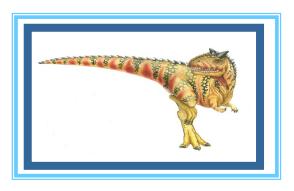


Chapter 5: CPU Scheduling





CPU Scheduling CPU调度

- 5.1 <u>Basic Concepts</u>
- 5.2 <u>Scheduling Criteria</u>
- 5.3 <u>Scheduling Algorithms</u>
- 5.4 *Multiple-Processor Scheduling*
- 5.5 <u>Real-Time Scheduling</u>
- 5.6 Thread Scheduling
- 5.7 Operating Systems Examples
- 5.8 Java Thread Scheduling
- 5.9 Algorithm Evaluation



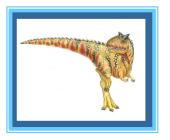


OBJECTIVES

- Describe various CPU scheduling algorithms.
- Assess CPU scheduling algorithms based on scheduling criteria.
- Explain the issues related to multiprocessor and multicore scheduling.
- Describe various real-time scheduling algorithms.
- Describe the scheduling algorithms used in the Windows, Linux, and Solaris operating systems.
- Apply modeling and simulations to evaluate CPU scheduling algorithms.
- Design a program that implements several different CPU scheduling algorithms.



5.1 Basic Concepts





5.1 Basic Concepts

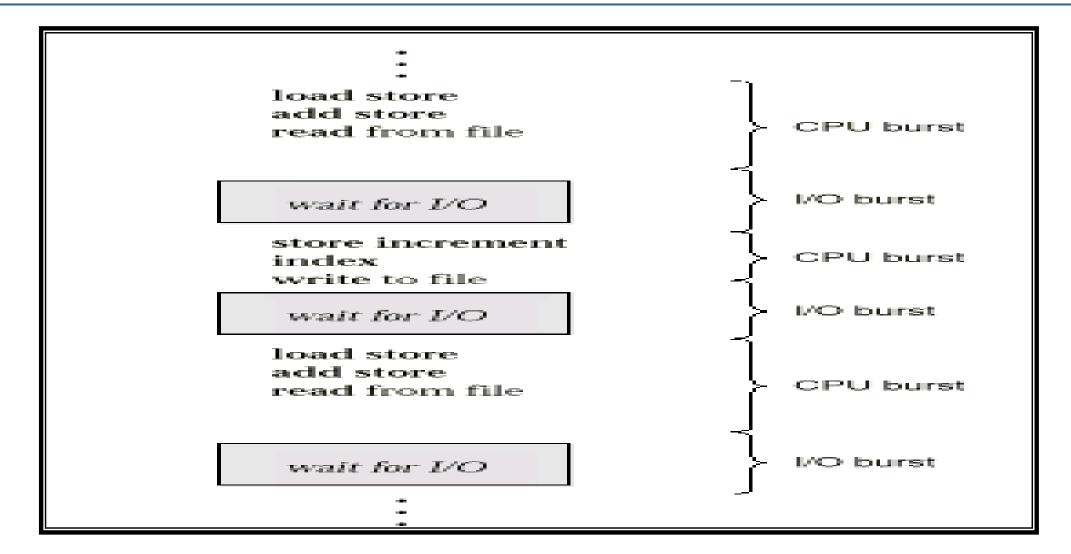
- CPU调度==处理机调度==进程调度
- Maximum CPU utilization obtained with multiprogramming
- CPU、I/O Burst Cycle脉冲(运行)周期– Process execution consists of a cycle of CPU execution and I/O wait.
- CPU Burst Time \ I/O Burst Time
- CPU-bound、I/O-bound program (CPU型、I/O型程序)
- CPU burst distribution







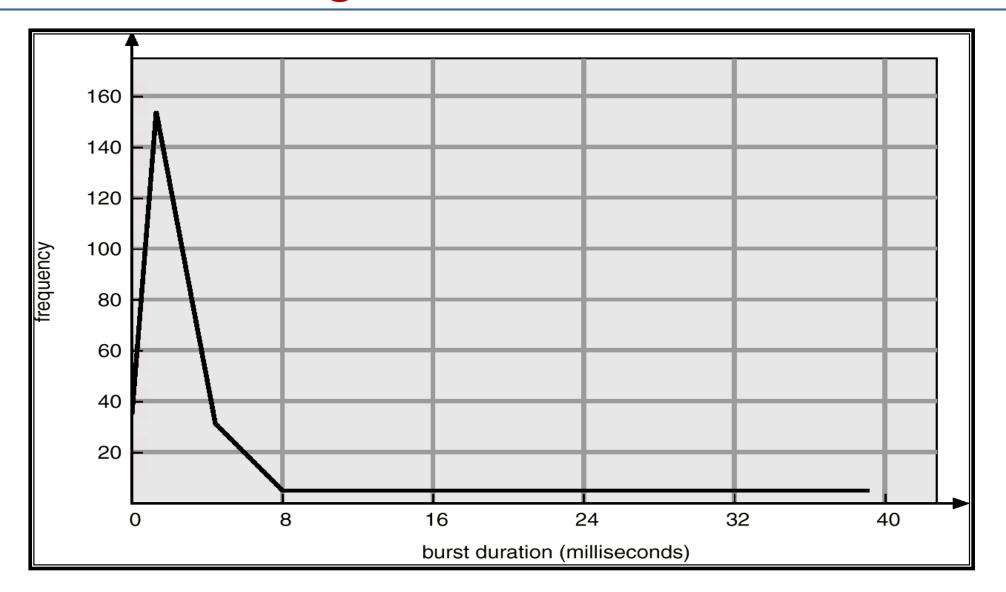
Fig 5.1 Alternating Sequence of CPU And I/O Bursts







