

Faculty of Science



Linear Classification

Machine Learning

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Outline

- 1 Logistic Regression
- 2 Linear Classification and Margins
- 3 Perceptron Learning
- Convergence of Perceptron Learning
- Summary

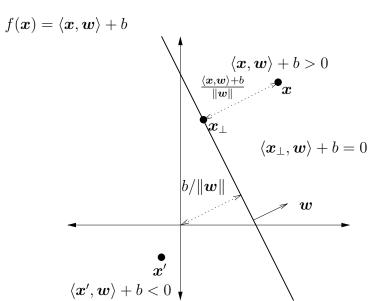


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Linear functions





Decision functions

- Classification assigns an input $x \in \mathcal{X}$ to one of a finite set of classes $\mathcal{Y} = \{\mathcal{C}_1, \dots, \mathcal{C}_m\}$, $2 \leq m$.
- One approach is to learn discriminant functions $\delta_k : \mathcal{X} \to \mathbb{R}$, $1 \leq k \leq m$, and assign a pattern x to class \hat{y} using

$$\hat{y} = h(x) = \operatorname{argmax}_k \delta_k(x)$$
.



Linear classification

We build affine linear decision functions

$$\delta(\boldsymbol{x}) = \sum_{i=1}^{d} w_i x_i + b = \boldsymbol{w}^{\mathsf{T}} \boldsymbol{x} + b$$

with $\boldsymbol{w} \in \mathbb{R}^d$ and $b \in \mathbb{R}$.

• For convenience, we define $\tilde{\boldsymbol{x}}_i^\mathsf{T} = (x_1, \dots, x_d, 1)$ for $i = 1, \dots, N$ and $\tilde{\boldsymbol{w}}^\mathsf{T} = (w_1, \dots, w_d, b)$ and consider the equivalent formulation

$$\delta(\tilde{\boldsymbol{x}}) = \sum_{i=1}^{d+1} \tilde{w}_i \tilde{x}_i = \tilde{\boldsymbol{w}}^\mathsf{T} \tilde{\boldsymbol{x}} \ .$$

We omit the tilde in the following.



Binary decision functions

• If we have only two classes, we can consider a single function

$$\delta(x) = \delta_1(x) - \delta_2(x)$$

and the hypothesis

$$h(x) = \begin{cases} \mathcal{C}_1 & \text{if } \delta(x) > 0 \\ \mathcal{C}_2 & \text{otherwise} \end{cases}.$$

• For $\mathcal{Y} = \{-1, 1\}$ this is equal to

$$h(x) = \operatorname{sgn}(\delta(x)) = \begin{cases} 1 & \text{if } \delta(x) > 0 \\ -1 & \text{otherwise} \end{cases}.$$



Decision functions and class posteriors

• If we know the class posteriors $P(Y \mid X)$ we can perform optimal classification: a pattern x is assigned to class \mathcal{C}_k with maximum $P(Y = \mathcal{C}_k \mid X = x)$, i.e.,

$$\hat{y} = h(x) = \operatorname{argmax}_k P(Y = C_k \mid X = x)$$

or in the binary case with $\mathcal{Y} = \{-1, 1\}$

$$\delta(\boldsymbol{x}) = P(Y = C_1 \mid X = x) - P(Y = C_2 \mid X = x)$$

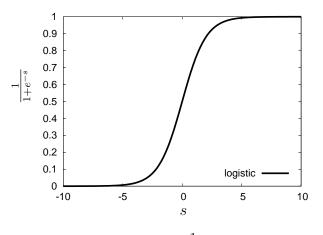
and
$$\hat{y} = h(x) = \operatorname{sgn}(\delta(x))$$
.

