

# Synthetic Aperture Radar Simplified

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## Abstract

The size of the Synthetic Aperture Radar (SAR) image matrix in terms of the number of range cells and azimuth cells is derived from parameters such as frequency, chirp bandwidth, range, and antenna sizes. The equations for the number of range and azimuth cells clearly show the tradeoffs in the design of SAR systems as well as predict the complexity of image formation. The SEASAT SAR system is illustrated.

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## 1 Introduction

Define the number of azimuth cells as  $N_x$  and the number of range cells as  $N_y$  for the area that is being imaged. The final processed SAR image will be an  $N_x \times N_y$  image for a one look case. The image formation process will consist of operating on a matrix of this size. The complexity of SAR image formation is thus directly related to the number of azimuth and range cells. Below, we will present a simple derivation of  $N_x$  and  $N_y$  in terms of SAR parameters.

## 2 Derivation of Number of Range Cells $N_y$

The geometry of the SEASAT SAR is illustrated in Figure 1. In Figure 2 the cross section along the range direction is shown (the range plane). The "look angle" is  $\theta$  and  $\psi$  is the beam width along the range direction. The beam width is,

$$\psi = a_y \frac{\lambda}{D_y} \quad (1)$$

where  $a_y$  is the aperture factor of the antenna and  $D_y$  is the antenna length along the range direction. Now from Figure 2,

$$R_0 \psi = L_y \cos \theta \quad (2)$$

from which

$$L_y = \frac{R_0 \psi}{\cos \theta} \quad (3)$$

where  $L_y$  is the illuminated area along the range plane. Thus,

$$L_y = a_y \frac{\lambda R_0}{D_y \cos \theta} \quad (4)$$

Now the range resolution is related to the time interval between two received echoes from two targets and the ability of the receiver to distinguish between the two received pulses. This time interval is related inversely to the bandwidth. We assume that the chirp pulse compression technique is used. The ambiguity diagram for a single frequency-modulated pulse is shown in Figure 3 in which the time resolution is seen to be inversely proportional to the chirp bandwidth. The transmitted pulse and the compressed pulse are illustrated in Figure 4. Thus, the range resolution along the beam is,

$$\delta r = \frac{c}{2} \delta T = \frac{c}{2B} \quad (5)$$

By projecting the range ground resolution (xy plane) on the along-beam range direction we can obtain the expression for the ground range resolution.

$$\delta y = \frac{\delta r}{\sin \theta} = \frac{c}{2B \sin \theta} \quad (6)$$

The total number of range cells is, therefore,

$$N_y = \frac{L_y}{\delta y} \quad (7)$$

$$N_y = 2a_y \frac{R_0 B \lambda}{D_y c} \tan \theta \quad (8)$$

### 3 Derivation of number of Azimuth Cells $N_x$

The SEASAT SAR geometry showing the azimuth beam width is shown in Figure 5. The viewing geometry in the azimuth plane is shown in Figure 6. From the figure we have the length of the illuminated area along the azimuth direction at range  $R_0$  is,

$$L_x = R_0 \varphi \quad (9)$$

where  $\varphi$  is the beam width,

$$\varphi = a_x \frac{\lambda}{D_x} \quad (10)$$

Let the pulse repetition rate be  $f_p$ . The transmitter pulses at

$$T_p = \frac{1}{f_p} \quad (11)$$

intervals apart. Now, a target in the azimuth direction at a constant range  $R_0$  remains in the antenna beam for a distance  $L_x$ . Thus if the vehicle velocity is  $v$ , the total time in which the target is in view is,

$$T_t = \frac{L_x}{v} \quad (12)$$

Thus the total number of pulse echoes that the radar receives during the interval  $T_t$  is (see Figure 7)

$$N_x = \frac{T_t}{T_p} \quad (13)$$

Now, the pulse repetition rate must be twice the doppler bandwidth along the azimuth direction. The doppler bandwidth is related to the "synthesizing" of the aperture as the vehicle approaches the target and then recedes. The doppler shift at each extreme is,

$$f_D = \frac{f_0 v_r}{c} = \frac{v_r}{\lambda} \quad (14)$$

Projecting vehicle velocity along the azimuth path onto the path along the beam,

$$f_D = \frac{v \sin \frac{\varphi}{2}}{\lambda} \quad (15)$$

The doppler bandwidth  $B_D$  is twice  $f_d$ . Thus, assuming that  $\varphi$  is small,

$$B_D = \frac{v\varphi}{\lambda} \quad (16)$$

Or substituting for  $\varphi$ ,

$$B_D = \frac{a_x}{\lambda} \frac{v\lambda}{D_x} = a_x \frac{v}{D_x} \quad (17)$$