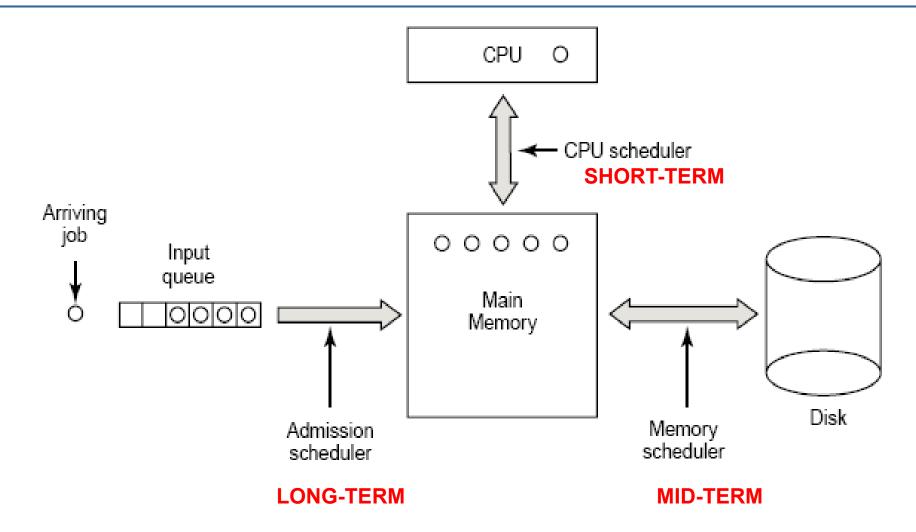
Histogram of CPU-burst Times







Three-level Scheduling

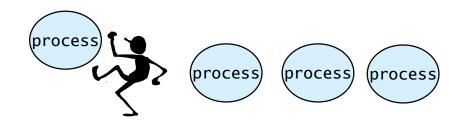






CPU Scheduler

- CPU scheduling decisions may take place when a process (调度的时机):
 - 1. Switches from running to waiting state.
 - 2. Switches from running to ready state.
 - 3. Switches from waiting to ready.
 - 4. Terminates.



■ 调度方式:

- 非抢占式(Nonpreemptive)调度:调度程序一旦把处理机分配给某进程后便让它一直运行下去,直到进程完成或发生某事件而阻塞时,才把处理机分配给另一个进程。如上1、4
- 抢占式 (Preemptive) 调度: 当一个进程正在运行时, 系统可以基于某种原则, 剥夺已分配给它的处理机, 将之分配给其它进程。剥夺原则有: 优先权原则、短进程优先原则、时间片原则。如上2、3



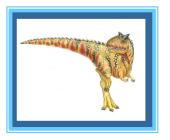


Dispatcher (调度程序)

- Dispatcher module gives control of the CPU to the process selected by the short-term scheduler; this involves:
 - switching context
 - switching to user mode
 - jumping to the proper location in the user program to restart that program
- Dispatch latency(调度延迟) time it takes for the dispatcher to stop one process and start another running调度程序停止一个进程到启动一个进程所需要的时间
 - Linux命令: vmstat



5.2 Scheduling Criteria





调度算法的选择准则和评价

1.面向用户(User-oriented)的准则和评价

- **周转时间**Turnaround time: 进程从提交到完成所经历的时间。包括: 在CPU上执行, 就绪队列和阻塞队列中等待。
 - 周转时间 T=完成时间-提交时间
 - 平均周转时间=∑周转时间/进程数
 - 带权周转时间W= T(周转时间)/t(CPU执行时间)
 - 平均带权周转时间=∑W/进程数
- 响应时间Response time: 从进程提出请求到首次被响应(而不是输出结果)的时间段(在分时系统环境下)
- 等待时间Waiting time 进程在就绪队列中等待的时间总和
- 截止时间: 开始截止时间和完成截止时间——实时系统, 与周转时间有些相似。
- 公平性:不因作业或进程本身的特性而使上述指标过分恶化。如长进程等待很长时间。
- 优先级:可以使关键任务达到更好的指标





调度算法的选择准则和评价

2. 面向系统的调度性能准则

- 吞吐量Throughput:单位时间内所完成的进程数,跟进程本身特性和调度算法都有关系 ——批处理系统
 - 平均周转时间不是吞吐量的倒数,因为并发执行的进程在时间上可以重叠。如:在2
 小时内完成4个进程,而每个周转时间是1小时,则吞吐量是2个进程/小时
- 处理机利用率CPU utilization: 使CPU尽可能的忙碌
- 各种设备的均衡利用:如CPU繁忙的进程和I/O繁忙的进程搭配——大中型主机

