

COMP 3271

# Programming Assignment 1

# Submission

- Deadline:

**11:59pm, Oct 17, 2019 HKT.**

- Submission:

**Code.cpp**

If you want to change any other files or implement the program without the template, please email me([wenhua00@hku.hk](mailto:wenhua00@hku.hk)) before submission.

# Outline

- Review of Homogeneous Coordinates and Transformation Matrix
- 2D Transformation in OpenGL
- Fractal Drawing – Programming Assignment
  - About the Template
  - About the Task
  - Submission

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# Review: Homogeneous Coordinates

- Common Transfer Matrix

- Translation
- Rotation
- Scaling

- Add an extra dimension

Euclidean formulation

$$\begin{pmatrix} x' \\ y' \end{pmatrix} = \begin{pmatrix} a & b \\ d & e \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} + \begin{pmatrix} c \\ f \end{pmatrix}$$
$$\mathbf{p}' = \mathbf{M}_{2 \times 2} \mathbf{p} + \mathbf{T}$$

Homogeneous formulation

$$\begin{pmatrix} x' \\ y' \\ 1 \end{pmatrix} = \begin{pmatrix} a & b & c \\ d & e & f \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ 1 \end{pmatrix}$$
$$\bar{\mathbf{p}}' = \mathbf{M}_{3 \times 3} \bar{\mathbf{p}}$$

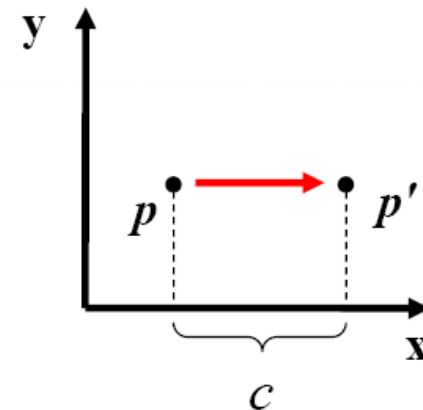
# Review: 2D Transformation

- Translation Matrix

$$\begin{pmatrix} x' \\ y' \\ 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & x_{offset} \\ 0 & 1 & y_{offset} \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ 1 \end{pmatrix}$$

- Example : Translate “c” units in x direction

$$\begin{pmatrix} x' \\ y' \\ 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & c \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ 1 \end{pmatrix} = \begin{pmatrix} x + c \\ y \\ 1 \end{pmatrix}$$



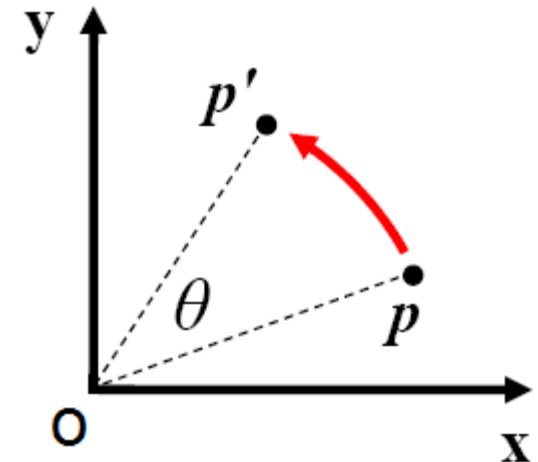
# Review: 2D Transformation

- Rotation Matrix

$$\begin{pmatrix} x' \\ y' \\ 1 \end{pmatrix} = \begin{pmatrix} \cos \varphi & -\sin \varphi & 0 \\ \sin \varphi & \cos \varphi & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ 1 \end{pmatrix}$$

- Example : Rotate  $\theta$  around the origin point

$$\begin{pmatrix} x' \\ y' \\ 1 \end{pmatrix} = \begin{pmatrix} \cos \theta & -\sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ 1 \end{pmatrix}$$