Since  $f_p = 2B_D$  to satisfy the Nyquist criterion,

$$N_x = 2a_x \frac{v}{D_x} \frac{L_x}{v} \quad (18)$$

Or,

$$N_x = 2a_x^2 \frac{R_0\lambda}{D_x^2} \quad (19)$$

We are done!

## 4 Azimuth Resolution

From the number of azimuth cells  $N_x$  and the length of the illuminated area along the azimuth direction,  $L_x$ , we can obtain the azimuth resolution  $\delta_{az}$ :

$$\delta_{az} = \frac{L_x}{N_x} \quad (20)$$

Now from Equation 9 substituting for  $\varphi$  from Equation 10 we have,

$$L_x = R_0 a_x \frac{\lambda}{D_x} \quad (21)$$

Substituting for  $L_x$  and  $N_x$  we have,

$$\delta_{az} = \frac{R_0 a_x \frac{\lambda}{D_x}}{2a_x^2 \frac{R_0\lambda}{D_x^2}} \quad (22)$$

Cancelling terms we have:

$$\delta_{az} = \frac{D_x}{2a_x} \quad (23)$$

If we assume  $a_x \approx 1$ , then

$$\delta_{az} = \frac{D_x}{2} \quad (24)$$

This result shows that the azimuth resolution only depends on the physical size of the antenna in the along-track direction.

