

```
function pointCloud = farthest_point_sampling(obj_file)
% get data from parser,
% modified object file reader function implemented by someone else
obj = wf_load(obj_file);

% get vertices and faces of the object
vert = obj.vertex;
face = obj.faces;

% calculate area and weights of triangles in mesh
area_tri = tri_area_mesh(vert,face);
weight = area_tri/sum(area_tri);

% determine number of points to sample from each triangle
total_pts = 10000;
num_pts = round(weight*total_pts);

% sampling of about 10K points
P = zeros(sum(num_pts),3);
count = 1;

for i=1:size(face,1)
    vert1 = vert(face(i,1),:);
    vert2 = vert(face(i,2),:);
    vert3 = vert(face(i,3),:);
    D = sample_pts(vert1, vert2, vert3, num_pts(i));

    P(count:(count+num_pts(i)-1),:) = D;
    count = count+num_pts(i);
end

% calculation of distance matrix
dist_mat = pdist2(P,P);

% farthest point sampling pipeline
S = zeros(1000,3);
S_ind = zeros(1000,1); % index of point from set P

init = randi([1,size(P,1)]);
S(1,:) = P(init,:); % initial pt
S_ind(1) = init;
dist = dist_mat(init,:);

for i=2:1000
    [max_val, ind] = max(dist);
    S(i,:) = P(ind,:);
    S_ind(i) = ind;
    dist_new = dist_mat(ind,:);
    dist = min(dist, dist_new);
end
```

```
pointCloud = S;
end
```

```
function area = tri_area_mesh(ver, face)
    s12 = ver(face(:,2),:) - ver(face(:,1),:);
    s13 = ver(face(:,3),:) - ver(face(:,1),:);
    val = cross(s12,s13);
    area = 0.5 * sqrt(val(:,1).^2 + val(:,2).^2 + val(:,3).^2);
end
```

```
function D = sample_pts(A, B, C, numPts)
    r = rand(numPts,2);
    r1 = sqrt(r(:,1));
    r2 = r(:,2);
    D = ((1-r1)*A) + ((r1.*(1-r2))*B) + ((r1.*r2)*C);
end
```

```
%%
function bundle = wf_load(filename)
% WF_LOAD Loads a wavefront object from a file.
% OBJ = WF_LOAD(FILENAME) Loads a 3D model contained in the file with
% the given FILENAME. The file must be in the format specified by the
% Wavefront specification. The full specification can be found in the
% following URL:
%
% http://netghost.narod.ru/gff/vendspec/waveobj/obj_spec.txt
%
% Generally speaking, a wavefront object is a structure which contains
% the XYZ coordinates of points in a 3D space. These points are used as
% reference points to define polygons, lines, curves and surfaces which
% define the object. The structure contains the required information to
% construct the 3D object. This information may specify a set of
% vertices and the way in which such a set should be connected to form a
% polygon.
%
% Example 1
% -----
% This is an example of how a simple cube would be represented in a .obj
% file:
%
% # Vertices
% v -0.5 -0.5 -0.5
% v -0.5 -0.5 0.5
% v -0.5 0.5 -0.5
% v -0.5 0.5 0.5
% v 0.5 -0.5 -0.5
% v 0.5 -0.5 0.5
% v 0.5 0.5 -0.5
% v 0.5 0.5 0.5
```

```

%
%      # Triangle facets
%      f  1  7  5
%      f  1  3  7
%      f  2  6  8
%      f  2  8  4
%      f  1  4  3
%      f  1  2  4
%      f  3  8  7
%      f  3  4  8
%      f  5  7  8
%      f  5  8  6
%      f  1  5  6
%      f  1  6  2
%
%      In the example above the vertices of the cube are defined first,
%      and then the vertices are joined to form triangular facets, which form
%      the cube. In this case, the 1st ( -0.5 -0.5 -0.5 ), 7th (  0.5  0.5
%      -0.5 ) and 5th ( 0.5 -0.5 -0.5 ) vertices form the first face, and
%      so on.
%
%      NOTES:
%      - Parser is very lazy and will not generate errors on for badly
%      formatted OBJ files.
%      - Parser does not implement some statements (free-form geometry
%      statements), however a warning is displayed when a non-implemented
%      method is encountered.