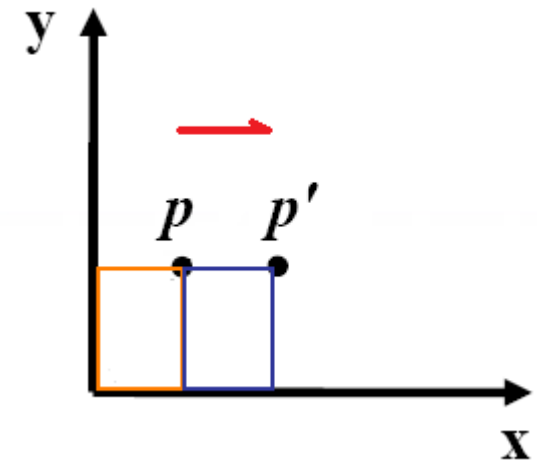
# Review: 2D Transformation

- Scaling Matrix

$$\begin{pmatrix} x' \\ y' \\ 1 \end{pmatrix} = \begin{pmatrix} S_x & 0 & 0 \\ 0 & S_y & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ 1 \end{pmatrix}$$

- Example: Scale 2 in x coordinate

$$\begin{pmatrix} x' \\ y' \\ 1 \end{pmatrix} = \begin{pmatrix} 2 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ 1 \end{pmatrix} = \begin{pmatrix} 2x \\ y \\ 1 \end{pmatrix}$$



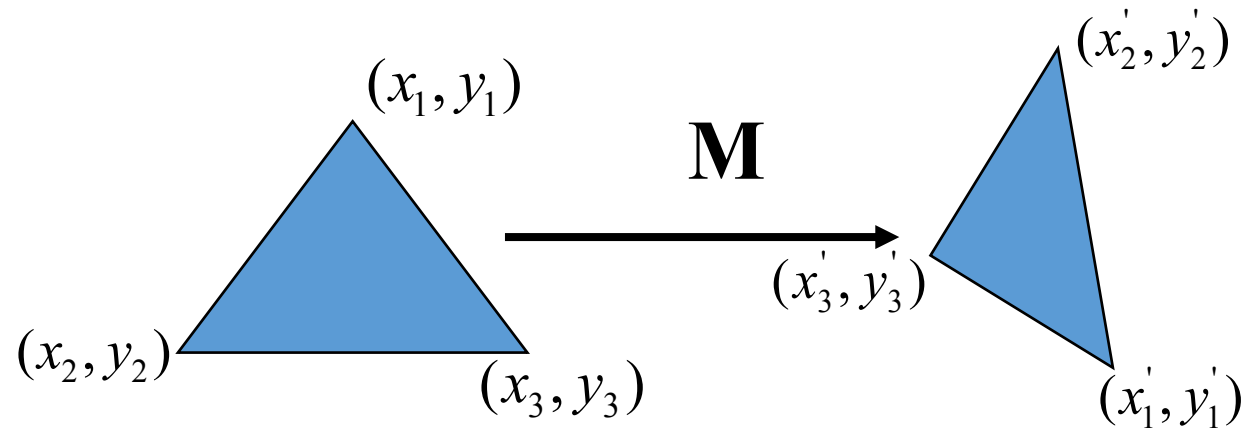


# Review: Arbitrary Affine Transformation

$$\begin{pmatrix} x'_1 & x'_2 & x'_3 \\ y'_1 & y'_2 & y'_3 \\ 1 & 1 & 1 \end{pmatrix} = \begin{pmatrix} a & b & c \\ d & e & f \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x_1 & x_2 & x_3 \\ y_1 & y_2 & y_3 \\ 1 & 1 & 1 \end{pmatrix}$$

$$\mathbf{T}' = \mathbf{M} \mathbf{T}$$

$$\mathbf{M} = \mathbf{T}' \mathbf{T}^{-1}$$



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# Model View Matrix

$$\begin{pmatrix} x' \\ y' \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} a & b & 0 & c \\ d & e & 0 & f \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ 1 \\ 1 \end{pmatrix}$$
$$\bar{\mathbf{p}}' = \mathbf{M} \bar{\mathbf{p}}$$

- In OpenGL we use Model View Matrix to represent the transformation matrix  $\mathbf{M}$ .
- OpenGL provides some functions to modify matrix  $\mathbf{M}$ .