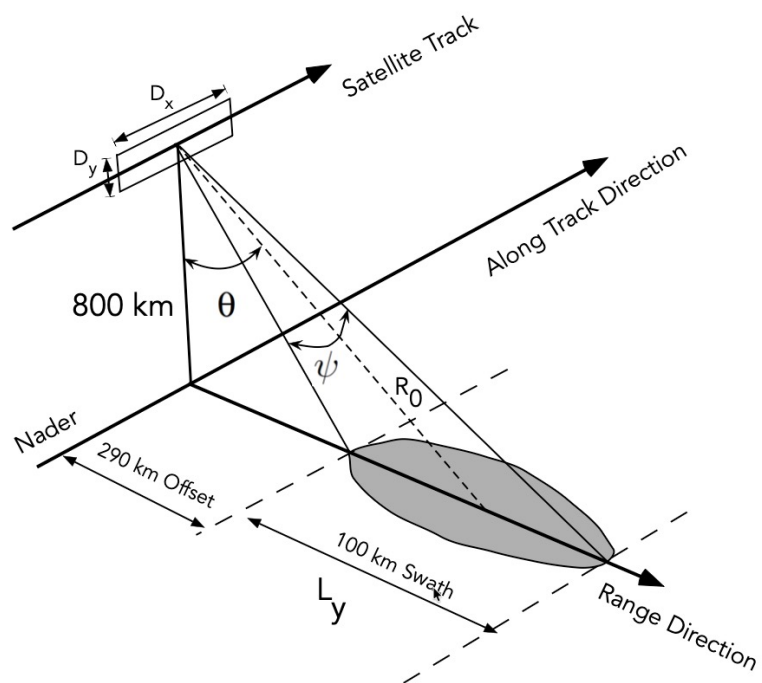


Figure 1: SAR Geometry Derived From NASA/JPL

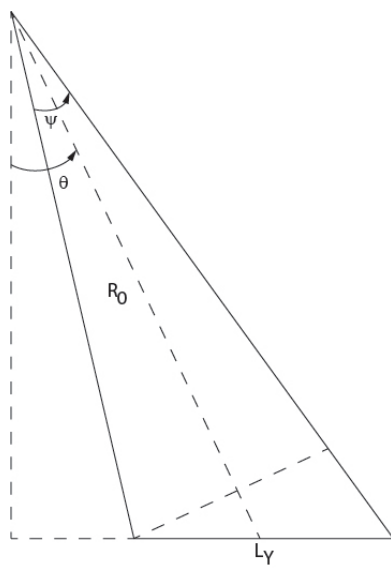


Figure 2: Geometry in Range Plane

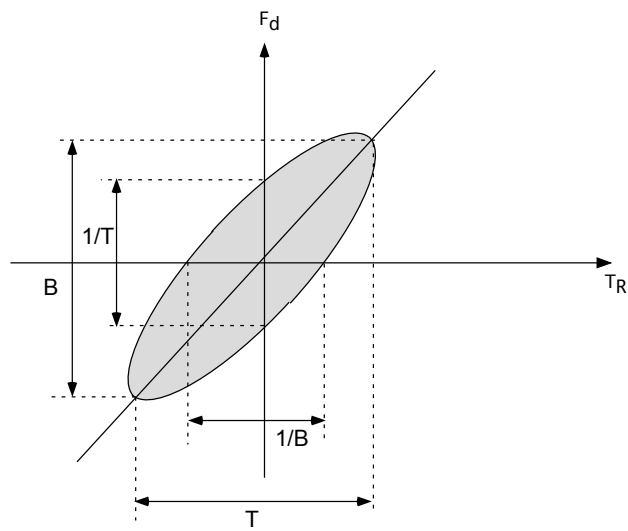


Figure 3: Ambiguity Diagram Chirp Pulse Compression



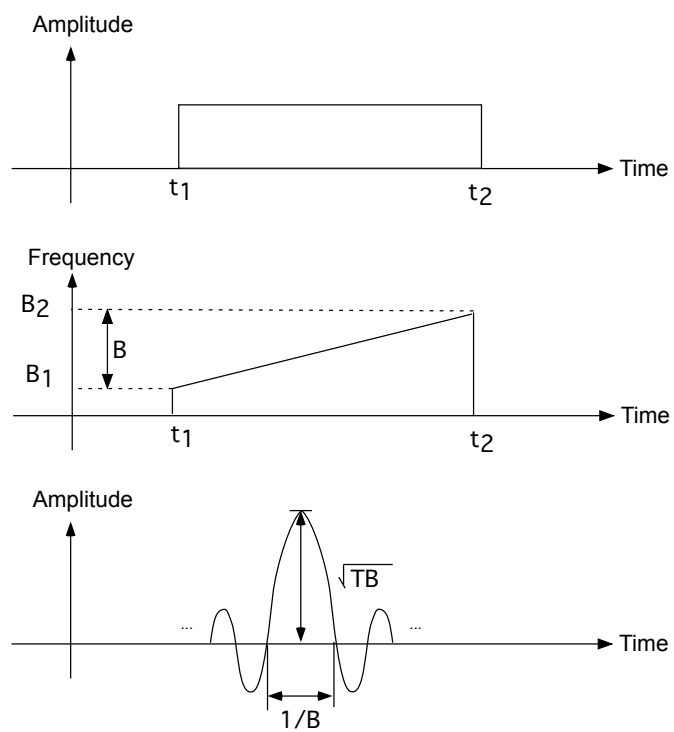


