

# Principles of Programming Languages

Names, Binding and Scope

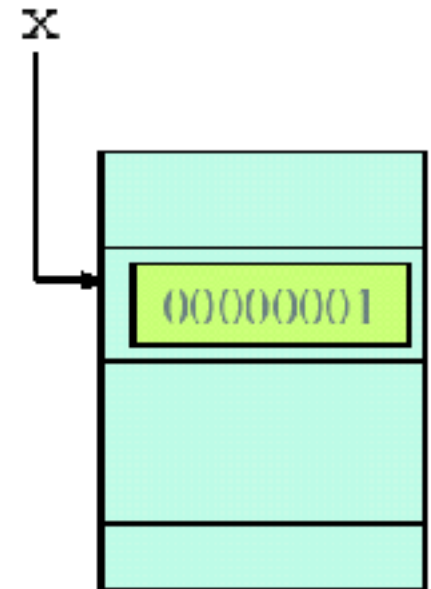
# Overview

Study fundamental semantic issues of variables:

- ◆ Attributes of variables (Sec. 5.1, 5.2, 5.3)
  - Name, value, type, address, lifetime, scope
- ◆ Binding of variables (Sec. 5.4)
- ◆ Scope and lifetime (Sec. 5.5, 5.6)
- ◆ Referencing environments (Sec. 5.7)
- ◆ Named constants (Sec. 5.8)

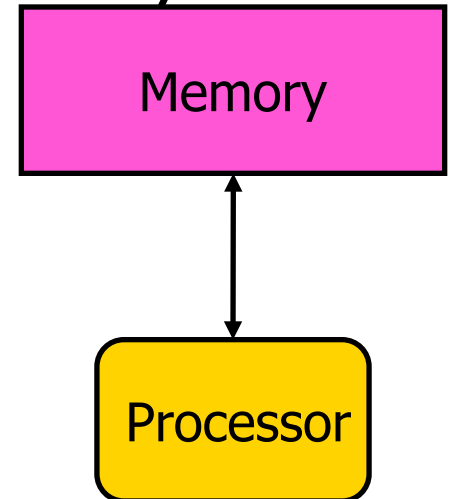
# The Concept of Variables

- ◆ What do  $x = 1$  ; and  $x = x + 1$  ; mean?
  - “=” is not the equal sign of mathematics!
  - “ $x=1$ ” does not mean “x is one” !
- ◆ “x” is the name of a variable; refer to a variable
  - A variable is an abstraction of a memory cell
  - “x” is an identifier (name) refers to a location where certain values can be stored.



# Imperative Lang. and von Neumann

- ◆ Imperative languages are abstractions of von Neumann architecture
- ◆ Key components of von Neumann architecture:
  - Memory: store data and instructions
  - Processor: do operations to modify memory contents
- ◆ Imperative language abstractions:
  - Variables  $\leftrightarrow$  memory cells
  - Expressions  $\leftrightarrow$  CPU executions