# Model View Matrix

- Transformation based on OpenGL

Translation Matrix

$$\begin{pmatrix} x' \\ y' \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 & c \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ 1 \\ 1 \end{pmatrix}$$

Rotation Matrix

$$\begin{pmatrix} x' \\ y' \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} \cos \varphi & -\sin \varphi & 0 & 0 \\ \sin \varphi & \cos \varphi & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ 1 \\ 1 \end{pmatrix}$$

Scaling Matrix

$$\begin{pmatrix} x' \\ y' \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} S_x & 0 & 0 & 0 \\ 0 & S_y & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ 1 \\ 1 \end{pmatrix}$$

# \*OpenGL Functions

- void **glTranslate**{fd}(TYPE x, TYPE y, TYPE z);

Translate an object by the given x, y, and z.

- void **glRotate**{fd}(TYPE angle, TYPE x, TYPE y, TYPE z);

Rotate an object in a counterclockwise direction about the ray from the origin through the point (x, y, z). The angle parameter specifies the angle of rotation in degrees.

- void **glScale**{fd}(TYPE x, TYPE y, TYPE z);

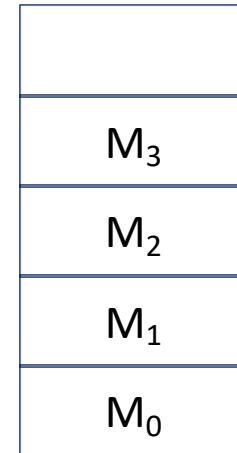
Stretch, shrink, or reflect an object along the axes. Each x, y, and z coordinate of every point in the object is multiplied by the corresponding argument x, y, or z.

# OpenGL Functions

- `void glMultMatrix(const GLdouble *m);`  
`GLdouble m[16];`  
`M=M*m`, where M is the Model View Matrix.
- OpenGL Matrix is column major:
  - Example: `GLdouble m[16]` layout is  
m[0] m[4] m[8] m[12]  
m[1] m[5] m[9] m[13]  
m[2] m[6] m[10] m[14]  
m[3] m[7] m[11] m[15]

# OpenGL Functions

- void **glPushMatrix**(void);  
Put current model view matrix into matrix stack.  
Current matrix is unchanged.
- Void **glPopMatrix**(void);  
Pop matrix in stack to replace current matrix.



How can we draw fractal using  
these transformations?