%
%      See also ISWF

file = fopen(filename,'r');
if file < 0
    error([ 'Could not open file: ' filename ]);
else
    disp(['Reading file: ' filename]);
end

% Initialize object fields
bundle.vertex    = [];
bundle.vtex      = [];
bundle.vnorm     = [];
bundle.vparam    = [];
bundle.points    = {};
bundle.lines     = {};
bundle.faces     = [];
% bundle.faces    = {};
bundle.curvs     = [];
bundle.curvs2    = [];
bundle.surfs     = [];
bundle.conn      = [];

```

```
curv_surf      = [];  
  
while ~feof(file)  
    elems = getline(file);  
  
    if ~isempty(elems)  
        command = lower(elems{1});  
  
        if command(1)=='#' % It is a comment, do nothing  
        elseif strcmp(command,'v') % GEOMETRIC VERTICES  
            x = str2double(elems{2});  
            y = str2double(elems{3});  
            z = str2double(elems{4});  
            % if length(elems)>=5  
            %     w = str2double(elems{5});  
            % else  
            %     w = 1;  
            % end  
            % bundle.vertex = [ bundle.vertex; x y z w ];  
            bundle.vertex = [ bundle.vertex; x y z ];  
        elseif strcmp(command,'vt') % TEXTURE VERTICES  
            u = str2double(elems{2});  
            v = str2double(elems{3});  
            if length(elems)>=4  
                w = str2double(elems{4});  
            else  
                w = 0;  
            end  
            bundle.vtex = [ bundle.vtex; u v w ];  
        elseif strcmp(command,'vn') % VERTEX NORMALS  
            i = str2double(elems{2});  
            j = str2double(elems{3});  
            k = str2double(elems{4});  
            bundle.vnorm = [ bundle.vnorm; i j k ];  
        elseif strcmp(command,'vp') % PARAMETER SPACE VERTICES  
            u = str2double(elems{2});  
            v = str2double(elems{3});  
            if length(elems)>=4  
                w = str2double(elems{4});  
            else  
                w = 1;  
            end  
            bundle.vparam = [ bundle.vparam; u v w ];  
        elseif strcmp(command,'cstype') % CURVE/SURFACE TYPE  
            if length(elems)==2  
                rat = false;  
                type = lower(elems{2});  
            elseif length(elems)==3  
                if strcmpi(elems{2},'rat')
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```
        rat = true;
    end
    type = lower(elems{3});
end
if sum(strcmp(type, {'bmatrix','bezier','bspline',...
    'cardinal','taylor'}))
    curv_surf = getFFCurvSurf(file,rat,type);
end

elseif strcmp(command,'curv')    % CURVE
    if isempty(curv_surf)
        error(' ERROR: CSTYPE not defined while defining CURV');
    else
        curv = curv_surf;    % Makes a copy with the same values
    end
    curv.u0 = str2double(elems{2});
    curv.u1 = str2double(elems{3});

    curv.v = zeros(length(elems)-3,1);
    curv.v(1) = getTriplet(elems{4}, bundle);
    curv.v(2) = getTriplet(elems{5}, bundle);
    for i=3:size(curv.v,1)
        curv.v(i) = getTriplet(elems{i+3}, bundle);
    end
    curv = getCSBodyStatements(file,curv);
    bundle.curvs = [ bundle.curvs ; curv ];
elseif strcmp(command,'curv2')    % CURVE 2
    if isempty(curv_surf)
        error(' ERROR: CSTYPE not defined while defining CURV2');
    else
        curv2 = curv_surf;    % Makes a copy with the same values
    end
    curv2.vp = zeros(length(elems)-1,1);
    curv2.vp(1) = handleNegVert(str2double(elems{2}), ...
        size(bundle.vparam,1));
    curv2.vp(2) = handleNegVert(str2double(elems{3}), ...
        size(bundle.vparam,1));
    for i=3:size(curv2.vp,1)
        curv2.vp(i) = handleNegVert(str2double(elems{i+1}), ...
            size(bundle.vparam,1));
    end
    curv2 = getCSBodyStatements(file,curv2);
    bundle.curvs2 = [ bundle.curvs2 ; curv2 ];
elseif strcmp(command,'surf')    % SURFACE
    if isempty(curv_surf)
        error(' ERROR: CSTYPE not defined while defining SURF');
    else
        surf = curv_surf;    % Makes a copy with the same values
    end
    surf.s0 = str2double(elems{2});
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surf.s1 = str2double(elems{3});
surf.t0 = str2double(elems{4});
surf.t1 = str2double(elems{5});

surf.v = zeros(length(elems)-5,3);
for i=1:size(surf.v,1)
    [ surf.v(i,1) surf.v(i,2) surf.v(i,3) ] = ...