3. 调度算法本身的调度性能准则

- 易于实现
- 执行开销比较小





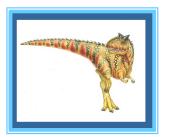
4. Optimization Criteria最优准则

- 最大的CPU利用率 Max CPU utilization
- 最大的吞吐量 Max throughput
- 最短的周转时间 Min turnaround time
- 最短的等待时间 Min waiting time
- 最短的响应时间 Min response time

■公平



5.3 Scheduling Algorithms





Scheduling Algorithms

- First-Come, First-Served (FCFS) Scheduling先来先服务调度
- Shortest-Job-First (SJF) Scheduling 短作业优先调度
- Priority Scheduling 优先权调度
- Round Robin (RR) 时间片轮转调度
- Multilevel Queue Scheduling 多级队列调度
- Multilevel Feedback Queue Scheduling多级反馈队列调度
- 高响应比优先调度算法 Highest Response Ratio Next(HRRN)
 - 响应比R=(等待时间+要求执行时间)/要求执行时间





5.3.1 First-Come, First-Served (FCFS) Scheduling

■ FCFS算法

- 按照进程或作业提交顺序形成就绪状态的先后次序,分派CPU
- 当前进程或作业占用CPU, 直到执行完或阻塞, 才出让CPU(非抢占方式)
- 在进程或作业唤醒后(如I/O完成),并不立即恢复执行,通常等到当前 作业或进程出让CPU
- 最简单的算法
- FCFS的特点
 - 比较有利于长进程,而不利于短进程。
 - 有利于CPU Bound的进程,而不利于I/O Bound的进程。





FCFS Scheduling(Cont.)

<u>Process</u>	Burst Time
P_I	24
P_2	3
P_3	3

- Suppose that the processes arrive in the order: P_1 , P_2 , P_3
- The Gantt Chart for the schedule is:



- Waiting time for P1 = 0; P2 = 24; P3 = 27
- Turnaround time for P1 = 24; P2 = 27; P3 = 30
- Average waiting time: (0 + 24 + 27)/3 = 17
- Average Turnaround time: (24 + 27 + 30)/3 = 27

turnaround time = termination time - arrival time.





FCFS Scheduling (Cont.)

- Suppose that the processes arrive in the order P_2 , P_3 , P_1 .
- The Gantt chart for the schedule is:

	P ₂	P ₃	P ₁
0		3	6 30

	Waiting	time:	<i>for P1 =</i>	6; P2 =	= 0; P3 =	3
--	---------	-------	-----------------	---------	-----------	---

- Turnaround time: for P1 = 30; P2 = 3; P3 = 6
- Average waiting time : (6 + 0 + 3)/3 = 3
- Average Turnaround time: (30 + 3 + 6)/3 = 13
- Much better than previous case.
- Convoy effect short process behind long process

Waiting time = turnaround time - burst time.

Process	CPU
P_1	24
P_2	3
P_3	3

What if the arrival order is changed?





5.3.2 Shortest-Job-First (SJF) Scheduling

■ 又称为"短进程优先" SPF(Shortest Process First); 这是对FCFS算法的改进, 其目标是减少平均周转时间。

■ SJF算法:

- 对预计执行时间短的作业(进程)优先分派处理机。
- Two schemes:
 - nonpreemptive once CPU given to the process it cannot be preempted until completes its CPU burst
 - preemptive if a new process arrives with CPU burst length less than remaining time of current executing process, preempt. This scheme is know as the Shortest-Remaining-Time-First (SRTF)
- SJF is optimal gives minimum average waiting time for a given set of processes.





CPU Scheduling 季江民

SJF的变型

- 最短剩余时间优先SRT(Shortest Remaining Time)-基于抢占的SJF算法
 - 允许比当前进程剩余时间更短的进程来抢占
- 最高响应比优先HRRN(Highest Response Ratio Next)
 - 响应比R=(等待时间+要求执行时间)/要求执行时间
 - 是FCFS和SJF的折衷



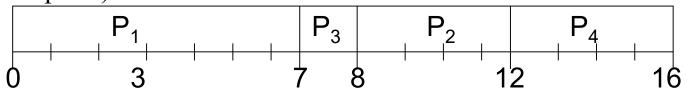




Example of Non-Preemptive SJF

Process	Arrival Time	Burst Time
P_I	0	7
P_2	2	4
P_3	4	1
P_{4}	5	4

■ SJF (non-preemptive)



- *Average Turnaround time*=(7+10+4+11)/4=8
- Average waiting time = (0 + 6 + 3 + 7)/4 = 4

turnaround time = termination time - arrival time.