# Programmers' View of Memory

```
int i, a[100];
```

```
void foo()
```

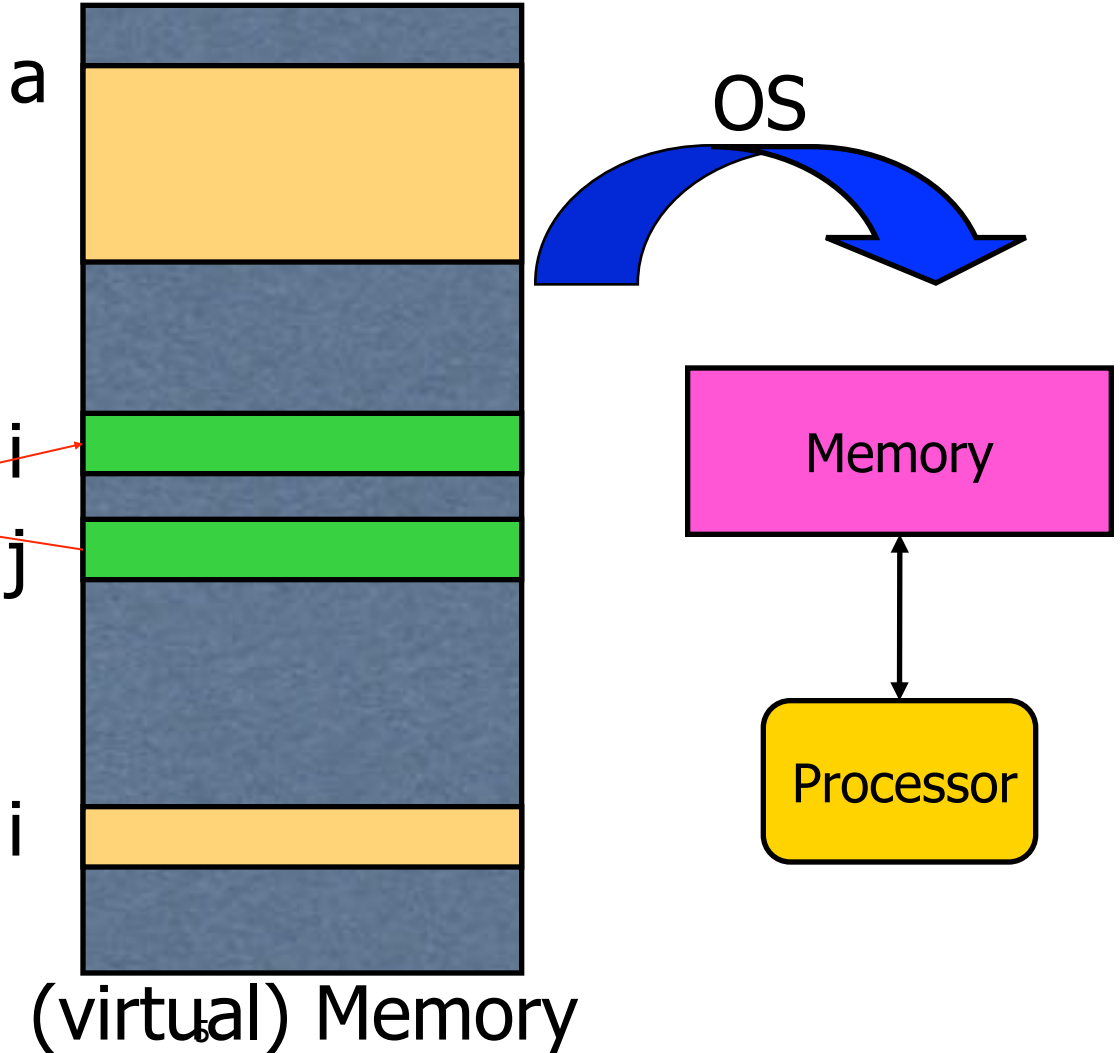
```
{ int i, j;
```

```
  .. = j;
```

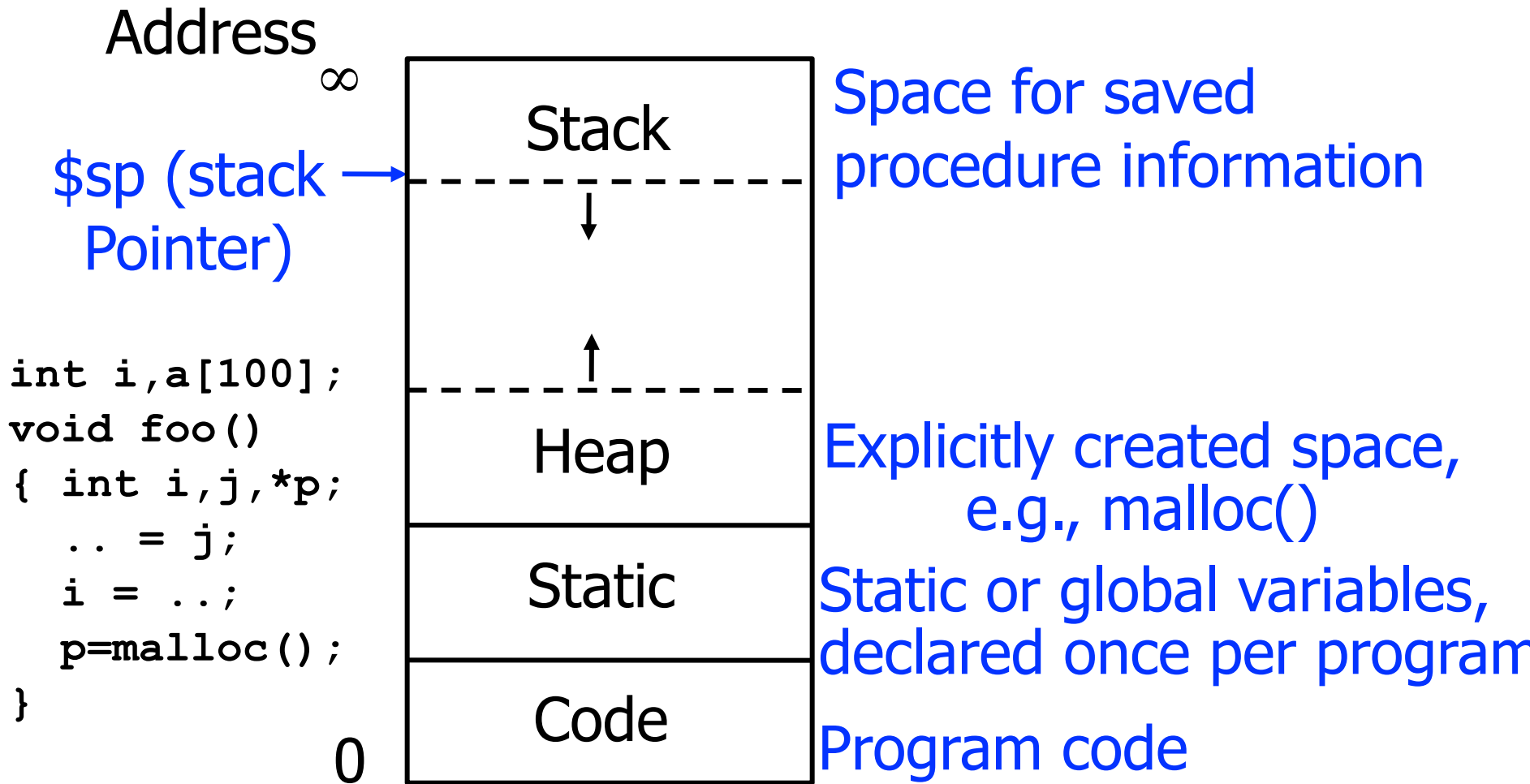
```
  i = ..;
```

```
}
```

- How variables are defined?
- How are they associated with storage?



# General Memory Layout



# Variable Attributes: Name, Value

- ◆ Name: also called identifier
  - Length:
    - Most modern PL do not impose a limit
  - Connectors: e.g., underscore “\_”
    - Most PL prefer camel notation, e.g., **MyStack**
  - Case sensitivity:
    - C, C++, and Java names are case sensitive
    - Names that look alike are different: `rose`, `ROSE`
- ◆ Value:
  - The contents of the location with which the variable is associated

# Variable Attributes: Type

## ◆ Type:

- Determines (1) the range of values that the variable can store; and (2) the set of operations that can be performed for values of that type
- Uses of type system: error detection through type checking, program modularization, documentation
- Can a variable have different types at different times?
- Are two given types equivalent?
- What happen when two variables of different types operate together?
- Type will be discussed in length in next chapter

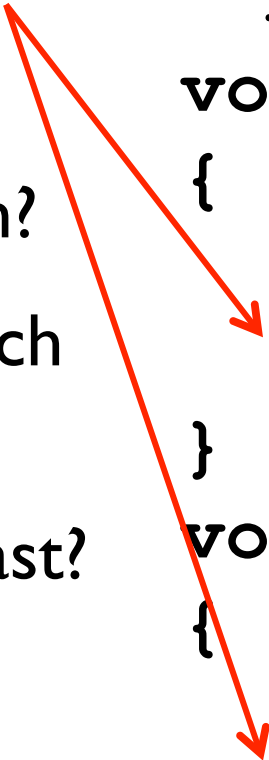


# Variable Attributes: Address

- ◆ Which address is variable `i` bound?
  - What if `foo()` is in recursion?
- ◆ Which binding is visible in which part of the code?
- ◆ For how long does a binding last?

