

Quantitative Finance.

2. 条件期望: conditional expectation:

↓
条件分布的期望)

↓ one random variable takes a specific value

$$f_{Y|X}(y|x=2)$$

• conditional variance;

3. Expected Value:

$$E(X) = \sum P(x_i) x_i$$

$$\rightarrow [E(X)]^2 \neq E(X^2)$$

$$\rightarrow \text{Variance: } \sigma^2(x) = E(X^2) - [E(x)]^2$$

$$\rightarrow E(X+Y) = E(X) + E(Y)$$

$$\rightarrow \text{generally, } E(XY) \neq E(X)E(Y)$$

if X and Y are independent, $E(XY) = E(X)E(Y)$

4. Median: (50% Quantile)

$$\cdot \text{odd median } (x) = x_{(\frac{n+1}{2})}$$

$$\cdot \text{even median } (x) = \frac{1}{2} [x_{(\frac{n}{2})} + x_{(\frac{n}{2}+1)}]$$

5. 25% Quantile, 75% Quantiles:

① sorted

$$\textcircled{2} \text{ unit interval} = \frac{100\%}{(n-1)}$$

③ Interpretation. (linear)

$$\widehat{IQR} = \widehat{q}_{75} - \widehat{q}_{25}$$

inter-quartile range

6. Variance and Moments

二阶矩: 数据的离散程度
(measure dispersion)

$$\text{定义式: } \sigma_x^2 = E(X-\mu)^2 = E[X-E(x)]^2$$

$$\text{计算式: } \sigma_x^2 = E(X^2) - [E(x)]^2$$

$$\sigma^2(ax+bY) = a^2\sigma^2(x) + b^2\sigma^2(Y) + 2ab\cdot \sigma_x\cdot \sigma_y$$

1. Expectation of a function $g(X, Y)$:

$$E[g(x, y)] = \sum \sum g(x, y) f_{X,Y}(x, y)$$

7. Covariance:

<一个变量随另一变量的变化>

$$\text{Covariance} = E[(X - E(X))(Y - E(Y))]$$

$$= E(XY) - E(X)E(Y)$$

$$\bullet \text{定义式: } E[(X - E(X))(Y - E(Y))]$$

$$\bullet \text{计算式: } E(XY) - E(X)E(Y)$$

$$\bullet (-\infty, +\infty)$$

• relationship between covariance and variance:

$$\rightarrow \sigma^2_{x+y} = \sigma^2_x + \sigma^2_y + 2\text{Cov}(X, Y)$$

$$\rightarrow \text{cov}(ax+bx, Y) = \text{cov}(a, cY) + \text{cov}(bx, cY) \\ = b \times c \times \text{cov}(X, Y)$$

8. Correlation coefficient:

<标准化后的协方差>

$$\rho_{x,y} = \frac{\text{Cov}(X, Y)}{\sigma_x \cdot \sigma_y} = \frac{\sigma_{xy}}{\sigma_x \cdot \sigma_y} = \frac{E[(X-\mu_x)(Y-\mu_y)]}{\sigma_x \cdot \sigma_y}$$

• no unit,

• from $(-1, +1)$

9. Skewness and Moments:

• Skewness 三阶矩 $\begin{matrix} \text{mean} < \text{median} < \text{mode.} \\ \uparrow \end{matrix}$

• 对称性: $\left\{ \begin{array}{l} \text{左偏: } \curvearrowleft \rightarrow \text{极端大的损失.} \\ \text{右偏: } \curvearrowright \rightarrow \text{极端大的收益.} \\ \downarrow \\ \text{mean} > \text{median} > \text{mode.} \end{array} \right.$
 $\rightarrow \left\{ \begin{array}{l} \text{正偏: positive-skewed.} \\ \text{负偏: Negative-skewed.} \end{array} \right.$

$$\bullet S = \frac{[E(X-\mu_x)]^3}{\sigma_x^3} \Rightarrow S = \frac{E(X-\mu_x)^3}{\sigma_x^3}$$

10. kurtosis 四阶矩

〈陡峭程度 (尾巴薄厚)〉

measure of tallness or flatness of a PDF

$$k = \frac{E(X - \mu_x)^4}{[E(X - \mu_x)^2]^2}$$

	Excess
• Leptokurtic > 3	> 0
Mesokurtic $= 3$	$= 0$
Platykurtic < 3	< 0

11. Moments and Linear Transformation:

$$Y = a + bX, \quad a, b \text{ constant.}$$

$$\bullet E(Y) = E(a + bX) = a + bE(X)$$

$$\bullet V(Y) = V(a + bX) = b^2 V(X) = b^2 \sigma^2$$

$$\bullet b > 0, \text{Skewness}(x) = \text{Skewness}(Y)$$

$$\text{kurtosis}(x) = \text{kurtosis}(Y)$$

$$b < 0, \text{Skewness}(x) = -\text{Skewness}(Y)$$

$$\text{kurtosis}(x) = \text{kurtosis}(Y)$$

12. the BLUE mean estimator:

{ estimator: 样本数据特点, (\bar{x})
parameter: 总体数据特点, (μ)

① Linear

$$\textcircled{2} \text{ Unbiased: } E(\bar{x}) = \mu \\ E(S_x^2) = \sigma_x^2$$

③ Best: minimum variance (Best)

• The mean estimator is the "Best Linear

Unbiased estimator (BLUE) of the

population mean when the data are iid.