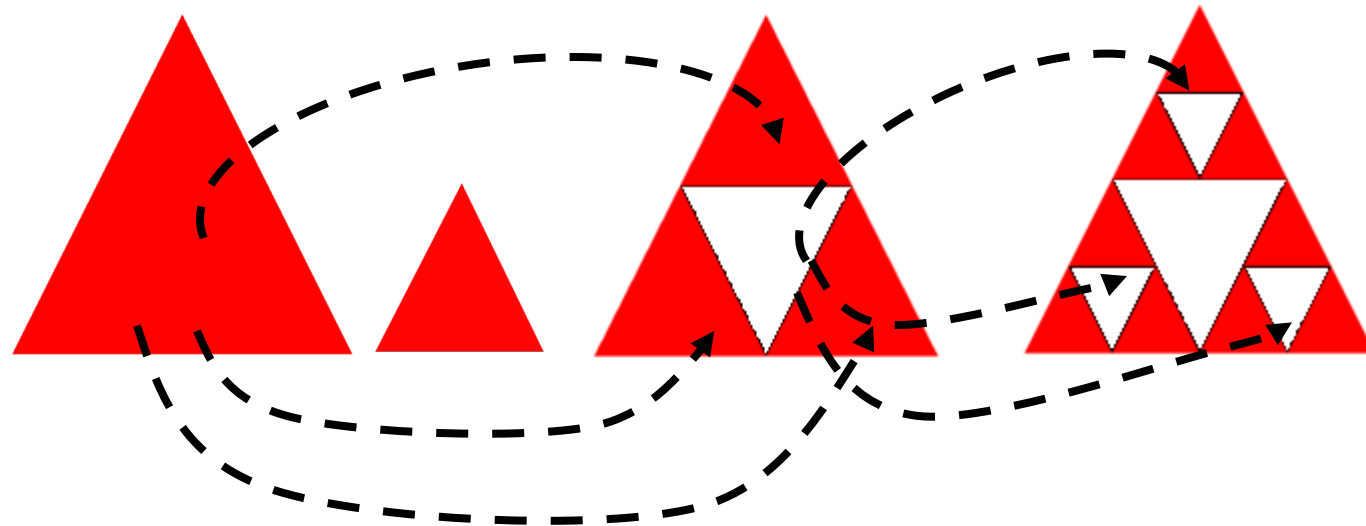
# Iterated Function System

## Iterated Function System(IFS)

- IFS is a method of constructing fractals, the resulting constructions are always self-similar.
- The fractal is made up of the union of several copies of itself, each copy being transformed by a function.

# Iterated Function System - Example

- Sierpinski gasket triangle evolution
  - Start with any triangle in a plane
  - Shrink the triangle to  $\frac{1}{2}$  height and  $\frac{1}{2}$  width, make three copies, and position the three shrunk triangles so that each triangle touches the two other triangles at a corner
  - Repeat step 2 with each of the smaller triangles