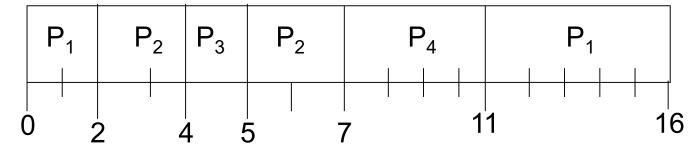




Example of Preemptive SJF

Process	Arrival Time	Burst Time
P_{I}	0	7
P_2	2	4
P_3	4	1
P_{4}	5	4

■ SJF (preemptive)



- *Average Turnaround time*=(16+5+1+6)/4=7
- Average waiting time = (9 + 1 + 0 + 2)/4 = 3





5.Determining Length of Next CPU Burst

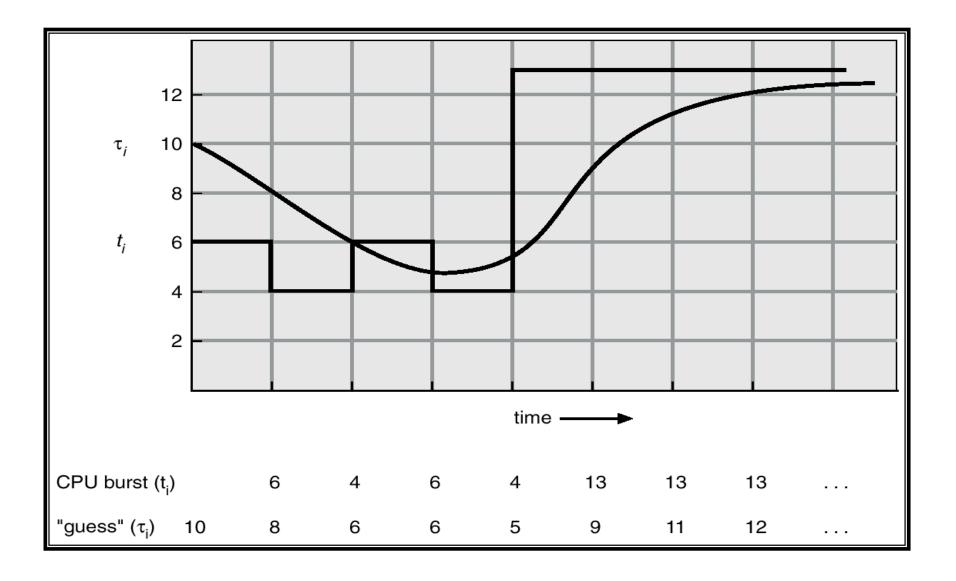
- Can only estimate the length.
- Can be done by using the length of previous CPU bursts, using exponential averaging.
 - 1. $t_n = \text{actual lenght of } n^{th} \text{CPU burst}$
 - 2. τ_{n+1} = predicted value for the next CPU burst
 - 3. α , $0 \le \alpha \le 1$
 - 4. Define:

$$\tau_{n+1} = \alpha t_n + (1 - \alpha)\tau_n.$$





Fig 5.3 Prediction of the Length of the Next CPU Burst







Examples of Exponential Averaging

- $\alpha = 0$
 - $\bullet \quad \tau_{n+1} = \tau_n$
 - Recent history does not count.
- $\alpha = 1$
 - $\bullet \quad \tau_{n+1} = t_n$
 - Only the actual last CPU burst counts.
- If we expand the formula, we get:

$$\tau_{n+1} = \alpha t_n + (1 - \alpha) \alpha t_n - 1 + \dots$$

$$+ (1 - \alpha)^j \alpha t_n - 1 + \dots$$

$$+ (1 - \alpha)^{n+1} t_n \tau_0$$

Since both α and $(1 - \alpha)$ are less than or equal to 1, each successive term has less weight than its predecessor.



5.3.3 Priority Scheduling

- Associate a priority number with each process
- **该算法总是把处理机分配给就绪队列中具有最高优先权的进程。**常用以下两种方法来确定进程的优先权:
 - **静态优先权**: 静态优先权是在创建进程时确定的, 在整个运行期间不再改变。依据有: 进程类型、进程对资源的要求、用户要求的优先权。
 - 动态优先权: 动态优先权是基于某种原则, 使进程的优先权随时间改变而改变。
- 假定:最小的整数 = 最高的优先级.

typically, a lower priority number indicates a higher priority

■ SJF是以下一次CPU脉冲长度作为优先数的优先级调度





Priority Scheduling

- Is priority scheduling preemptive or non-reemptive?
 - Non-preemptive priority scheduling places higher-priority processes at the head of the queue
 - Preemptive priority scheduling requires a running process to be interrupted and preempted upon the arrival of a higher-priority process

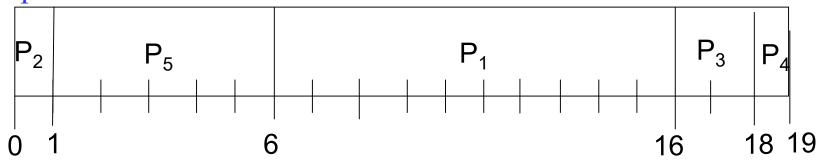




Example of Priority Scheduling

Process	Burst Time	Priority
P_I	10	3
P_2	1	1
P_3	2	4
P_4	1	5
P_5	5	2

non-preemptive



- *Average Turnaround time*=(16+1+18+19+6)/5=12
- Average waiting time = (6+0+16+18+1)/5 = 8.2

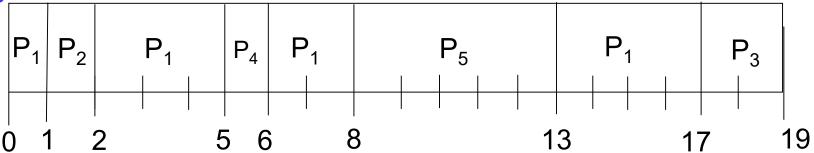




Example of Priority Scheduling

Process	Arrival Time	Burst Time	<u>Priority</u>
P_I	0	10	3
P_2	1	1	1
P_3	4	2	4
P_4	5	1	2
P_5	8	5	2

preemptive



- *Average Turnaround time*=(17+1+15+1+5)/5=7.8
- Average waiting time = (7+0+13+0+0)/5 = 4





Priority Scheduling (Cont.)