Summary:

- Random variable:

① 定义: 取值不确定的量

② 分类: { discrete
continuous.

③ 多元: probability matrix

④ marginal / conditional distribution. 条件期望,

⑤ Independence: $P(XY) = P(X) \cdot P(Y)$

二. 阶 moment:

① 一阶矩: 中心趋势

1) mean $\left\{ \begin{array}{l} X \left(\frac{n+1}{2} \right) \\ \frac{1}{2}(X_{\left(\frac{n}{2}\right)} + X_{\left(\frac{n}{2}+1\right)}) \end{array} \right.$

3) quantile

50% \rightarrow median

25% $\rightarrow Q_{25\%}$

75% $\rightarrow Q_{75\%}$

$$IQR = Q_{75\%} - Q_{25\%}$$

② 二阶矩: 离散程度

1) Variance: $\left\{ \begin{array}{l} \text{Var}(x) = E(x - \mu)^2 \\ \text{Var}(x) = E(x^2) - E(x)^2 \end{array} \right.$

2) Covariance: $\left\{ \begin{array}{l} \text{Cov}(X, Y) = E[(X - E(X))(Y - E(Y))] \\ \text{Cov}(X, Y) = E(XY) - E(X)E(Y) \end{array} \right.$

3) Correlation coefficient:

$$\rightarrow \rho_{x,y} = \frac{\text{Cov}(X, Y)}{\sigma_x \cdot \sigma_y} = \frac{E(x, y)}{\sigma_x \cdot \sigma_y}$$

\rightarrow linear relationship.

③ 三阶矩: 对称关系:

1) Skewness
定义 $\left\{ \begin{array}{l} \rightarrow \text{左} \curvearrowleft \text{ Left tail.} \\ \rightarrow \text{右} \curvearrowright \text{ right tail} \end{array} \right.$

$\left\{ \begin{array}{l} \rightarrow \text{正: positive tail} \curvearrowleft \text{ (好) 极端大的收益} \\ \rightarrow \text{负: negative tail} \curvearrowleft \text{ (极端大的损失)} \end{array} \right.$

④ 四阶矩：陡峭程度

（尾巴的薄厚）

⇒ kurtosis:

- 定义

Leptokurtic (尖)	$k > 3$
Mesokurtic (平)	$k = 3$
Platykurtic (矮)	$k < 3$

• 性质：

⑤ BLUE 标准：

• An estimator is BLUE means the true parameter can be approached through infinite sampling.

• $\hat{\mu}$ and S^2 are BLUE

• $\hat{\sigma}^2$ is not BLUE

• law of large number.
central limit theory.

• Best Linear Unbiased Estimator

→ Best: minimum variance.

→ Linear: linear function

→ Unbiased: $E(\bar{x}) = \mu$

$$E(S_{\bar{x}}^2) = \sigma^2$$

三. 两个定理：

⇒ 大数定理: LLN Law of Large Number

⇒ 中心极限定理: CLT Central Limit Theory.

⇒ 区别

① Binomial distribution:

⇒ Bernoulli distribution

$$P(X=1) = p$$

$$P(X=0) = 1-p$$

⇒ 独立、重复 N 次 Bernoulli:

$$P(x) = P(X=x) = C_n^x p^x (1-p)^{n-x}$$

⇒ 性质：

	Bernoulli	Binomial
Expectation:	p	np
Variance :	$p(1-p)$	$np(1-p)$

② Poisson Distribution:

$$P(k) = P(X=k) = \frac{\lambda^k}{k!} e^{-\lambda} \quad (\lambda = np)$$

1) $n \rightarrow \infty$

2) $P \rightarrow 0$

3) $np = \lambda$ (constant)

$\lambda = \text{mean} = \text{variance}$
 $\text{mean} = np$

• λ means average.

Part 3 : Distribution

一. Discrete distribution:

⇒ Binomial

⇒ Poisson

二. Continuous distribution:

⇒ normal.

⇒ lognormal.

⇒ t-distribution.

⇒ Chi-square

⇒ F-distribution.

↑ Discrete distribution:

↓ Continuous distribution:

③ Normal distribution: density function:

1) 性质

$$f(x) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{1}{2\sigma^2}(x-\mu)^2}$$

2) 标准化.

3) confidence interval.

1) 性质:

Skewness = 0, bell-shaped

kurtosis = 3

$$X \sim N(\mu, \sigma^2)$$

tail get thin and go to zero, but extend infinitely

① $X \sim N(\mu_1, \sigma_1^2)$ $Y \sim N(\mu_2, \sigma_2^2)$ independent.

- $aX + bY \sim N(a\mu_1 + b\mu_2, a^2\sigma_1^2 + b^2\sigma_2^2)$
- $\mu_p = w_1 \cdot \mu_1 + w_2 \cdot \mu_2$
- $\sigma_p^2 = w_1^2 \cdot \sigma_1^2 + w_2^2 \cdot \sigma_2^2 + 2\rho w_1 w_2 \sigma_1 \sigma_2$
if independent. $\rho = 0$

from $\frac{X-\mu}{\sigma}$
to
 $\frac{\bar{X}-\mu_x}{S_x/\sqrt{n}}$ (S_x/\sqrt{n} 为 X 的标准差)

五. Lognormal distribution:

1) 性质:

$X \sim \text{lognormal} \Leftrightarrow \ln X \sim \text{normal}$

$\ln X \sim \text{normal} \Leftrightarrow X \sim \text{lognormal}$

never take negative value.