→ **Binding** and **lifetime**

```
int
    i, a[100];
void foo()
{ int i, j;
  .. = j;
  i = ..;
}
void bar()
{ int j;
  .. = j;
  i = ..;
}
```



# The Concept of Binding

- ◆ Binding: an association, e.g. between a variable and its storage or its type
- ◆ Possible binding times
  - Language design time: bind operator symbols to operations
  - Language implementation time: bind floating point type to a representation
  - Compile time: bind a variable to a type in C or Java
  - Load time: bind a FORTRAN 77 variable to a memory cell (or a C `static` variable)
  - Runtime: bind a local variable to a memory in stack

# Static and Dynamic Binding

- ◆ A binding is static if it first occurs before run time and remains unchanged throughout program execution
- ◆ A binding is dynamic if it first occurs during execution or can change during execution

```
int i,a[100];
```

```
void foo()  
{ int i,j;  
  .. = j;  
  i = ..;  
}
```

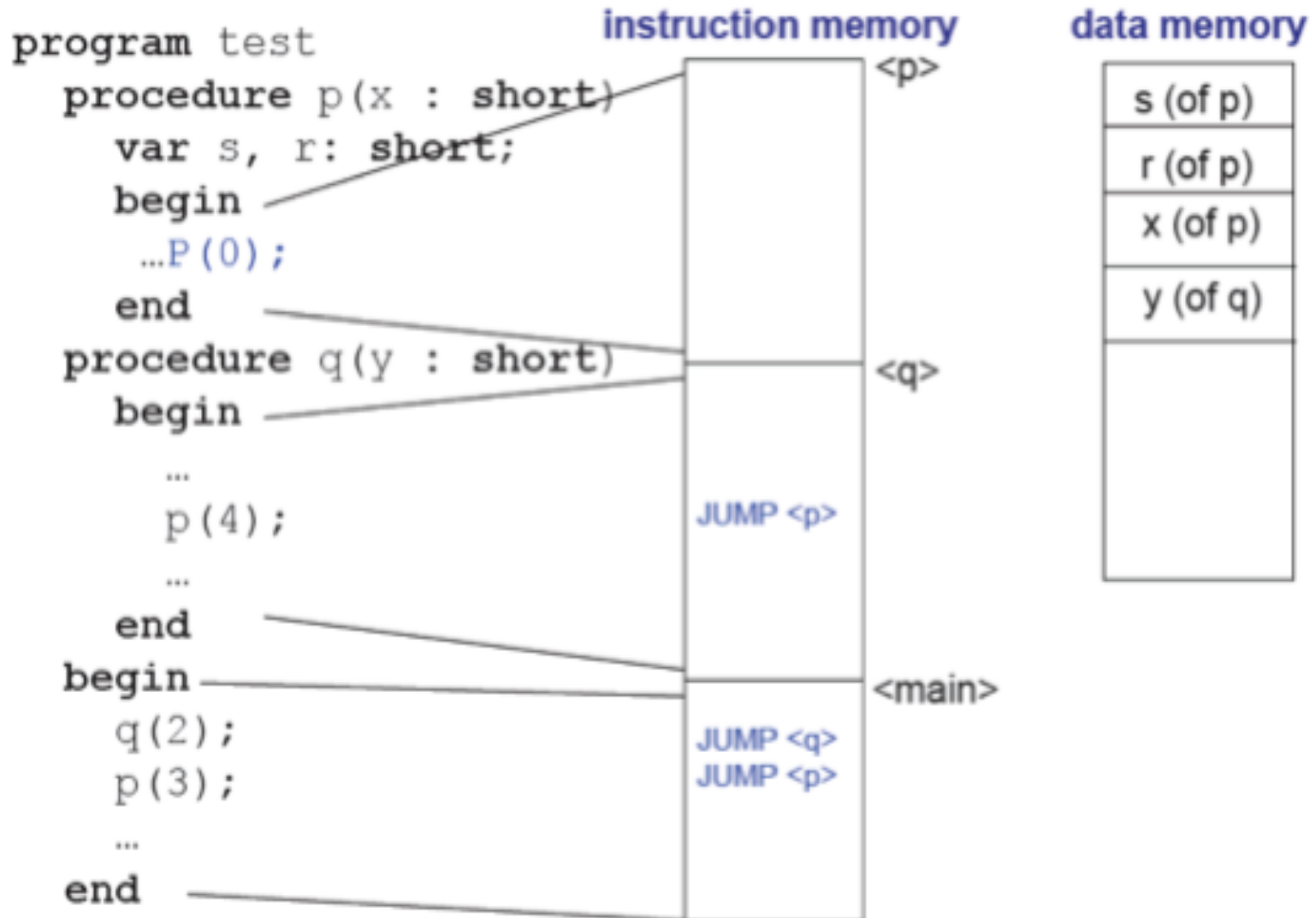
# Storage Bindings and Lifetime

- ◆ Storage binding:
  - Allocation: get a cell from some pool of available cells
  - Deallocation: put a cell back into the pool
- ◆ The lifetime of a variable is the time during which it is bound to a particular memory cell
  - Starts when a variable is bound to a specific cell and ends when it is unbound
  - Four categories for scalar variables according to lifetimes: static, stack-dynamic, explicit-heap-dynamic, implicit heap-dynamic

# Static Variables

- ◆ Bound to memory cells before execution begins and remains throughout execution, e.g., all FORTRAN 77, C static and global variables
- ◆ Advantages:
  - Efficiency (direct addressing, no runtime allocation overhead), for globally accessible variables, history-sensitive subprogram support
- ◆ Disadvantage:
  - Lack of flexibility (no recursion), no sharing of storage among variables
  - Size of data objects must be known at compile time
  - Data structures cannot be created dynamically

