}^n$,

$$\|\mathbf{x} + \mathbf{y}\|_1 = \sum_{i=1}^n |x_i + y_i| \leq \sum_{i=1}^n (|x_i| + |y_i|) = \sum_{i=1}^n |x_i| + \sum_{i=1}^n |y_i| = \|\mathbf{x}\|_1 + \|\mathbf{y}\|_1. \quad \checkmark$$

Thus, $\|\cdot\|_1$ is a norm on \mathbb{R}^n .

Section 7.1, Problem 2(c): Prove that for all $\mathbf{x} \in \mathbb{R}^n$, $\|\mathbf{x}\|_1 \geq \|\mathbf{x}\|_2$.

Solution: Let $\mathbf{x} = (x_1, x_2, \dots, x_n)^T$, and note that

$$(|x_1| + |x_2| + \dots + |x_n|)^2 \geq x_1^2 + x_2^2 + \dots + x_n^2,$$

or

$$\left(\sum_{i=1}^n |x_i| \right)^2 \geq \sum_{i=1}^n x_i^2,$$

or

$$\sum_{i=1}^n |x_i| \geq \left(\sum_{i=1}^n x_i^2 \right)^{\frac{1}{2}},$$

which means that $\|\mathbf{x}\|_1 \geq \|\mathbf{x}\|_2$.

Section 7.1, Problem 4(c): Find $\|\cdot\|_\infty$ for the following matrix:

$$A = \begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{bmatrix}.$$

Solution: We have

$$\|A\|_\infty = \max_{1 \leq i \leq n} \sum_{j=1}^n |a_{ij}|.$$

Since

$$\begin{aligned} \sum_{j=1}^n |a_{1j}| &= |a_{11}| + |a_{12}| + |a_{13}| = |2| + |-1| + |0| = 3, \\ \sum_{j=1}^n |a_{2j}| &= |a_{21}| + |a_{22}| + |a_{23}| = |-1| + |2| + |-1| = 4, \\ \sum_{j=1}^n |a_{3j}| &= |a_{31}| + |a_{32}| + |a_{33}| = |0| + |-1| + |2| = 3, \end{aligned}$$

we have $\|A\|_\infty = \max\{3, 4, 3\} = 4$.

Section 7.1, Problem 7: Show by example that $\|\cdot\|_\otimes$, defined by $\|A\|_\otimes = \max_{1 \leq i, j \leq n} |a_{ij}|$, does not define a matrix norm.

Solution: A function $\|\cdot\|_\otimes$ is a matrix norm only if it satisfies definition 7.8 on page 424. Consider $A = \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix}$ and $B = \begin{bmatrix} 1 & 0 \\ 1 & 0 \end{bmatrix}$. Then, $AB = \begin{bmatrix} 2 & 0 \\ 0 & 0 \end{bmatrix}$. We have $\|A\|_\otimes = 1$, $\|B\|_\otimes = 1$, and $\|AB\|_\otimes = 2$, and thus, $\|AB\|_\otimes \geq \|A\|_\otimes \|B\|_\otimes$, which contradicts one of the conditions for being a norm.

Section 7.1, Problem 9(a): The Frobenius norm (which is not a natural norm) is defined for an $n \times n$ matrix A by

$$\|A\|_F = \left(\sum_{i=1}^n \sum_{j=1}^n |a_{ij}|^2 \right)^{\frac{1}{2}}.$$

Show that $\|\cdot\|_F$ is a matrix norm.

Solution: For all $n \times n$ matrices A and B and all real numbers α , we have:

(i)

$$\|A\|_F = \left(\sum_{i=1}^n \sum_{j=1}^n |a_{ij}|^2 \right)^{\frac{1}{2}} \geq 0. \quad \checkmark$$

(ii)

$$\|A\|_F = \left(\sum_{i=1}^n \sum_{j=1}^n |a_{ij}|^2 \right)^{\frac{1}{2}} = 0 \quad \text{if and only if } A \text{ is a 0 matrix.} \quad \checkmark$$

(iii)

$$\begin{aligned} \|\alpha A\|_F^2 &= \sum_{i=1}^n \sum_{j=1}^n |\alpha a_{ij}|^2 = \sum_{i=1}^n \sum_{j=1}^n |\alpha|^2 |a_{ij}|^2 = |\alpha|^2 \sum_{i=1}^n \sum_{j=1}^n |a_{ij}|^2 = |\alpha|^2 \|A\|_F^2. \\ \Rightarrow \|\alpha A\|_F &= |\alpha| \|A\|_F. \quad \checkmark \end{aligned}$$