• $P(Y = C_k \mid X = x)$ is proportional to the class-conditional density $p(X = x \mid Y = C_k)$ times the class prior $P(Y = C_k)$:

$$P(Y = \mathcal{C}_k \mid X = x) = \frac{p(X = x \mid Y = \mathcal{C}_k)P(Y = \mathcal{C}_k)}{p(X = x)}$$



Logistic function



$$\theta(s) = \frac{1}{1 + e^{-s}}$$



Predicting probabilities

Instead of predicting the class label, we want to learn

$$f(\boldsymbol{x}) = P(Y = 1 \mid X = \boldsymbol{x})$$

assuming that the data is generated by

$$P(Y=y\,|\,X=\boldsymbol{x}) = \begin{cases} f(\boldsymbol{x}) & \text{for } y=1\\ 1-f(\boldsymbol{x}) & \text{for } y=-1 \end{cases}.$$

• In the binary case, our model takes the form $h: \mathcal{X} \to [0,1]$:

$$h(\boldsymbol{x}) = \theta(\boldsymbol{w}^\mathsf{T} \boldsymbol{x})$$



Likelihood function

• Our hypothesis h describes the probability distribution:

$$P(Y = y \,|\, X = \boldsymbol{x}; \boldsymbol{w}) = \theta(y \boldsymbol{w}^\mathsf{T} \boldsymbol{x}) = \begin{cases} \theta(\boldsymbol{w}^\mathsf{T} \boldsymbol{x}) & \text{for } y = 1 \\ 1 - \theta(\boldsymbol{w}^\mathsf{T} \boldsymbol{x}) & \text{for } y = -1 \end{cases}$$

- $S = \{(x_1, y_1), \dots, (x_N, y_N)\} \subseteq (\mathbb{R}^n \times \{-1, 1\})^N$
- Likelihood (function) of the parameters w given training data S is the probability of observing S when the data is generated by h with parameters w.
- Likelihood for i.i.d. S:

$$\prod_{i=1}^N P(Y=y_i \,|\, X=\boldsymbol{x}_i;h) \text{ or short } \prod_{i=1}^N P(y_i \,|\, \boldsymbol{x}_i)$$



Maximum likelihood

- Learning principle: Maximize the likelihood function!
- Equivalently, we can minimize the negative logarithmic likelihood.
- Negative log-likelihood (divided by N):

$$-\frac{1}{N}\ln\left(\prod_{i=1}^{N}P(y_i \mid \boldsymbol{x}_i)\right) = -\frac{1}{N}\sum_{i=1}^{N}\ln\left(P(y_i \mid \boldsymbol{x}_i)\right)$$

Plugging in our linear hypothesis gives the error function:

$$-\frac{1}{N}\sum_{n=1}^{N}\ln\left(\theta(y_n w^{\mathsf{T}}\boldsymbol{x}_n)\right) = \frac{1}{N}\sum_{n=1}^{N}\ln\left(1 + e^{-y_n \boldsymbol{w}^{\mathsf{T}}\boldsymbol{x}_n}\right)$$



Recall: Gradient

• The gradient

$$\nabla f(\boldsymbol{x}) = \left(\frac{\partial f(\boldsymbol{x})}{\partial x_1}, \frac{\partial f(\boldsymbol{x})}{\partial x_2}, \dots, \frac{\partial f(\boldsymbol{x})}{\partial x_d}\right)^{\mathsf{T}}$$

points in the direction $\nabla f(x)/\|\nabla f(x)\|$ giving maximum rate of change $\|\nabla f(x)\|$.



Gradient descent

• Consider learning by iteratively changing the parameters:

$$\boldsymbol{w} \leftarrow \boldsymbol{w} + \Delta \boldsymbol{w}$$

Simplest choice is (steepest) gradient descent

$$\Delta \boldsymbol{w} = -\eta \nabla f|_{\boldsymbol{w}}$$

with learning rate $\eta > 0$.



Gradient for training logistic regression

• For data $\{(\boldsymbol{x}_1,y_1),\ldots,\boldsymbol{x}_N,y_N)\}\subseteq (\mathbb{R}^n\times\{-1,1\})^N$, we have the following gradient of the negative log-likelihood:

$$-\frac{1}{N} \sum_{n=1}^{N} \frac{y_n \boldsymbol{x}_n}{1 + e^{y_n \boldsymbol{w}^{\mathsf{T}} \boldsymbol{x}_n}}$$

This equals:

$$-rac{1}{N}\sum_{n=1}^{N}\left[rac{y_n+1}{2}- heta(oldsymbol{w}^{\mathsf{T}}oldsymbol{x})
ight]oldsymbol{x}_n$$