# Static Memory Model Cannot Support Recursion



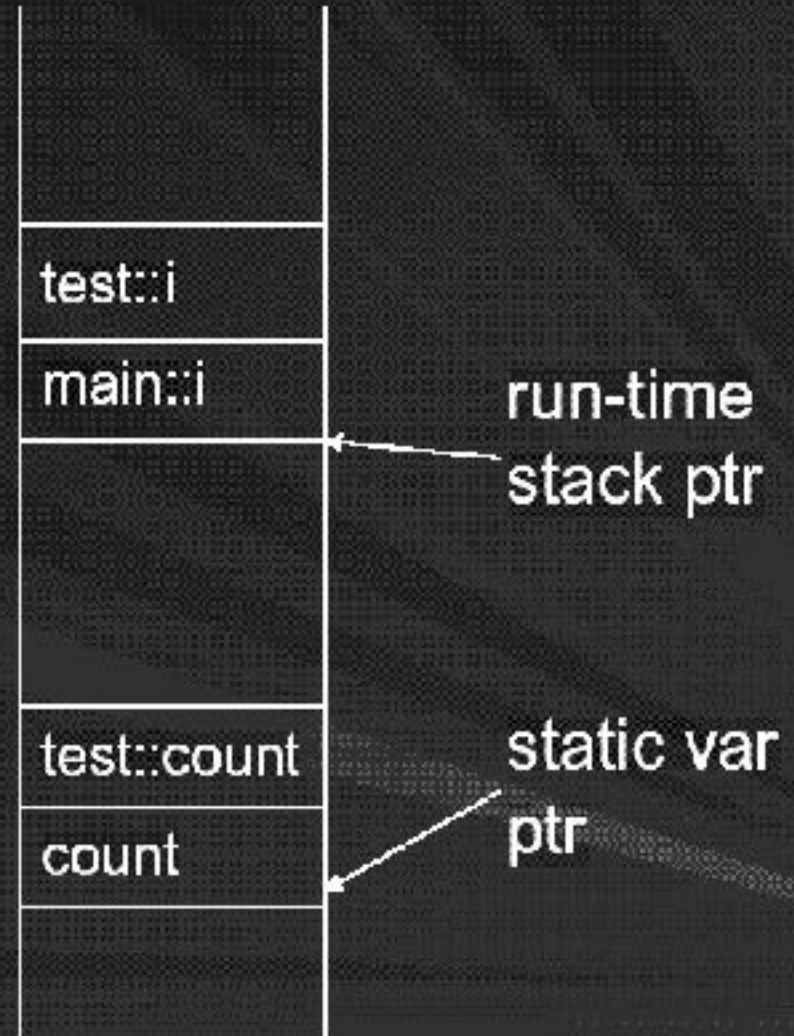
# Stack-dynamic Variables

- ◆ Storage bindings are created when declaration statements are elaborated at runtime
  - If scalar, all attributes except address are statically bound, e.g., local variables in C subprograms and Java methods, allocated from the runtime stack
- ◆ Advantage:
  - Allows recursion; conserves storage by all subprog.
- ◆ Disadvantages:
  - Overhead of allocation and deallocation
  - Subprograms cannot be history sensitive
  - Inefficient references (indirect addressing)

# Stack-dynamic Variables

```
#include <stdio.h>
int count;
main( ) {
    int i ;
    for (i=0; i<=10; i++)
    { test( ) ; }
}
test( ) {
    int i ;
    static int count = 0;
    count = count + 1 ;
}
```

virtual address space





# Explicit Heap-dynamic Variables

- ◆ Heap: a section of virtual address space reserved for dynamic memory allocation
