

Limits

- **Maxima:**  $f(c)$  is local maximum if  $f(c) \geq f(x)$  for  $x$  near  $c$  (note that inequality is non-strict)
- **Differentiability:**  $f$  is differentiable at  $a$  if  $f'(a)$  exists  
 $f$  is differentiable (in its domain) if  $f$  is differentiable at every point in its domain  
 $f$  is differentiable at point  $a \implies f$  is continuous at  $a$  (but not the converse)
- **Critical Point:**  $c$  is a critical point if  $c$  is an interior point in the domain and either  $f'(c) = 0$  or  $f'(c)$  does not exist (A critical point may not be a local extremum)
- **Inflection Point:**  $c$  is an inflection point if concavity changes at  $c$  ( $c$  is an inflection point  $\implies f''(c) = 0$ , but the converse is not always true)
- $\lim_{x \rightarrow 0} \frac{\sin(x)}{x} = 1$
- **L'Hôpital's Rule:**  
 $f(a) = g(a) = 0$  or  $\infty \implies \lim_{x \rightarrow a} \frac{f(x)}{g(x)} = \lim_{x \rightarrow a} \frac{f'(x)}{g'(x)}$   
use  $\ln(\dots)$  for other forms:  $\infty - \infty, 1^\infty, \infty^0, 0^0$

Differentiation & Integration

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|---|--|
| • <b>Common derivatives:</b>            | $\log_a x \longrightarrow \frac{1}{x \ln a}$             |
| $y \longrightarrow \frac{dy}{dx}$       | $\sin^{-1} x \longrightarrow \frac{1}{\sqrt{1-x^2}}$     |
| $\sin x \longrightarrow \cos x$         | $\cos^{-1} x \longrightarrow -\frac{1}{\sqrt{1-x^2}}$    |
| $\cos x \longrightarrow -\sin x$        | $\tan^{-1} x \longrightarrow \frac{1}{1+x^2}$            |
| $\tan x \longrightarrow \sec^2 x$       | $\cot^{-1} x \longrightarrow -\frac{1}{1+x^2}$           |
| $\cot x \longrightarrow -\csc^2 x$      | $\sec^{-1} x \longrightarrow \frac{1}{ x \sqrt{x^2-1}}$  |
| $\sec x \longrightarrow \sec x \tan x$  | $\csc^{-1} x \longrightarrow -\frac{1}{ x \sqrt{x^2-1}}$ |
| $\csc x \longrightarrow -\csc x \cot x$ | $x^x \longrightarrow x^x (\ln x + 1)$                    |
| $a^x \longrightarrow a^x \ln a$         |  |
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- |  |   |
|--|---|
| • <b>Common integrals:</b>                 | $\cot x \longrightarrow \ln  \sin x  + C$           |
| $y \longrightarrow \int y \, dx$           | $\sec x \longrightarrow \ln  \sec x + \tan x  + C$  |
| $\sin x \longrightarrow -\cos x + C$       | $\csc x \longrightarrow -\ln  \csc x + \cot x  + C$ |
| $\cos x \longrightarrow \sin x + C$        |   |
| $\tan x \longrightarrow -\ln  \cos x  + C$ |   |
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- **Trigonometric formulae:**  $1 + \cot^2 x = \csc^2 x$

- **Power rule:**  $\frac{d}{dx} x^n = nx^{n-1}$
- **Product rule:**  $(fg)'(x) = f'(x)g(x) + f(x)g'(x)$
- **Quotient rule:**  $\left(\frac{f}{g}\right)'(x) = \frac{f'(x)g(x) - f(x)g'(x)}{[g(x)]^2}$
- **Chain rule:**  $(f \circ g)'(x) = f'(g(x))g'(x)$
- **Parametric differentiation:**  $\frac{dy}{dx} = \frac{dy}{dt} \div \frac{dx}{dt}$
- **Implicit differentiation:** Differentiate both sides of an equation containing  $x$  and  $y$ , then solve the resulting equation for the  $\frac{dy}{dx}$  term.
- **Integration by parts:**  $\int u \, dv = uv - \int v \, du$   
Try to differentiate in this order (highest to lowest priority):  $\ln x, x^n, e^x, e^{-x}, \sin x, \cos x$
- $\frac{d}{dx} \int_a^x f(t) \, dt = f(x)$
- $\frac{d}{dx} \int_a^{g(x)} f(t) \, dt = f(g(x))g'(x)$
- Integral with  $\sqrt{R^2 - x^2}$ : Sub  $x = R \sin \theta$  or  $x = R \cos \theta$
- Integral with  $\sqrt{R^2 + x^2}$ : Sub  $x = R \tan \theta$
- **Notable formula:**  
$$\int \frac{A \cos \theta + B \sin \theta}{\cos \theta + \sin \theta} d\theta$$
$$= \int \frac{\frac{A+B}{2} (\cos \theta + \sin \theta) + \frac{A-B}{2} (\cos \theta - \sin \theta)}{\cos \theta + \sin \theta} d\theta$$
$$= \int \frac{A+B}{2} d\theta + \int \frac{A-B}{2} \frac{\cos \theta - \sin \theta}{\cos \theta + \sin \theta} d\theta$$
$$= \frac{A+B}{2} \theta + \frac{A-B}{2} \ln(\cos \theta + \sin \theta) + C$$