Right tail.

\Rightarrow Right tail $\left\{ \begin{array}{l} \cdot \text{lognormal} \\ \cdot \text{Chi-square} \quad \text{右偏, } > 0 \\ \cdot F\text{-distribution.} \end{array} \right.$

六. LLN and CLT

① LLN: Strong Law of Large Number:

$E[X_i] = \mu$ (iid random variable)
(恒等)

$$\Rightarrow \hat{\mu}_n = \frac{1}{n} \sum_{i=1}^n X_i \xrightarrow{\text{a.s.}} \mu$$

(收敛于)

• the mean in large sample $\hat{\mu}_n$ ($n \rightarrow \infty$)

is approximate the true population mean μ .

② CLT: Central Limit theorem

中心极限定理

① 什么: 未知分布 \rightarrow 正态分布

② 定义: $\bar{X}_m \sim N(\mu, \frac{\sigma^2}{n})$

③ 性质:

$$\rightarrow E(\bar{X}_m) = \mu$$

$$\rightarrow \text{Var}(\bar{X}_m) = \frac{\sigma^2}{n}$$

$\rightarrow n$ large enough. ($n \geq 30$)

\Rightarrow Standard error:

$$\sigma_{\bar{X}_m} = \frac{\sigma}{\sqrt{n}}$$

样本均值的标准差

② 标准化: standardization

• if $X \sim N(\mu, \sigma^2)$

$$Z = \frac{X-\mu}{\sigma} \sim N(0, 1)$$

• check Z-table to find CDF. $\Phi\left(\frac{X-\mu}{\sigma}\right)$

③ key quantiles in normal distribution:

68%	$\mu \pm \sigma$
90%	$\mu \pm 1.65\sigma$
95%	$\mu \pm 1.96\sigma$
99%	$\mu \pm 2.58\sigma$

④ Approximating discrete random variables to normal random variable.

if $\begin{cases} \cdot np > 10 \\ \cdot n(1-p) > 10 \end{cases}$

\Rightarrow binomial \rightarrow normal random variable.

if $\lambda \geq 1000$

\Rightarrow Poisson \rightarrow normal random variable $N(\lambda, \lambda)$

正态分布是一切分布的终极

四. t-distribution (矮峰, 肥尾)

1) 性质

2) 公式

3) 查表.

① 性质: • symmetrical

• mean = 0

• if Variance known \rightarrow normal distribution.

Variance unknown \rightarrow t-distribution.

3) Compare LLN and CLT

{ LLN: mean
CLT: mean & Variance.

Summary: Distribution { discrete
continuous.

- Discrete

① Binomial } 性质, mean, variance
② Poisson 公式,

- Continuous

① Normal distribution:

→ 性质
→ 标准化
→ key value.

② t 分布

→ 性质: fat tail
→ 公式: $\frac{\bar{x} - \mu_x}{S_x / \sqrt{n}}$
→ 查表

③ Lognormal :

→ 性质 • $x \sim \text{normal}$ \downarrow $x \sim \text{lognormal}$
 \downarrow \downarrow
 $x \sim \text{lognormal}$ $\ln x \sim \text{normal}$
 • right-skewed

三. CCI & LLN

① CCI → 目的 → 内容 → 性质

② LLN → 内容

③ 对比

二. Hypothesis testing

① 步骤

② 种类

③ p-value

④ Type I, II, error.

- Statistical inference:

population $\xrightarrow{\text{sampling}}$ sample.

sample statistic $\xrightarrow{\text{estimation}}$ population parameter
→ mean
→ variance
→ skew
→ kurtosis

二. 点估计: $\bar{x} \rightarrow M_x$, $S^2 \rightarrow S_x^2$

三. 区间估计:

confidence interval = $\bar{x} \pm k \cdot S_E$

$k \rightarrow$ reliability factor.

$S_E \rightarrow$ standard error.

• α - level of confidence.

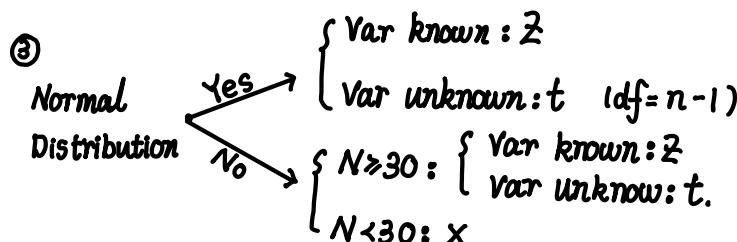
• $(1-\alpha)$ - degree of confidence.

① Normal distribution with known variance.

$\bar{x} \pm Z(\frac{\alpha}{2}) \cdot \frac{S}{\sqrt{n}}$ (Z-distribution)

② Normal distribution with unknown variance.

$\bar{x} \pm t(\frac{\alpha}{2}) \cdot \frac{S}{\sqrt{n}}$



part 3: Hypothesis Testing

- Confidence interval:

① spot estimate

② interval estimate

非正态, 小样本不可估计 → 未知分布

• Step 1:

- > 原假设: $H_0: \mu = \mu_0$ Null
- > 备择假设: $H_a: \mu \neq \mu_0$ Alternative
- > $\begin{cases} \text{one tail: } \begin{cases} H_0: \mu \geq \mu_0 & H_a: \mu < \mu_0 \\ H_0: \mu \leq \mu_0 & H_a: \mu > \mu_0 \end{cases} \\ \text{two tails: } H_0: \mu = \mu_0 & H_a: \mu \neq \mu_0. \end{cases}$

• Step 2: Identify the test statistics
映射到 normal distribution

$$\frac{\bar{x} - \mu}{\sigma / \sqrt{n}} \quad \text{or} \quad \frac{\bar{x} - \mu}{S / \sqrt{n}}$$

• Step 3: select a level of significance: α
显著性水平.