- ◆ Allocated and deallocated (in heap) by explicit directives or operators, specified by the programmer, which take effect during execution
  - Referenced through pointers or references, e.g. dynamic objects in C++ (via **new** and **delete**)
  - Static type binding, dynamic storage binding
  - Explicit or implicit deallocation (garbage collection)

# Explicit Heap-dynamic Variables

```
Person *p;
```

```
p=(Person *) malloc(sizeof Person);
```

```
p->name = "Mike"; p->age = 40;
```

```
free(p);
```

- ◆ Java objects are explicit heap-dynamic variable
  - implicit garbage collection (no free or delete)
- ◆ Advantage: can construct dynamic structures
- ◆ Disadvantage: inefficient, unreliable, heap management cost

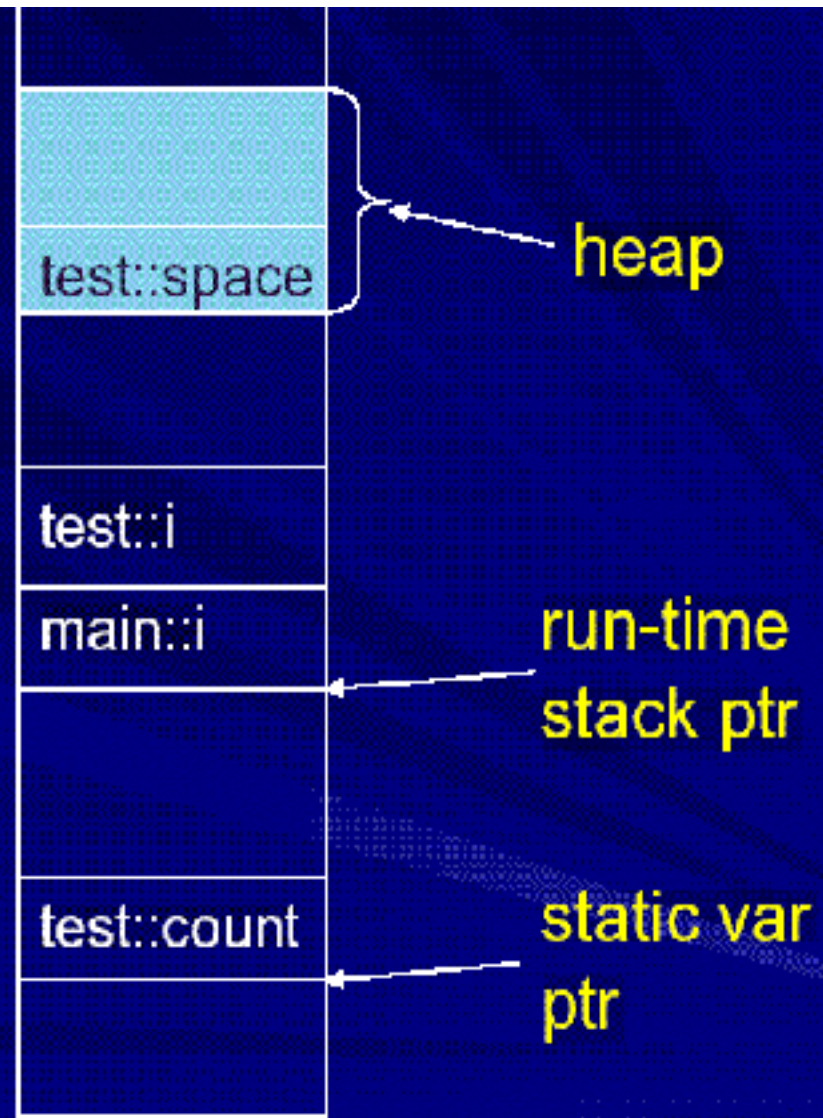
# Explicit Heap-dynamic Variables

```
#include <stdio.h>

main() {
    int i;
    test();
}

test() {
    int i;
    char *space;
    static int count = 0;
    space = (char *) malloc(64);
    // memory leak
}
```

