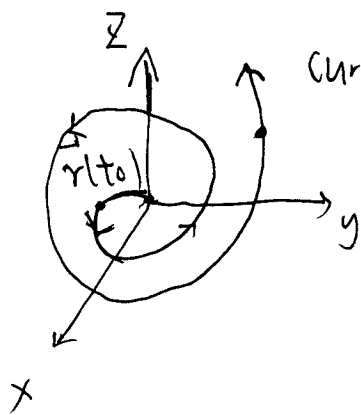


08/24 Chapter 13. Vector-Valued functions and motion in space.



curve  $\rightarrow \vec{r}(t) = (x(t), y(t), z(t))$

$$\vec{r}(t) = \underline{x(t)} \vec{i} + \underline{y(t)} \vec{j} + \underline{z(t)} \vec{k}$$

vector-valued function      component functions

eg:  $\vec{r}(t) = \cos t \vec{i} + \sin t \vec{j} + t \vec{k}$

$$= (\cos t, \sin t, t)$$

$t=0$

$$\vec{r}(0) = (1, 0, 0)$$

$$\vec{r}(\frac{\pi}{2}) = (0, 1, \frac{\pi}{2})$$

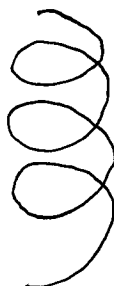
$$\cos^2 t + \sin^2 t = 1.$$

$$x^2(t) + y^2(t) = 1. \quad \text{for all time}$$

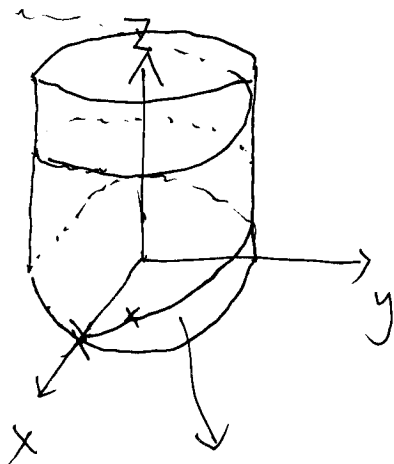
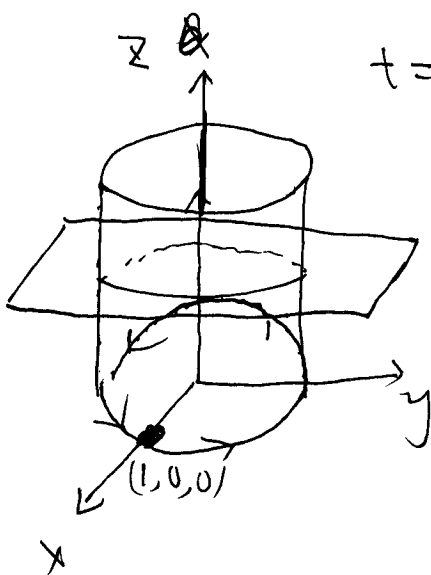
what is  $x^2 + y^2 = 1$  ?

$$z=0$$

$$( \cos t, \sin t, 0 ) \leftarrow ( \cos t, \sin t, \underline{t} )$$



curve called as helix

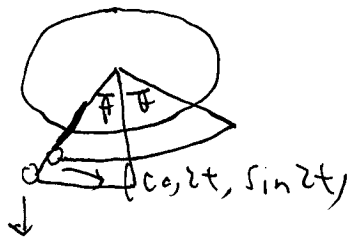


$$\vec{r}_1 (\cos 2t, \sin 2t, \underline{t})$$

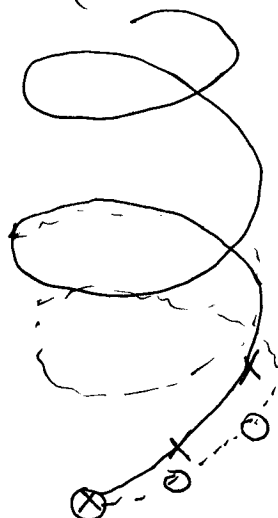
$$\vec{r}_2 (\cos t, \sin t, t)$$

$$t = t_0$$

$\hookrightarrow \vec{r}_1$  and  $\vec{r}_2$  locate at  $z = t_0$  plane.