Figure 4: Chirp Pulse Compression

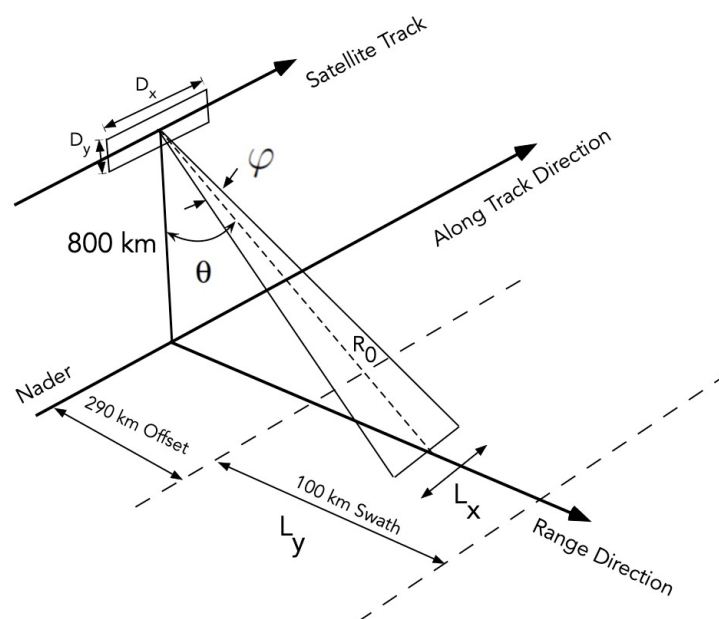


Figure 5: SAR Geometry Azimuth

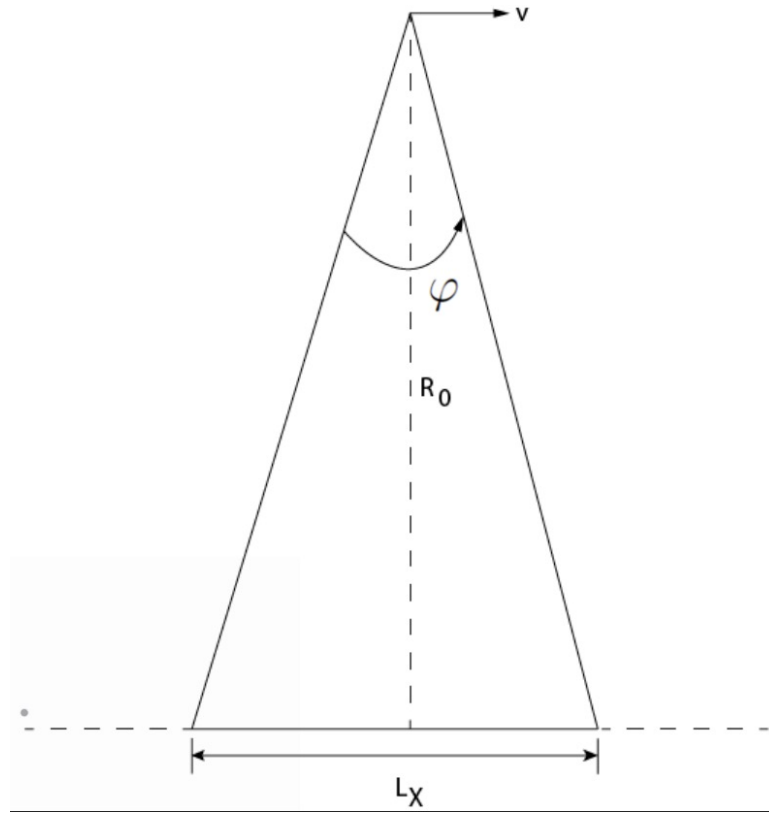


Figure 6: Viewing Geometry Azimuth Plane

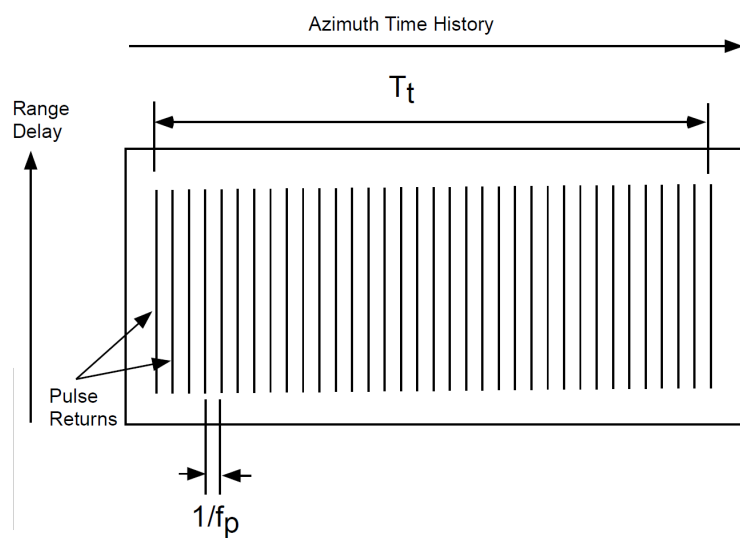


Figure 7: SAR Record Radar Returns