• Step 4: Formulate a decision rule:

if $| \text{test statistic} | > \text{critical value} \Rightarrow \text{Reject.}$

if $| \text{test statistic} | < \text{critical value} \Rightarrow \text{Fail to reject.}$

• Step 5: Arrive at decision.

\Rightarrow significantly different from μ_0 .

⑤ Hypothesis test 种类

1) $H_0: \mu = \mu_0$ (一组均值)

$$\rightarrow z\text{-statistic: } z = \frac{\bar{x} - \mu_0}{\sigma / \sqrt{n}}$$

$$\rightarrow t\text{-statistic: } t = \frac{\bar{x} - \mu_0}{S / \sqrt{n}}$$

2) 两组均值是否相等:

$$\begin{aligned} &H_0: \mu_x = \mu_y \\ &\mu_x - \mu_y = 0 \quad (\mu_z = 0) \end{aligned}$$

$$T = \frac{(\hat{\mu}_x - \hat{\mu}_y) - 0}{\sqrt{\frac{\sigma_x^2 + \sigma_y^2 - 2\rho\sigma_x\sigma_y}{n}}} = \frac{\hat{\mu}_z - 0}{\sqrt{\frac{\sigma_z^2}{n}}}$$

$$(\text{因为 } \sigma_z^2 = \sigma_{x-y}^2 = \sigma_x^2 + \sigma_y^2 - 2\rho\sigma_x\sigma_y)$$

if X, Y iid & mutually independent.

$$T = \frac{\hat{\mu}_x - \hat{\mu}_y}{\sqrt{\frac{\sigma_x^2}{n_x} + \frac{\sigma_y^2}{n_y}}}$$

3) 方差是否为常数:

① $H_0: \sigma^2 = \text{constant}$

② Chi-square distribution.

$$\chi^2 = \frac{S^2(B)}{S_0^2(A)} (n-1) = \frac{(n-1)S^2}{S_0^2} \quad df = n-1$$



4) 两组数据方差是否相关.

$$H_0: \sigma_1^2 = \sigma_2^2$$

$$\text{F-test: } F = \frac{S_1^2}{S_2^2} \quad \begin{cases} df_1 = n_1 - 1 \\ df_2 = n_2 - 1 \end{cases}$$

Always put the large variance in the numerator ($S_1^2 > S_2^2$)

大的方差放在分子上. ($\frac{S_1^2}{S_2^2} > 1$)

5) Summary of hypothesis Testing:

→ Mean:

① $H_0: \mu = \mu_0$ (normal distribution)
(known variance)

$$z = \frac{\bar{x} - \mu_0}{\sigma / \sqrt{n}}$$

② $H_0: \mu = \mu_0$ (normal distribution)
(unknown variance)

$$t = \frac{\bar{x} - \mu_0}{S / \sqrt{n}}$$

④ Two means: $H_0: \mu_1 = \mu_2$ (t-distribution)

$$\cdot T = \frac{\hat{\mu}_2 - \hat{\mu}_1}{\sqrt{\frac{S_x^2 + S_y^2 - 2S_{xy}}{n}}}$$

• t(n-1)

⑤ Variance: $H_0: \sigma^2 = \sigma_0^2$

$$\cdot \text{Chi-square: } \chi^2 = \frac{(n-1)S^2}{\sigma_0^2} \quad \chi^2(n-1)$$

⑥ Variance: $H_0: \sigma_1^2 = \sigma_2^2 = 0$

$$\cdot F = S_1^2 / S_2^2 \quad F(n_1-1, n_2-1)$$

▲ Summary: hypothesis test:

① $H_0: H_a:$

$$② t = \frac{\bar{X} - \mu}{S/\sqrt{n}}$$

③ $\alpha \rightarrow \text{critical value}$

④ $|t| > |\text{critical}|$

▲ Summary:

- Confidence Interval.

① spot estimate.

② 区间估计：概念：

$$\bar{x} \pm k \cdot SE, \text{ 表格 } \times \begin{cases} \text{normal} \\ \text{variance} \\ \text{sample.} \end{cases}$$

二. 假设检查:

① 步骤: 1) 2) 3) 4) 5)

② 种类: mean. variance
t.2. χ^2 F

③ P-value: 越小越拒绝.

④ type I / type II: {
 1) 定义
 2) 性质

四. P-value (概率)

• P-value 与 α 相比 (与单双尾无关)

• 越小越拒绝.

五: Type I and Type II Errors:

• Type I: 拒真 $P(\text{type I}) = \text{significance level } (\alpha)$

• Type II: 取伪 $1 - P(\text{type II}) = \text{power of a test.}$

①

	$H_0: \text{true}$	$H_0: \text{false}$
reject	type I, α	power of test
not reject	confidence level	type II $= 1 - \text{power of test}$

② 性质: type I / II 此消彼长

$n \uparrow$, type I, II 都下降.

Linear Regression.