$$(\cos t, \sin t)$$



$$\vec{r}_1 (\cos 2t, \sin 2t, \underline{t})$$

$$\vec{r}_3 (\cos 2t, \sin 2t, \underline{\frac{1}{2}t})$$

Def: Let  $\vec{r}(t) = x(t)\vec{i} + y(t)\vec{j} + z(t)\vec{k}$  with domain  $D$

we say  $\lim_{t \rightarrow t_0} \vec{r}(t) = \vec{L} = x_0\vec{i} + y_0\vec{j} + z_0\vec{k}$

if  $\forall \epsilon > 0, \exists \delta > 0$ , such that when  $|t - t_0| < \delta$ ,  
length  $\leftarrow |\vec{r}(t) - \vec{L}| < \epsilon$ .

position  $\nearrow$  if and only if

$$\lim_{t \rightarrow t_0} \vec{r}(t) = \vec{L} \quad \text{iff} \quad \lim_{t \rightarrow t_0} x(t) = x_0, \quad \lim_{t \rightarrow t_0} y(t) = y_0, \quad \lim_{t \rightarrow t_0} z(t) = z_0$$

eg  $\vec{r}(t) = (\cos t, \sin t, t) \rightarrow \frac{1}{t-\frac{\pi}{3}}$

$$\lim_{t \rightarrow \frac{\pi}{3}} \vec{r}(t) = \left( \lim_{t \rightarrow \frac{\pi}{3}} \cos t, \lim_{t \rightarrow \frac{\pi}{3}} \sin t, \lim_{t \rightarrow \frac{\pi}{3}} t \right)$$

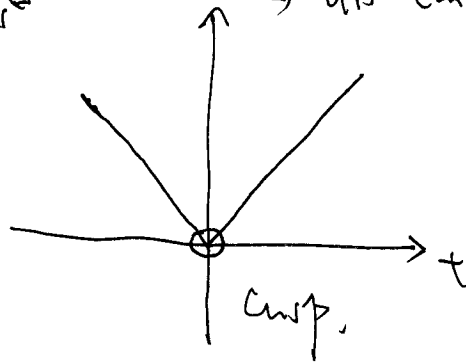
$$= \left( \frac{1}{2}, \frac{\sqrt{3}}{2}, \frac{\pi}{3} \right)$$

Def:  $\vec{r}(t)$  is continuous at  $t = t_0$ ,

if  $\lim_{t \rightarrow t_0} \vec{r}(t) = \vec{r}(t_0)$

$\vec{r}(t)$  is a continuous fun if  $\vec{r}(t)$  is continuous on any  $t$ .

eg:  $\vec{r}(t) = \underbrace{\cos t \vec{i} + \sin t \vec{j}}_{\text{continuous}} + \underbrace{|t| \vec{k}}_{\text{dis-continuous at } t=0}$



$$\vec{r}(t) = x(t) \vec{i} + y(t) \vec{j} + z(t) \vec{k}$$

$$\Delta \vec{r}(t) = \vec{r}(t + \Delta t) - \vec{r}(t)$$

$$= (x(t + \Delta t) - x(t)) \vec{i} + (y(t + \Delta t) - y(t)) \vec{j} + (z(t + \Delta t) - z(t)) \vec{k}$$

$$\lim_{\Delta t \rightarrow 0} \frac{\Delta \vec{r}(t)}{\Delta t} = \lim_{\Delta t \rightarrow 0} \left( \frac{x(t + \Delta t) - x(t)}{\Delta t} \right) \vec{i} + \lim_{\Delta t \rightarrow 0} \vec{j} + \lim_{\Delta t \rightarrow 0} \vec{k}$$