virtual address space



# Implicit Heap-dynamic Variables

- ◆ Allocation and deallocation caused by assignment statements, regardless of what the variable was previously used for
  - All variables in APL; all strings and arrays in Perl and JavaScript
- ◆ Advantage: flexibility
- ◆ Disadvantages:
  - Runtime overhead for maintaining dynamic attributes
  - Loss of error detection by compiler

# Why Scope?

- Two bindings for “x”
  - One of type `int`
  - Another `float`

An occurrence of “x”

```
int x;  
void foo (int y)  
{ float x;  
  ... x ...  
}  
int main() {  
  ...  
  foo(x) ;  
  // which binding of x?  
  ...  
}
```

# Scope

- ◆ The scope of a variable is the range of statements over which it is visible
  - A variable is visible in a statement if it can be referenced in that statement
- ◆ The nonlocal variables of a program unit are those that are visible but not declared there
- ◆ The scope rules of a language determine how a reference to a name is associated with a variable and its declaration

# Scope

- `"int X;"`  
has a global scope

- `"float X;"`  
has a local scope.

```
int X = 0;  
void foo (int X)  
{  
    float X;  
    X = ...    // which X?  
}  
int main() {  
    int y;  
    foo(X);    // which X?  
    ...  
}
```

# Static Scope

- ◆ Scope of a variable can be statically determined
  - Based on program text, a spatial concept
- ◆ To connect a name reference to a variable, you (or the compiler) must find the declaration
  - First search locally, then in increasingly larger enclosing scopes, until one is found for the given name, or an undeclared variable error



# Static Scope

- ◆ Variables can be hidden from a unit by having a "closer" variable with the same name

- C++ and Ada allow access to "hidden" variables:

`unit.name` (in Ada)

`class_name::name` (in C++)

- ◆ Block: a method of creating new static scopes inside program units (from ALGOL 60)

- e.g.: C and C++ in any compound statement

```
for (...) {  
    int index;  
    ...  
}
```

# An Example of Block Scope in C

```
int x;  
void p(void)  
{  
    int i; ...  
}  
void q(void)  
{  
    int j; ...  
}  
main()  
{  
    int k; ...  
}
```

The diagram illustrates the block scope of variables in the provided C code. It uses nested curly braces to group the code blocks and labels to identify the scope of each variable:

- The outermost brace, labeled `x`, encompasses the entire code block, indicating that `x` is in global scope.
- The next level brace, labeled `p`, encompasses the `void p(void)` function block, indicating that variables declared within `p` are in its local scope.
- The next level brace, labeled `q`, encompasses the `void q(void)` function block, indicating that variables declared within `q` are in its local scope.
- The next level brace, labeled `main`, encompasses the `main()` function block, indicating that variables declared within `main` are in its local scope.
- Inside the `main` block, there are three individual braces labeled `k`, `j`, and `i`, each corresponding to a variable declared within that specific block.