(iv) Here, we will use Cauchy-Schwarz Inequality: $\sum_{i=1}^n x_i y_i \leq \left(\sum_{i=1}^n x_i^2 \right)^{\frac{1}{2}} \left(\sum_{i=1}^n y_i^2 \right)^{\frac{1}{2}}.$

$$\begin{aligned} \|A+B\|_F^2 &= \sum_{i=1}^n \sum_{j=1}^n |a_{ij} + b_{ij}|^2 \\ &\leq \sum_{i=1}^n \sum_{j=1}^n (|a_{ij}| + |b_{ij}|)^2 \\ &= \sum_{i=1}^n \sum_{j=1}^n (|a_{ij}|^2 + 2|a_{ij}||b_{ij}| + |b_{ij}|^2) \\ &= \sum_{i=1}^n \sum_{j=1}^n |a_{ij}|^2 + 2 \sum_{i=1}^n \sum_{j=1}^n |a_{ij}||b_{ij}| + \sum_{i=1}^n \sum_{j=1}^n |b_{ij}|^2 \leq \quad (\text{Cauchy-Schwarz}) \\ &\leq \sum_{i=1}^n \sum_{j=1}^n |a_{ij}|^2 + 2 \left(\sum_{i=1}^n \sum_{j=1}^n |a_{ij}|^2 \right)^{\frac{1}{2}} \left(\sum_{i=1}^n \sum_{j=1}^n |b_{ij}|^2 \right)^{\frac{1}{2}} + \sum_{i=1}^n \sum_{j=1}^n |b_{ij}|^2 \\ &= \left(\left(\sum_{i=1}^n \sum_{j=1}^n |a_{ij}|^2 \right)^{\frac{1}{2}} + \left(\sum_{i=1}^n \sum_{j=1}^n |b_{ij}|^2 \right)^{\frac{1}{2}} \right)^2 \\ &= (\|A\|_F + \|B\|_F)^2. \\ \Rightarrow \|A+B\|_F &\leq \|A\|_F + \|B\|_F. \quad \checkmark \end{aligned}$$

(v) Note that

$$AB = \begin{bmatrix} \sum_{k=1}^n a_{1k}b_{k1} & \sum_{k=1}^n a_{1k}b_{k2} & \cdots & \cdots & \sum_{k=1}^n a_{1k}b_{kn} \\ \sum_{k=1}^n a_{2k}b_{k1} & \sum_{k=1}^n a_{2k}b_{k2} & \cdots & \cdots & \sum_{k=1}^n a_{2k}b_{kn} \\ \vdots & \vdots & & & \vdots \\ \vdots & \vdots & & & \vdots \\ \sum_{k=1}^n a_{nk}b_{k1} & \sum_{k=1}^n a_{nk}b_{k2} & \cdots & \sum_{k=1}^n a_{nk}b_{k,n-1} & \sum_{k=1}^n a_{nk}b_{kn} \end{bmatrix}.$$

$$\begin{aligned}
\|AB\|_F^2 &= \sum_{i=1}^n \sum_{j=1}^n \left| \sum_{k=1}^n a_{ik} b_{kj} \right|^2 \leq \sum_{i=1}^n \sum_{j=1}^n \left(\sum_{k=1}^n |a_{ik} b_{kj}| \right)^2 \leq \quad (\text{Cauchy-Schwarz}) \\
&\leq \sum_{i=1}^n \sum_{j=1}^n \left(\sum_{k=1}^n |a_{ik}|^2 \sum_{k=1}^n |b_{kj}|^2 \right) \dots \\
&\leq \left(\sum_{i=1}^n \sum_{j=1}^n |a_{ij}|^2 \right) \left(\sum_{i=1}^n \sum_{j=1}^n |b_{ij}|^2 \right) = \|A\|_F^2 \|B\|_F^2. \\
\Rightarrow \quad \|AB\|_F &\leq \|A\|_F \|B\|_F. \quad \checkmark
\end{aligned}$$

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Section 7.1, Problem 9(c): For any matrix A , show that $\|A\|_2 \leq \|A\|_F \leq n^{1/2}\|A\|_2$.