Series

The following is for  $\sum a_n$  - a series of numbers.

- **Convergence:** A sequence  $\{a_n\}$  is convergent if for some fixed  $L \in \mathbb{R}$ , we have  $\lim_{n \rightarrow \infty} a_n = L$   
Otherwise, the sequence is divergent
- **Partial sum of geometric series:**  $s_n = a \frac{1 - r^n}{1 - r}$ ,  
 $r \neq 1$   
 $s_n$  converges  $\iff |r| < 1$
- **Ratio test for convergence of series:**  
$$\lim_{n \rightarrow \infty} \left| \frac{a_{n+1}}{a_n} \right| = \rho, \{s_n\} = \left\{ \sum_{i=1}^n a_i \right\} \begin{cases} \text{converges} & \text{if } \rho < 1 \\ \text{diverges} & \text{if } \rho > 1 \\ \text{unknown} & \text{if } \rho = 1 \end{cases}$$

- **Radius of convergence:** No concept of "radius".  
Series either converges if  $\rho < 1$  or diverges when  $\rho > 1$ .
- **p-series:**  $\sum_{n=1}^{\infty} \frac{1}{n^p} \begin{cases} \text{converges} & \text{if } p > 1 \\ \text{diverges} & \text{if } 0 \leq p < 1 \\ \text{no conclusion} & \text{if } p = 1 \end{cases}$

The following is for  $\sum f_n(x)$  - a series of functions.

- **Power series about  $x = a$ :**  $f(x) = \sum_{n=0}^{\infty} c_n (x - a)^n$
- **Radius of convergence:** The "allowed range" of value for  $x$  such that  $\rho < 1$  — may be 0, some real no.  $h$ , or  $\infty$   
For e.g.,  $\left| \frac{a_{n+1}}{a_n} \right| = \frac{n}{n+1} |x| \longrightarrow x$  as  $n \longrightarrow \infty$ , so it converges when  $|x| < 1$  and diverges otherwise.
- **Differentiation & integration of power series:**  
$$f'(x) = \sum_{n=1}^{\infty} n c_n (x - a)^{n-1}$$
radius of convergence  $R$  is unchanged by differentiation  
$$\int f(x) dx = \sum_{n=0}^{\infty} c_n \frac{(x - a)^{n+1}}{n + 1} + C$$
radius of convergence is unchanged by integration
- **Taylor series:**  $f(x) = \sum_{k=0}^{\infty} \frac{f^{(k)}(a)}{k!} (x - a)^k$
- **Maclaurin series:** Taylor series with  $a = 0$
- **Common Maclaurin series:**  

for  $-1 < x < 1$

$$\frac{1}{1 - x} = \sum_{n=0}^{\infty} x^n = 1 + x + x^2 + x^3 + \dots$$
$$\frac{1}{1 + x} = \sum_{n=0}^{\infty} (-1)^n x^n = 1 - x + x^2 - x^3 + \dots$$
$$\frac{1}{1 + x^2} = \sum_{n=0}^{\infty} (-1)^n x^{2n} = 1 - x^2 + x^4 - x^6 + \dots$$
$$\ln(1 + x) = \sum_{n=1}^{\infty} \frac{(-1)^{n-1} x^n}{n} = x - \frac{x^2}{2} + \frac{x^3}{3} - \frac{x^4}{4} + \dots$$
$$\tan^{-1} x = \sum_{n=0}^{\infty} \frac{(-1)^n}{2n + 1} x^{2n+1} = x - \frac{x^3}{3} + \frac{x^5}{5} - \frac{x^7}{7} + \dots$$
$$\frac{1}{(1 - x)^2} = \sum_{n=1}^{\infty} n x^{n-1} = 1 + 2x + 3x^2 + 4x^3 + \dots$$
$$\frac{1}{(1 - x)^3} = \frac{1}{2} \sum_{n=2}^{\infty} n(n - 1) x^{n-2} = \frac{1}{2} (2 + 6x + 12x^2 + \dots)$$
$$\frac{1}{(1 + x)^2} = \sum_{n=0}^{\infty} (-1)^n (n + 1) x^n = 1 - 2x + 3x^2 - 4x^3 + \dots$$