- 假设 $X Y$
- 计算参数 a, b . OLS. $Y = a + bX$
- 检验模型: 置信区间 假设检验
- 评价模型: $R^2, \text{adj.}R^2$
- 违反假设 (后果)
- Elements of linear regression.
 - $Y = b_0 + b_1 X_i + \varepsilon$
 - error term (ε 是不能由 X 解释 Y 的部分, 通常由 error term 解释)
- assumption 中没有一条与 y 相关.
- Old assumption:
 - linear relationship between X and Y
 - X are not random,
 - $\rho_{x_i, \varepsilon} = 0$
 - $\rho_{x_i, x_j} = 0$
 - $E(\varepsilon_i) = 0$ $\text{Var}(\varepsilon_i) = \text{constant}$.
 - $\rho_{\varepsilon, \varepsilon} = 0$ across observation.
 - $\varepsilon \sim N(\mu, \sigma^2)$ normal distribution.
- New assumption: (5)
 - $E(\varepsilon_i) = 0$
 - $\text{Var}(\varepsilon_i) = \text{constant}$.
 - $\sigma^2 > 0$ x 是变量
 - Large outliers are unlikely.
 - sample observations are i.i.d.
 - the explanatory variables are not perfectly linear dependent. ($\rho_{x_i, x_j} \neq 1$)

2. OLS Ordinary Least Squares:

① 原理: 得到的 b_0, b_1 , 可以使回归方程的 $\sum \varepsilon_i^2$

$$\text{minimize } \sum \varepsilon_i^2 = \sum [Y_i - (\hat{b}_0 + \hat{b}_1 \times X_i)]^2$$

$$\hat{b}_1 = \frac{\text{Cov}(X, Y)}{S_x^2} = \hat{\rho}_{X, Y} \cdot \frac{S_Y}{S_X}$$

$$\hat{b}_0 = \bar{Y} - \bar{X} \hat{b}_1 \text{ 代入点 } (X, Y)$$

② Confidence interval for the regression coefficient b_1 and b_0

$$\hat{b}_1 \pm (\text{Critical Value} \times S_{\hat{b}_1})$$

$$\hat{b}_0 \pm (\text{Critical Value} \times S_{\hat{b}_0})$$

③ Regression coefficient hypothesis testing:
 \hat{b}_1 的检验.

$$H_0: \hat{b}_1 = 0 \quad H_a: \hat{b}_1 \neq 0$$

⇒ test statistic:

$$T = \frac{\hat{b}_1 - b_1}{S_{\hat{b}_1}} = \frac{\hat{b}_1}{S_{\hat{b}_1}} \sim S/\sqrt{n}, \sigma/\sqrt{n}$$

$$\Rightarrow p\text{-value} = \frac{2(1 - \Phi(|T|))}{2} \text{ two tail.}$$

$\Phi(T)$: 累计概率

④ Joint hypothesis testing (多元线性回归)

$$H_0: b_1 = b_2 = b_3 = \dots = b_k = 0$$

$$F = \frac{ESS/k}{RSS/(n-k-1)} \quad E - \text{explained} \quad R - \text{residual}$$

• if $F(\text{test}) > F(\text{critical value}) \Rightarrow \text{reject}$.

⑥ 三个 tables

- Regression statistics
- ANOVA
-

$$\rightarrow R^2 = \frac{ESS}{TSS}$$

$$\text{Multiple } R = \sqrt{R^2} = R$$

$$\rightarrow \text{Adjusted } R^2 : 1 - \frac{RSS / (n-k-1)}{TSS / (n-1)}$$

$$\rightarrow \text{Standard error (regression)} = \sqrt{\frac{RSS}{n-k-1}}$$

- Regression/explained df = k

Residual df = n - k - 1

Total df = n - 1

$$F = \frac{ESS/k}{RSS/(n-k-1)}$$

三. Measure model fit.

① R^2 (the coefficient of determination)

$$R^2 = \frac{ESS}{TSS} = 1 - \frac{RSS}{TSS} \uparrow X \text{ 解释 } y \text{ 力度大.}$$

\rightarrow simple two variable regression:

$$r^2 = R^2 \rightarrow r = \pm \sqrt{R^2}$$

$$\frac{r^2}{2} = R^2$$

correlation coefficient

② Adjusted R^2

- adding a new variable to the model always increases the R^2

$$\bullet \text{Adj. } R^2 = 1 - \frac{RSS / (n-k-1)}{TSS / (n-1)}$$

- R^2 can not be compared across models with different dependent variables.

四. Violation of the assumption.

- Assumption: ① $E(\epsilon_i) = 0$

② $\text{Var}(\epsilon_i) = \text{constant}$. (异方差.)

③ $\text{Var}(x) > 0$

④ i.i.d.

⑤ no outliers.

* ⑥ $\rho_{x,x+1}$

• conditional heteroskedasticity. 异方差.

⑦ 定义: $\sigma_e^2 \neq \text{constant}$

- σ_e^2 与 X 有关
- σ_e^2 与 X 无关

⑧ 影响:

• $\frac{1}{\sqrt{n}} \uparrow \Rightarrow \downarrow \text{更容易 fail to reject.}$

⑨ test heteroskedasticity:

• White Test.

• 多重共线性: Multi-collinearity (Multiple-regression only)

⑩ 定义: $Y = b_0 + b_1 X_1 + b_2 X_2 + \epsilon$
(高度相关)

\rightarrow T-test fail to reject.

$|r| > 0.7$

\rightarrow common sense.