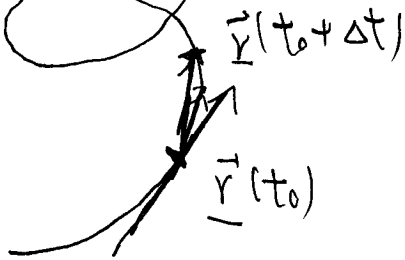
↓  
scale

$$= \frac{dx}{dt} \vec{i} + \frac{dy}{dt} \vec{j} + \frac{dz}{dt} \vec{k}$$

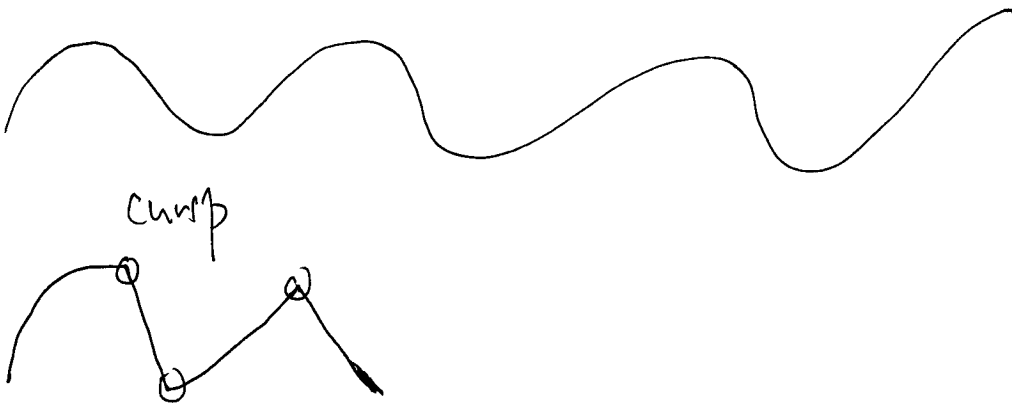
def:  $\vec{r}(t) = x(t)\vec{i} + y(t)\vec{j} + z(t)\vec{k}$  is differentiable / has derivatives at  $t$  if  $x(t), y(t), z(t)$  has derivatives at  $t$ .

$$\vec{r}'(t) = \frac{d\vec{r}}{dt} = x'(t)\vec{i} + y'(t)\vec{j} + z'(t)\vec{k}$$

→ the direction of tangent line at  $t=t_0$ .

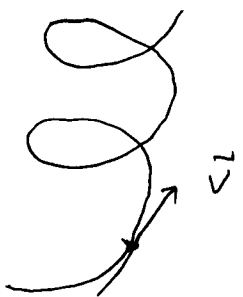


smooth.



if curve is smooth if  $\frac{d\vec{r}}{dt}$  is continuous and nonzero.

Def: velocity vector:  $\vec{v}(t) = \frac{d\vec{r}}{dt}$ , where  $\vec{r}(t)$  represent position of a particle.



velocity:  $\vec{v}(t) = \frac{d\vec{r}}{dt}$

speed:  $|\vec{v}| \geq 0$

acceleration:  $\vec{a} = \frac{d\vec{v}}{dt}$

$\frac{\vec{v}}{|\vec{v}|} \rightarrow$  the direction of motion.

Rules: a)  $\frac{d}{dt} \vec{c} = \vec{0}$

b)  $\frac{d}{dt} (c \vec{u}) = c \frac{d}{dt} \vec{u}$

$$\frac{d}{dt} (f(t) \vec{u}(t)) = f'(t) \vec{u}(t) + f(t) \cdot \frac{d\vec{u}}{dt}$$

c)  $\frac{d}{dt} (\vec{u} \pm \vec{v}) = \frac{d}{dt} \vec{u} \pm \frac{d}{dt} \vec{v}$

d)  $\frac{d}{dt} (\vec{u} \cdot \vec{v}) = \vec{u}' \cdot \vec{v} + \vec{u} \cdot \vec{v}'$  dot product rule.  
scale differentiation

$$\vec{u} = u_1 \vec{i} + u_2 \vec{j} + u_3 \vec{k} \quad \vec{v} = v_1 \vec{i} + v_2 \vec{j} + v_3 \vec{k}$$

$$\frac{d}{dt} (\vec{u} \cdot \vec{v}) = \frac{d}{dt} (u_1 v_1 + u_2 v_2 + u_3 v_3)$$

$$= \underline{u_1'} v_1 + \underline{u_1 v_1'} + \underline{u_2'} v_2 + \underline{u_2 v_2'} + \underline{u_3'} v_3 + \underline{u_3 v_3'}$$

$$= \vec{u}' \cdot \vec{v} + \vec{u} \cdot \vec{v}'$$

e)  $\frac{d}{dt} (\vec{u} \times \vec{v}) = \vec{u}' \times \vec{v} + \vec{u} \times \vec{v}'$   
vector                      vector                      vector