$$\text{for } -\infty < x < +\infty$$

$$\sin x = \sum_{n=0}^{\infty} \frac{(-1)^n x^{2n+1}}{(2n+1)!} = x - \frac{x^3}{3!} + \frac{x^5}{5!} - \frac{x^7}{7!} + \dots$$

$$\cos x = \sum_{n=0}^{\infty} \frac{(-1)^n x^{2n}}{(2n)!} = 1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \frac{x^6}{6!} + \dots$$

$$e^x = \sum_{n=0}^{\infty} \frac{x^n}{n!} = 1 + x + \frac{x^2}{2!} + \frac{x^3}{3!} + \dots$$

### • Deriving more Maclaurin/Taylor series:

Substitution:

$$f(x) = \sum g(x) \implies f(h(x)) = \sum g(h(x))$$

$$\text{Multiplication: } f(x) = \sum g(x) \implies h(x)f(x) =$$

$$h(x) \sum g(x) = \sum h(x)g(x)$$

$$\text{Differentiation: } f(x) = \sum g(x) \implies f'(x) = \sum g'(x)$$

Integration:

$$f(x) = \sum g(x) \implies \int_0^x f(x)dx = \int_0^x \sum g(x)dx$$

... and other usual operations on functions

Example: Find Taylor series of  $\frac{1}{2x+1}$  at  $x = -2$  (Note: this means finding Taylor series  $(x-a)$  where  $a = -2$ ).

One way is to **hardcore** differentiate  $\frac{1}{2x+1}$  and calculate  $\sum_{n=0}^{\infty} \frac{f^{(k)}(-2)}{k!} (x - (-2))^k$ . Better soln: write  $\frac{1}{2x+1}$  as

$$q_{\frac{1}{1-p(x+2)}} \text{ and apply } \frac{1}{1-x} = \sum_{n=0}^{\infty} x^n = 1 + x + x^2 \dots$$

### • Taylor polynomial:

$n^{\text{th}}$  order Taylor polynomial:  $P_n(x) :=$  terms until (and including)  $x^n$ , use for approximation

remainder of order  $n$ :  $R_n(x) :=$  remaining terms

error := absolute value of remaining terms =  $|R_n(x)|$

### • Taylor's Theorem: $R_n(x) = \frac{f^{(n+1)}(c)}{(n+1)!} (x-a)^{n+1}$

where  $x \leq c \leq a$  (when  $x \leq a$ ) or  $a \leq c \leq x$  (when  $a \leq x$ )

This provides an upper bound for the error term

## Partial Differentiation

- Partial derivative wrt  $x$  – denoted by  $f_x(a, b)$  or  $\left. \frac{\partial f}{\partial x} \right|_{(a,b)}$

- $f_{xy} = (f_x)_y = \frac{\partial^2 f}{\partial y \partial x}$

- $f_{xy}(a, b) = f_{yx}(a, b)$  (if  $f_x, f_y, f_{xy}, f_{yx}$  are continuous in the neighbourhood around  $(a, b)$ )

- To check if  $f(x, y)$  has partial derivatives of all orders, check if  $f_{xy} = f_{yx}$

- Chain rule:** For  $z = f(x, y)$  and  $x = x(t), y = y(t)$ :

$$\frac{dz}{dt} = \frac{\partial f}{\partial x} \frac{dx}{dt} + \frac{\partial f}{\partial y} \frac{dy}{dt}$$

For  $z = f(x, y)$  and  $x = x(s, t), y = y(s, t), w = w(s, t)$ :

$$\frac{\partial z}{\partial s} = \frac{\partial f}{\partial x} \frac{\partial x}{\partial s} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial s} + \frac{\partial f}{\partial w} \frac{\partial w}{\partial s}$$

- Directional derivative**  $D_u f$  measures change  $\delta f$  when  $f$  moves a small distance  $\delta t$  **in direction of vector**  $u$ .