重大遗漏变量: omitted variable Bias

⑪ 定义: $\left\{ \begin{array}{l} \text{at least one of the included regressors correlated} \\ \text{determinant} \end{array} \right.$

⑫ implication:

\rightarrow the larger the correlation, the larger is the bias.

• Outliers:

⑬ 定义: remove \hat{y}_i , 最影响较大,

$$\text{Cook's distance: } D_j = \frac{\sum_{i=1}^n (\hat{y}_{ij} - \hat{y}_i)^2}{k s^2}$$

• cook's distance $> 1 \Rightarrow$ outlier.

Summary:

一. 假设: 老的新的.

$$\text{OLS: } \hat{b}_1 = \frac{\text{Cov}(X, Y)}{\sigma_X \cdot \sigma_Y} = \rho \cdot \frac{\sigma_y}{\sigma_X}$$

$$\hat{b}_0 = \bar{Y} - \hat{b}_1 \bar{X}$$

三. ANOVA Table.

• R^2 : 拟合程度好坏.

• $\text{Adj. } R^2$: 拟合程度好坏的指标.

$$\begin{aligned}\text{Adj. } R^2 &= 1 - \frac{\text{RSS}/(n-k-1)}{\text{TSS}/(n-1)} \\ &= 1 - \left(\frac{n-1}{n-k-1} \right) (1-R^2)\end{aligned}$$

四. 假设检测:

① t-test: 单个系数检验.

$$H_0: b_1 = 0 \text{ (常规)}$$

② F-test: 对所有系数检验.

$$H_0: b_1 = b_2 = b_3 = \dots = 1 \text{ (ANOVA table)}$$

$$F = \frac{\text{ESS}/k}{\text{RSS}/(n-k-1)}$$

五. 违反假设:

① 异方差 $\text{Var}e \neq \text{constant}$

• 定义

• 图示

• 影响.

• 检验. white test.

② 多重共线性: \triangleright 定义 X_1, X_2 高度相关

\Rightarrow 方法

\Rightarrow 纠正: 去掉一个 X , 重新做回归.

③ 重大遗漏变量: ① 定义

④ Outliers:

$$\text{cook's distance} = \frac{\sum (\hat{y}_i - \hat{y}_{i,j})^2}{k s^2} > 1 \text{ (outlier)}$$

Time Series

1. Trend

2. seasonality

3. random walk.

4. noise

1. covariance stationary

2. white noise

3. 模型 $\begin{cases} AR \\ MA \\ ARMA \end{cases}$

一. Introduction to time series analysis:

- time series $\xrightarrow{\text{decompose}}$
 - trend
 - seasonal component
 - cyclical component (noise)

二. Non-Stationary time series:

• covariance-stationary time series.

mean, var, covariances do not depend on time.

if depend on time \Rightarrow Non-stationary

三. Trend.

• Polynomial trends.

• Linear time trend.

mean depends on time.

$$E[Y_t] = \delta_0 + \delta_1 t.$$

• Nonlinear trend:

including higher powers of time

$$Y_t = \delta_0 + \delta_1 t + \delta_2 t^2 + \dots + \delta_m t^m + \varepsilon_t.$$

• Log-linear trend:

\Rightarrow constant growth rate.

$$\ln Y_t = \delta_0 + \delta_1 t + \varepsilon_t.$$

四. Seasonality.

- relating the mean of the process to the month or quarter of the year.
- seasonal dummy variables.:
 - $l_{it} = 1 \text{ or } 0$.
 - $Y_t = \delta + r_1 l_{1t} + r_2 l_{2t} + \dots + r_s l_{st} + \varepsilon_t$
 - dummy variable trap.

五. Random Walk:

$$Y_t = Y_0 + \sum \varepsilon_i$$

$$V(Y_t) = V(\sum \varepsilon_i)$$

$$V^2(\varepsilon_1 + \varepsilon_2) = \sqrt{V^2(\varepsilon_1) + V^2(\varepsilon_2) + 2\rho V(\varepsilon_1)V(\varepsilon_2)}$$

$$\cdot V(Y_t) = t\sigma^2 \quad (\text{Variance is not constant anymore})$$

• 如何判断 random walk.

→ 引入滞后算子 (算法)

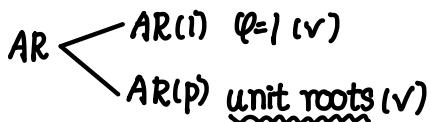
$$\rightarrow Y_t = L Y_{t-1}$$

$$L^2 Y_{t-2} = Y_t$$

$$\rightarrow Y_t (1 - 1.8L + 0.8L^2) = \varepsilon_t$$

if unit roots (单位根, 说明有 random walk)

在AR模型中确定是否平稳?



• Testing for unit Roots:

Augmented Dickey-Fuller (ADF)

Test.

- 1) $\Delta Y_t = r Y_{t-1} + \varepsilon_t$
 - 2) Null: $H_0: r = 0$. $H_1: r < 0$. (but查two-tail)
 - 3) t-test (two tail)
- if reject H_0 , 不是 random walk.

Stationary Time Series

- Sources of non-stationarity:

① Time trends

② Seasonalities

③ Unit roots (random walk)

• Stationary time series:

1) time trend X

2) seasonalities X

3) cyclical component ✓
 { shock
 memory }

• why is stationary so important?

< the ability of a model to forecast a time series depends crucially on whether the past resembles future >

<历史会重演>

< if probabilistic structure changes over time (not stationary) ⇒ no way to predict.