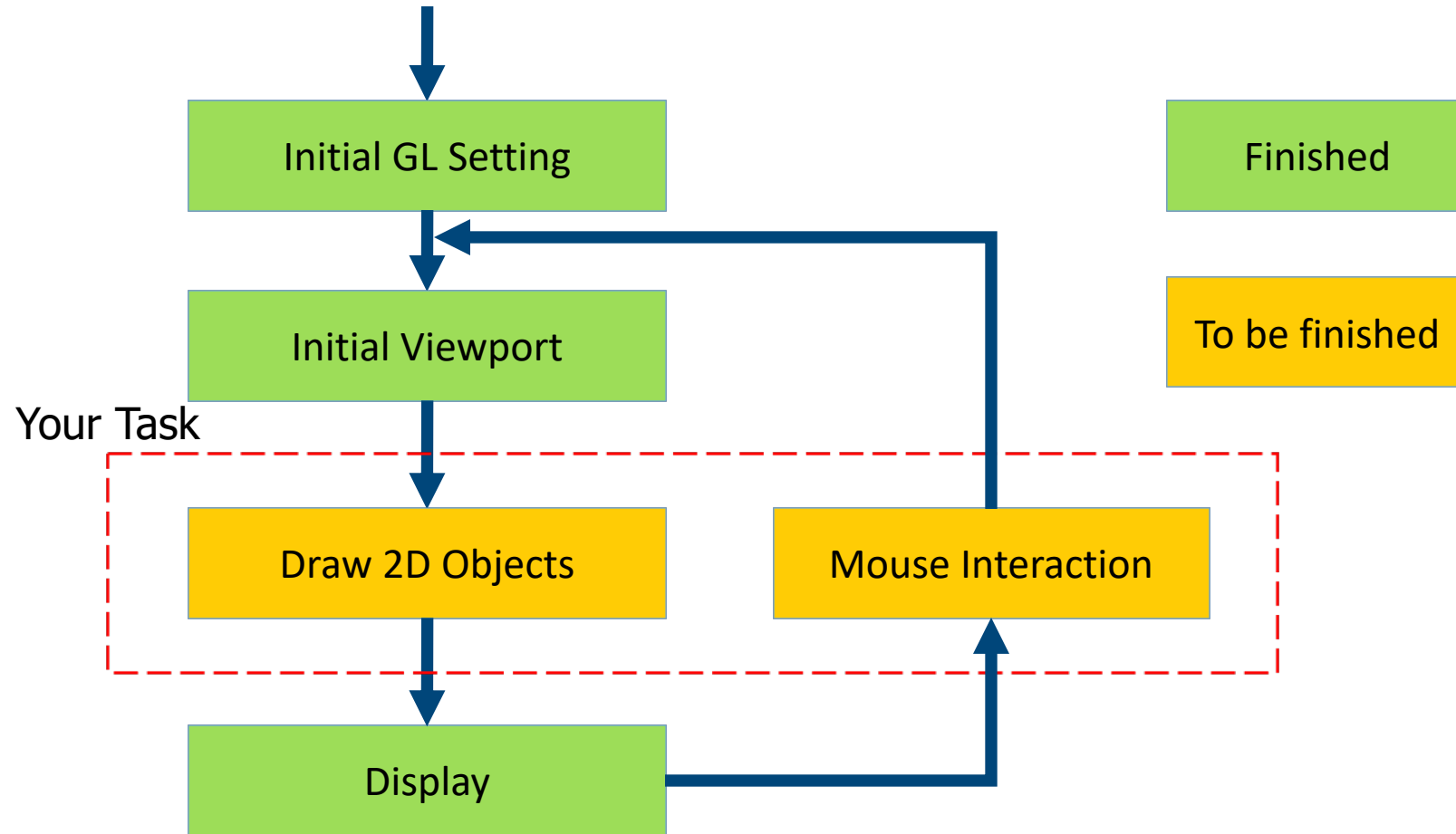
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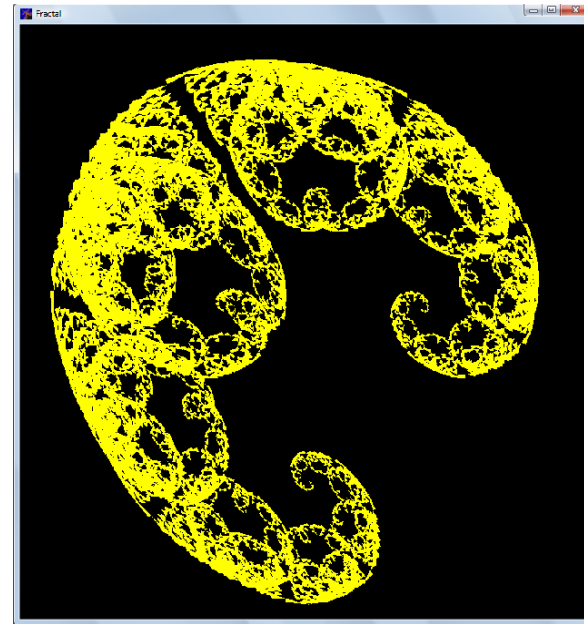
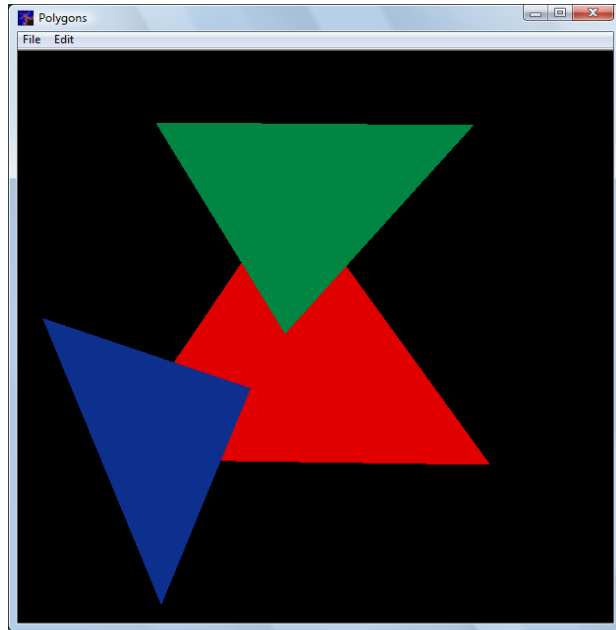
# About the Template

- MS-Windows: Use Visual Studio 2019, Interface based on MS Foundation Class (MFC). Written in C++.
- Download from the course webpage.
- Double-click the file D2CG.sln to open the project.
- A sample program D2CG.exe in the folder “bin”.
- Template includes:
  - An interface with two window for 2D objects rendering.
  - OpenGL init and projection setup.