For unit vector  $u = u_1 \mathbf{i} + u_2 \mathbf{j}$ :

$$D_u f(a, b) = f_x(a, b)u_1 + f_y(a, b)u_2$$

$$\Delta f(\text{actual change}) \approx \delta f = D_u f(a, b) \cdot \delta t$$

**Convert**  $u$  if not a unit vector!  $u' = \frac{1}{\sqrt{u_1^2 + u_2^2}}(u_1 \mathbf{i} + u_2 \mathbf{j})$

- Gradient vector** essentially  $D_u f$  without direction:

$$\nabla f(a, b) = f_x(a, b)\mathbf{i} + f_y(a, b)\mathbf{j} \text{ or } \nabla f(a, b) \cdot u = D_u f(a, b)$$

$$D_u f(a, b) = \|\nabla f(a, b)\| \cos \theta$$

Direction of  $\nabla f(a, b)$  is steepest, maximum value of

$$D_u f(x, y) \text{ is } \|\nabla f(x, y)\| = \sqrt{f_x(a, b)^2 + f_y(a, b)^2}$$

- Maxima:**  $f(a, b)$  is local maximum if  $f(a, b) \geq f(x_1, y_1)$

$\forall$  points  $(x_1, y_1)$  near  $(a, b)$  (note  $\geq$ )

- Critical point:**  $(a, b)$  is a critical point if  $(f_x(a, b) = 0$  and  $f_y(a, b) = 0)$  or  $(f_x(a, b)$  or  $f_y(a, b)$  does not exist).

**Not all critical pts are min/max points**

- Discriminant:**  $D = f_{xx}(a, b)f_{yy}(a, b) - (f_{xy}(a, b))^2$

If  $D > 0$  and  $f_{xx}(a, b) > 0$  then  $(a, b)$  is a local minimum

If  $D > 0$  and  $f_{xx}(a, b) < 0$  then  $(a, b)$  is a local maximum

If  $D < 0$  then  $(a, b)$  is a saddle point

If  $D = 0$  then no conclusion can be drawn

For finding max/min,  $f_{yy}$  may be used in place of  $f_{xx}$

## Ordinary Differential Equations

- Definition:**  $\sum_{i=0}^n a_i(x)y^{(i)}(x) = F(x)$

where  $a_i(x)$  and  $F(x)$  are functions of  $x$

and  $y^{(i)}(x)$  is the  $i^{\text{th}}$  derivative of  $y$  w.r.t.  $x$

- Separable equations:** Separate and integrate both sides

- Exponential decay:**  $\frac{dx}{dt} = kx \implies x(t) = x(0)e^{kt}$

$x(0)$  is the initial val.,  $k = -\frac{\ln 2}{\tau}$  where  $\tau$  is the half-life

- Exponential cooling/heating:**

$$\frac{dx}{dt} = k(x - x_0) \implies x(t) - x_0 = (x(0) - x_0)e^{kt}$$

$x(0)$  is the initial value,  $x_0$  is the target value

- Hyperbolic functions:**  $\sinh(x) = \frac{e^x - e^{-x}}{2}$

$$\cosh(x) = \frac{e^x + e^{-x}}{2} \quad \tanh(x) = \frac{e^x - e^{-x}}{e^x + e^{-x}}$$

- Linear 1<sup>st</sup> order ODEs:**  $\frac{dy}{dx} + P(x)y = Q(x)$

$$\implies ye^{\int P(x)dx} = \int Q(x)e^{\int P(x)dx} dx$$

- Bernoulli equation:**  $\frac{dy}{dx} + P(x)y = Q(x)y^n$

$$\implies \frac{dz}{dx} + (1-n)P(x)z = (1-n)Q(x) \text{ where } z = y^{1-n}$$

... which is a linear 1<sup>st</sup> order ODE

## Homogeneous linear 2<sup>nd</sup> order ODEs

$$\frac{d^2 y}{dx^2} + p(x)\frac{dy}{dx} + q(x)y = 0$$

- Superposition principle:** If  $y_1$  and  $y_2$  are **linearly independent** solns then  $c_1 y_1 + c_2 y_2$  is also a solution.

- Dimension:** The solution space has dimension 2, so finding 2 **linearly independent** solutions is sufficient to obtain the general solution

- Guessing:** Obtain 2 lin. indep. solutions by guessing

- Constant  $p(x)$  and  $q(x)$ :**

Let  $\frac{d^2 y}{dx^2} + A\frac{dy}{dx} + By = 0$ , then solutions have form  $y = e^{\lambda x}$  for some value  $\lambda$

By substitution,  $\lambda^2 + A\lambda + B = 0$ , solve for  $\lambda = \lambda_1, \lambda_2$

Two distinct real roots:  $y = c_1 e^{\lambda_1 x} + c_2 e^{\lambda_2 x}$

Two repeated (real) roots:  $y = c_1 e^{\lambda x} + c_2 x e^{\lambda x}$

Two distinct complex roots: If  $\lambda_1$  or  $\lambda_2 = a + b\sqrt{-1}$  then  $y = e^{ax}(c_1 \cos bx + c_2 \sin bx)$