        getTriplet(elems{i+5}, bundle);
end
surf = getCSBodyStatements(file,surf);
bundle.surfs = [ bundle.surfs ; surf ];
elseif strcmp(command,'p')          % POINT
p = zeros(length(elems)-1,1);
for i=1:size(p,1)
    p(i) = getTriplet(elems{i+1}, bundle);
end
bundle.points = [ bundle.points ; p ];
elseif strcmp(command,'l')          % LINE
l = zeros(length(elems)-1,2);
for i=1:size(l,1)
    [ l(i,1) l(i,2) ] = getTriplet(elems{i+1}, bundle);
end
bundle.lines = [ bundle.lines ; l ];
elseif strcmp(command,'f')          % FACE
f1 = str2num(elems{2});
f2 = str2num(elems{3});
f3 = str2num(elems{4});
bundle.faces = [ bundle.faces; f1 f2 f3 ];
% elseif strcmp(command,'f')          % FACE
% f = zeros(length(elems)-1,3);
% for i=1:size(f,1)
%     [ f(i,1) f(i,2) f(i,3) ] = getTriplet(elems{i+1}, bundle);
% end
% bundle.faces = [ bundle.faces ; f ];
%
% elseif strcmp(command,'v')          % GEOMETRIC VERTICES
% x = str2double(elems{2});
% y = str2double(elems{3});
% z = str2double(elems{4});
% if length(elems)>=5
%     w = str2double(elems{5});
% else
%     w = 1;
% end
% bundle.vertex = [ bundle.vertex; x y z w ];
elseif strcmp(command,'con')        % CONNECTIVITY
conn.surf_1 = str2double(elems{2});
conn.q0_1   = str2double(elems{3});
conn.q1_1   = str2double(elems{4});

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```
conn.curv2d_1=str2double(elems{5});
conn.surf_2 = str2double(elems{6});
conn.q0_2   = str2double(elems{7});
conn.q1_2   = str2double(elems{8});
conn.curv2d_2=str2double(elems{9});

bundle.conn = [ bundle.conn ; conn ];
elseif strcmp(command,'g')      % GROUP NAME
    unimplemented(command,filename);
elseif strcmp(command,'s')      % SMOOTHING GROUP
    unimplemented(command,filename);
elseif strcmp(command,'mg')     % MERGING GROUP
    unimplemented(command,filename);
elseif strcmp(command,'o')      % OBJECT NAME
    unimplemented(command,filename);
elseif strcmp(command,'bevel')  % BEVEL INTERPOLATION
    unimplemented(command,filename);
elseif strcmp(command,'c_interp') % COLOUR INTERPOLATION
    unimplemented(command,filename);
elseif strcmp(command,'d_interp') % DISSOLVE INTERPOLATION
    unimplemented(command,filename);
elseif strcmp(command,'lod')    % LEVEL OF DETAIL
    unimplemented(command,filename);
elseif strcmp(command,'maplib') % LIBRARY MAP
    unimplemented(command,filename);
elseif strcmp(command,'usemap') % TEXTURE MAP
    unimplemented(command,filename);
elseif strcmp(command,'usentl') % MATERIAL
    unimplemented(command,filename);
elseif strcmp(command,'mtllib') % MATERIAL LIBRARY
    unimplemented(command,filename);
elseif strcmp(command,'shadow_obj') % SHADOW
    unimplemented(command,filename);
elseif strcmp(command,'trace_obj') % RAY TRACING
    unimplemented(command,filename);
else
    disp(['Unknown element: ' command]);
end
end
end

fclose(file);

function curv_surf = getFFCurvSurf(fid,rat,type)
% Create Curvature/Surface object
curv_surf.type = type;
curv_surf.israt = rat;

doit = 1;
while doit && ~feof(fid)
```

```
pos = ftell(fid);
elems = getline(fid);
if ~isempty(elems)
    command = lower(elems{1});

    if strcmp(command, 'deg') % DEGREE
        if strcmp(curv_surf.type, 'cardinal')
            curv_surf.degu = 3;
        else
            curv_surf.degu = str2double(elems{2});
        end

        if length(elems) >= 3
            if strcmp(curv_surf.type, 'cardinal')
                curv_surf.degv = 3;
            else
                curv_surf.degv = str2double(elems{3});
            end
        end
    elseif strcmp(command, 'bmat') % BASIS MATRIX
        if strcmpi(elems{2}, 'u')
            deg = curv_surf.degu;
        elseif strcmpi(elems{2}, 'v')
            deg = curv_surf.degv;
        end

        mat = zeros(deg+1);
        idx = 3;
        for i=1:deg+1;
            for j=1:deg+1;
                mat(i,j) = str2double(elems{idx});
                idx = idx + 1;
            end
        end

        if strcmpi(elems{2}, 'u')
            curv_surf.matu = mat;
        elseif strcmpi(elems{2}, 'v')
            curv_surf.matv = mat;
        end
    elseif strcmp(command, 'step') % STEP
        curv_surf.stepu = str2double(elems{2});
        if length(elems) >= 3
            curv_surf.stepv = str2double(elems{3});
        end
    elseif strcmp(command, 'ctech') % CURVE APPROX TECHNIQUE
        unimplemented(command, ' ');
    elseif strcmp(command, 'stech') % SURFACE APPROX TECHNIQUE
        unimplemented(command, ' ');
    else % NON CURV/SURF ELEMENT - UNREAD
```



```
        doit = 0;
        fseek(fid,pos,'bof');
    end
end
end

function strs = getline(fid)
% Lines can be logically joined with the line continuation character ( \ )
% at the end of a line.