• Covariance stationary

满足协方差平稳)

→ mean and autocovariance 不随时间的改变而改变

→ mean, variance 满足以下条件:

1) $E[Y_t] = \mu \text{ for all } t$

2) $\text{Cov}(Y_t, Y_{t+h}) = \gamma_h \text{ for all } t$
 auto covariance.

only depends on the distance between observation h

3) $V[Y_t] = \gamma_0 < \infty \text{ for all } t$.

$\text{cov}[Y_t, Y_t] = \text{cov}[Y_{t+h}, Y_{t-h}]$

二. Autocovariance:

- as the covariance between a stationary time series at different points in time.

λ^{th} autocovariance:

$$\gamma_{t+h} = E[(Y_t - E(Y_t))(Y_{t+h} - E(Y_{t+h}))]$$

- $h=0$. $\gamma_{t,0}$ is the variance γ_t :

$$\gamma_{t,0} = E[(Y_t - E(Y_t))^2]$$

滞后期相同，协方差相同。

independent white noise:

$\varepsilon_t \stackrel{iid}{\sim} (0, \sigma^2)$

① mean=0

② variance= σ^2

③ independent

Gaussian white noise (normal white noise)

① mean=0

② Variance=constant

③ $\varepsilon_t \stackrel{iid}{\sim} N(0, \sigma^2)$

三. Autocovariance function:

- A function of h that returns the autocovariance between Y_t and Y_{t+h} :
- $\text{cov}[Y_t, Y_{t+h}] = \text{Cov}[Y_{t+h}, Y_t]$

四. Autocorrelation function (ACF)

$$\rho_h = \frac{\text{cov}(Y_t, Y_{t+h})}{\sqrt{\text{Var}(Y_t)} \sqrt{\text{Var}(Y_{t+h})}} = \frac{\gamma(h)}{\sqrt{\gamma(0)} \sqrt{\gamma(0)}} = \frac{\gamma(h)}{\gamma(0)}$$

五. Partial Autocorrelation function (PACF)

- measure relationship between Y_t and Y_{t+h} removed the effects of $Y_{t-1}, \dots, Y_{t-h+1}$

t. Stationary Time Series - AR, MA, ARMA

- model stationary time series process

① AR(p) model:

autoregressive model

$$Y_t = \delta + \phi_1 Y_{t-1} + \phi_2 Y_{t-2} + \dots + \phi_p Y_{t-p} + \varepsilon_t$$

$$\varepsilon_t \sim WN(0, \sigma^2)$$

- detect an AR(p) model to be stationary?
(是否存在 random walk)

② lag polynomial

$$\text{引入 L (滞后算子)} \quad Y_t = L \cdot Y_{t-1}$$

$$\text{引入滞后多项式: } 1 - \Phi_1 L - \Phi_2 L^2$$

六. Stationary Time Series - White Noise:

- fundamental building block / simple WN / weak WN

all the stationary time series models are established on white noise.

$$\varepsilon_t \sim WN(0, \sigma^2)$$

White noise

- i) mean=0
- ii) var=constant
- iii) Autocorrelation=0
 $\gamma(h) = \rho(h) = 0 \quad (h \neq 0)$

Covariance stationary

- mean=constant
- var=constant
- autocorrelation=constant

② 特征等式:

$$(z^2 - \phi_1 z - \phi_2)$$

③ 特征根: z_1 and z_2
if $z_1 = 1 \Rightarrow$ random walk.

Example:

Test the stationarity of an AR(2) model:

$$Y_t = 1.4 \times Y_{t-1} - 0.45 Y_{t-2} + \varepsilon_t$$

① Log polynomial: $(\frac{Y_t}{L} = L Y_{t-1}, Y_t = L^2 Y_{t-2})$

$$1 - \phi_1 L - \phi_2 L^2 - \dots - \phi_p L^p$$

$$\hat{\phi}(L) = 1 - 1.4L + 0.45L^2$$

② Let $Z = 1/L$

$$\hat{\phi}(Z) = Z^2 - 1.4Z + 0.45$$

$$\textcircled{3} \quad \hat{\phi}(Z) = 0 \Rightarrow (Z - 0.9)(Z - 0.5) = 0$$

$$Z_1 = 0.9 / Z_2 = 0.5$$

② MA model: moving average model

- the current value of the observed series is expressed as a function of **current** and **lagged unobservable shocks**.

• MA(1) model

$$Y_t = \mu + \varepsilon_t + \theta \varepsilon_{t-1}$$

weight $\begin{matrix} \downarrow & \downarrow \\ \text{X} & \end{matrix}$ $\varepsilon_t \sim WN(0, \sigma^2)$

$$Y_t = \theta \varepsilon_{t-1} + \varepsilon_t$$

$$Y_{t-1} = \theta \varepsilon_{t-2} + \varepsilon_{t-1}$$

$$Y_{t-2} = \theta \varepsilon_{t-3} + \varepsilon_{t-2}$$

→ if

$\theta > 0$ persistent (两个连续的数值之间有正向关系)

$\theta < 0$ aggressively mean reverts

* AR(1): $Y_t = \varphi Y_{t-1} + \varepsilon_t + \mu$

MA(1): $Y_t = \mu + \theta \varepsilon_{t-1} + \varepsilon_t$

For MA(1) model:

1) $E(Y_t) = \mu$

2) $\text{Var}(Y_t) = (1 + \theta^2) \sigma^2$ ($\varepsilon_t \varepsilon_t'$ variance)

③ Difference between MA(1) and AR(1)

- MA(1) have a short memory
- AR(1) has a much long memory

④ ARMA model:

Autoregressive moving average (ARMA)

• ARMA(1,1)

$$Y_t = \delta + \phi_1 Y_{t-1} + \theta \varepsilon_{t-1} + \varepsilon_t$$

$$\text{mean: } E[Y_t] = \mu = \frac{\delta}{1 - \phi_1}$$

Variance:

$$V[Y_t] = \gamma_0 = \frac{\delta^2 (1 + 2\phi_1\theta + \theta^2)}{1 - \phi_1^2}$$

⑤ Application of AR, MA and ARMA.

