clickable, active status signalled

clickable

on/off / tickbox

number input (see details)

\*\*\*\*\*\*

variable output

# Motor control:

**motor:** x  y  R          **current position:** \*\*\*\*\*

depends on selected motor

## main

**1. Position control**

show saved position

go to:       rev.       mm

Revolutions /   0.01-999.99     Pos. A    \*\*\*\*\*\*   \*\*\*\*\*\*
deg / mm on axis   0.01-999.99     Pos. B    \*\*\*\*\*\*   \*\*\*\*\*\*     } overwrite with
                    Pos. C    \*\*\*\*\*\*   \*\*\*\*\*\*        current position
RPM               Pos. D    \*\*\*\*\*\*   \*\*\*\*\*\*

-maxRPM - maxRPM ->sett.

**2. Permanent**                          **3. When pushed**

forward ○   STOP   removes                forward   mouse input:
back ○          tickbox enable            back     on until released

RPM                                    RPM

-maxRPM - maxRPM ->sett.

**4. Keyboard control**

Used for small adjustments.
Hold / click keyboard arrow produces a defined motion distance.
Keyboard arrows control number of steps. Check settings page for details.

Info:
- usually 30-120 RPM is a good choice, at higher RPM, torque decreases
- ....