■ Problem: Starvation(饥饿)— low priority processes may never execute.

(Rumor has it that ,When they shut down the IBM 7094 at MIT in 1973,they found a low-priority process that had been submitted in 1967 and had not yet been run)





■ Solution: Aging(老化)— as time progresses increase the priority of the process.——动态优先级





5.3.4时间片轮转调度Round Robin (RR)

■ 基本思路: 通过时间片轮转, 提高进程并发性和响应时间特性, 从而提高资源利用率。

■ RR算法:

- 将系统中所有的就绪进程按照FCFS原则,排成一个队列。
- 每次调度时将CPU分派给队首进程,让其**执行一个时间片**(time slice)。时间片的长度从几个ms到几百ms。
- 在一个时间片结束时,发生时钟中断。
- 调度程序据此暂停当前进程的执行,将其送到就绪队列的末尾,并通过上下文切换执行 当前的队首进程。
- 进程可以未使用完一个时间片,就出让CPU(如阻塞)。





5.3.4 Round Robin (RR)

■ Each process gets a small unit of CPU time (*time quantum*), usually 10-100 milliseconds. After this time has elapsed, the process is preempted and added to the end of the ready queue.



RR情境





Round Robin

- Performance
 - $q \text{ large} \Rightarrow \text{FIFO}$



- $q \text{ small} \Rightarrow q \text{ must be large with respect to context switch, otherwise overhead is too high}$
- 时间片长度的影响因素:
 - 就绪进程的数目:数目越多,时间片越小(当响应时间一定时)
 - 系统的处理能力:应当使用户输入通常在一个时间片内能处理完,否则使响应时间,平均周转时间和平均带权周转时间延长。

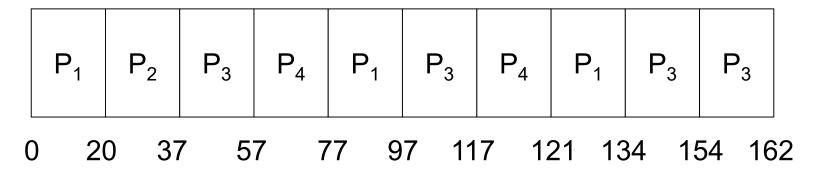




Example of RR with Time Quantum = 20

<u>Process</u>	Burst Time
P_{I}	53
P_2	17
P_3	68
P_4	24

■ The Gantt chart is:

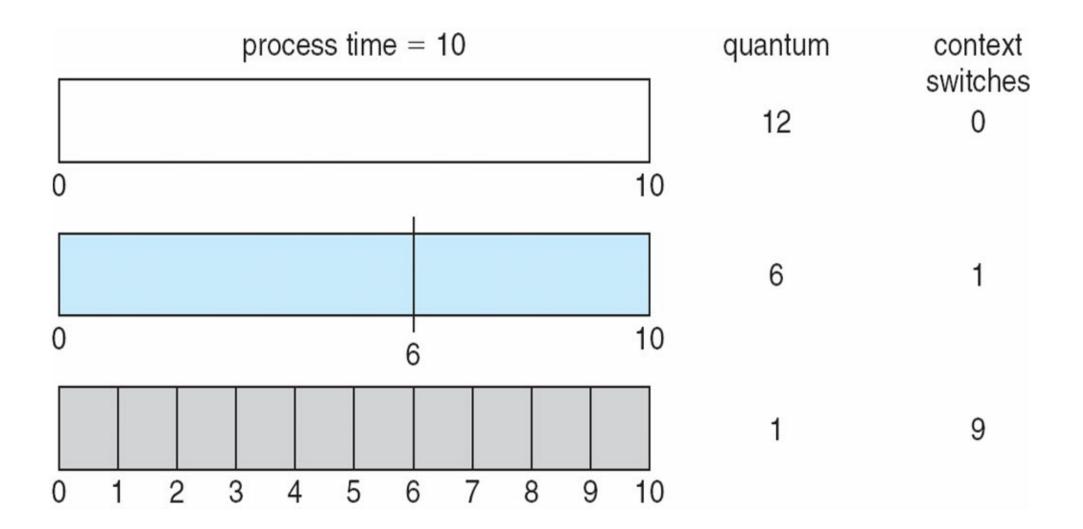


- Average Turnaround time=(134+37+162+121)/4=113.5
- Average waiting time = (81+20+94+97)/4=70.5
- Typically, higher average turnaround than SJF, but better *response*.