→ ACF & PACF → define the characteristic of the time series.

ACF	PACF	Model
gradually decay	Sharp cutoff	AR
sharp cutoff	gradually decay	MA
gradually decay	gradually decay	ARMA

⑥ Hypothesis test for autocorrelation:

- if ARMA, ACF decay to 0.

• Box-pierce statistic & Ljung-Box

→ χ^2 table, Chi-square

→ $H_0: \rho_1 = \rho_2 = \dots = \rho_n = 0$

Summary:

time series $\xrightarrow{\text{①}}$ 去 trend $\xrightarrow{\text{②}}$ 去 seasonality

$\xrightarrow{\text{③}} \text{检验是否存在 random walk}$

if $\xrightarrow{\text{④}}$ 无 noise

$\xrightarrow{\text{⑤}}$ 有 去掉 random walk \rightarrow noise

$\xrightarrow{\text{⑥}}$ covariance stationary $\left\{ \begin{array}{l} \text{mean} \\ \text{variance} \xrightarrow{\text{⑦}} \\ P(h) \end{array} \right.$

选择3个模型 $\xrightarrow{\text{⑧}}$, $P(t)$ ACF
 $P(t)$ PACF

ACF PACF

表格 $\left\{ \begin{array}{l} \text{AR} \\ \text{MA} \\ \text{ARMA} \end{array} \right. \begin{array}{c} \diagup \\ \diagdown \end{array} \quad \begin{array}{c} \diagdown \\ \diagup \end{array}$

$$Y_t = u + b_1 Y_{t-1} + b_2 Y_{t-2} + b_3 Y_{t-3} + \theta Y_{t-4} + \phi X_{t-1} + \varepsilon_t$$

⑥ Simple return vs. Continuously compounded returns

\Rightarrow simple return

$$R_t = \frac{P_t - P_{t-1}}{P_{t-1}}$$

\Rightarrow continuous compounded return:

$$\gamma_t = \ln P_t - \ln P_{t-1}$$

\Rightarrow Relationship: $1 + R_t = e^{\gamma_t}$.

⑦ Measure volatility and risk.

• $\sigma_{\text{annual}} = \sqrt{252} \sigma_{\text{daily}}$

$$\hat{\sigma}^2 = \frac{1}{T} \sum_{i=1}^T (r_i - \bar{r})^2$$

⑧ Distribution of Financial Returns

• many return series are skewed and fat-tailed.

\Rightarrow test normality of a distribution.

- {the Jarque-Bera test
power laws}

⑨ The Jarque-Bera Test:

$\rightarrow H_0: \text{skewness} = 0 \& \text{kurtosis} = 3$

$$\rightarrow JB = (T-1) \left[\frac{\hat{s}^2}{6} + \frac{(\hat{k}-3)^2}{24} \right]$$

$\rightarrow \text{Chi-square 卡方分布}$

⑩ Power Law:

\rightarrow compare tail behaviour is to examine the natural log of the tail probability

$$\rightarrow \ln P(X > x)$$

⑪ Dependence:

\rightarrow joint density: $f_{X,Y}(x,y) = f_X(x) \cdot f_Y(y)$

\rightarrow linear dependence:

$$\rho_{X,Y} = \frac{\text{Cov}(X,Y)}{\sigma_X \cdot \sigma_Y}$$

\rightarrow 排序的相关系数: linear, nonlinear.

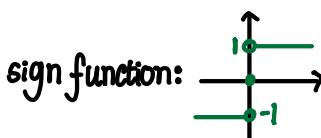
- Rank correlation (Spearman's correlation)
- Kendall's τ

⑫ Rank Correlation - Spearman's correlation:

$$\rightarrow \rho_S = 1 - \frac{6 \sum_{i=1}^n d_i^2}{n(n^2-1)}$$

\rightarrow from $(-1, 1)$

⑬ Rank Correlation - Kendall's τ



\rightarrow concordant pair (同组) $\Rightarrow \text{sgn}(X_2 - X_1) = \text{sgn}(Y_2 - Y_1)$

\rightarrow discordant pair

$$\text{sgn}(X_2 - X_1) = -\text{sgn}(Y_2 - Y_1)$$

$$\rightarrow \tau = \frac{n_c - n_d}{n(n-1)/2}$$

n_c : number of concordant

n_d : number of discordant pairs

\rightarrow ordinal correlation are less sensitive to outliers.

Simulation.

1. Monte Carlo simulation.

① increase the repeating times, N

$$\downarrow S_x = \frac{6}{\sqrt{n}} \uparrow$$

② Antithetic variables: negative correlation.

③ control variable.

<use the same draws on a related problem whose solution is known>

2. 抽样: (数据不足)

① Bootstrapping:

① iid bootstrap

② circular block bootstrap (CBB)