Solution: The definitions of $\|\cdot\|_F$ and $\|\cdot\|_2$ norms are:

$$\|A\|_F = \left(\sum_{i=1}^n \sum_{j=1}^n |a_{ij}|^2 \right)^{\frac{1}{2}}.$$

$$\|A\|_2 = \max_{\|\mathbf{x}\|_2=1} \|A\mathbf{x}\|_2.$$

Note, that $A\mathbf{x}$ is a vector:

$$A\mathbf{x} = \begin{bmatrix} \sum_{j=1}^n a_{1j}x_j \\ \sum_{j=1}^n a_{2j}x_j \\ \vdots \\ \sum_{j=1}^n a_{nj}x_j \end{bmatrix}.$$

Thus, we have

$$\|A\mathbf{x}\|_2 = \left(\sum_{i=1}^n \left(\sum_{j=1}^n a_{ij}x_j \right)^2 \right)^{\frac{1}{2}}.$$

❶ We first show that $\|A\|_2 \leq \|A\|_F$.

For vector \mathbf{x} , such that $\|\mathbf{x}\|_2 = 1$, we have

$$\begin{aligned} \|A\mathbf{x}\|_2^2 &= \sum_{i=1}^n \left(\sum_{j=1}^n a_{ij}x_j \right)^2 \leq \quad (\text{Cauchy-Schwarz}) \\ &\leq \sum_{i=1}^n \left(\left(\sum_{j=1}^n a_{ij}^2 \right)^{\frac{1}{2}} \left(\sum_{j=1}^n x_j^2 \right)^{\frac{1}{2}} \right)^2 \\ &= \sum_{i=1}^n \left(\left(\sum_{j=1}^n a_{ij}^2 \right) \left(\sum_{j=1}^n x_j^2 \right) \right) \\ &= \sum_{i=1}^n \left(\sum_{j=1}^n a_{ij}^2 \right) \cdot \|\mathbf{x}\|_2^2 \\ &= \sum_{i=1}^n \left(\sum_{j=1}^n a_{ij}^2 \right) \cdot 1 \\ &= \sum_{i=1}^n \sum_{j=1}^n a_{ij}^2 \\ &= \|A\|_F^2. \end{aligned}$$

We showed that, $\|A\mathbf{x}\|_2 \leq \|A\|_F$ for all \mathbf{x} , such that $\|\mathbf{x}\|_2 = 1$.

Thus, $\max_{\|\mathbf{x}\|_2=1} \|A\mathbf{x}\|_2 \leq \|A\|_F$, or $\|A\|_2 \leq \|A\|_F$.

❷ We now show that $\|A\|_F \leq n^{1/2}\|A\|_2$.

Let $x_i = \frac{1}{\sqrt{n}}$ for all $1 \leq i \leq n$. Then,

$$\|A\|_2 = \max_{\|\mathbf{x}\|_2=1} \|A\mathbf{x}\|_2 = \sum_{i=1}^n \left(\sum_{j=1}^n a_{ij}x_j \right)^2 = \sum_{i=1}^n \sum_{j=1}^n a_{ij}^2 \frac{1}{n} = \frac{1}{n} \sum_{i=1}^n \sum_{j=1}^n a_{ij}^2 = \frac{1}{n} \|A\|_F^2.$$

Thus, $\|A\|_F \leq n^{1/2}\|A\|_2$.

Section 7.3, Problem 2(c): Find the first two iterations of the Jacobi method for the following linear system, using $\mathbf{x}^{(0)} = \mathbf{0}$:

$$\begin{aligned} 4x_1 + x_2 - x_3 + x_4 &= -2, \\ x_1 + 4x_2 - x_3 - x_4 &= -1, \\ -x_1 - x_2 + 5x_3 + x_4 &= 0, \\ x_1 - x_2 + x_3 + 3x_4 &= 1. \end{aligned}$$

Solution: The linear system $A\mathbf{x} = \mathbf{b}$ given by

$$\begin{aligned} E_1 : \quad 4x_1 + x_2 - x_3 + x_4 &= -2, \\ E_2 : \quad x_1 + 4x_2 - x_3 - x_4 &= -1, \\ E_3 : \quad -x_1 - x_2 + 5x_3 + x_4 &= 0, \\ E_4 : \quad x_1 - x_2 + x_3 + 3x_4 &= 1 \end{aligned}$$

has the unique solution $\mathbf{x} = (-0.75342, 0.041096, -0.28082, 0.69178)$.