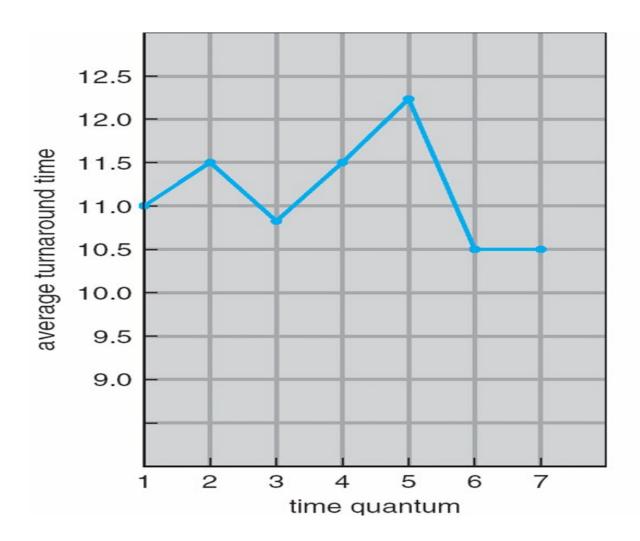
Fig 5.4 Time Quantum and Context Switch Time







Turnaround Time Varies With The Time Quantum



process	time
P_1	6
P_2	3
P_3	1
P_4	7

80% of CPU bursts should be shorter than q





5.3.5 多级队列调度

- 根据进程的性质或类型的不同,将就绪队列再分为若干个子队列。
- 每个作业固定归入一个队列。
- 各队列的不同处理:不同队列可有不同的优先级、时间片长度、调度策略等。如:系统进程、用户交互进程、批处理进程等。

本算法引入多个就绪队列,通过各队列的区别对待, 达到一个综合的调度目标





Multilevel Queue Scheduling

5.39

- Ready queue is partitioned into separate queues:
 - foreground (interactive) 前台(交互式)
 - background (batch) 后台 (批处理)
- Each queue has its own scheduling algorithm:
 - foreground RR
 - background FCFS





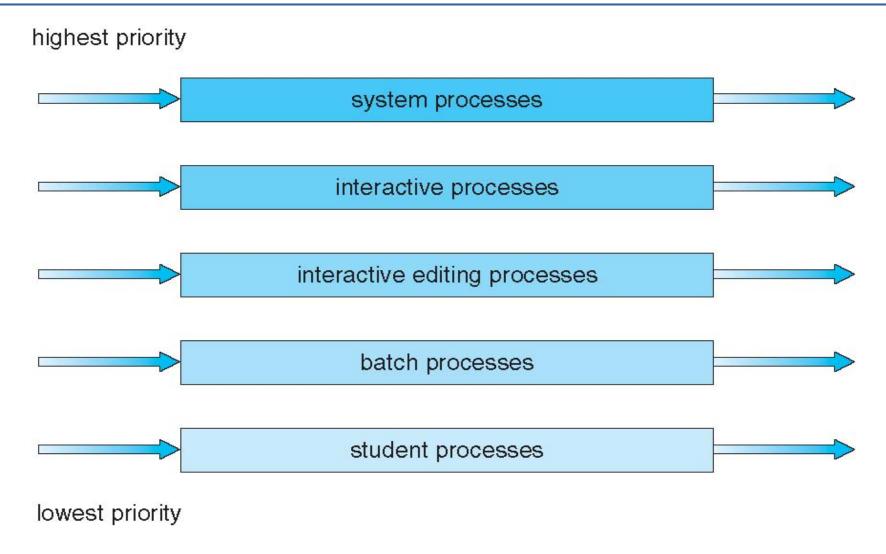
Multilevel Queue Scheduling (Cont.)

- 多级队列算法调度须在队列间进行
 - 固定优先级调度,即前台运行完后再运行后台。有可能产生饥饿
 - **给定时间片调度**,即每个队列得到一定的CPU时间,进程在给定时间内执行;如,80%的时间执行前台的RR调度,20%的时间执行后台的FCFS调度





Multilevel Queue Scheduling (Cont.)







5.3.6 Multilevel Feedback Queue Scheduling

- 多级反馈队列算法是时间片轮转算法和优先级算法的综合和发展。优点:
 - 为提高系统吞吐量和缩短平均周转时间而照顾短进程
 - 为获得较好的I/O设备利用率和缩短响应时间而照顾I/O型进程
 - 不必估计进程的执行时间, 动态调节





多级反馈队列算法

- 设置多个就绪队列,分别赋予不同的优先级,如逐级降低,队列1的优先级最高。每个队列执行时间片的长度也不同,规定优先级越低则时间片越长,如逐级加倍
- 新进程进入内存后,先投入队列1的末尾,按FCFS算法调度;若按队列1一个时间片未能执行完,则降低投入到队列2的末尾,同样按FCFS算法调度;如此下去,降低到最后的队列,则按"时间片轮转"算法调度直到完成。
- 仅当较高优先级的队列为空,才调度较低优先级的队列中的进程执行。如果 进程执行时有新进程进入较高优先级的队列,则抢占执行新进程,并把被抢 占的进程投入原队列的末尾。





