

# cse291\_hw2\_denoising\_autoencoder

February 16, 2018

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In [1]: %matplotlib inline
import matplotlib
import matplotlib.pyplot as plt
import tensorflow as tf
import numpy as np
import time
import sklearn
from tensorflow.examples.tutorials.mnist import input_data
from sklearn.metrics import euclidean_distances

In [2]: #Read Data
mnist = input_data.read_data_sets(".", one_hot = True)

Extracting .\train-images-idx3-ubyte.gz
Extracting .\train-labels-idx1-ubyte.gz
Extracting .\t10k-images-idx3-ubyte.gz
Extracting .\t10k-labels-idx1-ubyte.gz

In [3]: # def TRAIN_SIZE(num):
#     print ('Total Training Images in Dataset = ' + str(mnist.train.images.shape))
#     print ('-----')
#     x_train = mnist.train.images[:num,:]
#     print ('x_train Examples Loaded = ' + str(x_train.shape))
#     y_train = mnist.train.labels[:num,:]
#     print ('y_train Examples Loaded = ' + str(y_train.shape))
#     print('')
#     return x_train, y_train

def plot_image(img):
    plt.imshow(img.reshape(28,28), cmap="binary")

def gaussian_noise(img, sigma):
    mean = 0
    noisy_img = img + 0.5*np.random.normal(mean, sigma, img.shape)
    return noisy_img

In [4]: def encoder_layer(e):
    conv1 = tf.layers.conv2d(e, filters=32, kernel_size=(3,3), strides=(1,1), \
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        padding='same', activation=tf.nn.relu, name='conv1')
pool1 = tf.layers.max_pooling2d(conv1, pool_size=(2,2), strides=(2,2), name='pool1')
conv2 = tf.layers.conv2d(pool1, filters=16, kernel_size=(3,3), strides=(1,1), \
        padding='same', activation=tf.nn.relu, name='conv2')
pool2 = tf.layers.max_pooling2d(conv2, pool_size=(2,2), strides=(2,2), name='pool2')
flat = tf.reshape(pool2, [-1, 7*7*16])
fc1 = tf.layers.dense(inputs=flat, units=1000, activation=tf.nn.relu)
fc2 = tf.layers.dense(inputs=fc1, units=100, activation=tf.nn.relu)
return fc2

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def decoder_layer(d):
    enc = tf.reshape(d, [-1,10,10,1])
    # deconv1 = tf.layers.conv2d_transpose(enc, filters=32, kernel_size=(5,5), strides=(1,1),
    # padding='valid', activation=tf.nn.relu, name='deconv1')
    # deconv2 = tf.layers.conv2d_transpose(deconv1, filters=1, kernel_size=(3,3), strides=(1,1),
    # padding='same', name='deconv2')
    deconv1 = tf.layers.conv2d_transpose(enc, filters=32, kernel_size=(5,5), strides=(1,1),
        padding='valid', activation=tf.nn.relu, name='deconv1')
    deconv2 = tf.layers.conv2d_transpose(deconv1, filters=1, kernel_size=(3,3), strides=(1,1),
        padding='same', name='deconv2')
    return deconv2

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In [5]: #Placeholder for original noise free images
TARGET = tf.placeholder(tf.float32, [None, 784])
#Reshape original images
target = tf.reshape(TARGET, [-1, 28, 28, 1])

#Placeholder for noisy input images
X = tf.placeholder(tf.float32, [None, 784])
#Reshape noisy images
x = tf.reshape(X, [-1, 28, 28, 1])

encode = encoder_layer(x)
decode = decoder_layer(encode)

# reshape reconstructed image
RECONSTRUCTED = tf.reshape(decode, [-1,784])

loss = tf.reduce_mean(tf.square(TARGET-RECONSTRUCTED))
opt = tf.train.AdamOptimizer(learning_rate=0.009).minimize(loss)

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In [6]: sess = tf.InteractiveSession()
tf.global_variables_initializer().run()

#Make batches to train
epochs = 1
batch_size = 128

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loss_val = []

for epoch in range(epochs):
    total_loss = 0.0
    for i in range(mnist.train.num_examples//batch_size):
        orig, _ = mnist.train.next_batch(batch_size)
        noisy = gaussian_noise(orig, 0.1)
        _, L, R = sess.run([opt, loss, RECONSTRUCTED], feed_dict = {TARGET: orig, X: noi
        loss_val.append(L)
        print(i, ': ', L)
        total_loss += L
    print('Epoch {} - Total loss: {}'.format(epoch+1, total_loss))

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0 : 0.114301525  
1 : 0.11273749  
2 : 0.101647675  
3 : 0.096594624  
4 : 0.09525443  
5 : 0.082287766  
6 : 0.07695998  
7 : 0.08388837  
8 : 0.07779556  
9 : 0.073846556  
10 : 0.07389357  
11 : 0.077573165  
12 : 0.07648513  
13 : 0.073966116  
14 : 0.07251046  
15 : 0.07197156  
16 : 0.07383  
17 : 0.07106408  
18 : 0.06916287  
19 : 0.068117656  
20 : 0.06462246  
21 : 0.067905605  
22 : 0.06902473  
23 : 0.06766471  
24 : 0.06893855  
25 : 0.06464924  
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27 : 0.06481902  
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370 : 0.03271362

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399 : 0.032188255  
400 : 0.03205135  
401 : 0.031272415  
402 : 0.031246493  
403 : 0.031140924  
404 : 0.032461464  
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406 : 0.030477531  
407 : 0.031411987  
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409 : 0.0319795  
410 : 0.03181419  
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412 : 0.03269819  
413 : 0.032109357  
414 : 0.03156284  
415 : 0.03207601  
416 : 0.032088295  
417 : 0.032330003  
418 : 0.033526868

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419 : 0.03310865
420 : 0.033171892
421 : 0.030739402
422 : 0.03167176
423 : 0.03323218
424 : 0.032205094
425 : 0.031271532
426 : 0.03309433
427 : 0.0348631
428 : 0.03408198
Epoch 1 - Total loss: 17.911468723788857

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```

In [9]: # Examples to test reconstruction
        n_examples = 10

        test_orig, _ = mnist.test.next_batch(n_examples)
        test_noisy = gaussian_noise(test_orig, 0.1)
        recon = sess.run(RECONSTRUCTED, feed_dict = {TARGET: test_orig, X: test_noisy})
        # print(recon.shape)

        # Visualize original, noisy and reconstructed images
        #     Row 1 : Original
        #     Row 2 : Noisy
        #     Row 3 : Reconstructed
        fig, axs = plt.subplots(3, n_examples, figsize=(15,4))
        for example_i in range(n_examples):
            axs[0][example_i].imshow(np.reshape(test_orig[example_i,:], (28, 28)))
            axs[1][example_i].imshow(np.reshape(test_noisy[example_i,:], (28, 28)))
            axs[2][example_i].imshow(np.reshape(recon[example_i, :], (28, 28)))

```