• Thus, for $\{(\boldsymbol{x}_1,y_1),\ldots,\boldsymbol{x}_N,y_N)\}\subseteq (\mathbb{R}^n\times\{0,1\})^N$, we have:

$$-\frac{1}{N}\sum_{n=1}^{N} [y_n - \theta(\boldsymbol{w}^{\mathsf{T}}\boldsymbol{x})] \boldsymbol{x}_n$$



Logistic regression algorithm (steepest descent)

Algorithm 1: Logistic regression

```
Input: data \{(\boldsymbol{x}_1,y_1),\ldots,\boldsymbol{x}_N,y_N)\}\subseteq (\mathbb{R}^n\times\{-1,1\})^N, learning rate \eta
```

Output: weights of linear hypothesis $h(\boldsymbol{x}) = \langle \boldsymbol{w}, \boldsymbol{x} \rangle$

- $_{f 1}$ initialize w
- 2 repeat

// gradient of negative log-likelihood over
$$N$$

3
$$g \leftarrow -rac{1}{N}\sum_{n=1}^{N}rac{y_nx_n}{1+e^{y_noldsymbol{w}^{\mathsf{T}}}oldsymbol{x}_n}$$
 // model parameter update

4 |
$$oldsymbol{w} \leftarrow oldsymbol{w} - \eta oldsymbol{g}$$

5 until stopping criterion is met



Logistic regression algorithm (stochastic gradient descent, SGD)

Algorithm 2: Logistic regression

```
Input: data \{(\boldsymbol{x}_1,y_1),\dots\}\subseteq (\mathbb{R}^n\times\{-1,1\})^N, learning rate \eta
```

Output: weights of linear hypothesis $h(\boldsymbol{x}) = \langle \boldsymbol{w}, \boldsymbol{x} \rangle$

- ı initialize $oldsymbol{w}$
- 2 repeat
- $\mathbf{z} \mid \mathsf{pick} (\boldsymbol{x}, y) \in S$
- 4 $\boldsymbol{w} \leftarrow \boldsymbol{w} + \eta \frac{y\boldsymbol{x}}{1 + e^{y\boldsymbol{w}^\mathsf{T}}\boldsymbol{x}}$
- 5 until stopping criterion is met



Logistic regression algorithm (mini-batch gradient descent)

Algorithm 3: Logistic regression

Input: data
$$\{(\boldsymbol{x}_1,y_1),\dots\}\subseteq (\mathbb{R}^n\times\{-1,1\})^N$$
, learning rate η

Output: weights of linear hypothesis $h(\boldsymbol{x}) = \langle \boldsymbol{w}, \boldsymbol{x} \rangle$

- ı initialize $oldsymbol{w}$
- 2 repeat

$$s \mid \mathsf{pick}\ S' \subset S$$

4
$$g \leftarrow -\frac{1}{|S'|} \sum_{(oldsymbol{x},y) \in S'} rac{yoldsymbol{x}}{1 + e^{yoldsymbol{w}^{\mathsf{T}}oldsymbol{x}}}$$

5
$$\boldsymbol{w} \leftarrow \boldsymbol{w} - \eta \boldsymbol{g}$$

6 until stopping criterion is met



Multiple classes

• Binary, single decision function, $y \in \{0, 1\}$:

$$P(Y = 1 \mid \boldsymbol{x}) = \frac{1}{1 + e^{-\delta(\boldsymbol{x})}} = \frac{e^{\delta(\boldsymbol{x})}}{1 + e^{\delta(\boldsymbol{x})}}$$

• Binary, two decision functions, $y \in \{1, 2\}$:

$$P(Y = y \mid \boldsymbol{x}) = \frac{e^{\delta_y(\boldsymbol{x})}}{e^{\delta_1(\boldsymbol{x})} + e^{\delta_2(\boldsymbol{x})}} = \frac{e^{\delta_y(\boldsymbol{x}) + C}}{e^{\delta_1(\boldsymbol{x}) + C} + e^{\delta_2(\boldsymbol{x}) + C}}$$

for every constant C, thus logistic function is special case for $C = -\delta_1(\boldsymbol{x})$.