To convert $A\mathbf{x} = \mathbf{b}$ to the form $\mathbf{x} = T\mathbf{x} + \mathbf{c}$, solve equation E_1 for x_1 , E_2 for x_2 , E_3 for x_3 , E_4 for x_4 , to obtain

$$\begin{aligned} x_1 &= -\frac{1}{4}x_2 + \frac{1}{4}x_3 - \frac{1}{4}x_4 - \frac{1}{2}, \\ x_2 &= -\frac{1}{4}x_1 + \frac{1}{4}x_3 + \frac{1}{4}x_4 - \frac{1}{4}, \\ x_3 &= \frac{1}{5}x_1 + \frac{1}{5}x_2 - \frac{1}{5}x_4, \\ x_4 &= -\frac{1}{3}x_1 + \frac{1}{3}x_2 - \frac{1}{3}x_3 + \frac{1}{3}. \end{aligned}$$

Then $A\mathbf{x} = \mathbf{b}$ can be written in the form $\mathbf{x} = T\mathbf{x} + \mathbf{c}$, with

$$T = \begin{bmatrix} 0 & -\frac{1}{4} & \frac{1}{4} & -\frac{1}{4} \\ -\frac{1}{4} & 0 & \frac{1}{4} & \frac{1}{4} \\ \frac{1}{5} & \frac{1}{5} & 0 & -\frac{1}{5} \\ -\frac{1}{3} & \frac{1}{3} & -\frac{1}{3} & 0 \end{bmatrix} \quad \text{and} \quad \mathbf{c} = \begin{bmatrix} -\frac{1}{2} \\ -\frac{1}{4} \\ 0 \\ \frac{1}{3} \end{bmatrix}.$$

For initial approximation, we let $\mathbf{x}^{(0)} = (0, 0, 0, 0)^T$. Then $\mathbf{x}^{(1)}$ is given by

$$\begin{aligned} x_1^{(1)} &= -\frac{1}{4}x_2^{(0)} + \frac{1}{4}x_3^{(0)} - \frac{1}{4}x_4^{(0)} - \frac{1}{2} = -0.5, \\ x_2^{(1)} &= -\frac{1}{4}x_1^{(0)} + \frac{1}{4}x_3^{(0)} + \frac{1}{4}x_4^{(0)} - \frac{1}{4} = -0.25, \\ x_3^{(1)} &= \frac{1}{5}x_1^{(0)} + \frac{1}{5}x_2^{(0)} - \frac{1}{5}x_4^{(0)} = 0, \\ x_4^{(1)} &= -\frac{1}{3}x_1^{(0)} + \frac{1}{3}x_2^{(0)} - \frac{1}{3}x_3^{(0)} + \frac{1}{3} = 1/3. \end{aligned}$$

The next iterate, $\mathbf{x}^{(2)}$, is given by

$$\begin{aligned} x_1^{(2)} &= -\frac{1}{4}x_2^{(1)} + \frac{1}{4}x_3^{(1)} - \frac{1}{4}x_4^{(1)} - \frac{1}{2} = -0.52083, \\ x_2^{(2)} &= -\frac{1}{4}x_1^{(1)} + \frac{1}{4}x_3^{(1)} + \frac{1}{4}x_4^{(1)} - \frac{1}{4} = -0.041667, \\ x_3^{(2)} &= \frac{1}{5}x_1^{(1)} + \frac{1}{5}x_2^{(1)} - \frac{1}{5}x_4^{(1)} = -0.21667, \\ x_4^{(2)} &= -\frac{1}{3}x_1^{(1)} + \frac{1}{3}x_2^{(1)} - \frac{1}{3}x_3^{(1)} + \frac{1}{3} = 0.41667. \end{aligned}$$

Section 7.3, Problem 4(c): Find the first two iterations of the Gauss-Seidel method for the following linear system, using $\mathbf{x}^{(0)} = \mathbf{0}$:

$$\begin{aligned} 4x_1 + x_2 - x_3 + x_4 &= -2, \\ x_1 + 4x_2 - x_3 - x_4 &= -1, \\ -x_1 - x_2 + 5x_3 + x_4 &= 0, \\ x_1 - x_2 + x_3 + 3x_4 &= 1. \end{aligned}$$