几点说明

- I/O型进程: 让其进入最高优先级队列,以及时响应I/O交互。通常执行一个小时间片,要求可处理完一次I/O请求的数据,然后转入到阻塞队列。
- **计算型进程**:每次都执行完时间片,进入更低级队列。最终采用最大时间片 来执行,减少调度次数。
- I/O次数不多,而主要是CPU处理的进程:在I/O完成后,放回优先I/O请求时离开的队列,以免每次都回到最高优先级队列后再逐次下降。
- 为适应一个进程在不同时间段的运行特点, I/O完成时, 提高优先级; 时间片用完时, 降低优先级;





Example of Multilevel Feedback Queue

- Example of Multilevel Feedback Queue Three queues:
 - Q_0 time quantum 8 milliseconds
 - Q_1 time quantum 16 milliseconds
 - $Q_2 FCFS$





Example of Multilevel Feedback Queue

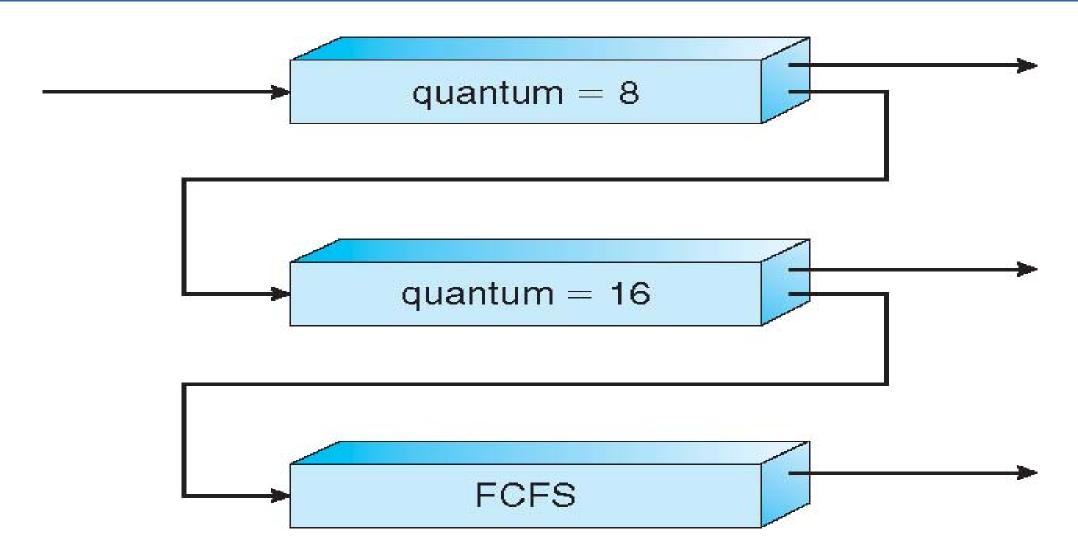
Scheduling

- A new job enters queue Q_0 which is served FCFS. When it gains CPU, job receives 8 milliseconds. If it does not finish in 8 milliseconds, job is moved to queue Q_1 .
- At Q_1 job is again served FCFS and receives 16 additional milliseconds. If it still does not complete, it is preempted and moved to queue Q_2 .





Fig 5.7 Multilevel Feedback Queues







进程调度例题分析

假定在一个处理机上执行以下五个进程:

进程号	到达时间	运行时间	优先数
P1	0	35	4
P2	10	30	3
Р3	15	45	2
P4	20	20	5
P5	30	30	2

分别采用FCFS、SPF和非抢占优先数三种调度算法时:

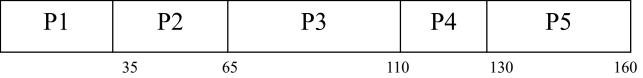
- ①画出调度Gantt图;
- ②计算每个进程的周转时间;
- ③计算平均周转时间。





进程调度例题分析





SPF(非抢占):

P1	P4	P2	P5	P3
	35	55	85	115

160

优先数(非抢占):

P1		P4	P2	Р3	P5	
160	35	55	8	5	130	

算法	每	每个进程周转时间				平均周转时 间
	P1	P2	Р3	P4	P5	
FCFS	35	55	95	110	130	85
SPF	35	75	145	35	85	75
优先数	35	75	115	35	130	78



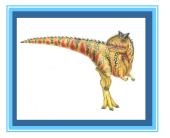


5.4* Multiple-Processor Scheduling

- CPU scheduling more complex when multiple CPUs are available
- Homogeneous processors within a multiprocessor
- Load sharing
- Asymmetric multiprocessing only one processor accesses the system data structures, alleviating the need for data sharing



5.5* Thread Scheduling





Thread Scheduling

 Local Scheduling – How the threads library decides which thread to put onto an available LWP