• Multiple classes, $y \in \{1, \dots, m\}$:

$$P(Y = y \mid \boldsymbol{x}) = \underbrace{\frac{e^{\delta_y(\boldsymbol{x})}}{\sum_{i=1}^{m} e^{\delta_i(\boldsymbol{x})}}}_{\text{softmax function}}$$



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Margins I

The functional margin of an example (\boldsymbol{x}_i,y_i) with respect to a hyperplane (\boldsymbol{w},b) is

$$\gamma_i := y_i(\langle \boldsymbol{w}, \boldsymbol{x}_i \rangle + b)$$
.

The geometric margin of an example (\boldsymbol{x}_i,y_i) with respect to a hyperplane (\boldsymbol{w},b) is

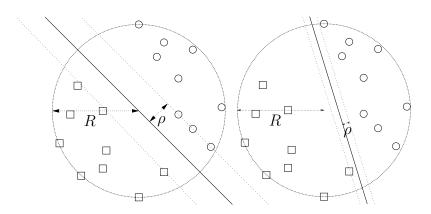
$$\rho_i := y_i(\langle \boldsymbol{w}, \boldsymbol{x}_i \rangle + b) / \|\boldsymbol{w}\| = \gamma_i / \|\boldsymbol{w}\|$$
.

A positive margin implies correct classification.

The margin of a hyperplane (\boldsymbol{w},b) with respect to a training set S is $\min_i \rho_i$. The margin of a training set S is the maximum geometric margin over all hyperplanes. A hyperplane realizing this margin is called maximum margin hyperplane.



Margins II





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Analyzing the Perceptron

Why should we look at the Perceptron?

- Linear classifiers such as perceptrons are the basis of technical neurocomputing
- Support Vector Machines are basically linear classifiers
- Basic concepts of learning theory can be explained easily:
 - Margins
 - Dual representation
 - Bounds involving margins and the radius of the ball containing the data



Perceptron learning algorithm (primal form)

For simplicity, consider hyperplanes with no bias (b=0), i.e., $\mathcal{H} = \{h(\boldsymbol{x}) = \operatorname{sgn}(\langle \boldsymbol{w}, \boldsymbol{x} \rangle) \, | \, \boldsymbol{w} \in \mathbb{R}^n\}.$

Algorithm 4: Perceptron

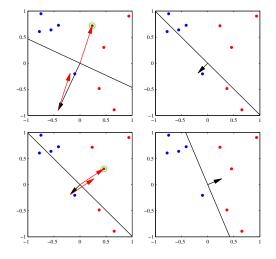
```
Input: separable data \{(\boldsymbol{x}_1,y_1),\dots\}\subseteq (\mathbb{R}^n\times\{-1,1\})^N
Output: hypothesis h(\boldsymbol{x})=\mathrm{sgn}(\langle \boldsymbol{w}_k,\boldsymbol{x}\rangle)
1 \boldsymbol{w}_0\leftarrow\mathbf{0}; k\leftarrow0
2 repeat
```

 $\begin{array}{c|c} \mathbf{3} & \mathbf{for} \ i=1,\ldots,N \ \mathbf{do} \\ \mathbf{4} & \mathbf{if} \ y_i \left< \boldsymbol{w}_k, \boldsymbol{x}_i \right> \leq 0 \ \mathbf{then} \\ \mathbf{5} & \boldsymbol{w}_{k+1} \leftarrow \boldsymbol{w}_k + y_i \boldsymbol{x}_i \\ \mathbf{6} & \boldsymbol{k} \leftarrow k+1 \end{array}$

7 until no mistake made within for loop



Perceptron learning in pictures





C. M. Bishop. Pattern Recognition and Machine Learning. Springer-Verlag, 2006

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Novikoff

Theorem (Novikoff)

Let $S = \{(\boldsymbol{x}_1, y_1), \dots, (\boldsymbol{x}_N, y_N)\}$ be a non-trivial training set (i.e., containing patterns of both classes), $b = \mathbf{0} = \sum_{i=1}^m 0\boldsymbol{x}_i$ and let

$$R \leftarrow \max_{1 \leq i \leq N} \|\boldsymbol{x}_i\|$$
.