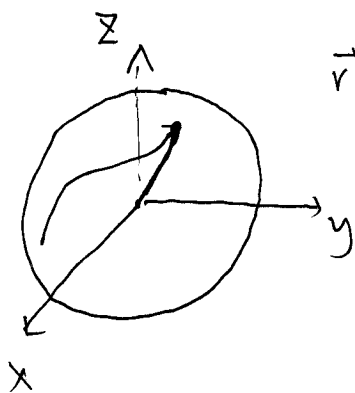
$$\frac{d}{dt} (\vec{u} \times \vec{v}) = \lim_{\Delta t \rightarrow 0} \frac{\vec{u}(t+\Delta t) \times \vec{v}(t+\Delta t) - \vec{u}(t) \times \vec{v}(t)}{\Delta t}$$

$$= \lim_{\Delta t \rightarrow 0} \frac{\vec{u}(t+\Delta t) \times \vec{v}(t+\Delta t) - \vec{u}(t+\Delta t) \times \vec{v}(t) + \vec{u}(t+\Delta t) \times \vec{v}(t) - \vec{u}(t) \times \vec{v}(t)}{\Delta t}$$

$$= \lim_{\Delta t \rightarrow 0} \frac{\vec{u}(t+\Delta t) \times (\vec{v}(t+\Delta t) - \vec{v}(t))}{\Delta t} + \lim_{\Delta t \rightarrow 0} \frac{(\vec{u}(t+\Delta t) - \vec{u}(t)) \times \vec{v}(t)}{\Delta t} = \vec{u}(t) \times \vec{v}'(t) + \vec{u}'(t) \times \vec{v}(t)$$

$$f). \frac{d}{dt}(\vec{u}(f(t))) = \underbrace{f'(t)} \cdot \underbrace{u'(f(t))}$$

$$u_1(f(t)) \vec{i} + u_2(f(t)) \vec{j} + u_3(f(t)) \vec{k}$$



$\vec{r}(t)$  sphere with  $R$ .

$$|\vec{r}(t)| = R$$

$$\vec{r}(t) \cdot \vec{r}(t) = R^2$$

$$\frac{d}{dt}(\vec{r}(t) \cdot \vec{r}(t)) = 0$$

$$\vec{r}'(t) \cdot \vec{r}(t) + \vec{r}(t) \cdot \vec{r}'(t) = 0$$

$$2 \vec{r}(t) \cdot \vec{r}'(t) = 0$$

$$\vec{r}(t) \cdot \vec{r}'(t) = 0$$

↓

$$\vec{r}(t) \perp \vec{r}'(t)$$

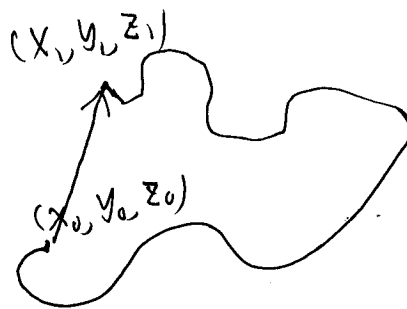
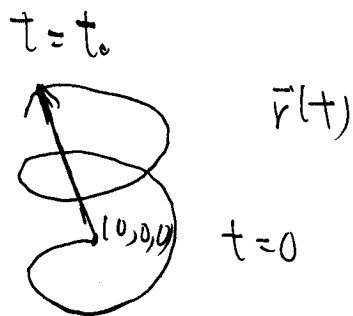
Thm: if  $\vec{r}(t)$  is differentiable and of constant length,

$$\text{then } \underline{\vec{r}(t) \cdot \frac{d\vec{r}}{dt}} = 0$$

Sec 13.2. Integrals of vector function.

Def: the indefinite integral of  $\vec{r}$ , if ~~the~~  $\vec{R}$  is the antiderivative of  $\vec{r}$ , then  $\int \vec{r}(t) dt = \vec{R}(t) + C$ .

$$\text{Def: definite integral: } \int_a^b \vec{r}(t) dt = \left( \int_a^b x(t) dt \right) \vec{i} + \left( \int_a^b y(t) dt \right) \vec{j} + \left( \int_a^b z(t) dt \right) \vec{k}$$



$$\begin{aligned}
 & \int_0^\pi (\cos t \vec{i} + \sin t \vec{j} + t \vec{k}) dt \\
 &= \left( \int_0^\pi \cos t dt \right) \vec{i} + \left( \int_0^\pi \sin t dt \right) \vec{j} + \left( \int_0^\pi t dt \right) \vec{k} \\
 &= \sin t \Big|_0^\pi \vec{i} + -\cos t \Big|_0^\pi \vec{j} + \frac{1}{2} t^2 \Big|_0^\pi \vec{k} \\
 &= (0, -(-1-1), \frac{1}{2} \pi^2) \\
 &= (0, 2, \frac{1}{2} \pi^2)
 \end{aligned}$$