 Global Scheduling – How the kernel decides which kernel thread to run next





Pthread Scheduling API

```
#include <pthread.h>
#include <stdio.h>
#define NUM THREADS 5
int main(int argc, char *argv[])
    int i;
   pthread t tid[NUM THREADS];
   pthread attr t attr;
   /* get the default attributes */
   pthread attr init(&attr);
   /* set the scheduling algorithm to PROCESS or SYSTEM */
   pthread attr setscope(&attr, PTHREAD SCOPE SYSTEM);
   /* set the scheduling policy - FIFO, RT, or OTHER */
   pthread attr setschedpolicy(&attr, SCHED OTHER);
   /* create the threads */
   for (i = 0; i < NUM THREADS; i++)
       pthread create(&tid[i], &attr, runner, NULL);
```





Pthread Scheduling API

```
/* now join on each thread */
  for (i = 0; i < NUM THREADS; i++)
      pthread join(tid[i], NULL);
/* Each thread will begin control in this function */
void *runner(void *param)
  printf("I am a thread\n");
  pthread exit(0);
```





5.6 Operating System Examples

- Solaris scheduling
- Windows XP scheduling
- Linux scheduling





Linux Scheduling

- Two algorithms: time-sharing and real-time
- Time-sharing
 - Prioritized credit-based process with most credits is scheduled next
 - Credit subtracted when timer interrupt occurs
 - When credit = 0, another process chosen
 - When all processes have credit = 0, recrediting occurs
 - Based on factors including priority and history
- Real-time
 - Soft real-time
 - Posix.1b compliant two classes
 - FCFS and RR
 - Highest priority process always runs first





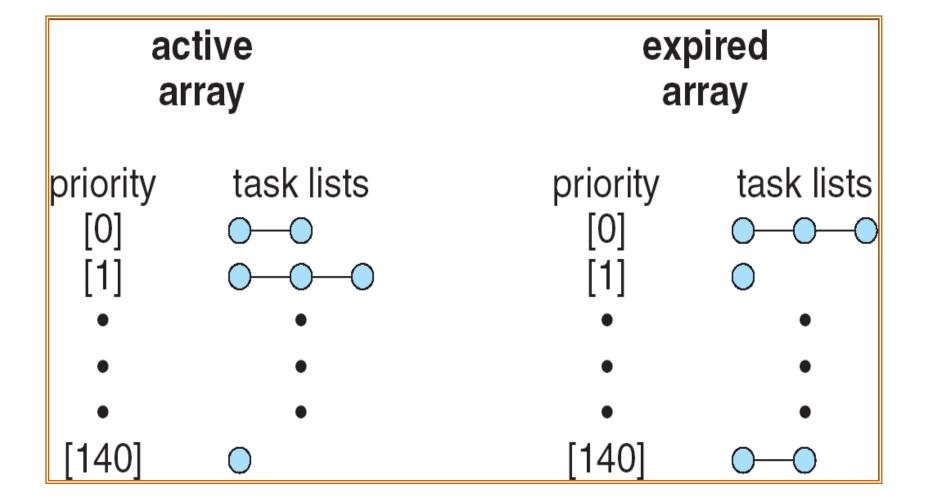
The Relationship Between Priorities and Time-slice length

numeric priority	relative priority		time quantum
0	highest	real-time	200 ms
99		tasks	
100 •		other	
• 140	lowest	tasks	10 ms





List of Tasks Indexed According to Prorities







Summary

- CPU Burst Time \ I/O Burst Time
- CPU-bound program(CPU型程序)、I/O-bound program(I/O型程序)
- long-term scheduler(长程调度)、medium-term scheduler(中程调度)short-term scheduler(短程调度)
- time slicing (时间片)
- response time(响应时间)、turnaround time(周转时间)、waiting time(等待时间)、Average Turnaround time(平均周转时间)Average waiting time(平均等待时间)
- preemptive scheduling(抢占式调度)Nonpreemptive scheduling(非抢占式调度)
- throughput(吞吐量)





Summary

- selecting a process from the ready queue and allocating CPU to it
- scheduling algorithms
 - first-come, first served (FCFS)
 - shortest job first (SJF)
 - provably optimal, but difficult to know CPU burst
 - general priority scheduling
 - starvation, and aging
 - round-robin (RR)
 - for time-sharing, interactive system
 - problem: how to select the time quantum?
 - Multilevel queue
 - different algorithms for different classes of processes
 - Multilevel feedback queue
 - allow process to move from one (ready) queue to another





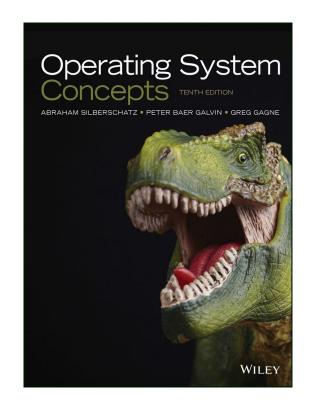
■习题分析

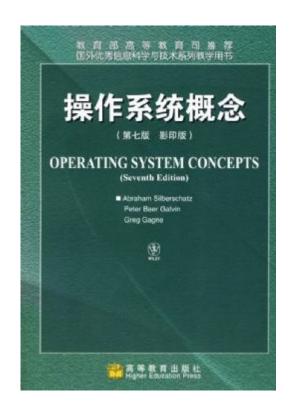




Reading Assignments

- Read for this week:
 - Chapters 5 of the text book:
- Read for next week:
 - Chapters 6 of the text book:









End of Chapter