Solution: In section 7.3, Problem 2(c), we used Jacobi method to solve the linear system above. The following equations were used:

$$\begin{aligned} x_1^{(k)} &= -\frac{1}{4}x_2^{(k-1)} + \frac{1}{4}x_3^{(k-1)} - \frac{1}{4}x_4^{(k-1)} - \frac{1}{2}, \\ x_2^{(k)} &= -\frac{1}{4}x_1^{(k-1)} + \frac{1}{4}x_3^{(k-1)} + \frac{1}{4}x_4^{(k-1)} - \frac{1}{4}, \\ x_3^{(k)} &= \frac{1}{5}x_1^{(k-1)} + \frac{1}{5}x_2^{(k-1)} - \frac{1}{5}x_4^{(k-1)}, \\ x_4^{(k)} &= -\frac{1}{3}x_1^{(k-1)} + \frac{1}{3}x_2^{(k-1)} - \frac{1}{3}x_3^{(k-1)} + \frac{1}{3}. \end{aligned}$$

However, since for $i > 1$, $x_1^{(k)}, \dots, x_{i-1}^{(k)}$ have already been computed, these are probably better approximations to the actual solutions x_1, \dots, x_{i-1} than $x_1^{(k-1)}, \dots, x_{i-1}^{(k-1)}$. Hence, Gauss-Seidel uses the most recently available approximations to x_1, \dots, x_{i-1} in a calculation of the next iterate:

$$\begin{aligned} x_1^{(k)} &= -\frac{1}{4}x_2^{(k-1)} + \frac{1}{4}x_3^{(k-1)} - \frac{1}{4}x_4^{(k-1)} - \frac{1}{2}, \\ x_2^{(k)} &= -\frac{1}{4}x_1^{(k)} + \frac{1}{4}x_3^{(k-1)} + \frac{1}{4}x_4^{(k-1)} - \frac{1}{4}, \\ x_3^{(k)} &= \frac{1}{5}x_1^{(k)} + \frac{1}{5}x_2^{(k)} - \frac{1}{5}x_4^{(k-1)}, \\ x_4^{(k)} &= -\frac{1}{3}x_1^{(k)} + \frac{1}{3}x_2^{(k)} - \frac{1}{3}x_3^{(k)} + \frac{1}{3}. \end{aligned}$$

For initial approximation, we let $\mathbf{x}^{(0)} = (0, 0, 0, 0)^T$. Then $\mathbf{x}^{(1)}$ is given by

$$\begin{aligned} x_1^{(1)} &= -\frac{1}{4}x_2^{(0)} + \frac{1}{4}x_3^{(0)} - \frac{1}{4}x_4^{(0)} - \frac{1}{2} = -0.5, \\ x_2^{(1)} &= -\frac{1}{4}x_1^{(1)} + \frac{1}{4}x_3^{(0)} + \frac{1}{4}x_4^{(0)} - \frac{1}{4} = -0.125, \\ x_3^{(1)} &= \frac{1}{5}x_1^{(1)} + \frac{1}{5}x_2^{(1)} - \frac{1}{5}x_4^{(0)} = -0.125, \\ x_4^{(1)} &= -\frac{1}{3}x_1^{(1)} + \frac{1}{3}x_2^{(1)} - \frac{1}{3}x_3^{(1)} + \frac{1}{3} = 0.5. \end{aligned}$$

The next iterate, $\mathbf{x}^{(2)}$, is given by

$$\begin{aligned} x_1^{(2)} &= -\frac{1}{4}x_2^{(1)} + \frac{1}{4}x_3^{(1)} - \frac{1}{4}x_4^{(1)} - \frac{1}{2} = -0.625, \\ x_2^{(2)} &= -\frac{1}{4}x_1^{(2)} + \frac{1}{4}x_3^{(1)} + \frac{1}{4}x_4^{(1)} - \frac{1}{4} = 0, \\ x_3^{(2)} &= \frac{1}{5}x_1^{(2)} + \frac{1}{5}x_2^{(2)} - \frac{1}{5}x_4^{(1)} = -0.225, \\ x_4^{(2)} &= -\frac{1}{3}x_1^{(2)} + \frac{1}{3}x_2^{(2)} - \frac{1}{3}x_3^{(2)} + \frac{1}{3} = 0.61667. \end{aligned}$$

Comparing $\mathbf{x}^{(2)}$ to the exact solution $\mathbf{x} = (-0.75342, 0.041096, -0.28082, 0.69178)$, we see that Gauss-Seidel method gave more accurate results than Jacobi method.