doit = 1;
strs = {};

while doit && ~feof(fid)
    line = fgetl(fid);
    line = strtrim(line);
    if ~isempty(line)
        elems = textscan(line,'%s');
        elems = elems{1};

        if strcmp('\', elems(length(elems)))
            elems(length(elems)) = [];
        else
            doit = 0;
        end
        strs = vertcat(strs,elems);
    end
end

function [ v vt vn ] = getTriplet(str, bundle)
x = textscan(str,'%n%n%n','delimiter','/');
v = handleNegVert(x{1}, size(bundle.vertex,1));
if isempty(x{2})
    vt = NaN;
else
    vt = handleNegVert(x{2}, size(bundle.vtex,1));
end
if isempty(x{3})
    vn = NaN;
else
    vn = handleNegVert(x{3}, size(bundle.vnorm,1));
end

function cs = getCSBodyStatements(fid,cs)
% Body statements are valid only when they appear between the free-form
% element statement (curv, curv2, surf) and the end statement. If they
% are anywhere else in the .obj file, they do not have any effect.
%
% You can use body statements to specify the following values:
%     parameter
%     knot vector
```

```
%      trimming loop
%      hole
%      special curve
%      special point
cs.body = {};

doit = true;
while doit && ~feof(fid)
    pos = ftell(fid);
    elems = getline(fid);
    if ~isempty(elems)
        command = lower(elems{1});

        if strcmp(command,'parm')      % PARAMETER
            x = struct;
            x.type = command;
            x.p = zeros(length(elems)-2,1);
            x.p(1) = str2double(elems{3});
            x.p(2) = str2double(elems{4});
            for i=3:size(x.p,1)
                x.p(i) = str2double(elems{i+2});
            end
            if strcmpi(elems{2},'u')
                x.dir = 'u';
            elseif strcmpi(elems{2},'v')
                x.dir = 'v';
            end
            cs.body = [ cs.body ; x ];
        elseif strcmp(command,'trim') || ... % TRIM or
            strcmp(command,'hole') || ... % HOLE or
            strcmp(command,'scrv')      % SPECIAL CURVE
            x = struct;
            x.type = command;
            x.curv = zeros((length(elems)-1)/3,1);
            x.u = zeros((length(elems)-1)/3,2);
            for i=1:size(x.curv,1)
                x.u(i,1) = str2double(elems{i*3-1});
                x.u(i,2) = str2double(elems{i*3});
                x.curv(i) = str2double(elems{i*3+1});
            end
            cs.body = [ cs.body ; x ];
        elseif strcmp(command,'sp')      % SPECIAL POINT
            x = struct;
            x.type = command;
            x.vp = zeros(length(elems)-1,1);
            for i=1:size(x.vp,1)
                x.vp(i) = str2double(elems{i+1});
            end
            cs.body = [ cs.body ; x ];
        elseif strcmp(command,'end') % END
```

```
        doit = false;
    else % NON CURV/SURF ELEMENT - UNREAD
        doit = false;
        fseek(fid,pos,'bof');
    end
end
end

function unimplemented(command, file)
    disp(['WARNING: ' command ' was found in file ' file ...
        ' but it was omitted by the parser! ']);

function v = handleNegVert(v1, v2)
    if v1<0
        v = 1 + v2 + v1;
    else
        v = v1;
    end
```