# About the Template



# About the Template



Finished View

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# Your Task

The functions to fill in:

//For Mouse Interaction

void MouseInteraction(GLdouble m\_x, GLdouble m\_y)

//For Drawing 2D Objects

void DrawTriangles ()

void AffineMatricesCalculation()

void RecursiveFractal(int k)



# The Data Structures to Use

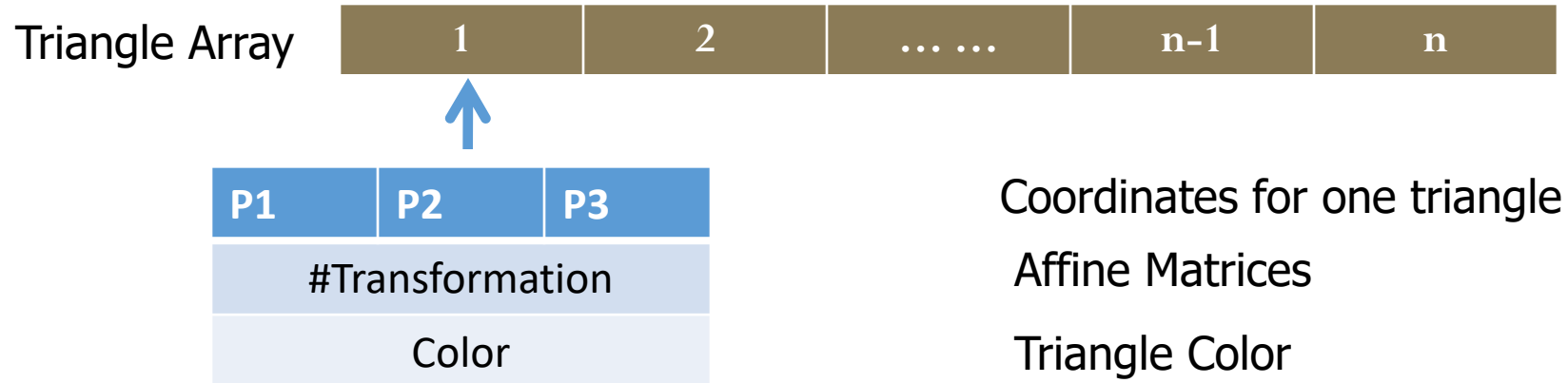
Data Structure Application

***triangle\_to\_draw*** : stores vertices of a triangle

***Triangles*** : list for triangles

***color\_array*** : list of different colors

***affine\_matrices*** : vector<D3Matrix>



# The Data Structures to Use

- Vector Operations

```
#include <vector>
```

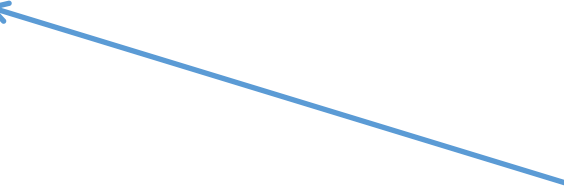
```
//Define Stack
```

```
vector<Triangle> TriangleStack;
```

```
//Usage:
```

```
vector::size() //Get vector size.
```

```
TriangleStack[i] //Get value of ith item.
```



```
typedef struct Triangle{  
    GLdouble vertices[3][2];  
    GLdouble matrix[3][3];  
    int      color_index;  
};
```

# Your Task

## Function : Mouse Interaction

**void MouseInteraction(GLdouble m\_x, GLdouble m\_y)**

- Called when left click happens
- m\_x and m\_y are the coordinates of clicked point in world coordinate system
- To-do: store points data for triangles
  - Store the points in *triangle\_to\_draw*
  - Once 3 new points are picked out, push this new triangle into *triangles*.