Given  $\lambda_1, \lambda_2$  we can recover  $A = -(\lambda_1 + \lambda_2), B = \lambda_1 \lambda_2$

# Mathematical Modelling

- **Malthusian growth model:**

$B :=$  per capita birth rate (constant, +ve)

$D :=$  per capita death rate (constant, +ve)

$$\frac{dN}{dt} = (B - D)N \implies N(t) = N(0)e^{(B-D)t}$$

$B > D \implies$  population explosion

$B = D \implies$  stable

$B < D \implies$  extinction

- **Logistic growth model:**

$B :=$  per capita birth rate (constant)

$sN :=$  per capita death rate (linear to population)

$$\frac{dN}{dt} = (B - sN)N \implies$$

$$N(t) = \frac{B}{s + (\frac{B}{N(0)} - s)e^{-Bt}} = \frac{\frac{B}{s}}{1 + \left(\frac{B}{s} \cdot \frac{1}{N(0)} - 1\right)e^{-Bt}}$$

$$B - sN(t) > 0 \quad \forall t \implies \frac{B}{s} > N(t)$$

$\implies$  smaller than sustainable population

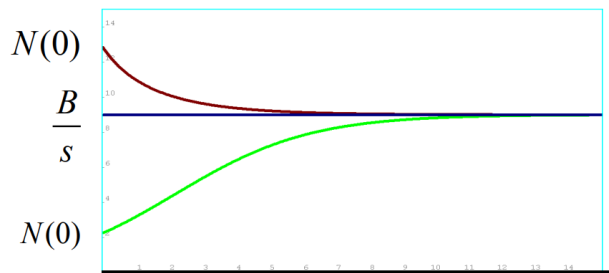
$$B - sN(t) = 0 \quad \forall t \implies \frac{B}{s} = N(t)$$

$\implies$  sustainable population (equilibrium)

$$B - sN(t) < 0 \quad \forall t \implies \frac{B}{s} < N(t)$$

$\implies$  larger than sustainable population

Population always tends to  $\boxed{\frac{B}{s}}$  — “carrying capacity”



- **Harvesting growth model:**

$B :=$  per capita birth rate (constant)

$sN :=$  per capita death rate (linear to population)

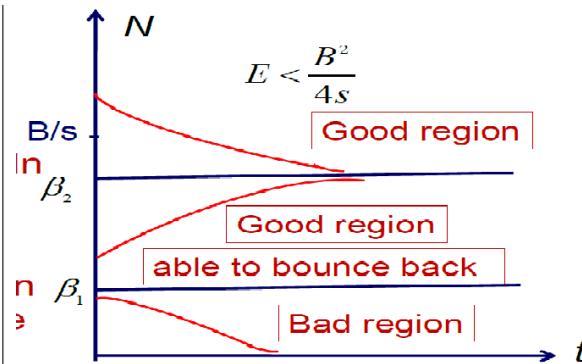
$E :=$  harvest rate

$$\frac{dN}{dt} = (B - sN)N - E = BN - sN^2 - E$$

Solve  $-sN^2 + BN - E = 0$  for equilibrium solutions

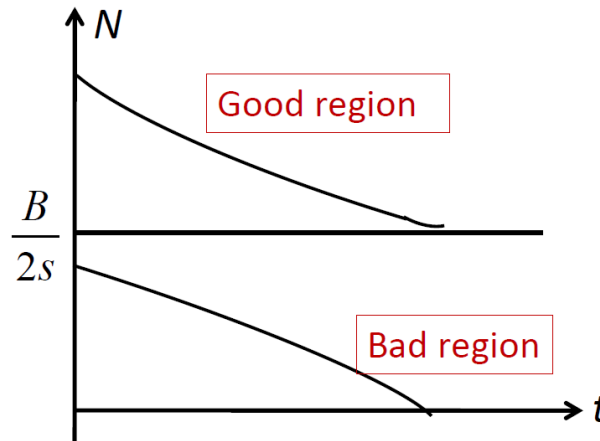
$$\implies \beta_1 < \beta_2 < \frac{B}{s}, \beta_1 + \beta_2 = \frac{B}{s} \text{ and } \beta_1\beta_2 = \frac{E}{s}$$

$$B^2 - 4sE > 0 \implies \frac{B^2}{4s} > E \implies \text{two equilibriums}$$



$$\beta_2 \text{ is stable but not } \beta_1$$

$$B^2 - 4sE = 0 \implies \frac{B^2}{4s} = E \implies \text{one equilibrium}$$



$$\implies \beta = \frac{B}{2s}$$

$$B^2 - 4sE < 0 \implies \frac{B^2}{4s} < E \implies \text{no equilibrium}$$