Suppose that there exists $oldsymbol{w}_{ ext{opt}}$ and ho>0 such that

$$\| \boldsymbol{w}_{opt} \| = 1$$
 and

$$y_i \left\langle \boldsymbol{w}_{opt}, \boldsymbol{x}_i \right\rangle \ge \rho > 0$$

for $1 \le i \le N$. Then the number of updates k made by the online perceptron algorithm on S is at most

$$\left(\frac{R}{\rho}\right)^2$$



Novikoff, sketch of proof I

Let i be the index of the example in update k

$$\|\boldsymbol{w}_{k+1}\|^2 = \langle \boldsymbol{w}_k + y_i \boldsymbol{x}_i, \boldsymbol{w}_k + y_i \boldsymbol{x}_i \rangle$$

$$= \|\boldsymbol{w}_k\|^2 + 2y_i \langle \boldsymbol{w}_k, \boldsymbol{x}_i \rangle + \|\boldsymbol{x}_i\|^2$$

$$\leq \|\boldsymbol{w}_k\|^2 + R^2$$

$$\leq (k+1)R^2$$



Novikoff, sketch of proof II

$$\langle \boldsymbol{w}_{\mathsf{opt}}, \boldsymbol{w}_{k+1} \rangle = \langle \boldsymbol{w}_{\mathsf{opt}}, \boldsymbol{w}_{k} \rangle + y_{i} \langle \boldsymbol{w}_{\mathsf{opt}}, \boldsymbol{x}_{i} \rangle$$

$$\geq \langle \boldsymbol{w}_{\mathsf{opt}}, \boldsymbol{w}_{k} \rangle + \rho$$

$$\geq (k+1)\rho$$

$$k^2 \rho^2 \le \langle \boldsymbol{w}_{\mathsf{opt}}, \boldsymbol{w}_k \rangle^2 \le \|\boldsymbol{w}_{\mathsf{opt}}\|^2 \|\boldsymbol{w}_k\|^2 \le kR^2$$

$$k \le \frac{R^2}{\rho^2}$$



Dual representation

 Weight vector of hyperplane computed by online perceptron algorithm can be written as

$$m{w} = \sum_{i=1}^N lpha_i y_i m{x}_i$$

• Function $h(\boldsymbol{x}) = \operatorname{sgn}(\delta(\boldsymbol{x}))$ can be written in dual coordinates

$$\delta(\boldsymbol{x}) = \langle \boldsymbol{w}, \boldsymbol{x} \rangle$$

$$= \left\langle \sum_{i=1}^{N} \alpha_i y_i \boldsymbol{x}_i, \boldsymbol{x} \right\rangle$$

$$= \sum_{i=1}^{N} \alpha_i y_i \langle \boldsymbol{x}_i, \boldsymbol{x} \rangle$$



Perceptron learning algorithm (dual form)

Algorithm 5: Perceptron (dual form)

```
Input: separable data \{(\boldsymbol{x}_1,y_1),\dots\}\subseteq (\mathbb{R}^n\times\{-1,1\})^N
   Output: hypothesis h(\boldsymbol{x}) = \mathrm{sgn}\left(\sum_{i=1}^{N} \alpha_i y_i \langle \boldsymbol{x}_i, \boldsymbol{x} \rangle\right)
1 \alpha \leftarrow 0
```

$$\begin{array}{c|c} \mathbf{3} & \mathbf{for} \ i=1,\dots,N \ \mathbf{do} \\ \mathbf{4} & \mathbf{if} \ y_i \sum_{j=1}^N \alpha_j y_j \, \langle \boldsymbol{x}_j,\boldsymbol{x}_i \rangle \leq 0 \ \mathbf{then} \\ \mathbf{5} & \alpha_i \leftarrow \alpha_i + 1 \end{array}$$

6 until no mistake made within for loop



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Summary I

Logistic regression

- is easy to use, has in its simplest form no hyperparameters (not counting η),
- gives surprisingly good results, is highly recommended as baseline method,
- does typically not tend to overfit (assuming $d \ll N$), but does not capture non-linearities,
- can be used with non-linear transformations,
- can be parallelized and is applicable to "Big Data".



Summary II

Hey, we also now know about

- perceptron learning,
- margins,
- dual representation,
- bounds involving margins and the radius of the ball containing the data.