# Dynamic Scope

- ◆ Based on calling sequences of program units, not their textual layout (temporal versus spatial)
  - Can only be determined at run time
- ◆ References to variables are connected to declarations by searching back through the chain of subprogram calls that forced execution to this point

# Scope Example

```
MAIN
[ - declaration of x
  SUB1
  [ - declaration of x
    ...
    call SUB2
    ...
  ]
  SUB2
  [ ...
    - reference to x
    ...
  ]
  ...
call SUB1
...
```

MAIN calls SUB1  
SUB1 calls SUB2  
SUB2 uses x

Static scoping:

Reference to x in SUB2  
is to MAIN's x

Dynamic scoping:

Reference to x in SUB2  
is to SUB1's x

# Static vs. Dynamic Scoping

```
program MAIN;
  var a : integer;

  procedure P1;
  begin
    print a;
  end; {of P1}

  procedure P2;
  var a : integer;
  begin
    a := 0;
    P1;
  end; {of P2}

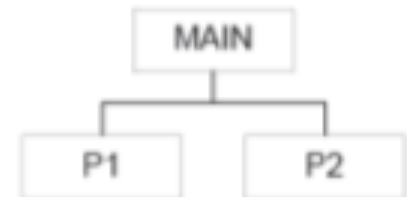
begin
  a := 7;
  P2;
end. {of MAIN}
```

## static (lexical)

non-local variables are  
bound based on program  
structure

if not local, go "out" a level

→ example prints 7

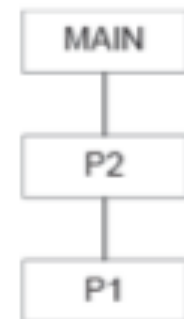


## dynamic

non-local variables are  
bound based on calling  
sequence

if not local, go to calling point

→ example prints 0



# Evaluation of Dynamic Scope

## ◆ Advantage:

- Convenience (no need to pass parameters from caller to callee)

## ◆ Disadvantage:

- Local variables of an active subprogram are visible to any other active subprograms → reliability
- Cannot statically type check references to nonlocals
- Poor readability
- Longer accesses to nonlocal variables

# Scope and Lifetime

- ◆ Scope and lifetime are sometimes closely related, but are different concepts
- ◆ Ex.: a `static` variable in a C or C++ function
  - Scope is static and local to the function
  - Lifetime extends over entire execution of program
- ◆ Ex.: subprogram calls

```
void printhead() { ... }  
void compute() {  
    int sum; ...    //scope vs lifetime of sum  
    printhead();  
}
```

# Referencing Environments

- ◆ Referencing environment of a statement is the collection of all names visible to the statement
- ◆ In a static-scoped language, it is the local variables plus all of the visible variables in all of the enclosing scopes
- ◆ In a dynamic-scoped language, the referencing environment is the local variables plus all visible variables in all active subprograms
  - A subprogram is active if its execution has begun but has not yet terminated



# Referencing Environments

```
procedure Example is
  A, B : Integer;
  ...
  procedure Sub1 is
    X, Y : Integer;
    begin -- of Sub1
    ... <----- 1
    end; -- of Sub1
  procedure Sub2 is
    X : Integer;
    ...
    procedure Sub3 is
      X : Integer;
      begin -- of Sub3
      ... <----- 2
      end; -- of Sub3
    begin -- of Sub2
    ... <----- 3
    end; -- of Sub2
  begin -- of Example
  ... <----- 4
  end. -- of Example
```

*Referencing Environment*

X and Y of Sub1, A and B of Example

X of Sub3, (X of Sub2 is hidden), A and B of Example

X of Sub2, A and B of Example

# Named Constants

- ◆ A named constant is a variable that is bound to a value only once, when it is bound to storage
  - Advantages: readability, modifiability, can be used to parameterize programs
- ◆ Binding of values to named constants can be static (called manifest constants) or dynamic
  - FORTRAN 90: only constant-valued expressions
  - Ada, C++, Java: expressions of any kind
- ◆ The binding of a variable to a value at the time it is bound to storage is called initialization
  - Often done on declaration statement

# Summary

- ◆ Variables are abstractions for memory cells of the computer and are characterized by name, address, value, type, lifetime, scope
- ◆ Binding is the association of attributes with program entities: type and storage binding
- ◆ Scope determines the visibility of variables in a statement