# Your Task

## DrawTriangles ()

- Called when the scene is rendered
- To-do: Render triangles using OpenGL
  - Extract data of triangles from *triangles*
  - Draw each triangle with different colors in *color\_array*.
    - `glColor3ubv(color_array[i] );`

# Your Task

## Function: AffineMatricesCalculation()

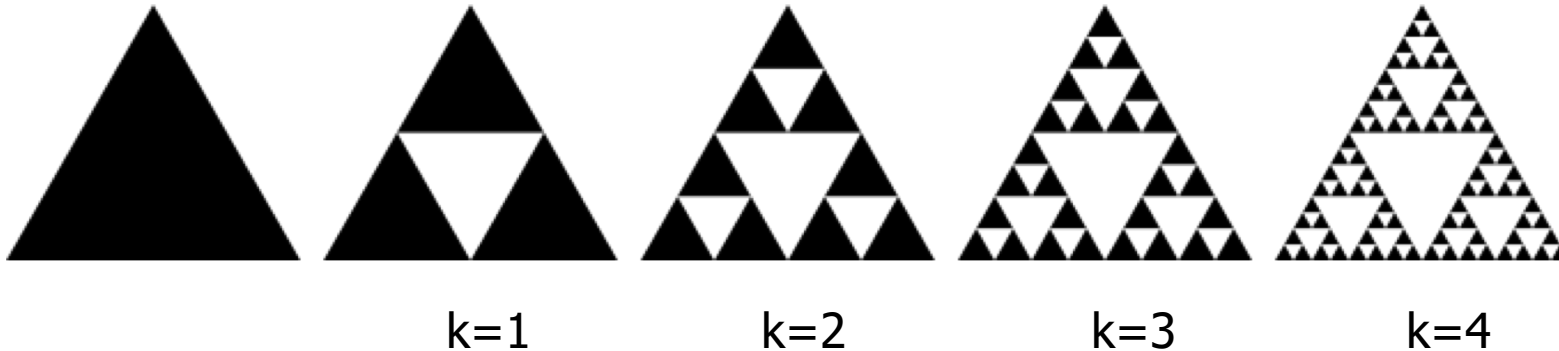
- Called after triangles are specified and before fractals are drawn
- To-do: Compute the affine transformation matrices
  - Compare the first triangle with subsequent ones to determine the affine transformations
  - Store each affine transformation matrix into *affine\_matrices*

# Your Task

Function : RecursiveFractal()

**void RecursiveFractal(int k)**

- Called to draw the fractal
- K is the depth of recursion



# Your Task

## Pseudo code for RecursiveFractal()

Procedure: RecursiveFractal ( k )

//The parameter k above is the times of recursion.

Begin

  If ( k > 0 ) Then

    For each transformation matrix  $M_i$

      Step (1): Push current modelview matrix into stack.

      Step (2): Multiply current matrix with  $M_i$ .

      //  $M_i$  is transformation matrix from  $T_0$  to  $T_i$ .

      Step (3): RecursiveFractal (k-1) to draw a fractal in  $T_{k-1,i}$ .

      Step (4): Pop matrix from matrix stack.

  Else

    Draw triangle  $T(P_1, P_2, P_3)$  with current modelview matrix

END

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# Hand-in

- Submit the finished program source file(`code.cpp`)
- Ensure that your file can be compiled and run successfully.
- Submit your file through the Web-handin.
- Late Policy
  - 50% off for the delay of each working day.
  - Re-submission after deadline is treated as late submission.
- NO PLAGIARISM!

**Deadline: 11:59pm, Oct 17, 2018 HKT**

# Some Useful Links

- OpenGL Official Site  
<http://www.opengl.org>
- OpenGL reference can be found in MSDN  
[http://msdn.microsoft.com/library/default.asp?url=/library/en-us/opengl/apxb4\\_82lh.asp](http://msdn.microsoft.com/library/default.asp?url=/library/en-us/opengl/apxb4_82lh.asp)  
or inside VS.NET. (search for “opengl reference”)
- GLU reference  
<http://pyopengl.sourceforge.net/documentation/manual/reference-GLU.html>

**Thank you!**